#### Processes and Exceptions

### an infinite loop

```
int main(void) {
    while (1) {
        /* waste CPU time */
    }
}
```

If I run this on a lab machine, can you still use it?

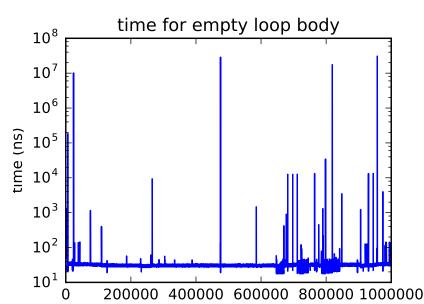
... even if the machine only has one core?

# timing nothing

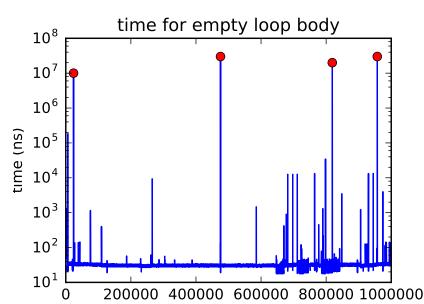
```
long times[NUM_TIMINGS];
int main(void) {
    for (int i = 0; i < N; ++i) {</pre>
        long start, end;
        start = get time();
        /* do nothing */
        end = get_time();
        times[i] = end - start;
    }
    output_timings(times);
}
```

same instructions — same difference each time?

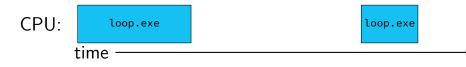
### doing nothing on a busy system



### doing nothing on a busy system



### time multiplexing



# time multiplexing



call get\_time
 // whatever get\_time does
movq %rax, %rbp
 million cycle delay
call get\_time
 // whatever get\_time does
subq %rbp, %rax

. . .

# time multiplexing



call get\_time
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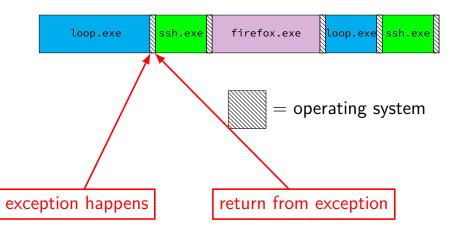
### illusion: dedicated processor

- time multiplexing: illusion of dedicated processor
- including dedicated registers
- sometimes called a thread
- illusion is perfect except for performance

### time multiplexing really



# time multiplexing really



### OS and time multiplexing

starts running instead of normal program mechanism for this: exceptions (later)

saves old program counter, registers somewhere

sets new registers, jumps to new program counter

called context switch

saved information called context

#### context

all registers values %rax %rbx, ..., %rsp, ...

condition codes

program counter

i.e. all visible state in your CPU except memory

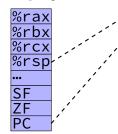
#### context switch pseudocode

```
context switch(last, next):
  copy preexception_pc last->pc
  mov rax, last->rax
  mov rcx, last->rcx
  mov rdx, last->rdx
  . . .
  mov next->rdx, rdx
  mov next->rcx, rcx
  mov next->rax, rax
  jmp next->pc
```

# contexts (A running)

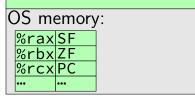
in Memory

in CPU



Process A memory: code, stack, etc.

Process B memory: code, stack, etc.



# contexts (B running)

in CPU

%rax %rbx %rcx

%rsp

•••

SF ZF PC in Memory

Process A memory: code, stack, etc.

Process B memory: code, stack, etc.

OS memory: %raxSF %rbxZF %rcxPC ... ...

#### memory protection

reading from another program's memory?

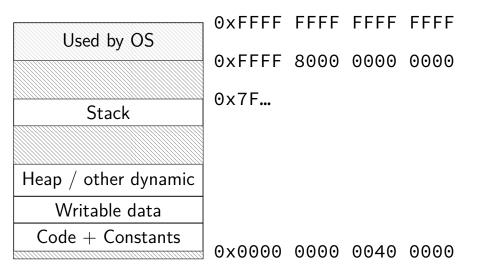
Program A	Program B
0x10000: .word 42 // // do work // movq 0x10000, %rax	// while A is working: movq \$99, %rax movq %rax, 0x10000 

#### memory protection

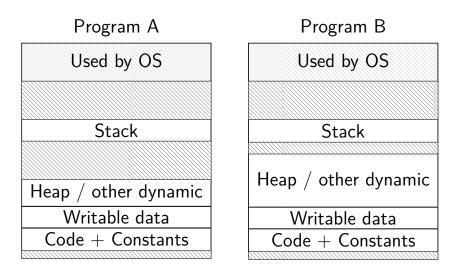
reading from another program's memory?

Program A	Program B
0x10000: .word 42 // // do work // movq 0x10000, %rax	// while A is working: movq \$99, %rax movq %rax, 0x10000 
result: %rax is 42 (always)	result: might crash

# **Recall: program memory**



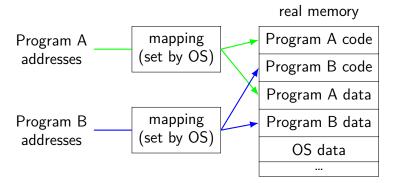
# program memory (two programs)

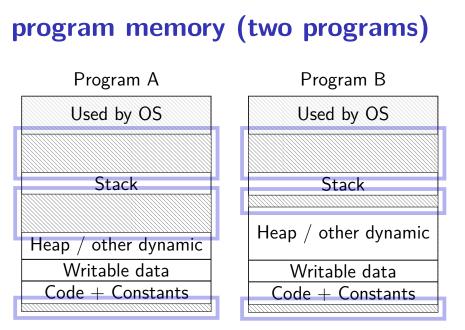


### address space

programs have illusion of own memory

called a program's address space

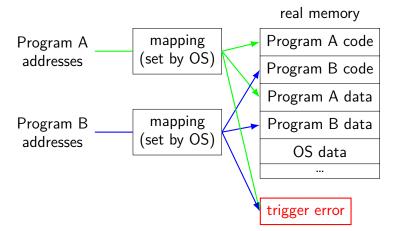




### address space

programs have illusion of own memory

called a program's address space



#### address space mechanisms

- next week's topic
- called virtual memory
- mapping called page tables
- mapping part of what is changed in context switch

#### context

all registers values %rax %rbx, ..., %rsp, ...

condition codes

program counter

i.e. all visible state in your CPU except memory

address space: map from program to real addresses

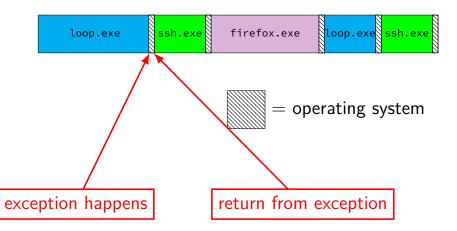
### **The Process**

process = thread(s) + address space

illusion of dedicated machine:

thread = illusion of own CPU address space = illusion of own memory

# time multiplexing really



### exceptions

special control transfer similar effect to function call but often not requested by the program

usually from user programs to the OS example: from timer expiring keeps our infinite loop from running forever

### types of exceptions

interrupts — externally-triggered

timer — keep program from hogging CPU I/O devices — key presses, hard drives, networks, ...

faults — errors/events in programs memory not in address space ("Segmentation fault") divide by zero invalid instruction

traps — intentionally triggered exceptions system calls — ask OS to do something

aborts

### timer interrupt

(conceptually) external timer device

OS configures before starting program

sends signal to CPU after a fixed interval

### types of exceptions

interrupts — externally-triggered

timer — keep program from hogging CPU I/O devices — key presses, hard drives, networks, ...

faults — errors/events in programs
 memory not in address space ("Segmentation fault")
 divide by zero
 invalid instruction

traps — intentionally triggered exceptions system calls — ask OS to do something

aborts

### protection fault

when program tries to access memory it doesn't own

- e.g. trying to write to bad address
- OS gets control can crash the program or more interesting things

### synchronous versus asynchronous

synchronous — triggered by a particular instruction particular mov instruction

asynchronous — comes from outside the program timer event keypress, other input event

### exception implementation

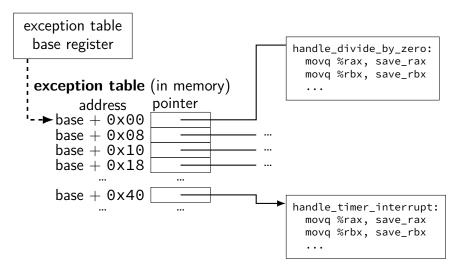
- detect condition (program error or external event)
- save current value of PC somewhere
- jump to exception handler (part of OS) jump done without program instruction to do so

#### exception implementation: notes

I/textbook describe a simplified version

real x86/x86-64 is a bit more complicated (mostly for historical reasons)

### locating exception handlers



## running the exception handler

hardware saves the old program counter

identifies location of exception handler via table

then jumps to that location

OS code can save registers, etc., etc.

#### exception handler structure

- 1. save process's state somewhere
- 2. do work to handle exception
- 3. restore a process's state (maybe a different one)
- 4. jump back to program

```
handle_timer_interrupt:
    mov_from_saved_pc save_pc_loc
    movq %rax, save_rax_loc
    ... // choose new process to run here
    movq new_rax_loc, %rax
    mov_to_saved_pc new_pc
    return_from_exception
```

## added to CPU for exceptions

- new instruction: set exception table base
- new logic: jump based on exception table
- new logic: save the old PC to special register or to memory
- new instruction: return from exception i.e. jump to saved PC

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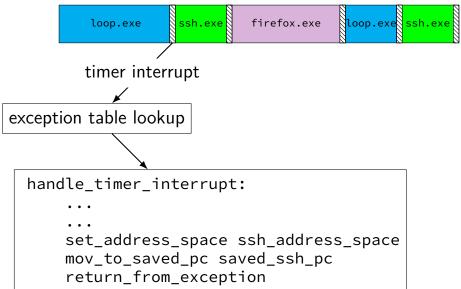
- new instruction: set exception table base
- new logic: jump based on exception table
- new logic: save the old PC to special register or to memory
- new instruction: return from exception i.e. jump to saved PC

## why return from exception?

not just ret — can't modify process's stack would break the illusion of dedicated CPU

reasons related to address spaces, protection (later)

## exceptions and time slicing



## defeating time slices?

```
main:
    set_exception_table_base my_exception_table
loop:
    jmp loop
```

## defeating time slices?

wrote a program that tries to set the exception table:

result: Segmentation fault (exception!)

## privileged instructions

can't let any program run some instructions

allows machines to be shared between users (e.g. lab servers)

examples:

set exception table set address space talk to I/O device (hard drive, keyboard, display, ...) ...

processor has two modes:

kernel mode — privileged instructions work user mode — privileged instructions cause exception instead

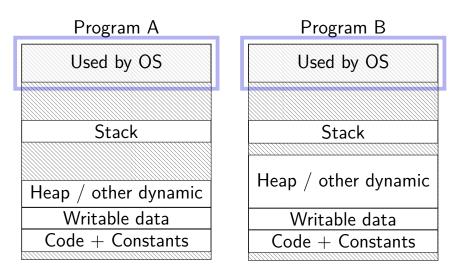
## kernel mode

extra one-bit register: "are we in kernel mode"

exceptions enter kernel mode

return from exception instruction leaves kernel mode

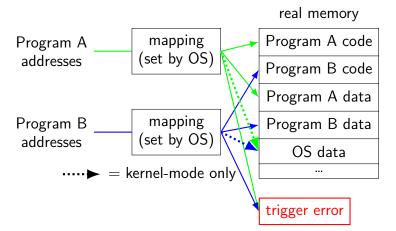
# program memory (two programs)



## address space

programs have illusion of own memory

called a program's address space



#### kernel services

allocating memory? (change address space)

reading/writing to file? (communicate with hard drive)

read input? (communicate with keyborad)

all need privileged instructions!

need to run code in kernel mode

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aborts

## Linux x86-64 system calls

special instruction: syscall

triggers trap (deliberate exception)

## Linux syscall calling convention

before syscall:

%rax — system call number

%rdi, %rsi, %rdx, %r10, %r8, %r9 — args

after syscall:

%rax — return value

on error: %rax contains -1 times "error number"

almost the same as normal function calls

#### Linux x86-64 hello world

syscall

```
.globl start
.data
hello_str: .asciz "Hello,_World!\n"
.text
start:
  movg $1, %rax # 1 = "write"
  movq $1, %rdi # file descriptor 1 = stdout
  movg $hello_str, %rsi
  movg 15, %rdx # 15 = strlen("Hello, World!\n")
  syscall
  movq $60, %rax # 60 = exit
  movq $0, %rdi
```

#### approx. system call handler

```
sys_call_table:
    .quad handle_read_syscall
    .quad handle_write_syscall
    // ...
```

```
handle_syscall:
    ... // save old PC, etc.
    pushq %rcx // save registers
    pushg %rdi
    call *sys_call_table(,%rax,8)
    . . .
    popq %rdi
    popq %rcx
    return from exception
```

#### Linux system call examples

mmap, brk — allocate memory

fork — create new process

execve — run a program in the current process

\_exit — terminate a process

open, read, write — access files terminals, etc. count as files, too

#### system calls and protection

exceptions are only way to access kernel mode operating system controls what proceses can do

... by writing exception handlers very carefully

## careful exception handlers

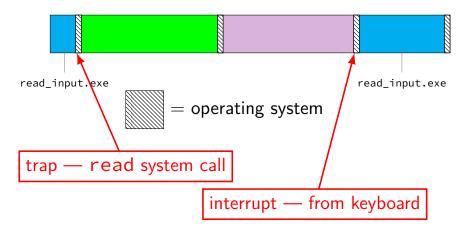
- movq \$important\_os\_address, %rsp
- can't trust user's stack pointer!
- need to have own stack in kernel-mode-only memory need to check all inputs really carefully

## reading keyboard input

```
int main(void) {
    char buf[1024];
    /* read a line from stdin ----
        waits for keyboard input */
    if (fgets(buf, sizeof buf, stdin) != NULL) {
        printf("You_typed_[%s]\n", buf);
    }
}
```

fgets uses read system call

## keyboard input timeline



## system call wrappers

library functions to not write assembly:

open:

**movq** \$2, %rax // 2 = sys\_open // 2 arguments happen to use same registers syscall // return value in %eax **cmp** \$0, %rax jl has\_error ret has\_error: neg %rax movq %rax, errno **movq** \$-1, %rax ret

## system call wrappers

library functions to not write assembly:

open:

**movq** \$2, %rax // 2 = sys\_open // 2 arguments happen to use same registers syscall // return value in %eax **cmp** \$0, %rax jl has\_error ret has\_error: neg %rax movq %rax, errno **movq** \$-1, %rax ret

#### system call wrapper: usage

```
/* unistd.h contains definitions of:
    O_RDONLY (integer constant), open() */
#include <unistd.h>
int main(void) {
  int file_descriptor;
  file_descriptor = open("input.txt", 0_RDONLY);
  if (file_descriptor < 0) {</pre>
      printf("error:_%s\n", strerror(errno));
      exit(1);
  }
  result = read(file descriptor, ...);
  . . .
```

#### system call wrapper: usage

```
/* unistd.h contains definitions of:
    O_RDONLY (integer constant), open() */
#include <unistd.h>
int main(void) {
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```

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## a note on terminology

the real world does not use consistent terms for exceptions

we will follow textbook's terms in this course

the real world won't

you might see:

'interrupt' meaning what we call 'exception' (x86) 'exception' meaning what we call 'fault' 'fault' meaning what we call 'fault' *or* 'abort' (ARM) ... and more

## signals

Unix-like operating system feature

like interrupts for processes:

can be triggered by external process (instead of device)

kill command/system call

can be triggered by special events pressing control-C

can invoke signal handler

## signal **API**

sigaction — register handler for signal

kill — send signal to process

pause — put process to sleep until signal received

sigprocmask — block some signals from being received until ready

... and much more

## example signal program

```
#include <signal.h>
#include <unistd.h>
```

```
void handle_sigint(int signum) {
    write(1, "Got_signal!\n", sizeof("Got_signal!
    _exit(0);
}
```

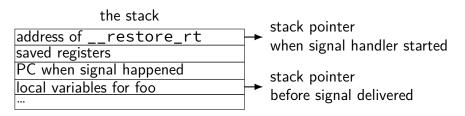
```
int main(void) {
    struct sigaction act;
    act.sa_handler = &handle_sigint;
    sigemptyset(&act.sa_mask);
    sigaction(&act);
```

# signal delivery (1)

signal happens while foo() is running

OS writes stack from to user stack

OS modifies registers to call signal handler



```
signal delivery (2)
```

```
handle_sigint:
    ...
    ret
...
__restore_rt:
    // 15 = "sigreturn" system call
    movq $15, %rax
    syscall
```

\_\_restore\_rt is return address for signal handler system call restores pre-signal state, then returns

# signal handler unsafety (1)

```
void *malloc(size_t size) {
    to_return = next_to_return;
    /* SIGNAL HAPPENS HERE */
    next to return += size;
    return to_return;
}
void foo() {
    /* This malloc() call interrupted */
    char *p = malloc(1024);
    p[0] = 'x';
}
```

# setjmp/longjmp

```
C flow control
jmp_buf env;
main() {
  if (setjmp(env) == 0) { // like try {
    read file()
  } else { // like catch
    printf("some_error_happened\n");
  }
}
read file() {
```

. . .

## implementing setjmp/lonjmp

setjmp:

copy all registers to jmp\_buf ... including stack pointer

longjmp copy registers from jmp\_buf ... but change %rax (return value)

## setjmp weirdness — local variables

Undefined behavior:

```
int x = 0;
if (setjmp(env) == 0) {
    ...
    x += 1;
    longjmp(env, 1);
} else {
    printf("%d\n", x);
}
```

## setjmp weirdness — fix

Defined behavior:

```
volatile int x = 0;
if (setjmp(env) == 0) {
    ...
    x += 1;
    longjmp(env, 1);
} else {
    printf("%d\n", x);
}
```

## on implementing try/catch

- could do something like setjmp()/longjmp()
- but want try to be really fast!
- instead: tables of information indexed by program counters:
  - where register values are stored on stack/in other registers where old program counters are stored on stack where catch blocks are located