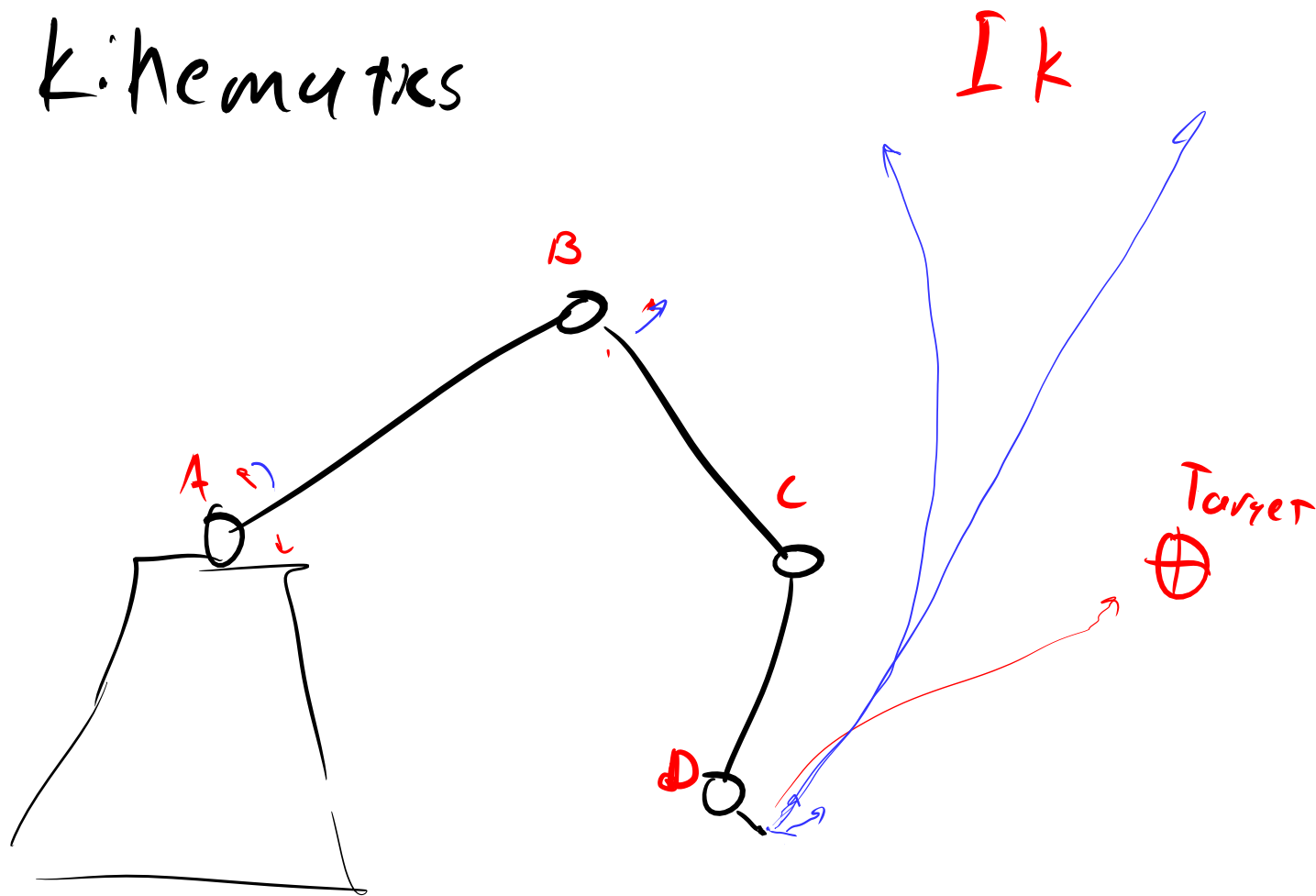


Forward Kinematics

Inverse Kinematics

	x	y
A	3	2.8
B	3.2	0.7



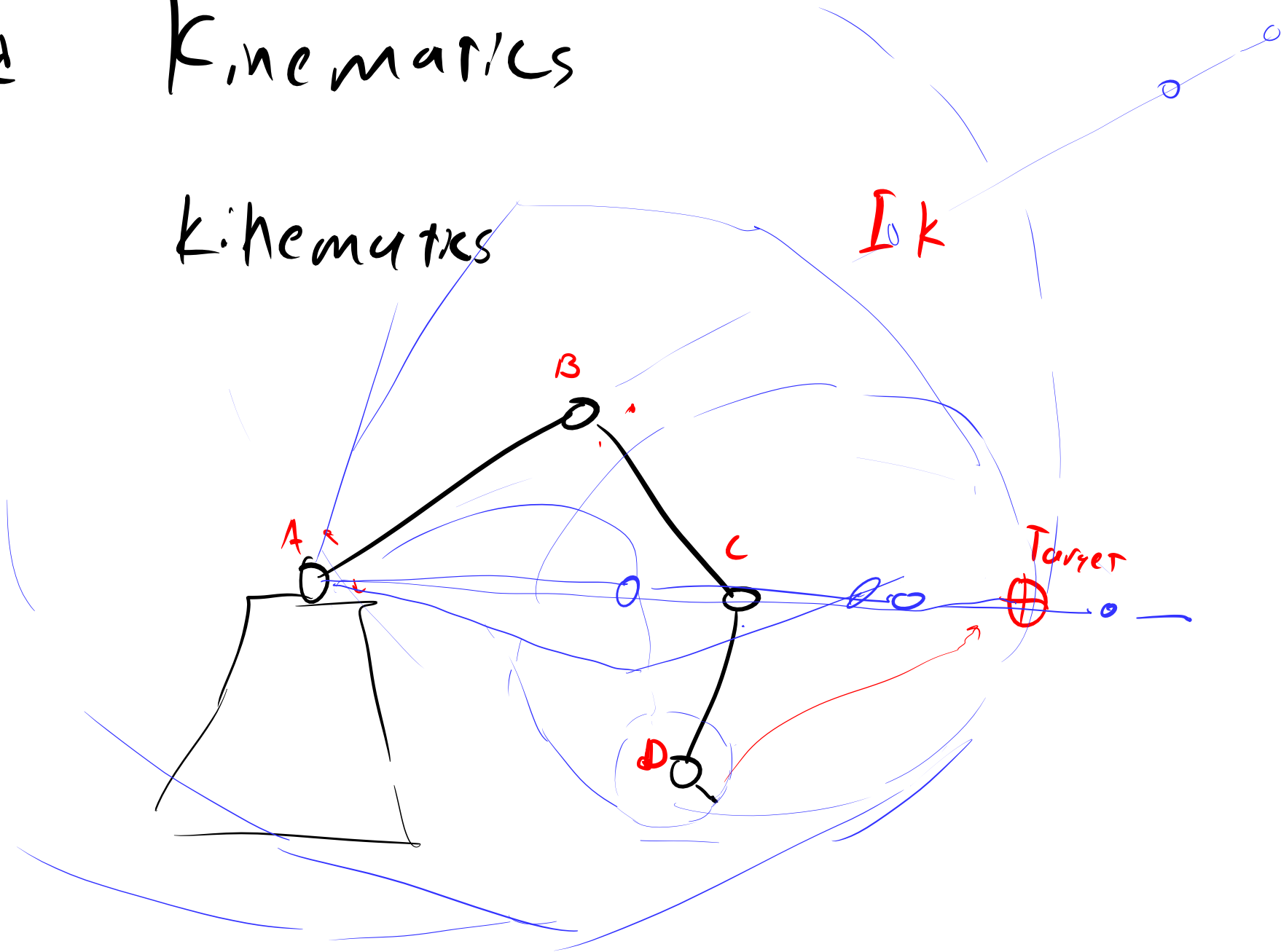
Forward

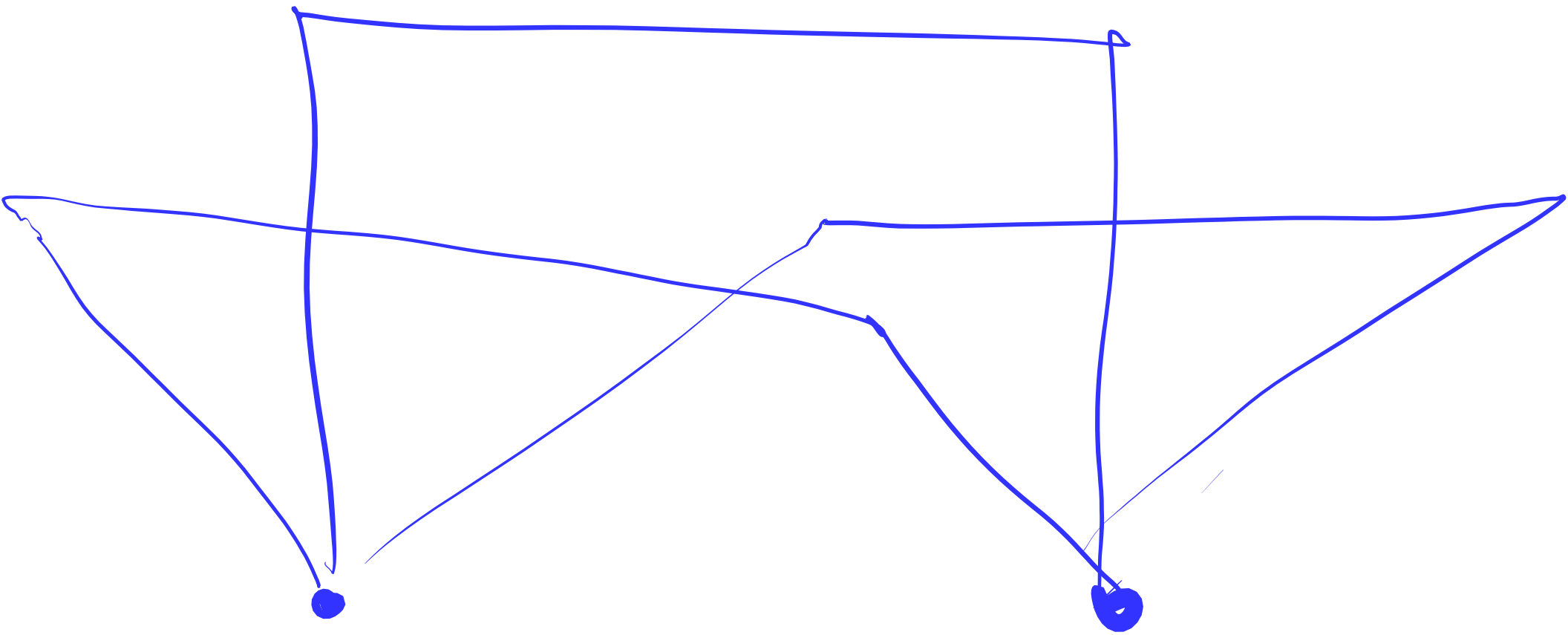
Kinematics

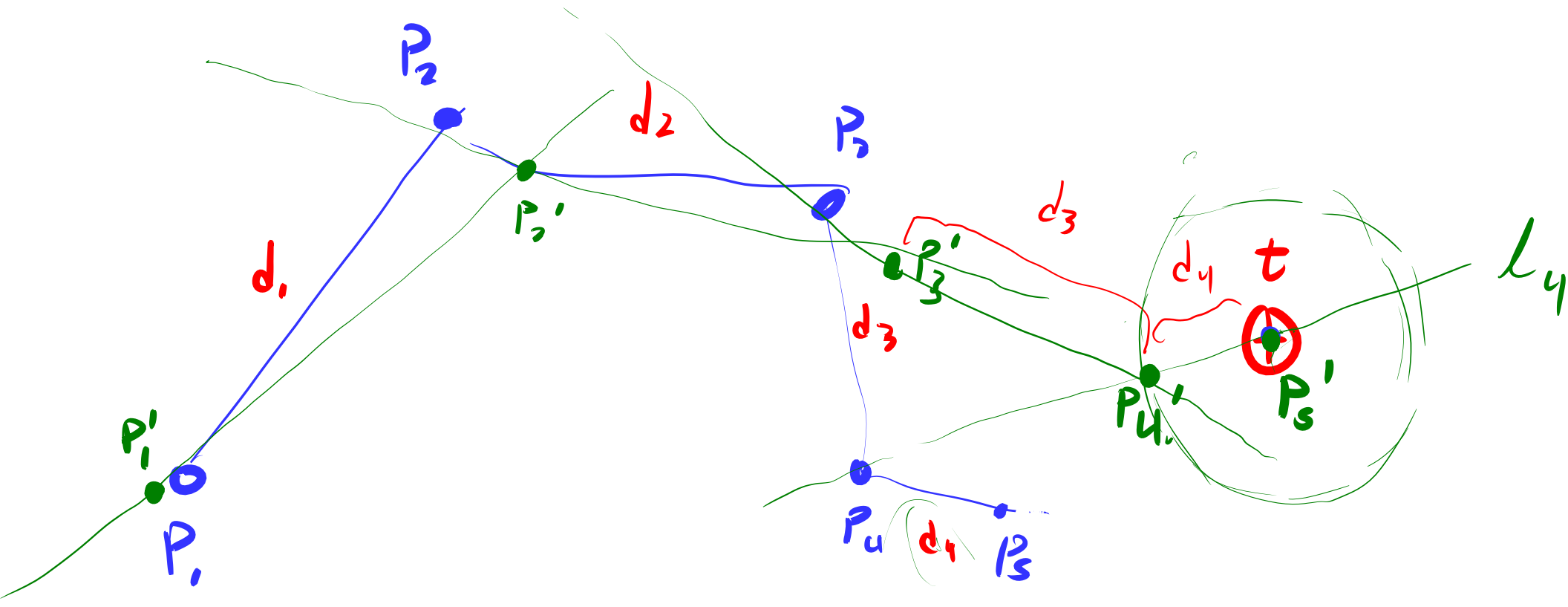
Inverse

Kinematics

I_k



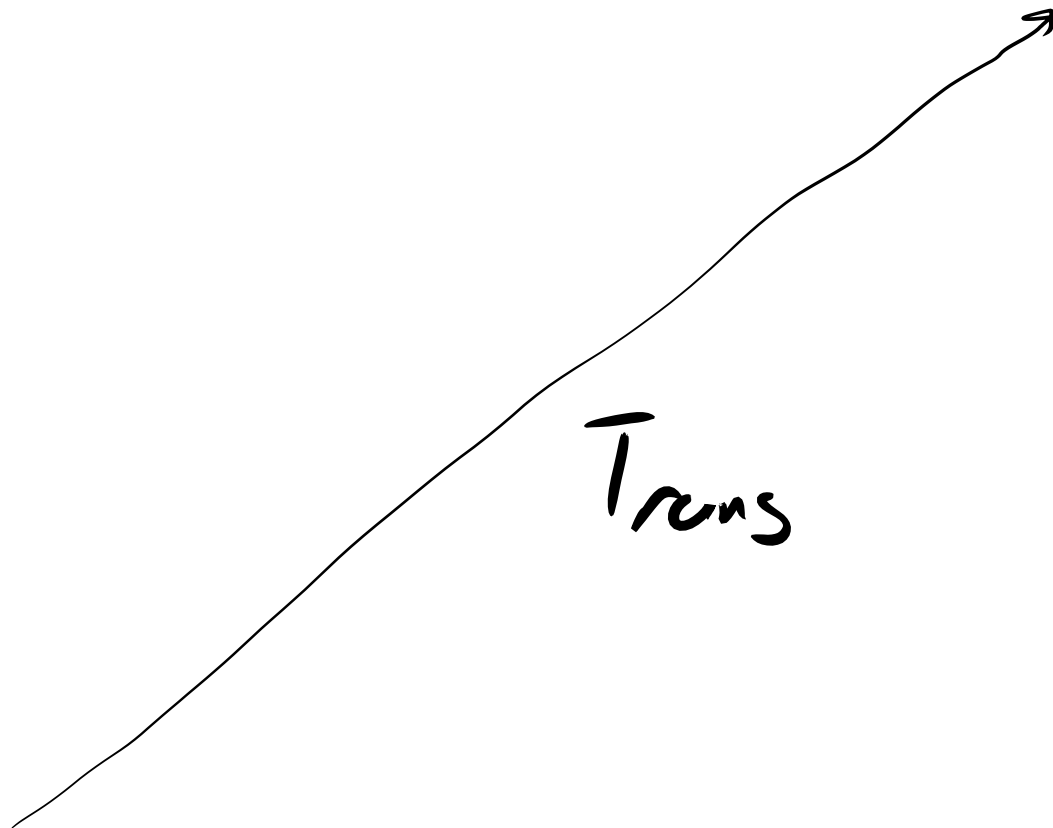




t



T



Trans

P



t

