

RoadAware: Learning Personalized Road Information on Daily Routes with Smartphones*

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Outline

- Introduction
- System Design
- Performance Evaluation
- Conclusion

Introduction

- Automobile is common in modern society
 - Boosting social and economical development
 - Meanwhile raising problems: traffic delay & safety
 - Americans spend over 100 hours a year on commuting cars
- Road and traffic monitoring is necessary
 - Provide traffic information for better management
 - Dedicated sensor networks can serve this purpose but are expensive

Introduction

- Vehicles are natural data source for road and traffic condition
 - Large amount of distributed “sensing nodes”
 - Offer first hand data at a low cost
- Vehicles are not yet ready for this purpose
 - Cars are relatively “closed” nowadays
 - Lacking interfaces to report collected data
 - Limited amount of sensors

Introduction

- Smart phones can be a suitable sensing tool on vehicles
 - Wide availability
 - Around 2 billion smart phone users now
 - Rich sensing & computing capability on smart phones
 - GHz level CPUs
 - Various sensors: GPS/Microphone/Accelerometer
- Open environment for application development

Introduction

- Rich investigation in this direction
 - Traffic light sensing (Infocom'12)
 - Traffic signal scheduling advisory (MobiSys'11)
 - Traffic delay estimation (SenSys'09)
 - Road & traffic condition monitoring (SenSys'08)
 - Etc.
- Most of current works are for overall road status
 - Few are for individual drivers to collect information on commute roads

Introduction

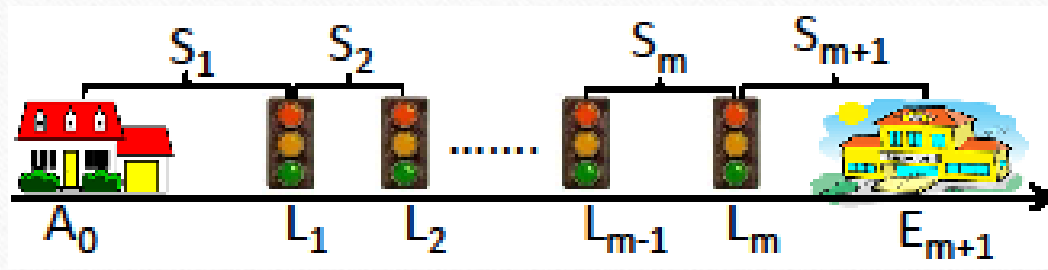
- Propose RoadAware for individual road information collection
 - Exploit smartphones carried by drivers
 - Collect and deduce some data on commuting roads
 - Travel distance and time between traffic lights
 - Average duration of red/green lights
 - Traffic volume on the roads between traffic lights
- Exclude road information during events such as football games and holidays because
 - 1) RoadAware aims to provide benchmark data during normal daily commute
 - 2) people are more sensitive to working day traffic status

Outline

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- **System Design**
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System Design : Route Model

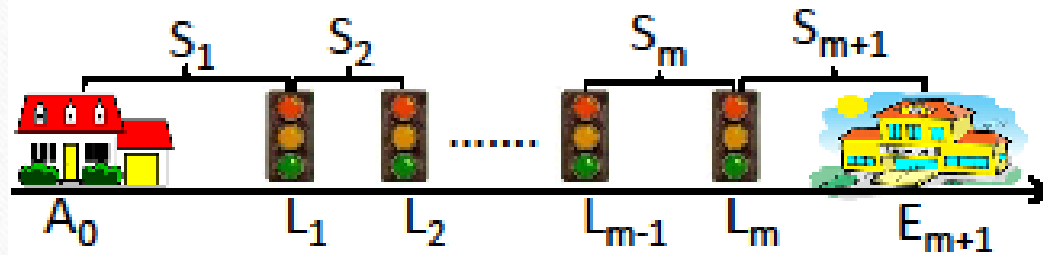
- Route R
 - A set of traffic lights (L) and road segments (S) in sequence



- A_0 is the start point and E_{m+1} is the ending point
- There are total m traffic lights, whose GPS positions are already known
- Only consider two traffic light statuses: **red (yellow)/stop** and **green/pass**

System Design : Measurement

- Measurement unit
 - Each segment and the traffic light at its end, e.g., S_1 and L_1



- Collect data daily to deduce information of each unit
 - Average travel length and time
 - Average traffic volume
 - Average length of the red/green signal

System Design : Measurement

- Trip Length & Time
 - Rely on periodically reading GPS data

$$D(P_j, P_{j+1}) = (t_{j+1} - t_j)(v_{j+1} + v_j)/2$$

- $(t_{j+1} - t_j)$ means the amount of time between two GPS readings
- $(v_{j+1} + v_j)/2$ means the average speed during this period of time
- More accurate than calculating the distance directly with two GPS positions

System Design : Deduce Information

- Traffic signal information
 - A car cannot get such information directly (does not always stay before the traffic light)
 - Observation:
 - A car's **waiting time** in front of a traffic light is related to the **traffic rate** and the **length** of red light
 - Solution:
 - Modeling the waiting queue before a traffic light
 - Combining daily collected waiting time and queue length information and use the model to deduce traffic signal information

System Design : Deduce Information

- Waiting queue modeling

- First, we have

$$\begin{aligned}T_{iw} &= Y_{ir} - T_{irp} + T_{irp} * \lambda_{ia}/\lambda_{id} \\ &= Y_{ir} + T_{irp} * \left(\frac{\lambda_{ia}}{\lambda_{id}} - 1\right)\end{aligned}$$

- Y_{ir} : the length of the red light
- $Y_{ir} - T_{irp}$: the remaining amount of time of the red light
- $T_{irp} * \lambda_{ia}/\lambda_{id}$: the time used by cars before the sensing car to leave the queue

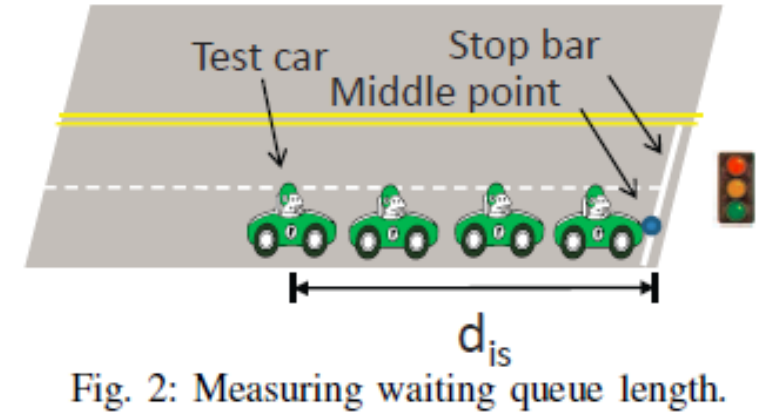
System Design : Deduce Information

- Waiting queue modeling

- On the other hand:

$$T_{irp} = (d_{is}/\bar{r})/\lambda_{ia}$$

- d_{is} : the length of the queue in front of the red light
- \bar{r} : average length of a car
- d_{is}/\bar{r} : the number of cars in front of the sensing car in the waiting queue
- $(d_{is}/\bar{r})/\lambda_{ia}$: the amount of time used by those cars to enter the waiting queue



System Design : Deduce Information

- Waiting queue modeling
 - Combine the above two equations, we have

$$T_{iw} = Y_{ir} + d_{is} * \kappa_i$$

where

$$\kappa_i = \frac{\lambda_{ia} - \lambda_{id}}{\lambda_{ia}\lambda_{id}\bar{r}}$$

- κ_i usually is negative as cars leave the queue quicker than entering it

System Design : Deduce Information

- Deduce traffic light information
 - Collect multiple pairs of waiting time (T_{iw}) and the distance to the traffic light when stopped (d_{is}) over multiple days
- Apply to the equation
- Obtain red light length (Y_{ir}) and traffic volume (λ_{ia})
- Use linear regression to enhance accuracy

where

$$T_{iw} = Y_{ir} + d_{is} * \kappa_i$$

$$\kappa_i = \frac{\lambda_{ia} - \lambda_{id}}{\lambda_{ia}\lambda_{id}\bar{r}}$$

System Design : Deduce Information

- Deduce traffic light information
 - Use the probability to meet green light and red light to deduce the length of green light

$$Y_{ig} = Y_{ir} * N_g / N_r$$

where N_g is number of green lights the car has met and N_r is the number of red lights

- Require accumulating data over a longer period of time to get good accuracy

Evaluation

- Toy implementation on Windows phones



(a) Main interface.

Travel time (in sec) and distance (in meters) since last traffic light

Current speed in mph

Remaining distance (in meters) to the next traffic light

The duration (in sec) of the next traffic light's red and green light

Sequence # of next traffic light

Traffic volume to the next traffic light

5.842	53.182	4	0.2	Zoom Out	Zoom In
Current Speed	15.4	Remaining Dist.	418.7	Red Light Len	125
Green Light Len	28				

(b) Information panel when the vehicle is on road.

Evaluation

- Toy implementation on Windows phones
- Tested over three routes
 - Home2Campus(H2C), Campus2Home(C2H), and LongRoute(LRt)

TABLE II: Experiment settings.

Route	# of traffic light	Length (m)	Test period
H2C	5	1900	7:30AM - 8:10AM
C2H	5	1900	4:30PM - 5:10PM
LRt	6	4900	5:20PM - 6:00PM

Evaluation : Travel Length & Time

TABLE IV: Travel distance of each route segment (m).

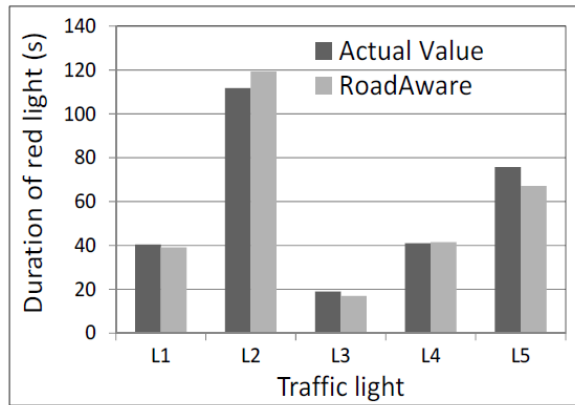
Traffic light	H2C	C2H	LRt
L_1	181.6	106.7	767.8
L_2	226.6	245.4	600.6
L_3	523.6	270.3	1299.7
L_4	325	311.2	726.3
L_5	271.5	521.2	897.3
L_6	350.4	416.6	436.3
L_7	-	-	195.7
Total	1878.7	1871.4	4923.7
Actual Total	1900	1900	4900

TABLE V: Travel time of each route segment (s).

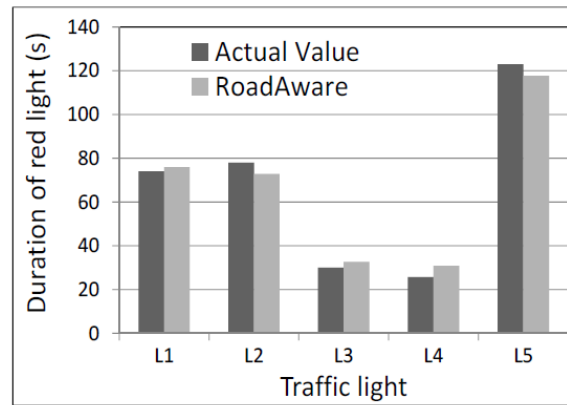
Traffic light	H2C	C2H	LRt
L_1	29.1	66.5	110.1
L_2	49.9	72.7	66.2
L_3	39.8	37.1	89.9
L_4	39.3	24.3	50.7
L_5	91.1	67.9	67.9
L_6	28.7	35.8	42.5
L_7	-	-	23.5
Total	277.9	304.3	450.8

The travel distance match with the ground truth well
(the ground truth is from Google map)

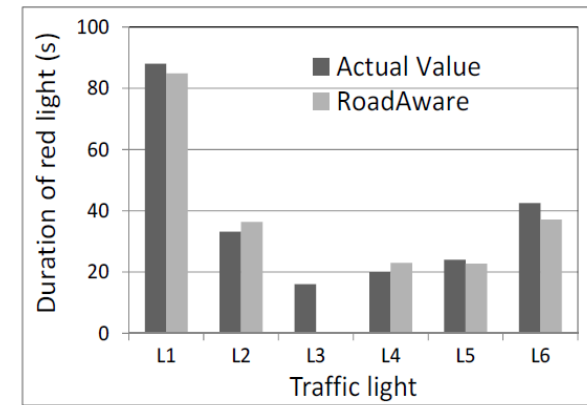
Evaluation : Red Light Length



(a) Home2Campus.



(b) Campus2Home.



(c) LongRoute.

Fig. 8: The duration of red lights on the three routes.

The deduced value is close to actual value measured manually

Evaluation : Traffic Volume

TABLE VI: Traffic volume at each L_i in *Home2Campus*.

	L_1	L_2	L_3	L_4	L_5
RoadAware	0.090	0.067	0.131	0.234	0.130
Actual Value	0.102	0.072	0.140	0.232	0.119

TABLE VII: Traffic volume at each L_i in *Campus2Home*.

	L_1	L_2	L_3	L_4	L_5
RoadAware	0.068	0.218	0.243	0.244	0.116
Actual Value	0.059	0.245	0.233	0.252	0.103

TABLE VIII: Traffic volume at each L_i in *LongRoute*.

	L_1	L_2	L_3	L_4	L_5	L_6
RoadAware	0.22	0.22	-	0.12	0.14	0.12
Actual Value	0.25	0.23	0.13	0.13	0.13	0.15

The deduced traffic volume is also close to manually counted data

Conclusion

- Exploit smartphones to record and deduce the traffic and trip information on commuting routes for a driver
- Solution:
 - Model a car's waiting time in front of a traffic light with the traffic rate and the length of red light
 - Use GPS to collect data and deduce more information
- Future work:
 - Large scale experiment and evaluation
 - Integrate data from multiple drivers for more useful applications



Thank you!
Questions & Comments?