UVA CS 4501 - 001 / 6501 - 007

Introduction to Machine Learning and Data Mining

Lecture 3: Linear Regression

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Last Lecture Recap

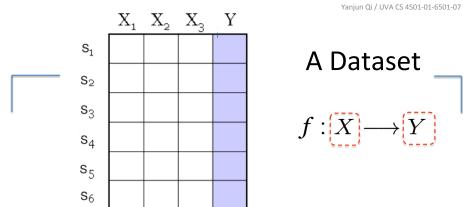
- Data Representation
- ☐ Linear Algebra Review

e.g. SUPERVISED LEARNING

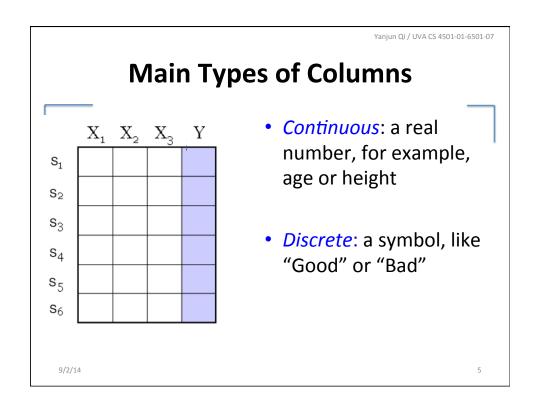
 $f: X \longrightarrow Y$

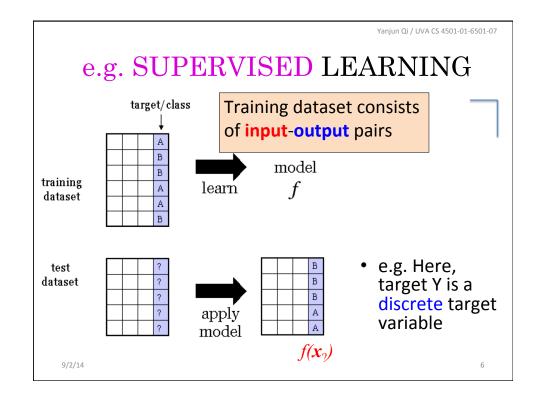
- Find function to map input space X to output space Y
- So that the difference between y and f(x)of each example x is small.

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- Data/points/instances/examples/samples/records: [rows]
- Features/attributes/dimensions/independent variables/covariates/ predictors/regressors: [columns, except the last]
- Target/outcome/response/label/dependent variable: special column to be predicted [last column]





MATRIX OPERATIONS

- 1) Transposition
- 2) Addition and Subtraction
- 3) Multiplication
- 4) Norm (of vector)
- 5) Matrix Inversion
- 6) Matrix Rank
- 7) Matrix calculus

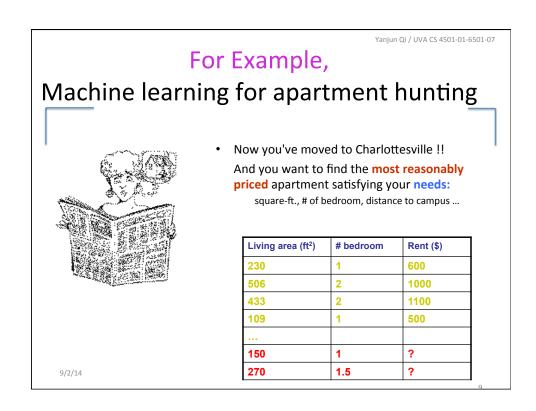
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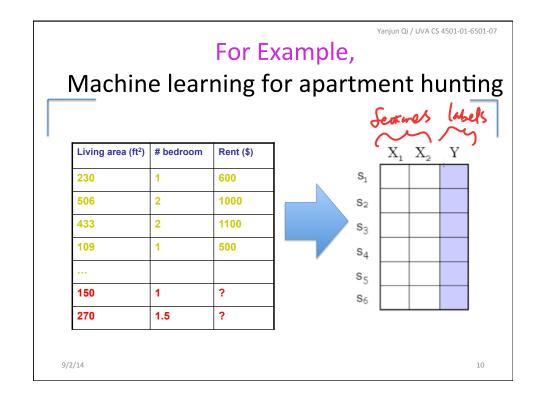
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Today

- ☐ Linear regression (aka least squares)
- ☐ Learn to derive the least squares estimate by optimization
- ☐ Evaluation with Cross-validation

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Linear SUPERVISED LEARNING

$$f: X \longrightarrow Y$$

e.g.
$$\hat{y} = f(x) = \theta_0 + \theta_1 x^1 + \theta_2 x^2$$

Features:

Living area, distance to campus, # bedroom ...

Target:

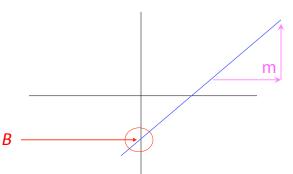
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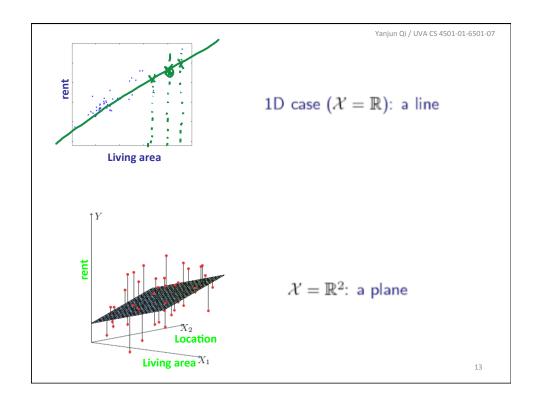
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Remember this: "Linear"?

Y=mX+B?

A slope of 2 (i.e. m=2) means that every 1-unit change in X yields a 2-unit change in Y.





A new representation

- Assume that each sample **x** is a column vector,
 - Here we assume a vacuous "feature" X^0 =1 (this is the intercept term), and define the feature vector to be:

$$\mathbf{x}^{\mathbf{T}} = [x^0, x^1, x^2, \dots x^{p-1}]$$

– the parameter vector heta is also a column vector



 $\hat{\mathbf{y}} = f(\mathbf{x}) = \mathbf{x}^T \boldsymbol{\theta}$

Training / learning problem

• We can represent the whole Training set:

$$\mathbf{X} = \begin{bmatrix} -- & \mathbf{x}_1^T & -- \\ -- & \mathbf{x}_2^T & -- \\ \vdots & \vdots & \vdots \\ -- & \mathbf{x}_n^T & -- \end{bmatrix} = \begin{bmatrix} x_1^0 & x_1^1 & \dots & x_1^{p-1} \\ x_2^0 & x_2^1 & \dots & x_2^{p-1} \\ \vdots & \vdots & \vdots & \vdots \\ x_n^0 & x_n^1 & \dots & x_n^{p-1} \end{bmatrix}$$

$$\mathbf{Y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \\ \frac{9/2/14}{} \end{bmatrix}$$

• Predicted output $\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$ • Predicted output $for each training \\ sample:$ $\begin{bmatrix} f(\mathbf{x}_1^T) \\ f(\mathbf{x}_2^T) \\ \vdots \\ f(\mathbf{x}_n^T) \end{bmatrix} = \begin{bmatrix} \mathbf{x}_1^T \theta \\ \mathbf{x}_2^T \theta \\ \vdots \\ \mathbf{x}_n^T \theta \end{bmatrix} = X\theta$

$$\begin{bmatrix} f(\mathbf{x}_1^T) \\ f(\mathbf{x}_2^T) \\ \vdots \\ f(\mathbf{x}_n^T) \end{bmatrix} = \begin{bmatrix} \mathbf{x}_1^T \theta \\ \mathbf{x}_2^T \theta \\ \vdots \\ \mathbf{x}_n^T \theta \end{bmatrix} = X\theta$$

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training / learning goal

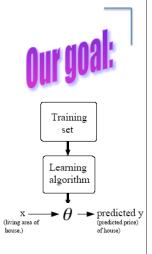
 Using matrix form, we get the following general representation of the linear function:

$$\mathbf{\hat{Y}} = X\theta$$

$$\mathbf{\hat{y}} = \mathbf{\hat{y}} + \mathbf{\hat{y}} +$$

• Our goal is to pick the optimal hetathat minimize the following cost function:

 $J(\theta) = \frac{1}{2} \sum_{i=1}^{n} (f(\vec{x}_i) - y_i)^2$



Today

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Method I: normal equations

• Write the cost function in matrix form:

$$J(\theta) = \frac{1}{2} \sum_{i=1}^{n} (\mathbf{x}_{i}^{T} \theta - y_{i})^{2}$$

$$= \frac{1}{2} (X\theta - \bar{y})^{T} (X\theta - \bar{y})$$

$$= \frac{1}{2} (\theta^{T} X^{T} X \theta - \theta^{T} X^{T} \bar{y} - \bar{y}^{T} X \theta + \bar{y}^{T} \bar{y})$$

$$\mathbf{X} = \begin{bmatrix} -- & \mathbf{x}_{1}^{T} & -- \\ -- & \mathbf{x}_{2}^{T} & -- \\ \vdots & \vdots & \vdots \\ -- & \mathbf{x}_{n}^{T} & -- \end{bmatrix}$$

$$\mathbf{Y} = \begin{bmatrix} y_{1} \\ y_{2} \\ \vdots \\ y_{n} \end{bmatrix}$$

To minimize $J(\theta)$, take derivative and set to zero:

$$\Rightarrow X^T X \theta = X^T \bar{y}$$
The normal equations

$$\boldsymbol{\theta}^* = \left(\boldsymbol{X}^T \boldsymbol{X}\right)^{-1} \boldsymbol{X}^T \vec{\boldsymbol{y}}$$

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IX

Review: Special Uses for Matrix Multiplication

Dot (or Inner) Product of two Vectors <x, y>

which is the sum of products of elements in similar positions for the two vectors

$$< x, y > = < y, x >$$

Where
$$\langle \mathbf{x}, \mathbf{y} \rangle = x^T y \in \mathbb{R} = \begin{bmatrix} x_1 & x_2 & \cdots & x_n \end{bmatrix} \begin{bmatrix} y_1 \\ x_2 \\ \vdots \\ y_n \end{bmatrix} = \sum_{i=1}^n x_i y_i.$$

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Review: Special Uses for Matrix Multiplication

- Sum the Squared Elements of a Vector
 - Premultiply a column vector a by its transpose
 If

$$\mathbf{a} = \begin{bmatrix} 5 \\ 2 \\ 8 \end{bmatrix}$$

then premultiplication by a row vector **a**^T

$$a^T = \begin{bmatrix} 5 & 2 & 8 \end{bmatrix}$$

will yield the sum of the squared values of elements for **a**, i.e.

$$\mathbf{a}^{\mathsf{T}}\mathbf{a} = \begin{bmatrix} 5 & 2 & 8 \end{bmatrix} \begin{bmatrix} 5 \\ 2 \\ 8 \end{bmatrix} = 5^2 + 2^2 + 8^2 = 93$$

Review: Matrix Calculus: Types of Matrix Derivatives

	Scalar	Vector	Matrix
Scalar	$\frac{\mathrm{d}y}{\mathrm{d}x}$	$\frac{\mathrm{d}\mathbf{y}}{\mathrm{d}x} = \left[\frac{\partial y_i}{\partial x}\right]$	$\frac{\mathrm{d}\mathbf{Y}}{\mathrm{d}x} = \left[\frac{\partial y_{ij}}{\partial x}\right]$
Vector	$\left[\frac{\mathrm{d}y}{\mathrm{d}\mathbf{x}} = \left[\frac{\partial y}{\partial x_j}\right]\right]$	$\frac{\mathrm{d}\mathbf{y}}{\mathrm{d}\mathbf{x}} = \left[\frac{\partial y_i}{\partial x_j}\right]$	
Matrix	$\frac{\mathrm{d}y}{\mathrm{d}\mathbf{X}} = \left[\frac{\partial y}{\partial x_{ji}}\right]$		

By Thomas Minka. Old and New Matrix Algebra Useful for Statistics

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Details for slide [18]:
$$J(\theta) = \sum_{i=1}^{n} (x_i^{T}\theta - y_i)^{2}$$

$$= (X\theta - y)^{T}(X\theta - y)$$

$$|X\theta - y| |X\theta - y|$$

Since
$$\psi^T \omega = ||\omega||_2^2 = \sum_{i=1}^h \omega_i^2$$

$$J(\theta) = (\chi \theta - \chi)^{T} (\chi \theta - \chi)$$

$$= ((\chi \theta)^{T} - \chi^{T}) (\chi \theta - \chi)$$

$$= (\theta^{T} \chi^{T} - \chi^{T}) (\chi \theta - \chi)$$

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See handout
$$4.1 + 4.3 \Rightarrow$$
 matrix alculus, partial doi \Rightarrow Gradicat

$$\nabla_{\theta} (\theta^{T} X^{T} X \theta) = 2 X^{T} X \theta \qquad (Pz4)$$

$$\nabla_{\theta} (-2 \theta^{T} X^{T} y) = -2 X^{T} Y \qquad (Pz4)$$

$$\nabla_{\theta} (-y^{T} y) = 0$$

$$\Rightarrow \nabla_{\theta} T(\theta) = 2 X^{T} X \theta - 2 X^{T} Y \xrightarrow{\text{Set to}} 0$$

$$\Rightarrow X^{T} X \theta = X^{T} Y$$

$$\Rightarrow \theta = (X^{T} X)^{-1} X^{T} Y$$
wher certain condition

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Comments on the normal equation

- In most situations of practical interest, the number of data points N is larger than the dimensionality p of the input space and the matrix \mathbf{X} is of full column rank. If this condition holds, then it is easy to verify that X^TX is necessarily invertible.
- The assumption that X^TX is invertible implies that it is positive definite, thus the critical point we have found is a minimum.
- What if X has less than full column rank? → regularization (later).

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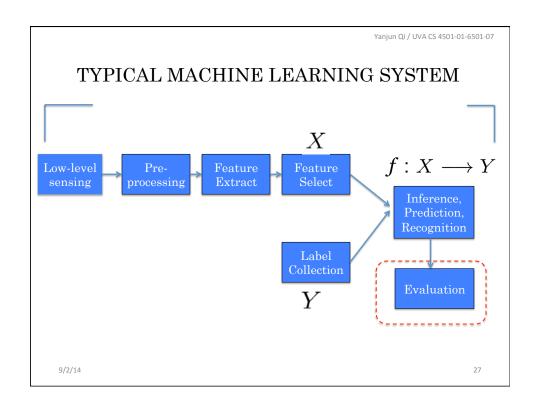
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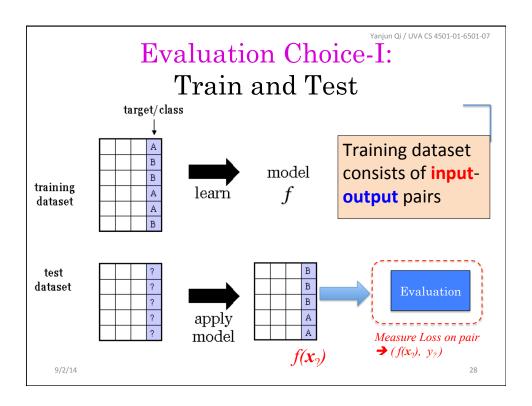
Today

- ☐ Linear regression (aka **least squares**)
- ☐ Learn to derive the least squares estimate by optimization
- Evaluation with Train/Test OR k-folds Cross-validation

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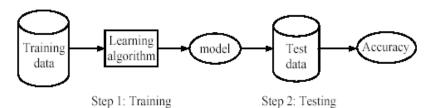




Evaluation Choice-I:

e.g. for supervised classification

- ✓ Training (Learning): Learn a model using the training data
- ✓ Testing: Test the model using unseen test data to assess the model accuracy



 $Accuracy = \frac{\text{Number of correct classifications}}{\text{Total number of test cases}}$

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Evaluation Choice-II:

Cross Validation

- Problem: don't have enough data to set aside a test set
- Solution: Each data point is used both as train and test
- Common types:
 - -K-fold cross-validation (e.g. K=5, K=10)
 - -2-fold cross-validation
 - -Leave-one-out cross-validation

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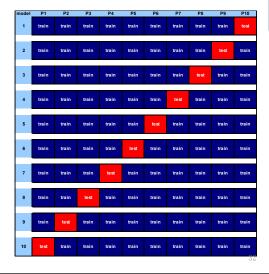
K-fold Cross Validation

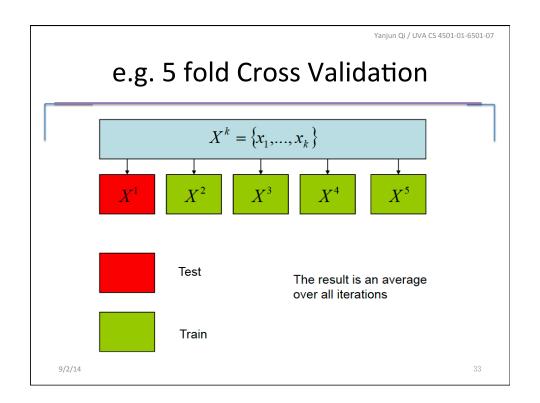
- Basic idea:
 - -Split the whole data to N pieces;
 - -N-1 pieces for fit model; 1 for test;
 - -Cycle through all N cases;
 - -K=10 "folds" a common rule of thumb.
- The advantage:
 - all pieces are used for both training and validation;
 - each observation is used for validation exactly once.

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e.g. 10 fold Cross Validation

- Divide data into 10 equal pieces
- 9 pieces as training set, the rest 1 as test set
- Collect the scores from the diagonal





Today Recap

☐ Linear regression (aka least squares)
☐ Learn to derive the least squares estimate by optimization
☐ Evaluation with Train/Test OR k-folds Crossvalidation

References

- Big thanks to Prof. Eric Xing @ CMU for allowing me to reuse some of his slides
- http://www.cs.cmu.edu/~zkolter/course/ 15-884/linalg-review.pdf (please read)
- http://www.cs.cmu.edu/~aarti/Class/10701/recitation/LinearAlgebra Matlab Review.ppt
- ☐ Prof. Alexander Gray's slides