Historical Perspectives

Kurt Gödel (1906-1978)

• Logician, mathematician, and philosopher
• Proved completeness of predicate logic and Gödel’s incompleteness theorem
• Proved consistency of axiom of choice and the continuum hypothesis
• Invented “Gödel numbering” and “Gödel fuzzy logic”
• Developed “Gödel metric” and paradoxical relativity solutions: “Gödel spacetime / universe”
• Made enormous impact on logic, mathematics, and science
Gödel’s Incompleteness Theorem

Frege & Russell:
- Mechanically verifying proofs
- Automatic theorem proving

A set of axioms is:
- **Sound**: iff only true statements can be proved
- **Complete**: iff any statement or its negation can be proved
- **Consistent**: iff no statement and its negation can be proved

Hilbert’s program: find an axiom set for **all** of mathematics
i.e., find a axiom set that is **consistent** and **complete**

Gödel: any **consistent axiomatic system** is **incomplete**!
(as long as it subsume elementary arithmetic)
i.e., any **consistent** axiomatic system must contain **true** but **unprovable** statements

Mathematical surprise: **truth** and **provability** are **not the same**!
Gödel’s Incompleteness Theorem

That some axiomatic systems are incomplete is not surprising, since an important axiom may be missing (e.g., Euclidean geometry without the parallel postulate)

However, that every consistent axiomatic system must be incomplete was an unexpected shock to mathematics! This undermined not only a particular system (e.g., logic), but axiomatic reasoning and human thinking itself!

Truth = Provability

Justice ≠ Legality
Gödel’s Incompleteness Theorem

Gödel: consistency or completeness - pick one!

Which is more important?

Incomplete: not all true statements can be proved. But if useful theorems arise, the system is still useful.

Inconsistent: some false statement can be proved. This can be catastrophic to the theory:

E.g., supposed in an axiomatic system we proved that “1=2”. Then we can use this to prove that, e.g., all things are equal!

Consider the set: \{Bush, Pope\}
| \{Bush, Pope\} | = 2
⇒ | \{Bush, Pope\} | = 1 (since 1=2)
⇒ Bush = Pope  QED
⇒ All things become true: system is “complete” but useless!
Gödel’s Incompleteness Theorem

Moral: it is better to be consistent than complete, if you can not be both.

“It is better to be feared than loved, if you cannot be both.”

“You can have it good, cheap, or fast – pick any two.”
- Popular business adage
Gödel’s Incompleteness Theorem

**Thm:** any **consistent axiomatic system is incomplete!**

**Proof idea:**

- Every formula is encoded uniquely as an integer
- Extend “Gödel numbering” to formula sequences (proofs)
- Construct a “**proof checking**” formula $P(n,m)$ such that $P(n,m)$ iff $n$ encodes a proof of the formula encoded by $m$
- Construct a self-referential formula that asserts its own non-provability: “I am not provable”
- Show this formula is **neither provable nor disprovable**

George Boolos (1989) gave shorter proof based on formalizing **Berry’s paradox**

The set of true statements is not R.E.!
"You simply associate each number with a word, such as 'table' and 3,476,029."
Gödel’s Incompleteness Theorem

Systems known to be complete and consistent:
- Propositional logic (Boolean algebra)
- Predicate calculus (first-order logic) [Gödel, 1930]
- Sentential calculus [Bernays, 1918; Post, 1921]
- Presburger arithmetic (also decidable)

Systems known to be either inconsistent or incomplete:
- Peano arithmetic
- Primitive recursive arithmetic
- Zermelo–Frankel set theory
- Second-order logic

Q: Is our mathematics both consistent and complete?  
A: No [Gödel, 1931]

Q: Is our mathematics at least consistent?  
A: We don’t know! But we sure hope so.
Gödel’s “Ontological Proof” that God exists!
Formalized Saint Anselm's ontological argument using modal logic:

Ax. 1. \( P(\varphi) \land \square \forall x[\varphi(x) \rightarrow \psi(x)] \rightarrow P(\psi) \)
Ax. 2. \( P(\neg \varphi) \leftrightarrow \neg P(\varphi) \)
Th. 1. \( P(\varphi) \rightarrow \lozenge \exists x[\varphi(x)] \)
Df. 1. \( G(x) \iff \forall \varphi[P(\varphi) \rightarrow \varphi(x)] \)
Ax. 3. \( P(G) \)
Th. 2. \( \lozenge \exists x \, G(x) \)
Df. 2. \( \varphi \text{ ess } x \iff \varphi(x) \land \forall \psi[\psi(x) \rightarrow \square \forall x[\varphi(x) \rightarrow \psi(x)]] \)
Ax. 4. \( P(\varphi) \rightarrow \square P(\varphi) \)
Th. 3. \( G(x) \rightarrow G \text{ ess } x \)
Df. 3. \( E(x) \iff \forall \varphi[\varphi \text{ ess } x \rightarrow \square \exists x \, \varphi(x)] \)
Ax. 5. \( P(E) \)
Th. 4. \( \square \exists x \, G(x) \)

For more details, see:
http://en.wikipedia.org/wiki/Godel_ontological_proof
Welcome

The Kurt Gödel Society was founded in 1987 and is chartered in Vienna. It is an international organization for the promotion of research in the areas of Logic, Philosophy, History of Mathematics, above all in connection with the biography of Kurt Gödel, and in other areas to which Gödel made contributions, especially mathematics, physics, theology, philosophy and Leibniz studies.

Top News

09-06-08 12:00

Fourth Vienna Tbilisi Summer School in Logic and Language

For the third time students and teachers meet in Tbilisi, Georgia, for a summer school. Please see the conference page http://www.logic.at/tbilisi08/ fo... [more...]

05-12-07 23:22

Collegium Logicum Lecture Series

6 December 2007, 16:00 Peter Schuster (LMU München) - Finite methods in commutative algebra [more...]

15-11-07 12:27

Workshop Two and beyond

The KGS is organizing a workshop on truth-functional logics. [more...]
Horizons of Truth

Logics, Foundations of Mathematics, and the Quest for Understanding the Nature of Knowledge

Gödel Centenary 2006

An International Symposium Celebrating the 100th Birthday of Kurt Gödel

27-29. April 2006

Festsaal of the University of Vienna

Horizons of Truth

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Festsaal of the University of Vienna

Organized by the Kurt Gödel Society with the support of the John Templeton Foundation. Co-organized by the University of Vienna, the Institute for Experimental Physics, the Kurt Gödel Research Center, the Institute Vienna Circle, and the Vienna University of Technology.

The purpose of the Symposium is to commemorate the life, work, and foundational views of Kurt Gödel, perhaps the greatest logician of the twentieth century. In the spirit of Gödel’s work, the Symposium will also explore current research advances and ideas for future possibilities in the fields of the foundations of mathematics and logic. The symposium intends to put Gödel’s ideas and works into a more general context in the light of current understanding and perception. The symposium will also present various implications of his work for other areas of intellectual endeavor such as artificial intelligence, cosmology, philosophy, and theology.

The Symposium will take place 27-29 April in the Celebration Hall of the University of Vienna, famous for its architectural beauty and the murals of Klimt. More than 20 lectures by eminent scientists in the fields of logics, mathematics, philosophy, physics, and theology will provide new insights into the life and work of Kurt Gödel and their implications for future generations.

Contributions

The program will contain

Talks by the invited speakers

John D. Barrow, Cambridge University, UK
Historical Perspectives

Alonzo Church (1903-1995)

- Founder of theoretical computer science
- Made major contributions to logic
- Invented Lambda-calculus, Church-Turing Thesis
- Originated Church-Frege Ontology, Church’s theorem
- Church encoding, Church-Kleene ordinal,
- Inspired LISP and functional programming
- Was Turing’s Ph.D. advisor! Other students: Davis, Kleene, Rabin, Rogers, Scott, Smullyan
- Founded / edited Journal of Symbolic Logic
- Taught at UCLA until 1990; published “A Theory of the Meaning of Names” in 1995, at age 92!
Adam Olszewski
Jan Woleński
Robert Janusz (Eds.)

Church's Thesis
After 70 Years

THE CALCULI OF LAMBDA-CONVERSION
ALONZO CHURCH
LISP IS OVER HALF A CENTURY OLD AND IT STILL HAS THIS PERFECT, TIMELESS AIR ABOUT IT.

I WONDER IF THE CYCLES WILL CONTINUE FOREVER.

A FEW CODERS FROM EACH NEW GENERATION RE-DISCOVERING THE LISP ARTS.

THESE ARE YOUR FATHER’S PARENTHESSES

ELEGANT WEAPONS

FOR A MORE... CIVILIZED AGE.

A GOD’S LAMENT

SOME SAID THE WORLD SHOULD BE IN PERL:
SOME SAID IN LISP.
NOW, HAVING GIVEN BOTH A WHIRL,
I HELD WITH THOSE WHO FAVORED PERL.
BUT I FEAR WE PASSED TO MEN
A DISAPPOINTING FOUNDING MYTH,
AND SHOULD WE WRITE IT ALL AGAIN,
I'D END IT WITH
A CLOSE-PAREN.

AS YOU KNOW, WE'RE IN THE EIGHTH YEAR OF OUR NORTHERN WARS AGAINST THE HASKELLERS.
THERE ARE RUMORS THAT MORE OF OUR TROOPS ARE DEFECTING TO THE OTHER SIDE EVERY DAY...

I ASSURE YOU, DON'T BE TEMPTED TO BREAK RANKS!
Historical Perspectives

Alan Turing (1912-1954)
- Mathematician, logician, cryptanalyst, and founder of computer science
- First to formally define computation / algorithm
- Invented the Turing machine model - theoretical basis of all modern computers
- Investigated computational “universality”
- Introduced “definable” real numbers
- Proved undecidability of halting problem
- Originated oracles and the “Turing test”
- Pioneered artificial intelligence
- Anticipated neural networks
- Designed the Manchester Mark 1 (1948)
- Helped break the German Enigma cypher
- Turing Award was created in his honor
ALAN TURING 1912 - 1954
Founder of computer science and cryptographer, whose work was key to breaking the wartime Enigma codes, lived and died here.
Bletchley Park ("Station X"), Bletchley, Buckinghamshire, England

England’s code-breaking and cryptanalysis center during WWII
“Bombe” - electromechanical computer designed by Alan Turing. Used by British cryptologists to break the German Enigma cipher.
1918 First Enigma Patent

The official history of the Enigma starts in 1918, when the German Arthur Scherbius filed his first patent for the Enigma coding machine. It is listed as patent number 416219 in the archives of the German Rechtspatentamt (patent office). Please note the time at which the Enigma was invented: 1918, just after the First World War, more than 20 years before WWII. The image below clearly shows the coding wheels (rotors) in the centre part of the drawing. Below it is the keyboard and to the right is the lamp panel. At the top left is a counter, used to count the number of letters entered on the keyboard. This counter can still be found on certain Enigma models.

Arthur Scherbius’ company Securitas was based in Berlin (Germany) and had an office in Amsterdam (The Netherlands). As he wanted to protect his invention outside Germany, he also registered his patent in the USA (1922), Great Britain (1923) and France (1923).

This image is taken from patent number 193,035 that was registered in Great Britain in 1923, long before WWII. It was also registered in a number of other countries, such as France and the USA.

During the 1920s the Enigma was available as a commercial device, available for use by companies and embassies for their confidential messages. Remember that in those days, most companies had to use morse code and radio links for long distance communication. The devices were advertised having over 800,000 possibilities.

In the following years, additional patents with improvements of the coding machine were applied. E.g. in GB Patent 267,482, dated 17 Jan 1927, the Umkehrwalze was added and a later patent of 14 Nov 1929 (GB 343,146) claims the addition of the Ringstellung, multiple notches, etc. One of the drawings of that patent shows a coding device, that we now know as The Enigma, in great detail.

http://www.xat.nl/enigma-e/
4-7 December 2008

Breaking the Code

by Hugh Whitemore

based on the book
Alan Turing, The Enigma
by Andrew Hodges

directed by phil rayner

it's not breaking the code that matters - it's where you go from there

020 8340 3488
Program for ACE computer
hand-written by Alan Turing
1937: Alan Turing’s theory of digital computing
British PM apologizes for treatment of gay code-breaker

updated 6:17 a.m. EDT, Fri September 11, 2009

By Hilary Whitman
CNN

LONDON, England (CNN) — British Prime Minister Gordon Brown has issued a posthumous apology for the “appalling” treatment of Alan Turing, the British code-breaker who was chemically castrated for being gay.

The apology came after more than 30,000 people signed an online petition on the UK Government Web site calling for the government to recognize the “tragic consequences of prejudice that ended this man’s life and career.”

Turing was just 41 years old when he committed suicide, two years after undergoing a court-ordered chemical castration. He had been found guilty of gross indecency for having a homosexual relationship. The punishment in 1952 was either a prison sentence or chemical castration. Turing chose the latter.

In a statement on the British Government Web site, Prime Minister Gordon Brown acknowledged Turing’s “outstanding” contribution during World War II.
"He truly was one of those individuals we can point to whose unique contribution helped to turn the tide of war," he wrote, adding, "The debt of gratitude he is owed makes it all the more horrifying, therefore, that he was treated so inhumanely."

Turing is considered one of Britain's greatest mathematicians, a genius who is credited with inventing the Bombe, a code-breaking machine that deciphered messages encoded by German Enigma machines during World War II.

He went on to develop the Turing machine, a theory that automatic computation cannot solve all mathematical problems, which is considered the basis of modern computing.

**Don't Miss**

- Petition seeks apology for Enigma code-breaker Turing
- Leaders mark 70th anniversary of WWII

Last month, the curious lack of public recognition for Turing's contribution to the war effort and computing in general motivated computer programmer John Graham-Cumming to campaign on his behalf.

The author of the "Geek Atlas," a travel guide for technology enthusiasts, started an online petition, and soon attracted high-profile signatories including scientist Richard Dawkins, actor Stephen Fry, author Ian McEwan and philosopher A.C. Grayling.

"I was surprised by both the number of people who signed and the fast response from the government," Graham-Cumming told CNN. He said the Prime Minister had called him personally to relay news of the apology.

Stories about calls for a British apology were carried in newspapers in France, Switzerland, Spain, Austria, Portugal Poland and the Czech Republic. Supporters set up an international petition which attracted more than 10,000 signatures.
Another famous belated apology:

1992: Catholic Church apologizes to Galileo, who died in 1642

In 1610, Century Italian astronomer/mathematician/inventor Galileo Galilei used a telescope he built to observe the solar system, and deduced that the planets orbit the sun, not the earth.

This contradicted Church teachings, and some of the clergy accused Galileo of heresy. One friar went to the Inquisition, the Church court that investigated charges of heresy, and formally accused Galileo. (In 1600, a man named Giordano Bruno was convicted of being a heretic for believing that the earth moved around the sun, and that there were many planets throughout the universe where life existed. Bruno was burnt to death.)

Galileo moved on to other projects. He started writing about ocean tides, but instead of writing a scientific paper, he found it much more interesting to have an imaginary conversation among three fictional characters. One character, who would support Galileo's side of the argument, was brilliant. Another character would be open to either side of the argument. The final character, named Simplicio, was dogmatic and foolish, representing all of Galileo's enemies who ignored any evidence that Galileo was right. Soon, Galileo wrote up a six-volume dialogue called "Dialogue on the Two Great Systems of the World." This book talked about the Copernican system.

"Dialogue" was an immediate hit with the public, but not, of course, with the Church. The pope suspected that he was the model for Simplicio. He ordered the book banned, and also ordered Galileo to appear before the Inquisition in Rome for the crime of teaching the Copernican theory after being ordered not to do so.

Galileo was 68 years old and sick. Threatened with torture, he publicly confessed that he had been wrong to have said that the Earth moves around the Sun. Legend then has it that after his confession, Galileo quietly whispered "And yet, it moves."

Unlike many less famous prisoners, Galileo was allowed to live under house arrest. Until his death in 1642, he continued to investigate science, and even published a book on force and motion after he had become blind.

The Church eventually lifted the ban on Galileo's Dialogue in 1822, when it was common knowledge that the Earth was not the center of the Universe. Still later, there were statements by the Vatican Council in the early 1960's and in 1979 that implied that Galileo was pardoned, and that he had suffered at the hands of the Church. Finally, in 1992, three years after Galileo Galilei's namesake spacecraft had been launched on its way to Jupiter, the Vatican formally and publicly cleared Galileo of any wrongdoing.

(info from NASA and the History Channel)

Theorem: A late apology is better than no apology.
Corollary: But sooner is better!
Turing’s Seminal Paper


- One of the most influential & significant papers ever!
- First formal model of “computation”
- First ever definition of “algorithm”
- Invented “Turing machines”
-Introduced “computational universality” i.e., “programmable”!
- Proved the undecidability of halting problem
- Explicates the Church-Turing Thesis
have valuable applications. In particular, it is shown (§11) that the Hilbertian Entscheidungsproblem can have no solution.

In a recent paper Alonzo Church† has introduced an idea of “effective calculability”, which is equivalent to my “computability”, but is very differently defined. Church also reaches similar conclusions about the Entscheidungsproblem‡. The proof of equivalence between “computability” and “effective calculability” is outlined in an appendix to the present paper.

We have said that the computable numbers are those whose decimals are calculable by finite means. This requires rather more explicit definition. No real attempt will be made to justify the definitions given until we reach §9. For the present I shall only say that the justification lies in the fact that the human memory is necessarily limited.

We may compare a man in the process of computing a real number to a machine which is only capable of a finite number of conditions $q_1, q_2, \ldots, q_n$ which will be called “m-configurations”. The machine is supplied with a “tape” (the analogue of paper) running through it, and divided into sections (called “squares”) each capable of bearing a “symbol”. At any moment there is just one square, say the $r$-th, bearing the symbol $\Theta(r)$ which is “in the machine”. We may call this square the “scanned square”. The symbol on the scanned square may be called the “scanned symbol”. The “scanned symbol” is the only one of which the machine is, so to speak, “directly aware”. However, by altering its m-configuration the machine can effectively remember some of the symbols which it has “seen” (scanned) previously. The possible behaviour of the machine at any moment is determined by the m-configuration $q_m$ and the scanned symbol $\Theta(r)$. This pair $q_m, \Theta(r)$ will be called the “configuration”; thus the configuration determines the possible behaviour of the machine.

In some of the configurations in which the scanned square is blank (i.e. bears no symbol) the machine writes down a new symbol on the scanned square: in other configurations it erases the scanned symbol. The machine may also change the square which is being scanned, but only by shifting it one place to right or left. In addition to any of these operations the m-configuration may be changed. Some of the symbols written down

Turing

2. Definitions.

If at each stage the motion of a machine (in the sense of §1) is completely determined by the configuration, we shall call the machine an "automatic machine" (or a-machine).

For some purposes we might use machines (choice machines or c-machines) whose motion is only partially determined by the configuration (hence the use of the word "possible" in §1). When such a machine reaches one of these ambiguous configurations, it cannot go on until some arbitrary choice has been made by an external operator. This would be the case if we were using machines to deal with axiomatic systems. In this paper I deal only with automatic machines, and will therefore often omit the prefix a-

Computing machines.

If an a-machine prints two kinds of symbols, of which the first kind (called figures) consists entirely of 0 and 1 (the others being called symbols of the second kind), then the machine will be called a computing machine. If the machine is supplied with a blank tape and set in motion, starting from the correct initial m-configuration, the subsequence of the symbols printed by it which are of the first kind will be called the sequence computed by the machine. The real number whose expression as a binary decimal is obtained by prefixing this sequence by a decimal point is called the number computed by the machine.

At any stage of the motion of the machine, the number of the scanned square, the complete sequence of all symbols on the tape, and the m-configuration will be said to describe the complete configuration at that stage. The changes of the machine and tape between successive complete configurations will be called the moves of the machine.

Circular and circle-free machines.

If a computing machine never writes down more than a finite number of symbols of the first kind, it will be called circular. Otherwise it is said to be circle-free.

A machine will be circular if it reaches a configuration from which there is no possible move, or if it goes on moving, and possibly printing symbols of the second kind, but cannot print any more symbols of the first kind. The significance of the term "circular" will be explained in §8.

Computable sequences and numbers.

A sequence is said to be computable if it can be computed by a circle-free machine. A number is computable if it differs by an integer from the number computed by a circle-free machine.

We shall avoid confusion by speaking more often of computable sequences than of computable numbers.

3. Examples of computing machines.

I. A machine can be constructed to compute the sequence 010101... . The machine is to have the four m-configurations “5”, “c”, “f”, “c” and is capable of printing “0” and “1”. The behaviour of the machine is described in the following table in which “R” means “the machine moves so that it scans the square immediately on the right of the one it was scanning previously”. Similarly for “L”. “E” means “the scanned symbol is erased” and “P” stands for “prints”. This table (and all succeeding tables of the same kind) is to be understood to mean that for a configuration described in the first two columns the operations in the third column are carried out successively, and the machine then goes over into the m-configuration described in the last column. When the second column is left blank, it is understood that the behaviour of the third and fourth columns applies for any symbol and for no symbol. The machine starts in the m-configuration 5 with a blank tape.

<table>
<thead>
<tr>
<th>Configuration</th>
<th>Behaviour</th>
</tr>
</thead>
<tbody>
<tr>
<td>m-config.</td>
<td>symbol</td>
</tr>
<tr>
<td>b</td>
<td>None</td>
</tr>
<tr>
<td>c</td>
<td>None</td>
</tr>
<tr>
<td>c</td>
<td>None</td>
</tr>
<tr>
<td>f</td>
<td>None</td>
</tr>
</tbody>
</table>
If (contrary to the description in § 1) we allow the letters \( L, R \) to appear more than once in the operations column we can simplify the table considerably.

\[
\begin{array}{|c|c|c|c|}
\hline
m\text{-config.} & symbol & operations & \text{final } m\text{-config.} \\
\hline
\text{None} & P0 & b & \\
0 & R, R, P1 & b & \\
1 & R, R, P0 & b & \\
\hline
\end{array}
\]

II. As a slightly more difficult example we can construct a machine to compute the sequence 0010110111011101111... The machine is to be capable of five \( m \)-configurations, viz. \( 'v' \), \( 'q' \), \( 'p' \), \( 'f' \), \( 't' \) and of printing \( 'a' \), \( 'x' \), \( '0' \), \( '1' \). The first three symbols on the tape will be \( 'a00' \); the other figures follow on alternate squares. On the intermediate squares we never print anything but \( 'x' \). These letters serve to "keep the place" for us and are erased when we have finished with them.

We also arrange that in the sequence of figures on alternate squares there shall be no blanks.

\[
\begin{array}{|c|c|c|c|c|}
\hline
m\text{-config.} & symbol & operations & final \ m\text{-config.} \\
\hline
b & P0, R, P0, R, P0, R, R, P0, L, L & 0 & \\
0 & R, P0, L, L, L & 0 & \\
1 & Any (0 or 1) & R, R & q & \\
q & None & P1, L & q & \\
None & R & f & \\
\hline
v & \ell & E, R & q & \\
None & L, L & p & \\
\hline
f & Any & R, R & f & \\
None & P0, L, L & 0 & \\
\hline
\end{array}
\]

With the \( m \)-configuration written below the scanned symbol. The successive complete configurations are separated by colons.

\[
:\ell 0 0 : \ell 0 0 0 : \ell 0 0 0 : \ell 0 0 0 : \ell 0 0 0 1 : \\
b \quad q \quad q \quad q \quad p \\
\ell 0 0 0 1 : \ell 0 0 0 1 : \ell 0 0 0 0 1 : \\
f \quad f \quad f \quad f \\
\ell 0 0 0 1 \ell 0 : \ldots \\
\ell \quad c \\
\]

This table could also be written in the form

\[
:\ell : \ell 0 0 0 : \ell 0 0 0 : \ldots , \quad \ell \\
\]

in which a space has been made on the left of the scanned symbol and the \( m \)-configuration written in this space. This form is less easy to follow, but we shall make use of it later for theoretical purposes.

The convention of writing the figures only on alternate squares is very useful: I shall always make use of it. I shall call the one sequence of alternate squares \( F \)-squares and the other sequence \( E \)-squares. The symbols on \( E \)-squares will be liable to erasure. The symbols on \( E \)-squares form a continuous sequence. There are no blanks until the end is reached. There is no need to have more than one \( E \)-square between each pair of \( F \)-squares: an apparent need of more \( E \)-squares can be satisfied by having a sufficiently rich variety of symbols capable of being printed on \( E \)-squares. If a symbol \( b \) is on an \( F \)-square \( S \) and a symbol \( a \) is on the \( E \)-square next on the right of \( S \), then \( S \) and \( b \) will be said to be marked with \( a \). The process of printing this \( a \) will be called marking \( b \) (or \( S \)) with \( a \).

4. Abbreviated tables.

There are certain types of process used by nearly all machines, and these, in some machines, are used in many connections. These processes include copying down sequences of symbols, comparing sequences, erasing all symbols of a given form, etc. Where such processes are concerned we can abbreviate the tables for the \( m \)-configurations considerably by the use of "skeleton tables". In skeleton tables there appear capital German letters and small Greek letters. These are of the nature of "variables". By replacing each capital German letter throughout by an \( m \)-configuration
and each small Greek letter by a symbol, we obtain the table for an  
m-configuration.

The skeleton tables are to be regarded as nothing but abbreviations:  
they are not essential. So long as the reader understands how to obtain  
the complete tables from the skeleton tables, there is no need to give any  
exact definitions in this connection.

Let us consider an example:

\[
\begin{array}{ccccc}
   & f(\mathbb{E}, a) & f_1(\mathbb{E}, a) & \vdots & \\
\mathbb{E} & \mathbb{E} & \mathbb{E} &  & \\
\text{not } \mathbb{E} & f(\mathbb{E}, a) & f_1(\mathbb{E}, a) & \vdots & \\
\alpha & \mathbb{E} & \mathbb{E} &  & \\
\text{not } \alpha & f_2(\mathbb{E}, a) & f_2(\mathbb{E}, a) & \vdots & \\
\text{None} & f_2(\mathbb{E}, a) & f_2(\mathbb{E}, a) & \vdots & \\
\end{array}
\]

From the \( m \)-configuration \( f(\mathbb{E}, a) \) the machine finds the  
symbol of form \( a \) which is farthest to the left (the "first \( a \)")  
and the \( m \)-configuration then becomes \( \mathbb{E} \). If there is no \( a \)  
then the \( m \)-configuration becomes \( \mathbb{B} \).

\( f(\mathbb{E}, a) \) is called an "\( m \)-configuration function" or "\( m \)-function".

The only expressions which are admissible for substitution in an  
\( m \)-function are the \( m \)-configurations and symbols of the machine. These  
have to be enumerated more or less explicitly: they may include expressions  
such as \( \psi(\mathbb{E}, \mathbb{E}) \); indeed they must if there are any \( m \)-functions used at all.

If we were to replace \( \mathbb{E} \) throughout by \( \alpha \) (say), \( \mathbb{B} \) by \( r \), and \( a \) by \( x \), we  
should have a complete table for the \( m \)-configuration \( f(q, r, x) \). \( f \) is  
called an "\( m \)-configuration function" or "\( m \)-function".

The only expressions which are admissible for substitution in an  
\( m \)-function are the \( m \)-configurations and symbols of the machine. These  
have to be enumerated more or less explicitly: they may include expressions  
such as \( \psi(\mathbb{E}, \mathbb{E}) \); indeed they must if there are any \( m \)-functions used at all.

If we did not insist on this explicit enumeration, but simply stated that  
the machine had certain \( m \)-configurations (enumerated) and all \( m \)-configurations  
obtainable by substitution of \( m \)-configurations in certain \( m \)-functions, we  
should usually get an infinity of \( m \)-configurations; e.g., we might say that  
the machine was to have the \( m \)-configuration \( q \) and all \( m \)-configurations  
obtainable by substituting an \( m \)-configuration for \( \mathbb{E} \) in \( \psi(\mathbb{E}) \). Then  
it would have \( q, \psi(q), \psi(\psi(q)), \psi(\psi(\psi(q))), \ldots \) as \( m \)-configurations.

Our interpretation rule then is this. We are given the names of the  
\( m \)-configurations of the machine, mostly expressed in terms of \( m \)-functions.  
We are also given skeleton tables. All we want is the complete table for  
the \( m \)-configurations of the machine. This is obtained by repeated  
substitution in the skeleton tables.

Further examples.

(In the explanations the symbol "→" is used to signify "the machine  
goes into the \( m \)-configuration. . . .")

\[ c(\mathbb{E}, \mathbb{B}, a) \rightarrow f(f_1(\mathbb{E}, \mathbb{B}, a), \mathbb{B}, a) \]  
From \( c(\mathbb{E}, \mathbb{B}, a) \) the first \( a \) is \( \mathbb{E} \). If there is no \( a \) \( \rightarrow \mathbb{B} \).

\[ c(\mathbb{B}, a) \rightarrow c(f(\mathbb{B}, a), \mathbb{B}, a) \]  
From \( c(\mathbb{B}, a) \) all letters \( a \) are \( \mathbb{E} \) and \( \mathbb{B} \).

The last example seems somewhat more difficult to interpret than  
most. Let us suppose that in the list of \( m \)-configurations of some machine  
there appears \( c(b, x) \). (\( \equiv q \), say). The table is

\[ c(b, x) \rightarrow c(c(b, x), b, x) \]  
or

\[ q \rightarrow c(q, b, x) \]

Or, in greater detail:

\[ q \rightarrow c(q, b, x) \rightarrow f(f_1(q, b, x), b, x) \]  
\[ \beta \rightarrow q. \]

In this we could replace \( f_1(q, b, x) \) by \( q' \) and then give the table for \( f \) (with  
the right substitutions) and eventually reach a table in which no  
\( m \)-functions appeared.

\[ \psi_1(\mathbb{E}, \beta) \rightarrow f(\psi_1(\mathbb{E}, \beta), \mathbb{E}, \alpha) \]  
From \( \psi_1(\mathbb{E}, \beta) \) the machine  
prints \( \beta \) at the end of the sequence of symbols and \( \rightarrow \mathbb{E} \).

\[ \psi(\mathbb{E}, \beta) \rightarrow f(\psi(\mathbb{E}, \beta), \mathbb{E}, \alpha) \]  
From \( f'(\mathbb{E}, \mathbb{B}, a) \) it does the  
same as for \( f(\mathbb{E}, \mathbb{B}, a) \) but  
moves to the left before \( \rightarrow \mathbb{E} \).

\[ c(\mathbb{E}, \mathbb{B}, a) \rightarrow f'(f_1(\mathbb{E}, \mathbb{B}, a), \mathbb{B}, a) \]  
\[ c(\mathbb{E}, \mathbb{B}, a) \rightarrow f'(f(\mathbb{E}, \mathbb{B}, a), \mathbb{B}, a) \]  
\[ c(\mathbb{E}, \mathbb{B}, a) \rightarrow c(\mathbb{E}, \mathbb{B}, a). \]  

The machine  
writes at the end the first symbol marked \( a \) and \( \rightarrow \mathbb{E} \).
The last line stands for the totality of lines obtainable from it by replacing \( \beta \) by any symbol which may occur on the tape of the machine concerned.

\[
\begin{align*}
cc(\varepsilon, \varepsilon, a) & \quad c \{ c(\varepsilon, \varepsilon, a), \varepsilon, a \} \\
c(\varepsilon, a) & \quad c(\varepsilon, a). 
\end{align*}
\]

The machine copies down in order at the end all symbols marked \( a \) and erases the letters \( \varepsilon \) \( \rightarrow \varepsilon \).

\[
\begin{align*}
tc(\varepsilon, \varepsilon, a, \beta) & \quad \{ tc(\varepsilon, \varepsilon, a, \beta), \varepsilon, a, \beta \} \\
t(\varepsilon, \varepsilon, a, \beta) & \quad \{ tc(\varepsilon, \varepsilon, a, \beta), \varepsilon, a, \beta \} \\
tc(\varepsilon, \varepsilon, a, \beta) & \quad E, P\beta \\
t(\varepsilon, \varepsilon, a, \beta) & \quad \{ tc(\varepsilon, \varepsilon, a, \beta), \varepsilon, a, \beta \}
\end{align*}
\]

The machine replaces the first \( a \) by \( \beta \) and \( \varepsilon \rightarrow \varepsilon \) if there is no \( a \).

\[
\begin{align*}
tc(\varepsilon, \varepsilon, a, \beta) & \quad c \{ tc(\varepsilon, \varepsilon, a, \beta), \varepsilon, a, \beta \} \\
tc(\varepsilon, \varepsilon, a, \beta) & \quad c(\varepsilon, \varepsilon, a, \beta, \varepsilon, a, \beta, \varepsilon, a, \beta)
\end{align*}
\]

The machine replaces all letters \( a \) by \( \beta \); \( \varepsilon \rightarrow \varepsilon \).

The first symbol marked \( a \) and the first marked \( \beta \) are compared. If there is neither \( a \) nor \( \beta \), \( \varepsilon \rightarrow \varepsilon \). If there are both and the symbols are alike, \( \varepsilon \rightarrow \varepsilon \). Otherwise \( \varepsilon \rightarrow \varepsilon \).

\[
\begin{align*}
cpc(\varepsilon, \varepsilon, E, \varepsilon, a, \beta) & \quad c(\varepsilon, \varepsilon, E, \varepsilon, a, \beta) \\
cpc(\varepsilon, \varepsilon, E, \varepsilon, a, \beta) & \quad c(\varepsilon, \varepsilon, E, \varepsilon, a, \beta) \\
cpc(\varepsilon, \varepsilon, E, \varepsilon, a, \beta) & \quad c(\varepsilon, \varepsilon, E, \varepsilon, a, \beta)
\end{align*}
\]

The sequence of symbols marked \( a \) is compared with the sequence marked \( \beta \) \( \varepsilon \rightarrow \varepsilon \) if they are similar. Otherwise \( \varepsilon \rightarrow \varepsilon \). Some of the symbols \( a \) and \( \beta \) are erased.
and, in particular, blank = $S_0$, 0 = $S_1$, 1 = $S_2$. The lines of the table are now of form

<table>
<thead>
<tr>
<th>m-config.</th>
<th>Symbol</th>
<th>Operations</th>
<th>Final m-config.</th>
</tr>
</thead>
<tbody>
<tr>
<td>$q_i$</td>
<td>$S_j$</td>
<td>PS, R</td>
<td>$q_m$</td>
</tr>
</tbody>
</table>

Lines such as

$\begin{align*}
q_i & \quad S_j \\
& \quad E, R \\
& \quad q_m
\end{align*}$

are to be written as

$\begin{align*}
q_i & \quad S_j \\
& \quad PS, R \\
& \quad q_m
\end{align*}$

and lines such as

$\begin{align*}
q_i & \quad S_j \\
& \quad R \\
& \quad q_m
\end{align*}$

are to be written as

$\begin{align*}
q_i & \quad S_j \\
& \quad PS, R \\
& \quad q_m
\end{align*}$

In this way we reduce each line of the table to a line of one of the forms $(N_1)$, $(N_2)$, $(N_3)$.

From each line of form $(N_1)$ let us form an expression $q_i S_j S_k L q_m$; from each line of form $(N_2)$ we form an expression $q_i S_j S_k R q_m$; and from each line of form $(N_3)$ we form an expression $q_i S_j S_k N q_m$.

Let us write down all expressions so formed from the table for the machine and separate them by semi-colons. In this way we obtain a complete description of the machine. In this description we shall replace $q_i$ by the letter “$D$”, followed by the letter “$A$” repeated $i$ times, and $S_j$ by “$D$” followed by “$C$” repeated $j$ times. This new description of the machine may be called the standard description (S.D.). It is made up entirely from the letters “$A$”, “$C$”, “$D$”, “$L$”, “$R$”, “$N$”, and from “,$$”.

If finally we replace “$A$” by “$1$”, “$C$” by “$2$”, “$D$” by “$3$”, “$L$” by “$4$”, “$R$” by “$5$”, “$N$” by “$6$”, and “,$$” by “$7$”, we shall have a description of the machine in the form of an arabic numeral. The integer represented by this numeral may be called a description number (D.N) of the machine. The D.N determine the S.D and the structure of the machine uniquely. The machine whose D.N is $n$ may be described as $\mathcal{A}_n$.

To each computable sequence there corresponds at least one description number, while to no description number does there correspond more than one computable sequence. The computable sequences and numbers are therefore enumerable.

Let us find a description number for the machine I of §3. When we rename the m-configurations its table becomes:

$\begin{align*}
q_1 & \quad S_0 \\
& \quad PS_1, R \\
& \quad q_2
\end{align*}$

$\begin{align*}
q_2 & \quad S_0 \\
& \quad PS_0, R \\
& \quad q_3
\end{align*}$

$\begin{align*}
q_3 & \quad S_0 \\
& \quad PS_2, R \\
& \quad q_4
\end{align*}$

$\begin{align*}
q_4 & \quad S_0 \\
& \quad PS_0, R \\
& \quad q_1
\end{align*}$

Other tables could be obtained by adding irrelevant lines such as

$\begin{align*}
q_1 & \quad S_1 \\
& \quad PS_1, R \\
& \quad q_2
\end{align*}$

Our first standard form would be

$\begin{align*}
q_1 S_0 S_1 R q_2; \quad q_2 S_0 S_0 R q_3; \quad q_3 S_0 S_2 R q_4; \quad q_4 S_0 S_0 R q_1.
\end{align*}$

The standard description is

$\text{DADDCCRDAA;DAADDRDAAA;}$

$\text{DAAAADDCCRDAAA;DAAAADDRDA;}$

A description number is

$\text{313325311731133531111731133225311117311133531731323253117}$

and so is

$\text{313325311731133531111731133225311117311133531731323253117}$

A number which is a description number of a circle-free machine will be called a satisfactory number. In §8 it is shown that there can be no general process for determining whether a given number is satisfactory or not.

6. The universal computing machine.

It is possible to invent a single machine which can be used to compute any computable sequence. If this machine $\mathcal{U}$ is supplied with a tape on the beginning of which is written the S.D of some computing machine $\mathcal{A}$,
then \( \mathcal{U} \) will compute the same sequence as \( \mathcal{M} \). In this section I explain in outline the behaviour of the machine. The next section is devoted to giving the complete table for \( \mathcal{U} \).

Let us first suppose that we have a machine \( \mathcal{M} \) which will write down on the \( F \)-squares the successive complete configurations of \( \mathcal{M} \). These might be expressed in the same form as on p. 235, using the second description, \( (C) \), with all symbols on one line. Or, better, we could transform this description (as in §5) by replacing each \( m \)-configuration by "D" followed by "A" repeated the appropriate number of times, and by replacing each symbol by "D" followed by "C" repeated the appropriate number of times. The numbers of letters "A" and "C" are to agree with the numbers chosen in §5, so that, in particular, "0" is replaced by "DC", "1" by "DCC", and the blanks by "D". These substitutions are to be made after the complete configurations have been put together, as in \( C \). Difficulties arise if we do the substitution first. In each complete configuration the blanks would all have to be replaced by "D", so that the complete configuration would not be expressed as a finite sequence of symbols.

If in the description of the machine \( \Pi \) of §3 we replace "D" by "DAA", "E" by "DCCC", "G" by "DAAA", then the sequence \( C \) becomes:

\[
DA: DCCCDDCCDAADCDDC: DCCCDDCCDAADCDDC: \ldots \quad (C_1)
\]

(This is the sequence of symbols on \( F \)-squares.)

It is not difficult to see that if \( \mathcal{M} \) can be constructed, then so can \( \mathcal{M}' \).

The manner of operation of \( \mathcal{M}' \) could be made to depend on having the rules of operation (i.e., the S.D.) of \( \mathcal{M} \) written somewhere within itself (i.e. within \( \mathcal{M}' \)); each step could be carried out by referring to these rules. We have only to regard the rules as being capable of being taken out and exchanged for others and we have something very akin to the universal machine.

One thing is lacking: at present the machine \( \mathcal{M}' \) prints no figures. We may correct this by printing between each successive pair of complete configurations the figures which appear in the new configuration but not in the old. Then \( (C_1) \) becomes

\[
DDA: 0:0: DCCCDDCCDAADCDDC: DCCC: \ldots \quad (C_2)
\]

It is not altogether obvious that the \( E \)-squares leave enough room for the necessary "rough work", but this is, in fact, the case.

The sequences of letters between the columns in expressions such as \( (C_1) \) may be used as standard descriptions of the complete configurations. When the letters are replaced by figures, as in §5, we shall have a numerical description of the complete configuration, which may be called its description number.

7. Detailed description of the universal machine.

A table is given below of the behaviour of this universal machine. The \( m \)-configurations of which the machine is capable are all those occurring in the first and last columns of the table, together with all those which occur when we write out the unabbreviated tables of those which appear in the table in the form of \( m \)-functions. E.g., \( e(\text{anf}) \) appears in the table and is an \( m \)-function. Its unabbreviated table is (see p. 239)

\[
e(\text{anf}) \begin{array}{ccc}
\phi & R & c_1(\text{anf}) \\
not\phi & L & e(\text{anf}) \\
\text{any} & R, E, R & c_1(\text{anf}) \\
\text{none} & \text{anf}
\end{array}
\]

Consequently \( c_1(\text{anf}) \) is an \( m \)-configuration of \( \mathcal{U} \).

When \( \mathcal{U} \) is ready to start work the tape running through it bears on it the symbol \( \phi \) on an \( F \)-square and again \( \phi \) on the next \( E \)-square; after this, on \( F \)-squares only, comes the S.D. of the machine followed by a double colon "::" (a single symbol, on an \( F \)-square). The S.D. consists of a number of instructions, separated by semi-colons.

Each instruction consists of five consecutive parts

(i) "D" followed by a sequence of letters "A". This describes the relevant \( m \)-configuration.

(ii) "D" followed by a sequence of letters "C". This describes the scanned symbol.

(iii) "D" followed by another sequence of letters "C". This describes the symbol into which the scanned symbol is to be changed.

(iv) "L", "R", or "N", describing whether the machine is to move to left, right, or not at all.

(v) "D" followed by a sequence of letters "A". This describes the final \( m \)-configuration.

The machine \( \mathcal{U} \) is to be capable of printing "A", "C", "D", "0", "1", "\text{u}", "\text{v}", "\text{w}", "x", "\text{y}", "z". The S.D. is formed from ":", "A", "C", "D", "L", "R", "N".

r 2
Subsidiary skeleton table.

\[ \begin{align*}
\text{con}(\xi, a) & \begin{cases} 
A & R, R, \text{con}(\xi, a) \\
A & L, Pa, R, \text{con}(\xi, a) \\
D & R, Pa, R, \text{con}(\xi, a) \\
C & R, Pa, R, \text{con}(\xi, a) \\
\text{Not} C & R, R, \text{con}(\xi, a)
\end{cases} \\
\text{con}_1(\xi, a) & \begin{cases} 
A & R, Pa, R, \text{con}_1(\xi, a) \\
D & R, Pa, R, \text{con}_1(\xi, a)
\end{cases} \\
\text{con}_2(\xi, a) & \begin{cases} 
C & R, Pa, R, \text{con}_2(\xi, a) \\
\text{Not} C & R, R, \text{con}_2(\xi, a)
\end{cases}
\end{align*} \]

The table for \( \text{anf} \).

<table>
<thead>
<tr>
<th>( \text{b} )</th>
<th>( f(\text{anf}_1, \text{anf}_1, :) )</th>
</tr>
</thead>
<tbody>
<tr>
<td>( \text{b}_1 )</td>
<td>( \text{R}, \text{R}, \text{P}, \text{R}, \text{R}, \text{PD}, \text{R}, \text{R}, \text{PA} )</td>
</tr>
<tr>
<td>( \text{anf} )</td>
<td>( g(\text{anf}_1, :) )</td>
</tr>
<tr>
<td>( \text{anf}_1 )</td>
<td>( \text{con}(\text{fem}, y) )</td>
</tr>
<tr>
<td>( \text{fem} )</td>
<td>( ; R, Pz, L, \text{con}(\text{fem}, y) )</td>
</tr>
<tr>
<td>( \text{fem}_1 )</td>
<td>( z ), ( \text{L}, \text{L} )</td>
</tr>
<tr>
<td>( \text{fem}_2 )</td>
<td>( \text{not} z ) nor ( ; ), ( \text{L} )</td>
</tr>
<tr>
<td>( \text{fem}_3 )</td>
<td>( c((\text{fem}, x, y), \text{sim}, x, y) )</td>
</tr>
<tr>
<td>( \text{fem}_4 )</td>
<td>( \text{con}\left(f\left(\text{fem}_3\right)\right))</td>
</tr>
<tr>
<td>( \text{fem}_5 )</td>
<td>( \text{not} D )</td>
</tr>
<tr>
<td>( \text{fem}_6 )</td>
<td>( \text{C} ), ( \text{R} )</td>
</tr>
<tr>
<td>( \text{fem}_7 )</td>
<td>( \text{not} C )</td>
</tr>
<tr>
<td>( \text{fem}_8 )</td>
<td>( \text{C} ), ( \text{R} )</td>
</tr>
<tr>
<td>( \text{fem}_9 )</td>
<td>( \text{not} C )</td>
</tr>
</tbody>
</table>

Anf. Taking the long view, the last instruction relevant to the last configuration is found. It can be recognised afterwards as the instruction following the last semi-colon marked \( z \). → \( \text{sim} \).

\[ \begin{align*}
\text{sim} & \begin{cases} 
\text{f}'(\text{sim}_1, \text{sim}_1, z) \\
\text{sim}_1 \\
\text{sim}_2 \\
\text{sim}_3 \\
\text{sim}_4 \\
\text{sim}_5 \\
\text{sim}_6 \\
\text{sim}_7 \\
\text{sim}_8 \\
\text{sim}_9 \\
\text{sim}_10
\end{cases} \\
\text{sim}_1 & \begin{cases} 
\text{anf} \\
\text{anf}_1 \begin{cases} 
\text{fem}_1 \\
\text{fem}_2 \\
\text{fem}_3 \\
\text{fem}_4 \\
\text{fem}_5 \\
\text{fem}_6 \\
\text{fem}_7 \\
\text{fem}_8 \\
\text{fem}_9 \\
\text{fem}_10
\end{cases}
\end{cases}
\end{align*} \]
Let us suppose that there is such a process; that is to say, that we can invent a machine $O$ which, when supplied with the S.D of any computing machine $\mathfrak{M}$ will test this S.D and if $\mathfrak{M}$ is circular will mark the S.D with the symbol "w" and if it is circle-free will mark it with "s". By combining the machines $O$ and $\mathfrak{M}$ we could construct a machine $\mathfrak{N}$ to compute the sequence $\beta'$. The machine $O$ may require a tape. We may suppose that it uses the $E$-squares beyond all symbols on $F$-squares, and that when it has reached its verdict all the rough work done by $O$ is erased.

The machine $\mathfrak{N}$ has its motion divided into sections. In the first $N-1$ sections, among other things, the integers $1, 2, ..., N-1$ have been written down and tested by the machine $O$. A certain number, say $R(N-1)$, of them have been found to be the D.N's of circle-free machines. In the $N$-th section the machine $O$ tests the number $N$. If $N$ is satisfactory, i.e., if it is the D.N of a circle-free machine, then $R(N) = 1 + R(N-1)$ and the first $R(N)$ figures of the sequence of which a $D_N$ is $N$ are calculated. The $R(N)$-th figure of this sequence is written down as one of the figures of the sequence $\beta'$ computed by $\mathfrak{N}$. If $N$ is not satisfactory, then $R(N) = R(N-1)$ and the machine goes on to the $(N+1)$-th section of its motion.

From the construction of $\mathfrak{N}$ we can see that $\mathfrak{N}$ is circle-free. Each section of the motion of $\mathfrak{N}$ comes to an end after a finite number of steps. For, by our assumption about $O$, the decision as to whether $N$ is satisfactory is reached in a finite number of steps. If $N$ is not satisfactory, then the $N$-th section is finished. If $N$ is satisfactory, this means that the machine $\mathfrak{M}(N)$ whose D.N is $N$ is circle-free, and therefore its $R(N)$-th figure can be calculated in a finite number of steps. When this figure has been calculated and written down as the $R(N)$-th figure of $\beta'$, the $N$-th section is finished. Hence $\mathfrak{N}$ is circle-free.

Now let $K$ be the D.N of $\mathfrak{N}$. What does $\mathfrak{N}$ do in the $K$-th section of its motion? It must test whether $K$ is satisfactory, giving a verdict "s" or "w". Since $K$ is the D.N of $\mathfrak{N}$ and since $\mathfrak{N}$ is circle-free, the verdict cannot be "w". On the other hand the verdict cannot be "s". For if it were, then in the $K$-th section of its motion $\mathfrak{N}$ would be bound to compute the first $R(K-1) + 1 = R(K)$ figures of the sequence computed by the machine with $K$ as its D.N and to write down the $R(K)$-th as a figure of the sequence computed by $\mathfrak{N}$. The computation of the first $R(K)-1$ figures would be carried out all right, but the instructions for calculating the $R(K)$-th would amount to "calculate the first $R(K)$ figures computed by $H$ and write down the $R(K)$-th". This $R(K)$-th figure would never be found. I.e., $\mathfrak{N}$ is circular, contrary both to what we have found in the last paragraph and to the verdict "s". Thus both verdicts are impossible and we conclude that there can be no machine $O$.

We can show further that there can be no machine $\mathcal{M}$ which, when supplied with the S.D. of an arbitrary machine \( M \), will determine whether \( M \) ever prints a given symbol (0 say).

We will first show that, if there is a machine $\mathcal{M}$, then there is a general process for determining whether a given machine \( M \) prints 0 infinitely often. Let \( \mathcal{M}_1 \) be a machine which prints the same sequence as \( M \), except that in the position where the first 0 printed by \( M \) stands, \( \mathcal{M}_1 \) prints 0. \( \mathcal{M}_2 \) is to have the first two symbols 0 replaced by 0, and so on. Thus, if \( M \) were to print
$$ABA01AA0010A\ldots,$$
then \( \mathcal{M}_1 \) would print
$$ABAA01A0A0010A\ldots$$
and \( \mathcal{M}_2 \) would print
$$ABA01A0010A\ldots$$

Now let \( \mathcal{N} \) be a machine which, when supplied with the S.D. of \( M \), will write down successively the S.D. of \( M_{11} \), of \( M_{12} \), of \( M_{22} \), etc. (there is such a machine). We combine \( \mathcal{N} \) with \( \mathcal{M} \) and obtain a new machine, \( \mathcal{L} \). In the motion of \( \mathcal{L} \) first \( \mathcal{N} \) is used to write down the S.D. of \( M \), and then \( \mathcal{M} \) tests it: 0; if it is written if it is found that \( M \) never prints 0; then \( \mathcal{N} \) writes the S.D. of \( M_{11} \), and this is tested; 0: being printed if and only if \( M \) never prints 0, and so on. Now let us test \( \mathcal{L} \) with \( \mathcal{M} \). If it is found that \( \mathcal{N} \) never prints 0; then \( \mathcal{M} \) prints 0 infinitely often; if \( \mathcal{N} \) prints 0 sometimes, then \( \mathcal{M} \) does not print 0 infinitely often.

Similarly there is a general process for determining whether \( M \) prints 1 infinitely often. By a combination of these processes we have a process for determining whether \( M \) prints an infinity of figures \( \ldots \). We have a process for determining whether \( M \) is circle-free. There can therefore be no machine \( \mathcal{M} \).

The expression "there is a general process for determining ..." has been used throughout this section as equivalent to "there is a machine which will determine ...". This usage can be justified if and only if we can justify our definition of "computable". For each of these "general process" problems can be expressed as a problem concerning a general process for determining whether a given integer \( n \) has a property \( G(n) \) [e.g. \( G(n) \) might mean "\( n \) is satisfactory" or "\( n \) is the Gödel representation of a provable formula"], and this is equivalent to computing a number whose \( n \)-th figure is 1 if \( G(n) \) is true and 0 if it is false.

9. The extent of the computable numbers.

No attempt has yet been made to show that the "computable" numbers include all numbers which would naturally be regarded as computable. All arguments which can be given are bound to be, fundamentally, appeals to intuition, and for this reason rather unsatisfactory mathematically. The real question at issue is "What are the possible processes which can be carried out in computing a number?"

The arguments which I shall use are of three kinds.

(a) A direct appeal to intuition.

(b) A proof of the equivalence of two definitions (in case the new definition has a greater intuitive appeal).

(c) Giving examples of large classes of numbers which are computable.

Once it is granted that computable numbers are all "computable", several other propositions of the same character follow. In particular, it follows that, if there is a general process for determining whether a formula of the Hilbert function calculus is provable, then the determination can be carried out by a machine.

I. (Type (a)). This argument is only an elaboration of the ideas of §1.

Computing is normally done by writing certain symbols on paper. We may suppose this paper is divided into squares like a child's arithmetic book. In elementary arithmetic the two-dimensional character of the paper is sometimes used. But such a use is always avoidable, and I think that it will be agreed that the two-dimensional character of paper is no essential of computation. I assume then that the computation is carried out on one-dimensional paper, i.e. on a tape divided into squares. I shall also suppose that the number of symbols which may be printed is finite. If we were to allow an infinity of symbols, then there would be symbols differing to an arbitrarily small extent.† The effect of this restriction of the number of symbols is not very serious. It is always possible to use sequences of symbols in the place of single symbols. Thus an Arabic numeral such as

† If we regard a symbol as literally printed on a square we may suppose that the square is \( 0 < x < 1, 0 < y < 1 \). The symbol is defined as a set of points in this square, viz. the set occupied by printer's ink. If these sets are restricted to be measurable, we can define the "distance" between two symbols as the cost of transforming one symbol into the other if the cost of moving unit area of printer's ink unit distance is unity, and there is an infinite supply of ink at \( z = 2, y = 0 \). With this topology the symbols form a conditionally compact space.
17 or 99999999999999 is normally treated as a single symbol. Similarly
in any European language words are treated as single symbols (Chinese,
however, attempts to have an enumerable infinity of symbols). The
differences from our point of view between the single and compound symbols
is that the compound symbols, if they are too lengthy, cannot be observed
at one glance. This is in accordance with experience. We cannot tell at
a glance whether 99999999999999 and 99999999999999 are the same.

The behaviour of the computer at any moment is determined by the
symbols which he is observing, and his "state of mind" at that moment.
We may suppose that there is a bound \( B \) to the number of symbols or
squares which the computer can observe at one moment. If he wishes to
observe more, he must use successive observations. We will also suppose
that the number of states of mind which need be taken into account is finite.
The reasons for this are of the same character as those which restrict the
number of symbols. If we admitted an infinity of states of mind, some of
them will be "arbitrarily close" and will be confused. Again, the restriction
is not one which seriously affects computation, since the use of more compi-
icated states of mind can be avoided by writing more symbols on the tape.

Let us imagine the operations performed by the computer to be split up
into "simple operations" which are so elementary that it is not easy to
imagine them further divided. Every such operation consists of some change
of the physical system consisting of the computer and his tape. We know
the state of the system if we know the sequence of symbols on the tape,
which of these are observed by the computer (possibly with a special order),
and the state of mind of the computer. We may suppose that in a
simple operation not more than one symbol is altered. Any other changes
can be split up into simple changes of this kind. The situation in regard
to the squares whose symbols may be altered in this way is the same as in
regard to the observed squares. We may, therefore, without loss of
generality, assume that the squares whose symbols are changed are always
"observed" squares.

Besides these changes of symbols, the simple operations must include
changes of distribution of observed squares. The new observed squares
must be immediately recognisable by the computer. I think it is reasonable
to suppose that they can only be squares whose distance from the closest
of the immediately previously observed squares does not exceed a certain
fixed amount. Let us say that each of the new observed squares is within
\( L \) squares of an immediately previously observed square.

In connection with "immediate recognisability", it may be thought
that there are other kinds of square which are immediately recognisable.
In particular, squares marked by special symbols might be taken as imme-
diately recognisable. Now if these squares are marked only by single
symbols there can be only a finite number of them, and we should not upset
our theory by adjoining these marked squares to the observed squares. If,
on the other hand, they are marked by a sequence of symbols, we
cannot regard the process of recognition as a simple process. This is a
fundamental point and should be illustrated. In most mathematical
papers the equations and theorems are numbered. Normally the numbers
do not go beyond (say) 1000. It is, therefore, possible to recognise a
theorem at a glance by its number. But if the paper was very long, we
might reach Theorem 157767734434477; then, further on in the paper, we
might find "... hence (applying Theorem 157767734434477) we have ...".
In order to make sure which was the relevant theorem we should have to
compare the two numbers figure by figure, possibly ticking the figures off
in pencil to make sure of their not being counted twice. If in spite of this
it is still thought that there are other "immediately recognisable" squares,
it does not upset my contention so long as these squares can be found by
some process of which my type of machine is capable. This idea is
developed in III below.

The simple operations must therefore include:

(a) Changes of the symbol on one of the observed squares.

(b) Changes of one of the squares observed to another square
within \( L \) squares of one of the previously observed squares.

It may be that some of these changes necessarily involve a change of
state of mind. The most general single operation must therefore be taken
to be one of the following:

(A) A possible change (a) of symbol together with a possible
change of state of mind.

(B) A possible change (b) of observed squares, together with a
possible change of state of mind.

The operation actually performed is determined, as has been suggested
on p. 280, by the state of mind of the computer and the observed symbols.
In particular, they determine the state of mind of the computer after the
operation is carried out.

We may now construct a machine to do the work of this computer. To
each state of mind of the computer corresponds an "m-configuration"
of the machine. The machine scans \( B \) squares corresponding to the \( B \) squares
observed by the computer. In any move the machine can change a symbol
on a scanned square or can change any one of the scanned squares to another
square distant not more than \( L \) squares from one of the other scanned
squares. The move which is done, and the succeeding configuration, are determined by the scanned symbol and the m-configuration. The machines just described do not differ very essentially from computing machines as defined in §2, and corresponding to any machine of this type a computing machine can be constructed to compute the same sequence, that is to say the sequence computed by the computer.

II. [Type (b)].

If the notation of the Hilbert functional calculus† is modified so as to be systematic, and so as to involve only a finite number of symbols, it becomes possible to construct an automatic‡ machine ɔ, which will find all the provable formulae of the calculus§.

Now let a be a sequence, and let us denote by ɔ(a) the proposition "The x-th figure of a is 1", so that −ɔ(a) means "The x-th figure of a is 0". Suppose further that we can find a set of properties which define the sequence a and which can be expressed in terms of ɔ(x) and of the propositional functions N(x) meaning "x is a non-negative integer" and F(x, y) meaning "y = x + 1". When we join all these formulae together conjunctively, we shall have a formula, ɔ, which defines a. The terms of ɔ must include the necessary parts of the Peano axioms, viz.,

\[(\exists u) N(u) & (x) \{ N(x) \to (\exists y) F(x, y) \} \& \{ F(x, y) \to N(y) \},\]

which we will abbreviate to P.

When we say "ɔ defines a", we mean that −ɔ is not a provable formula, and also that, for each n, one of the following formulae (A_n) or (B_n) is provable.

\[\quad \& \quad F^{(n)} \to ɔ(a^{(n)}) \]  
\[\quad \& \quad F^{(n)} \to (− ɔ(a^{(n)})) \]

… (B_n),

where F^{(n)} stands for F(u, u') & F(u', u'') & … F(u^{(n-1)}, u^{(n)}).

† The expression "the functional calculus" is used throughout to mean the restricted Hilbert functional calculus.
‡ It is most natural to construct first a choice machine (§2) to do this. But it is then easy to construct the required automatic machine. We can suppose that the choices are always between two possibilities 0 and 1. Each proof will then be determined by a sequence of choices t, 1, ..., t, where t = 0 or 1, 1, ..., t = 0 or 1, and hence the number 2^t - 1, 2^t - 1, ..., 2^t - 1 completely determines the proof. The automatic machine carries out successively proof 1, proof 2, proof 3, …
§ The author has found a description of such a machine.
\[\&\] The negation sign is written before an expression and not over it.
A sequence of primes denoted by ๑.
instructions and the symbols on the tape. That is, the state of the system may be described by a single expression (sequence of symbols), consisting of the symbols on the tape followed by $\Delta$ (which we suppose not to appear elsewhere) and then by the note of instructions. This expression may be called the "state formula". We know that the state formula at any given stage is determined by the state formula before the last step was made, and we assume that the relation of these two formulae is expressible in the functional calculus. In other words, we assume that there is an axiom $\mathfrak{U}$ which expresses the rules governing the behaviour of the computer, in terms of the relation of the state formula at any stage to the state formula at the preceding stage. If this is so, we can construct a machine to write down the successive state formulae, and hence to compute the required number.

10. Examples of large classes of numbers which are computable.

It will be useful to begin with definitions of a computable function of an integral variable and of a computable variable, etc. There are many equivalent ways of defining a computable function of an integral variable. The simplest is, possibly, as follows. If $\gamma$ is a computable sequence in which 0 appears infinitely often, and $n$ is an integer, then let us define $\xi(\gamma, n)$ to be the number of figures 1 between the $n$-th and the $(n + 1)$-th figure 0 in $\gamma$. Then $\phi(n)$ is computable if, for all $n$ and some $\gamma$, $\phi(n) = \xi(\gamma, n)$. An equivalent definition is this. Let $H(x, y)$ mean $\phi(x) = y$. Then, if we can find a contradiction-free axiom $\mathfrak{U}$, such that $\mathfrak{U} \rightarrow P$, and if for each integer $n$ there exists an integer $N$, such that

$$\exists x \land \phi(x) \rightarrow H(x, 0), \quad \phi(n) = \xi(\gamma, n).$$

and such that, if $m \neq \phi(n)$, then, for some $N'$,

$$\exists x \land \phi(x) \rightarrow \neg H(x, m), \quad \phi(n) \land \phi(m),$$

then $\phi$ may be said to be a computable function.

We cannot define general computable functions of a real variable, since there is no general method of describing a real number, but we can define a computable function of a computable variable. If $n$ is satisfactory, let $\gamma_n$ be the number computed by \(\ll(n)\), and let

$$a_n = \tan \left( \pi \gamma_n - \frac{1}{2} \right),$$

unless $\gamma_n = 0$ or $\gamma_n = 1$, in either of which cases $a_n = 0$. Then, as $n$ runs through the satisfactory numbers, $a_n$ runs through the computable numbers†. Now let $\phi(n)$ be a computable function which can be shown to be such that for any satisfactory argument its value is satisfactory†. Then the function $f$, defined by $f(a_n) = a_{\phi(n)}$, is a computable function and all computable functions of a computable variable are expressible in this form.

Similar definitions may be given of computable functions of several variables, computable-valued functions of an integral variable, etc.

I shall enunciate a number of theorems about computability, but I shall prove only (ii) and a theorem similar to (iii).

(i) A computable function of a computable function of an integral or computable variable is computable.

(ii) Any function of an integral variable defined recursively in terms of computable functions is computable. Let $\phi(m, n)$ is computable, and $r$ is some integer, then $\eta(n)$ is computable, where

$$\eta(0) = r,$$

$$\eta(n) = \phi(n, \eta(n-1)).$$

(iii) If $\phi(m, n)$ is a computable function of two integral variables, then $\phi(n, n)$ is a computable function of $n$.

(iv) If $\phi(n)$ is a computable function whose value is always 0 or 1, then the sequence whose $n$-th figure is $\phi(n)$ is computable. Dedekind's theorem does not hold in the ordinary form if we replace "real" throughout by "computable". But it holds in the following form:

(v) If $G(a)$ is a propositional function of the computable numbers and

(a) $\exists a \exists \beta \left[ G(a) \land \neg G(\beta) \right],$

(b) $G(a) \land \neg G(\beta) \rightarrow (a < \beta),$

and there is a general process for determining the truth value of $G(a)$, then

† A function $a_n$ may be defined in many other ways so as to run through the computable numbers.

† Although it is not possible to find a general process for determining whether a given number is satisfactory, it is often possible to show that certain classes of numbers are satisfactory.
there is a computable number $\xi$ such that

$$G(a) \rightarrow a \leq \xi,$$

$$-G(a) \rightarrow a \geq \xi.$$

In other words, the theorem holds for any section of the computables such that there is a general process for determining to which class a given number belongs.

Owing to this restriction of Dedekind's theorem, we cannot say that a computable bounded increasing sequence of computable numbers has a computable limit. This may possibly be understood by considering a sequence such as

$$-1, -\frac{1}{2}, -\frac{1}{3}, -\frac{1}{4}, \frac{1}{2}, \ldots .$$

On the other hand, (v) enables us to prove

(vi) If $a$ and $\beta$ are computable and $a < \beta$ and $\phi(a) < 0 < \phi(\beta)$, where $\phi(a)$ is a computable increasing continuous function, then there is a unique computable number $\gamma$, satisfying $a < \gamma < \beta$ and $\phi(\gamma) = 0$.

**Computable convergence.**

We shall say that a sequence $\beta_n$ of computable numbers converges computably if there is a computable integral valued function $N(\varepsilon)$ of the computable variable $\varepsilon$, such that we can show that, if $\varepsilon > 0$ and $n > N(\varepsilon)$ and $m > N(\varepsilon)$, then $|\beta_n - \beta_m| < \varepsilon$.

We can then show that

(vii) A power series whose coefficients form a computable sequence of computable numbers is computably convergent at all computable points in the interior of its interval of convergence.

(viii) The limit of a computably convergent sequence is computable.

And with the obvious definition of "uniformly computably convergent":

(ix) The limit of a uniformly computably convergent computable sequence of computable functions is a computable function. Hence

(x) The sum of a power series whose coefficients form a computable sequence is a computable function in the interior of its interval of convergence.

From (viii) and $\pi = 4(1 - \frac{1}{3} + \frac{1}{5} - \ldots)$ we deduce that $\pi$ is computable.

From $\varepsilon = 1 + 1 + \frac{1}{2} + \frac{1}{3} + \ldots$ we deduce that $\varepsilon$ is computable.

From (vi) we deduce that all real algebraic numbers are computable.

From (vi) and (x) we deduce that the real zeros of the Bessel functions are computable.

**Proof of (ii).**

Let $H(x, y)$ mean "$\eta(x) = y$", and let $K(x, y, z)$ mean "$\phi(x, y) = z$". $\eta_\alpha$ is the axiom for $\phi(x, y)$. We take $\eta_\alpha$ to be

$$\eta_\alpha & P \& \left( F(x, y) \rightarrow G(x, y) \right) \& \left( G(x, y) \& G(y, z) \rightarrow G(x, z) \right) \& \left( F\theta \rightarrow H(u, w^\theta) \right) \& \left( F\theta \& H(v, x) \& K(w, x, z) \rightarrow H(w, z) \right)$$

& \left[ H(w, z) \& G(z, t) \nu G(t, z) \nu \right] \right].

I shall not give the proof of consistency of $\eta_\alpha$. Such a proof may be constructed by the methods used in Hilbert and Bernays, Grundlagen der Mathematik (Berlin, 1934), p. 209 et seq. The consistency is also clear from the meaning.

Suppose that, for some $n, N$, we have shown

$$\eta_\alpha \& F^{(N)} \rightarrow H(u^{(n-1)}, w^{(n-1)}),$$

then, for some $M,$

$$\eta_\alpha \& F^{(M)} \rightarrow K(u^{(n)}, w^{(n-1)}),$$

$$\eta_\alpha \& F^{(M)} \rightarrow F(u^{(n)}, w^{(n)}) \& H(u^{(n-1)}, w^{(n-1)}),$$

$$\& K(u^{(n)}, w^{(n-1)}),$$

and

$$\eta_\alpha \& F^{(M)} \rightarrow \left[ F(u^{(n)}, w^{(n)}) \& H(u^{(n-1)}, w^{(n-1)})$$

$$\& K(u^{(n)}, w^{(n-1)}), H(u^{(n)}, w^{(n)}) \right].$$

Hence

$$\eta_\alpha \& F^{(M)} \rightarrow H(u^{(n)}, w^{(n)}).$$

Also

$$\eta_\alpha \& F^{(M)} \rightarrow H(u^{(n)}, w^{(n)}).$$

Hence for each $n$ some formula of the form

$$\eta_\alpha \& F^{(M)} \rightarrow H(u^{(n)}, w^{(n)})$$

is provable. Also, if $M' \geq M$ and $M' \geq m$ and $m \neq \eta(u)$, then

$$\eta_\alpha \& F^{(M')} \rightarrow G(u^{(m)}), w^{(m)} \nu G(u^{(m)}, w^{(m)}).$$
and
\[ \mathcal{U}_n \& F^{(m)} \rightarrow \left[ \{ G(u^{(m)}, u^{(m)}) \ldots \right. \]
\[ \& H(u^{(m)}, u^{(m)}) \rightarrow (-H(u^{(m)}, u^{(m)})) \right]. \]

Hence
\[ \mathcal{U}_n \& F^{(m)} \rightarrow (-H(u^{(m)}, u^{(m)})). \]

The conditions of our second definition of a computable function are therefore satisfied. Consequently \( \eta \) is a computable function.

**Proof of a modified form of (iii).**

Suppose that we are given a machine \( \mathcal{N} \), which, starting with a tape bearing on it \( \alpha \) as followed by a sequence of any number of letters \( \ldots F \ldots \) on \( F \)-squares and in the \( m \)-configuration \( b \), will compute a sequence \( \gamma_n \) depending on the number \( n \) of letters \( \ldots F \). If \( \phi_n(m) \) is the \( m \)-th figure of \( \gamma_n \), then the sequence \( \beta \) whose \( m \)-th figure is \( \phi_n(m) \) is computable.

We suppose that the table for \( \mathcal{N} \) has been written out in such a way that in each line only one operation appears in the operations column. We also suppose that \( \Xi, \Theta, \Upsilon, \Lambda \) do not occur in the table, and we replace \( \sigma \) throughout by \( \Theta, \Theta, \Theta, \Theta \) and \( \Upsilon \) by \( \Upsilon, \Upsilon, \Upsilon, \Upsilon \). Further substitutions are then made. Any line of form
\[ \Xi \quad \alpha \quad P\Phi \quad \Xi \]
we replace by
\[ \Xi \quad \alpha \quad P\Phi \quad r(\Xi, u, h, k) \]
and any line of the form
\[ \Xi \quad \alpha \quad P\Upsilon \quad \Xi \]
by
\[ \Xi \quad \alpha \quad P\Upsilon \quad r(\Xi, v, h, k) \]
and we add to the table the following lines:
\[ u \quad \text{pc}(u, 0) \]
\[ u_1 \quad R, P\Phi, R, P\Theta, R, P\Theta \]
\[ u_2 \quad r(u_1, u_2, h, k) \]
\[ u_3 \quad \text{pc}(u_2, F) \]
and similar lines with \( \nu \) for \( u \) and \( 1 \) for \( 0 \) together with the following line:
\[ c \quad R, P\Xi, R, P\Phi \quad \Upsilon. \]

We then have the table for the machine \( \mathcal{N}' \) which computes \( \beta \). The initial \( m \)-configuration is \( c \), and the initial scanned symbol is the second \( \alpha \).

11. **Application to the Entscheidungsproblem.**

The results of §8 have some important applications. In particular, they can be used to show that the Hilbert Entscheidungsproblem can have no solution. For the present I shall confine myself to proving this particular theorem. For the formulation of this problem I must refer the reader to Hilbert and Ackermann's *Grundzüge der Theoretischen Logik* (Berlin, 1931), chapter 3.

I propose, therefore, to show that there can be no general process for determining whether a given formula \( \Xi \) of the functional calculus \( K \) is provable, i.e. that there can be no machine which, supplied with any one \( \Xi \) of these formulae, will eventually say whether \( \Xi \) is provable.

It should perhaps be remarked that what I shall prove is quite different from the well-known results of Gödel†. Gödel has shown that (in the formalism of Principia Mathematica) there are propositions \( \Xi \) such that neither \( \Xi \) nor \( \neg \Xi \) is provable. As a consequence of this, it is shown that no proof of consistency of Principia Mathematica (or of \( K \)) can be within that formalism. On the other hand, I shall show that there is no general method which tells whether a given formula \( \Xi \) is provable in \( K \), or, what comes to the same, whether the system consisting of \( K \) with \( -\Xi \) adjoined as an extra axiom is consistent.

If the negation of what Gödel has shown had been proved, i.e. if, for each \( \Xi \), either \( \Xi \) or \( -\Xi \) is provable, then we should have an immediate solution of the Entscheidungsproblem. For we can invent a machine \( \mathcal{K} \) which will prove consecutively all provable formulae. Sooner or later \( \mathcal{K} \) will reach either \( \Xi \) or \(-\Xi \). If it reaches \( \Xi \), then we know that \( \Xi \) is provable. If it reaches \(-\Xi \), then, since \( \Xi \) is consistent (Hilbert and Ackermann, p. 65), we know that \( \Xi \) is not provable.

Owing to the absence of integers in \( K \) the proofs appear somewhat lengthy. The underlying ideas are quite straightforward.

Corresponding to each computing machine \( \mathcal{M} \) we construct a formula \( \text{Un}(\mathcal{M}) \) and we show that, if there is a general method for determining whether \( \text{Un}(\mathcal{M}) \) is provable, then there is a general method for determining whether \( \mathcal{M} \) ever prints \( 0 \).

The interpretations of the propositional functions involved are as follows:

\[ R_5(x, y) \text{ is to be interpreted as "in the complete configuration } x \text{ (of } \mathcal{M} \text{) the symbol on the square } y \text{ is } S".} \]

† *Loc. cit.*
\(I(x, y)\) is to be interpreted as “in the complete configuration \(x\) the square \(y\) is scanned”.

\(K_{q_m}(x)\) is to be interpreted as “in the complete configuration \(x\) the \(m\)-configuration is \(q_m\).

\(F(x, y)\) is to be interpreted as “\(y\) is the immediate successor of \(x\)”.

\(\text{Inst}\{q_i, S_j, S_k, Lq_l\}\) is to be an abbreviation for

\[
(x, y, x', y') \left\{ (R_{S_i}(x, y) \& I(x, y) \& K_{q_i}(x) \& F(x, x') \& F(y', y)) \rightarrow \left( I(x', y') \& R_{S_j}(x', y) \& K_{q_j}(x') \right) \& (z) \left[ F(y', z) \vee (R_{S_k}(x, z) \rightarrow R_{S_k}(x', z)) \right] \right\}.
\]

\(\text{Inst}\{q_i, S_j, S_k, Lq_l\}\) and \(\text{Inst}\{q_i, S_j, S_k, N_{q_l}\}\)

are to be abbreviations for other similarly constructed expressions.

Let us put the description of \(\ll\) into the first standard form of § 6. This description consists of a number of expressions such as “\(q_i, S_j, S_k, Lq_l\)” (or with \(R\) or \(N\) substituted for \(L\)). Let us form all the corresponding expressions such as \(\text{Inst}\{q_i, S_j, S_k, Lq_l\}\) and take their logical sum. This we call \(\text{Des}\{\ll\}\).

The formula \(\text{Un}\{\ll\}\) is to be

\[
(\exists u) \left[ N(u) \& (x) \left( N(x) \rightarrow (\exists x') F(x, x') \right) \& (y, z) \left( F(y, z) \rightarrow N(y) \& N(z) \right) \& (y) R_{S_i}(u, y) \& I(u, u) \& K_{q_i}(u) \& \text{Des}\{\ll\} \right] \rightarrow (\exists s) (\exists t) [N(s) \& N(t) \& R_{S_i}(s, t)].
\]

\(\text{Un}\{\ll\}\) may be abbreviated to \(A(\ll)\).

When we substitute the meanings suggested on p. 259–60 we find that \(\text{Un}\{\ll\}\) has the interpretation “in some complete configuration of \(\ll\) \(S_i\) \(i.e.\) 0 appears on the tape”. Corresponding to this I prove that

(a) If \(S_i\) appears on the tape in some complete configuration of \(\ll\), then \(\text{Un}\{\ll\}\) is provable.

(b) If \(\text{Un}\{\ll\}\) is provable, then \(S_i\) appears on the tape in some complete configuration of \(\ll\).

When this has been done, the remainder of the theorem is trivial.

**Lemma 1.** If \(S_i\) appears on the tape in some complete configuration of \(\ll\), then \(\text{Un}\{\ll\}\) is provable.

We have to show how to prove \(\text{Un}\{\ll\}\). Let us suppose that in the \(n\)-th complete configuration the sequence of symbols on the tape is \(S_{r(n,0)}, S_{r(n,1)}, \ldots, S_{r(n,n)}\) followed by nothing but blanks, and that the scanned symbol is the \(i(n)\)-th, and that the \(m\)-configuration is \(q_{k(n)}\). Then we may form the proposition

\[
\begin{align*}
R_{S_{r(n,0)}}(u^{(n)}, u) \& R_{S_{r(n,1)}}(u^{(n)}, u') \& \cdots \& R_{S_{r(n,n)}}(u^{(n)}, u^{(n)}) \& I(u^{(n)}, u^{(n)}) \& K_{q_{k(n)}}(u^{(n)}) \& (y) F((y, u') \vee F(u, y) \vee F(u', y) \vee \cdots \vee F(u^{(n-1)}, y) \vee R_{S_k}(u^{(n)}, y)),
\end{align*}
\]

which we may abbreviate to \(CC_n\).

As before, \(F(u, u') \& F(u', u'') \& \cdots \& F(u^{(n-1)}, u^{(n)})\) is abbreviated to \(F^n\).

I shall show that all formulae of the form \(A(\ll) \& F^n \rightarrow CC_n\) (abbreviated to \(CF_n\)) are provable. The meaning of \(CF_n\) is “The \(n\)-th complete configuration of \(\ll\) is so and so,” where “so and so” stands for the actual \(n\)-th complete configuration of \(\ll\). That \(CF_n\) should be provable is therefore to be expected.

\(CF_0\) is certainly provable, for in the complete configuration the symbols are all blanks, the \(m\)-configuration is \(q_1\), and the scanned square is \(u\), i.e.

\[
CC_0\text{ is } (y) R_{S_1}(u, y) \& I(u, u) \& K_{q_1}(u).
\]

\(A(\ll) \rightarrow CC_0\) is then trivial.

We next show that \(CF_n \rightarrow CF_{n+1}\) is provable for each \(n\). There are three cases to consider, according as in the move from the \(n\)-th to the \((n+1)\)-th configuration the machine moves to left or to right or remains stationary. We suppose that the first case applies, i.e. the machine moves to the left. A similar argument applies in the other cases. If \(r(n, i(n)) = a, r(n+1, i(n+1)) = c, k(i(n)) = b, \) and \(k(i(n+1)) = d\), then \(\text{Des}\{\ll\}\) must include \(\text{Inst}\{q_a, S_b, S_d, Lq_c\}\) as one of its terms, i.e.

\[
\text{Des}\{\ll\} \rightarrow \text{Inst}\{q_a, S_b, S_d, Lq_c\}.
\]

Hence \(A(\ll) \& F^{(n+1)} \rightarrow \text{Inst}\{q_a, S_b, S_d, Lq_c\} \& F^{(n+1)}\).

But \(\text{Inst}\{q_a, S_b, S_d, Lq_c\} \& F^{(n+1)} \rightarrow (CC_n \rightarrow CC_{n+1})\)

is provable, and so therefore is

\[
A(\ll) \& F^{(n+1)} \rightarrow (CC_n \rightarrow CC_{n+1})
\]
and

\[ (A(\lambda) \& F^{(n)} \rightarrow CC_n) \rightarrow (A(\lambda) \& F^{(n+1)} \rightarrow CC_{n+1}), \]

i.e.

\[ CF_n \rightarrow CF_{n+1}. \]

\(CF_n\) is provable for each \(n\). Now it is the assumption of this lemma that \(S_1\) appears somewhere, in some complete configuration, in the sequence of symbols printed by \(\cdot\lambda\); that is, for some integers \(N, K\), \(CC_N\) has \(R_{S_1}(u^{(N)}, u^{(K)})\) as one of its terms, and therefore \(CC_N \rightarrow R_{S_1}(u^{(N)}, u^{(K)})\) is provable. We have then

\[ CC_N \rightarrow R_{S_1}(u^{(N)}, u^{(K)}), \]

and

\[ A(\lambda) \& F^{(N)} \rightarrow CC. \]

We also have

\[ (\exists u) A(\cdot), (\exists u')(\exists u')... (\exists u^{(N)})\{ A(\lambda) \& F^{(N)}\}, \]

where \(N' = \max(N, K)\). And so

\[ (\exists u) A(\cdot) \rightarrow (\exists u)(\exists u')... (\exists u^{(N')}) R_{S_1}(u^{(N)}, u^{(K)}), \]

\[ (\exists u) A(\cdot) \rightarrow (\exists u^{(N)}) (\exists u^{(K)}) R_{S_1}(u^{(N)}, u^{(K)}), \]

\[ (\exists u) A(\cdot) \rightarrow (\exists s)(\exists t) R_{S_1}(s, t), \]

i.e. \(Un(\cdot\lambda)\) is provable.

This completes the proof of Lemma 1.

**Lemma 2.** If \(Un(\cdot\lambda)\) is provable, then \(S_1\) appears on the tape in some complete configuration of \(\cdot\lambda\).

If we substitute any propositional functions for function variables in a provable formula, we obtain a true proposition. In particular, if we substitute the meanings tabulated on pp. 259-260 in \(Un(\cdot\lambda)\), we obtain a true proposition with the meaning “\(S_1\) appears somewhere on the tape in some complete configuration of \(\cdot\lambda\)”.

We are now in a position to show that the Entscheidungsproblem cannot be solved. Let us suppose the contrary. Then there is a general (mechanical) process for determining whether \(Un(\cdot\lambda)\) is provable. By Lemmas 1 and 2, this implies that there is a process for determining whether \(\cdot\lambda\) over prints 0, and this is impossible, by §8. Hence the Entscheidungsproblem cannot be solved.

In view of the large number of particular cases of solutions of the Entscheidungsproblem for formulae with restricted systems of quantors, it is interesting to express \(Un(\cdot\lambda)\) in a form in which all quantors are at the beginning. \(Un(\cdot\lambda)\) is, in fact, expressible in the form

\[ (u) (\exists x)(\exists u_1)... (\exists u_n) B, \]

where \(B\) contains no quantors, and \(n = 6\). By unimportant modifications we can obtain a formula, with all essential properties of \(Un(\cdot\lambda)\), which is of form (I) with \(n = 5\).

**Added 28 August, 1936.**

**Appendix.**

Computation and effective calculability

The theorem that all effectively calculable (\(\lambda\)-definable) sequences and its converse are proved below in outline. It is assumed that the terms “well-formed formula” (W.F.F.) and “conversion” as used by Church and Kleene are understood. In the second of these proofs the existence of several formulae is assumed without proof; these formulae may be constructed straightforwardly with the help of, e.g., the results of Kleene in “A theory of positive integers in formal logic”, *American Journal of Math.*, 57 (1935), 153-173, 219-244.

The W.F.F. representing an integer \(n\) will be denoted by \(N_n\). We shall say that a sequence \(\gamma\) whose \(n\)-th figure is \(\phi(n)\) is \(\lambda\)-definable or effectively calculable if \(1 + \phi(n)\) is a \(\lambda\)-definable function of \(n\), i.e., if there is a W.F.F. \(M_\gamma\) such that, for all integers \(n\),

\[ \{M_\gamma\} (N_n)_{\text{conv}} N_{\phi(n)+1}. \]

i.e. \(\{M_\gamma\} (N_n)\) is convertible into \(\lambda x\cdot y\cdot x(y)\) or into \(\lambda x\cdot y\cdot x(y)\) according as the \(n\)-th figure of \(\lambda\) is 1 or 0.

To show that every \(\lambda\)-definable sequence \(\gamma\) is computable, we have to show how to construct a machine to compute \(\gamma\). For use with machines it is convenient to make a trivial modification in the calculus of conversion. This alteration consists in using \(x, x', x''\), ... as variables instead of \(\alpha, \beta, \gamma, \ldots\). We now construct a machine \(\mathcal{L}\) which, when supplied with the formula \(M_\gamma\), writes down the sequence \(\gamma\). The construction of \(\mathcal{L}\) is somewhat similar to that of the machine \(\mathcal{K}\) which proves all provable formulae of the functional calculus. We first construct a choice machine \(\mathcal{K}_1\), which, if supplied with a W.F.F., \(M\) say, and suitably manipulated, obtains any formula into which \(M\) is convertible. \(\mathcal{K}_1\) can then be modified so as to yield an automatic machine \(\mathcal{K}_2\) which obtains successively all the formulae
into which $M$ is convertible (cf. foot-note p. 252). The machine $L$ includes $L_2$ as a part. The motion of the machine $L$ when supplied with the formula $M_\gamma$ is divided into sections of which the $n$-th is devoted to finding the $n$-th figure of $\gamma$. The first stage in this $n$-th section is the formation of $\{N_{\gamma}\}(N_n)$. This formula is then supplied to the machine $L_2$, which converts it successively into various other formulae. Each formula into which it is convertible eventually appears, and each, as it is found, is compared with

$$\lambda x' \left[ \lambda x \{ (x')(x) \} \right], \text{ i.e. } N_2,$$

and with

$$\lambda x \left[ \lambda x \{ (x')(x) \} \right], \text{ i.e. } N_1.$$

If it is identical with the first of these, then the machine prints the figure 1 and the $n$-th section is finished. If it is identical with the second, then 0 is printed and the section is finished. If it is different from both, then the work of $L_2$ is resumed. By hypothesis, $\{M_\gamma\}(N_n)$ is convertible into one of the formulae $N_2$ or $N_1$; consequently the $n$-th section will eventually be finished, i.e. the $n$-th figure of $\gamma$ will eventually be written down.

To prove that every computable sequence $\gamma$ is $\lambda$-definable, we must show how to find a formula $M_\gamma$ such that, for all integers $n$,$$
\{M_\gamma\}(N_n) \text{ conv } N_1 \text{ if, in going from the } n \text{-th to the } (n+1) \text{-th complete configuration, the figure } 0 \text{ is printed.}
$$
$$\{M_\gamma\}(N_{(n+1)} \text{ conv } N_2 \text{ if the figure } 1 \text{ is printed.}
$$
$$\text{conv } N_3 \text{ otherwise.}
$$

Let $W_\gamma$ stand for

$$\lambda u \left[ \{V\} \{ \{A_\gamma\}(u) \} \right] \left( \{U_\gamma\}(u) \right),$$

so that, for each integer $n$,$$
\{V\}(N_{(n+1)} \text{ conv } W_\gamma \text{ conv } N_n,$$

and let $Q$ be a formula such that

$$\{Q\}(W_\gamma) \text{ conv } N_{r(q)},$$

where $r(q)$ is the $q$-th integer $q$ for which $\{W_\gamma\}(N_q)$ is convertible into either $N_1$ or $N_2$. Then, if $M_\gamma$ stands for

$$\lambda u \left[ \{W_\gamma\} \{ \{Q\}(W_\gamma) \} \right],$$

it will have the required property.$\dagger$

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Princeton University,
New Jersey, U.S.A.

$\dagger$ In a complete proof of the $\lambda$-definability of computable sequences it would be best to modify this method by replacing the numerical description of the complete configurations by a description which can be handled more easily with our apparatus. Let us choose certain integers to represent the symbols and the $m$-configurations of the machine. Suppose that in a certain complete configuration the numbers representing the successive symbols on the tape are $s_1, s_2, \ldots, s_m$, that the $m$-th symbol is scanned, and that the $m$-configuration has the number $i$; then we may represent this complete configuration by the formula

$$[N_n, N_m, \ldots, N_{m-1}], [N_1, N_m, [N_{m+1}, \ldots, N_n]],$$

where

$$[a, b] \text{ stands for } \lambda u \left[ \{ (u)(a)(b) \} \right],$$

$$[a, b, c] \text{ stands for } \lambda u \left[ \{ (u)(a)(b) \} \right] \left( (c) \right],$$

etc.
Turing’s insight: simple local actions can lead to arbitrarily complex computations!
Lego Turing Machines

See: http://www.youtube.com/watch?v=cYw2ewoO6c4
Lego Turing Machines
“Mechano” Computers

Babbage’s difference engine
Tinker Toy Computers

Plays tic-tac-toe!
Tinker Toy Computers

The Tinkertoy computer: ready for a game of tic-tac-toe
Mechanical Computers

De Morgan’s law!

The Pattern on the Stone

W. Daniel Hillis

The Simple Ideas That Make Computers Work

Science Masters
Hydraulic Computers

Voltage source or inductor

Diode

Resistor

Transistor

Simple circuit
Hydraulic Computers

Theorem: fluid-based “circuits” are Turing-complete / universal!
Alan Turing conceived of the modern computer in 1935. Today all digital computers are, in essence, "Turing machines." The British mathematician also pioneered the field of artificial intelligence, or AI, proposing the famous and widely debated Turing test as a way of determining whether a suitably programmed computer can think. During World War II, Turing was instrumental in breaking the German Enigma code in part of a top-secret British operation that historians say shortened the war in Europe by two years. When he died at the age of 41, Turing was doing the earliest work on what would now be called artificial life, simulating the chemistry of biological growth.

Throughout his remarkable career, Turing had no great interest in publicizing his ideas. Consequently, important aspects of his work have been neglected or forgotten over the years. In particular, few people—even those knowledgeable about computer science—are familiar with Turing's fascinating anticipation of connectionism, or neuron-like computing. Also neglected are his groundbreaking theoretical concepts in the exciting area of "hypercomputation." According to some experts, hypercomputers might one day solve problems heretofore deemed intractable.

The Turing Connection

Digital computers are superb number crunchers. Ask them to predict a rocket's trajectory or calculate the financial figures for a large multinational corporation, and they can churn out the answers in seconds. But seemingly simple actions that people routinely perform, such as recognizing a face or reading handwriting, have been devilishly tricky to program. Perhaps the networks of neurons that make up the brain have a natural facility for such tasks that standard computers lack. Scientists have thus been investigating computers modeled more closely on the human brain.

Connectionism is the emerging science of computing with networks of artificial neurons. Currently researchers usually simulate the neurons and their interconnections within an ordinary digital computer (just as engineers create virtual models of aircraft wings and skyscrapers). A training algorithm that runs on the computer adjusts the connections between the neurons, honing the network into a special-purpose machine dedicated to some particular function, such as forecasting international currency markets.

Modern connectionists look back to Frank Rosenblatt, who published the first of many papers on the topic in 1957, as the founder of their approach. Few realize that Turing had already investigated connectionist networks as early as 1948, in a little-known paper entitled "Intelligent Machinery."

Written while Turing was working for the National Physical Laboratory in London, the manuscript did not meet with his employer's approval. Sir Charles Darwin, the father and headmasterly director of the laboratory and grandchild of the great English naturalist, dismissed it as a "schoolboy essay." In reality, this foresighted paper was the first manifesto of the field of artificial intelli-
in such a way that it becomes a general-purpose computer. This discovery illuminates one of the most fundamental problems of concern to computer designers.

From a top-down perspective, cognition involves complex, sequential processes, often involving the dynamic and changing forms of symbols. As such, understanding the intelligence of machines is a complex task. Cognitive scientists face the problem of how to reconcile these very different perspectives.

The idea of a machine that could do this is known as the "universal Turing machine." It consists of a limitless memory that stores both program and data and a scanner that moves back and forth through the memory, symbol by symbol, reading the information and writing additional symbols. Each of the machine's basic actions is very simple—such as "identify the symbol on which the scanner is positioned," "write '1'" and "move one position to the left." Complexity is achieved by chaining together larger numbers of these basic actions. Despite its simplicity, a universal Turing machine can execute any task that can be done by the most powerful of today's computers. In fact, all modern digital computers are in essence universal Turing machines [see "Turing Machines," by John E. Hopcroft; SCIENTIFIC AMERICAN, May 1984].

Turing's aim in 1935 was to devise a machine—one as simple as possible—capable of any calculation that a human mathematician working in accordance with some algorithmic method could perform, given unlimited time, energy, paper and pencils, and perfect concentration. Calling a machine "universal" merely signifies that it is capable of all such calculations. As Turing himself wrote, "Electronic computers are intended to carry out any definite rule-of-thumb process which could have been done by hand through the memory, symbol by symbol, receiving the information and giving out additional symbols." The answer is that these "hypermachines" can be described on paper, but no one as yet knows whether it will be possible to build one. The field of hypercomputation is currently attracting a growing number of scientists. Some speculate that the human brain itself—the most complex information processor known—is actually a naturally occurring example of a hypercomputer.

Before the recent surge of interest in hypercomputation, any information-processing job that was known to be too difficult for universal Turing machines was written off as "uncomputable." In this sense, a hypermachine computes the uncomputable.

Examples of such tasks can be found in even the most straightforward areas of mathematics. For instance, given arithmetical statements picked at random, a universal Turing machine may not always be able to tell which are theorems (such as "7 + 5 = 12") and which are nontheorems (such as "every number is the sum of two even numbers."). Another type of uncomputable problem comes from geometry. A set of tiles—variously sized squares with different colored edges—"tiles the plane" if the Euclidean plane can be covered by copies of the tile with no gaps or overlaps and with adjacent edges always the same color. Logicians William Hand and Duke Myers of the University of Hawaii have discovered a tile set that tiles the plane only in patterns too complicated for a universal Turing machine to calculate. In the field of computer science, a universal Turing machine cannot always predict whether a given program will terminate or continue running forever. This is sometimes expressed by saying that no general-purpose programming language (Pascal, BASIC, Prolog, C, and so on) can have a foolproof crash detector; a tool that detects all bugs that could lead to crashes, including errors that result in infinite processing loops. Turing himself was the first to investigate the idea of machines that can perform mathematical tasks too difficult for human beings to perform.
Alan Turing proved that his universal machine—and by extension, even today’s most powerful computers—could never solve certain problems. For instance, a universal Turing machine cannot always determine whether a given software program will terminate or continue running forever. In some cases, the best the universal machine can do is execute the program and wait—maybe eternally—for it to finish. But in his doctoral thesis (below), Turing did imagine that a machine equipped with a special “oracle” could perform this and other “uncomputable” tasks. Here is one example of how, in principle, an oracle might work.

Consider a hypothetical machine for solving the formidable "terminating program" problem above. A computer program can be represented as a finite string of 1s and 0s. This sequence of digits can also be thought of as the binary representation of an integer, just as 101011 is the equivalent of 91. The oracle's job can then be restated as: “Given an integer that represents a program for any computer that can be simulated by a universal Turing machine, output a ‘1’ if the program will terminate or a ‘0’ otherwise.”

The oracle consists of a perfect measuring device and a store, or memory, that contains a precise value—call it t—for Turing—of some physical quantity. (The memory might, for example, resemble a capacitor storing an exact amount of electricity.) The value of t is an irrational number; its written representation would be an infinite string of binary digits, such as 0.000000011011...

The crucial property of t is that its individual digits happen to represent accurately which programs terminate and which do not. So, for instance, if the integer representing a program were 8,735,499, then the oracle could by measurement obtain the 8,735,499th digit of t (counting from left to right after the decimal point). If that digit were 0, the oracle would conclude that the program will forever.

Obviously, without the t oracle would be useless, and finding some physical variable in nature that takes this exact value might very well be impossible. So the search is for some practicable way of implementing an oracle. If such a means were found, for example, the field of computer science could be enormous.

Richard J. Fateman

Even among experts, Turing’s pioneering theoretical concept of a hypermachine has largely been forgotten.
Theorem [Turing]: the set of algorithms is countable.

Proof: Sort algorithms by length:

Dovetailing!
Theorem [Turing]: the set of functions is not countable.

Theorem: Boolean functions \( \{ f | f: \mathbb{N} \rightarrow \{0,1\} \} \) are uncountable.

Proof: Assume Boolean functions were countable; i.e., \( \exists \) table containing all of \( f_i \)'s and their corresponding values:

<table>
<thead>
<tr>
<th>( f_i )</th>
<th>( f_i(1) )</th>
<th>( f_i(2) )</th>
<th>( f_i(3) )</th>
<th>( f_i(4) )</th>
<th>( f_i(5) )</th>
<th>( f_i(6) )</th>
<th>( f_i(7) )</th>
<th>( f_i(8) )</th>
<th>( f_i(9) )</th>
</tr>
</thead>
<tbody>
<tr>
<td>( f_1 )</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
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<tr>
<td>( f_2 )</td>
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<tr>
<td>( f_3 )</td>
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<tr>
<td>( f_4 )</td>
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<tr>
<td>( f_5 )</td>
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</tbody>
</table>

\( f'(i) = 1 \ 0 \ 1 \ 0 \ 0 \ 0 \ ... \) \( f': \mathbb{N} \rightarrow \{0,1\} \)

But \( f' \) is missing from our table! \( f' \neq f_k \ \forall \ k \in \mathbb{N} \)

\( \Rightarrow \) table is not a 1-1 correspondence between \( \mathbb{N} \) and \( f_i \)'s

\( \Rightarrow \) contradiction \( \Rightarrow \) \( \{ f | f: \mathbb{N} \rightarrow \{0,1\} \} \) is not countable!

\( \Rightarrow \) There are more Boolean functions than natural numbers!
Theorem: the set of algorithms is countable.

Theorem: the set of functions is uncountable.

Theorem: the Boolean functions are uncountable.

<table>
<thead>
<tr>
<th>$f_i$</th>
<th>$f_i(1)$</th>
<th>$f_i(2)$</th>
<th>$f_i(3)$</th>
<th>$f_i(4)$</th>
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<th>$f_i(7)$</th>
<th>$f_i(8)$</th>
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<tr>
<td>$f_1$</td>
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</tbody>
</table>

$f'(i) = 1, 0, 1, 0, 0, \ldots$ $f': \mathbb{N} \rightarrow \{0, 1\}$

Corollary: there are “more” functions than algorithms / programs.

Corollary: some functions are not computable by any algorithm!

Corollary: most functions are not computable by any algorithm!

Corollary: there are “more” Boolean functions than algorithms.

Corollary: some Boolean functions on $\mathbb{N}$ are not computable.

Corollary: most Boolean functions on $\mathbb{N}$ are not computable.
**Theorem:** most Boolean functions on $\mathbb{N}$ are not computable.

Q: Can we find a concrete example of an uncomputable function?

A [Turing]: Yes, for example, the **Halting** Problem.

**Definition:** The Halting problem: given a program $P$ and input $I$, will $P$ halt if we ran it on $I$?

Define $H: \mathbb{N} \times \mathbb{N} \to \{0, 1\}$

$\begin{align*}
H(P, I) &= 1 \text{ if TM } P \text{ halts on input } I \\
H(P, I) &= 0 \text{ otherwise}
\end{align*}$

**Notes:**

- $P$ and $I$ can be encoded as integers, in some canonical order.
- $H$ is an everywhere-defined Boolean function on natural pairs.
- Alternatively, both $P$ and $I$ can be encoded as strings in $\Sigma^*$.
- We can modify $H$ to take only a single input: $H'(2^P3^I)$ or $H'(P$|$I)$

**Why $2^P3^I$?**

Gödel numbering / encoding

What else will work?
Theorem [Turing]: the halting problem (H) is not computable.

Corollary: we can not algorithmically detect all infinite loops.

Q: Why not? E.g., do the following programs halt?

main()
{ int k=3; }

Halts!

main()
{ while(1) {} }

Runs forever!

main()
{ Find a Fermat triple $a^n+b^n=c^n$ with $n>2$ & stop}

Runs forever!
Open from 1637-1995!

main()
{ Find a Goldbach integer that is not a sum of two primes & stop}

? Still open since 1742!

Theorem: solving the halting problem is at least as hard as solving arbitrary open mathematical problems!
Theorem [Turing]: the halting problem (H) is not computable.

Ex: the “3X+1” problem (the Ulam conjecture):
- Start with any integer \( X > 0 \)
- If \( X \) is even, then replace it with \( X/2 \)
- If \( X \) is odd then replace it with \( 3X+1 \)
- Repeat until \( X = 1 \) (i.e., short cycle 4, 2, 1, ...)

Ex: 26 terminates after 10 steps
27 terminates after 111 steps
Termination verified for \( X < 10^{18} \)

Q: Does this terminate for every \( X > 0 \) ?
A: Open since 1937!

“Mathematics is not yet ready for such confusing, troubling, and hard problems.” - Paul Erdős, who offered a $500 bounty for a solution to this problem

Observation: termination is in general difficult to detect!
Theorem [Turing]: the halting problem (H) is not computable.

Proof: Assume ∃ algorithm S that solves the halting problem H, that always stops with the correct answer for any P & I.

Using S, construct algorithm / TM T:

T(T) halts ⇒ T(T) does not halt
T(T) does not halt ⇒ T(T) halts

⇒ S cannot exist! (at least as an algorithm / program / TM)
Q: When do we want to feed a program to itself in practice?
A: When we build compilers.

Q: Why?
A: To make them more efficient!
   To boot-strap the coding in the compiler’s own language!
Theorem: Virus detection is not computable.

Theorem: Infinite loop detection is not computable.
One of My Favorite Turing Machines

“Kindle DX” wireless reading device

- 1/3 of an inch thin, 4GB memory
- holds 3,500 books / documents
- 532 MHz ARM-11 processor
- 9.7” e-ink auto-rotate 824x1200 display
- Full PDF and text-to-speech
- 3G wireless, < 1 min / book
- 18.0 oz, battery life 4 days
Generalized Numbers

- Naturals $\mathbb{N}$
- Integers $\mathbb{Z}$
- Rationals $\mathbb{Q}$
- Reals $\mathbb{R}$
- Quaternions $\mathbb{H}$
- Complex $\mathbb{C}$
- Hypernumbers
- Surcomplex $\mathbb{A} + Bi$
- SURREAL $\{L|R\}$
- Computable numbers
- Boolean $\mathbb{B}$
- Computable numbers
- Finitely describable numbers
- Surcomplex $\mathbb{A} + Bi$
- SURREAL $\{L|R\}$
- Computable numbers
- Boolean $\mathbb{B}$

Theorem: some real numbers are not finitely describable!
Theorem: some finitely describable real numbers are not computable!
**Theorem:** Some real numbers are not finitely describable.

**Proof:** The number of finite descriptions is countable. The number of real numbers is not countable. \[ \Rightarrow \text{Most real numbers do not have finite descriptions.} \]

**Theorem:** Some finitely describable reals are not computable.

**Proof:** Let \( h = 0.H_1H_2H_3H_4 \ldots \) where \( H_i = 1 \) if \( i = 2^p3^I \) for some integers \( P \& I \), and TM \( P \) halts on input \( I \), and \( H_i = 0 \) otherwise. Clearly \( 0 < h < 1 \) is a real number and is finitely describable. If \( h \) was computable, then we could exploit an algorithm that computes it into solving the halting problem, a contradiction. \[ \Rightarrow h \text{ is not computable.} \]
Theorem: all computable numbers are finitely describable.
Proof: A computable number can be outputted by a TM. A TM is a (unique) finite description.

What the unsolvability of the Halting Problem means:

There is no single algorithm / program / TM that correctly solves all instances of the halting problem in finite time each.

This result does not necessarily apply if we allow:

• Incorrectness on some instances
• Infinitely large algorithm / program
• Infinite number of finite algorithms / programs
• Some instances to not be solved
• Infinite “running time” / steps
• Powerful enough oracles
Oracles

- Originated in Turing’s Ph.D. thesis
- Named after the “Oracle of Apollo” at Delphi, ancient Greece
- Black-box subroutine / language
- Can compute arbitrary functions
- Instant computations “for free”
- Can greatly increase computation power of basic TMs

E.g., oracle for halting problem
The “Oracle of Omaha”
The “Oracle” of the Matrix
Turing Machines with Oracles

- A special case of “hyper-computation”
- Allows “what if” analysis: assumes certain undecidable languages can be recognized
- An oracle can profoundly impact the decidability & tractability of a language
- Any language / problem can be “relativized” WRT an arbitrary oracle
- Undecidability / intractability exists even for oracle machines!

Theorem [Turing]: Some problems are still not computable, even by Turing machines with an oracle for the halting problem!
Theorem [Turing]: the halting problem \( H^* \) is not computable.

Proof: Assume \( \exists \) algorithm \( S^* \) that solves the halting problem \( H^* \), that always stops with the correct answer for any \( P^* \& I \).

Using \( S^* \), construct algorithm / TM \( T^* \):

\[ T^*(T^*) \text{ halts} \Rightarrow T^*(T^*) \text{ does not halt} \]
\[ T^*(T^*) \text{ does not halt} \Rightarrow T^*(T^*) \text{ halts} \]
\[ \{ Q \Longleftrightarrow \neg Q \Rightarrow \text{Contradiction!} \} \]

Add to \( P \) an H-oracle:

\( P^* \) is “relativized” \( P \).
\( S^* \) is “relativized” \( S \).
\( T^* \) is “relativized” \( T \).

The halting problem for TMs with an H-oracle is not computable by TM’s with an H-oracle!
Turing Degrees

- Turing (1937); studied by Post (1944) and Kleene (1954)
- Quantifies the non-computability (i.e., algorithmic unsolvability) of (decision) problems and languages
- Some problems are “more unsolvable” than others!

Turing degree 2

Turing degree 1

Turing degree 0

• Defines computation “relative” to an oracle.
• “Relativized computation” - an infinite hierarchy!
• A “relativity theory of computation”!

Diagonalization

Students of Alonzo Church:

- Georg Cantor 1845-1918
- Emil Post 1897-1954
- Stephen Kleene 1909-1994
- Alan Turing 1912-1954
Turing Degrees

- Turing degree of a set $X$ is the set of all Turing-equivalent (i.e., mutually-reducible) sets: an equivalence class $[X]$.
- Turing degrees form a partial order / join-semilattice.
- $[0]$: the unique Turing degree containing all computable sets.
- For set $X$, the “Turing jump” operator $X'$ is the set of indices of oracle TMs which halt when using $X$ as an oracle.
- $[0']$: Turing degree of the halting problem $H$; $[0'']$: Turing degree of the halting problem $H^*$ for TMs with oracle $H$. 

Students of Alonzo Church:

- Alan Turing (1912-1954)
- Emil Post (1897-1954)
- Stephen Kleene (1909-1994)
Turing Degrees

• Each Turing degree is countably infinite (has exactly $\aleph_0$ sets)
• There are uncountably many ($2^{\aleph_0}$) Turing degrees
• A Turing degree $X$ is strictly smaller than its Turing jump $X'$
• For a Turing degree $X$, the set of degrees smaller than $X$ is countable; set of degrees larger than $X$ is uncountable ($2^{\aleph_0}$)
• For every Turing degree $X$ there is an incomparable degree (i.e., neither $X \geq Y$ nor $Y \geq X$ holds).
• There are $2^{\aleph_0}$ pairwise incomparable Turing degrees
• For every degree $X$, there is a degree $D$ strictly between $X$ and $X'$ so that $X < D < X'$ (there are actually $\aleph_0$ of them)

The structure of the Turing degrees semilattice is extremely complex!
"The beauty of this is that it is only of theoretical importance, and there is no way it can be of any practical use whatsoever."
The Extended Chomsky Hierarchy

2^{\Sigma^*}

Not finitely describable

\overline{H}

\overline{H^-}

Turing degrees

Recognizable

Not Recognizable

Decidable

Presburger arithmetic

EXPSPACE

EXPTIME

PSPACE

Context sensitive

LBA

NP

P

\{a^n b^n c^n\}

Context-free

\{ww^R\}

Det. CF

\{a^n b^n\}

Regular

\{a^*\}

Finite

\{a,b\}

Finite

Go

PSPACE-complete

QBF

EXPTIME-complete

Go

EXPSPACE-complete

Going from left to right, the classes are

Not finitely describable

Recognizable

Decidable

Presburger arithmetic

EXPSPACE

EXPTIME

PSPACE

Context sensitive

LBA

NP

P

Finite

\{a,b\}

Finite

Go

PSPACE-complete

QBF

EXPTIME-complete

Go

EXPSPACE-complete

\{a^n b^n c^n\}

\{ww^R\}

\{a^n b^n\}

\{a^*\}
The Limits of Reason

In 1956 Scientific American published an article by Ernest Nagel and James R. Newman entitled “Gödel’s Proof.” Two years later the writers published a book with the same title—a wonderful work that is still in print. I was a child, not even a teenager, and I was obsessed by this little book. I remember the thrill of discovering it in the New York Public Library. I used to carry it around with me and try to explain it to other children.

It fascinated me because Kurt Gödel used mathematics to show that mathematics itself has limitations. Gödel refuted the position of David Hilbert, who about a century ago declared that there was a theory of everything for math, a finite set of principles from which one could mindlessly deduce all mathematical truths by rigidly following the rules of symbolic logic. But Gödel demonstrated that mathematics contains true statements that cannot be proved that way. His result is based on two self-referential paradoxes: “This statement is false” and “This statement is unprovable.” (For more on Gödel’s incompleteness theorem, see www.sciam.com/ontheweb)

My attempt to understand Gödel’s proof took over my life, and now half a century later I have published a little book of my own. In some respects, it is my own version of Nagel and Newman’s book, but it does not focus on Gödel’s proof. The only things the two books have in common are their small size and their goal of critiquing mathematical methods.

Unlike Gödel’s approach, mine is based on measuring information and showing that some mathematical facts cannot be compressed into a theory because they are too complicated. This new approach suggests that what Gödel
overview irreducible complexity

kurt godel demonstrated that mathematics is necessarily incomplete, containing true statements that cannot be formally proved. a remarkable number known as omega reveals even greater incompleteness by providing an infinite number of theorems that cannot be proved by any finite system of axioms. a "theory of everything" for mathematics is therefore impossible.

omega is perfectly well defined [see box on opposite page] and has a definite value, yet it cannot be computed by any finite computer program.

omega's properties suggest that mathematicians should be more willing to postulate new axioms, similar to the way that physicists must evaluate experimental results and assert basic laws that cannot be proved logically.

the results related to omega are grounded in the concept of algorithmic information. gottfried w. leibniz anticipated many of the features of algorithmic information theory more than 300 years ago.

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son, a discovery that flies in the face of the principle of sufficient reason.

Indeed, as I will show later, it turns out that an infinite number of mathematical facts are irreducible, which means no theorem whatever they are true. These facts are not just computationally irreducible, they are logically irreducible. The only way to "prove" such facts is to assume them directly as new axioms, without using reasoning at all.

The concept of an "axiom" is closely related to the idea of logical irreducibility. Axioms are mathematical facts that we take as self-evident and do not try to prove from simpler principles. All formal mathematical theories start with axioms and then deduce the consequences of these axioms, which are called theorems. That is how Euclid did things in Alexandria two millennia ago, and his treatise on geometry is the classical model for formal mathematical exposition.

In ancient Greece, if you wanted to convince your fellow citizens to vote with you on some issue, you had to reason with them—which I guess is how the Greeks came up with the idea that in mathematics you have to prove things rather than just discover them experimentally. In contrast, previous cultures in Mesopotamia and Egypt apparently relied on experiment. Using reason has certainly been an extremely fruitful approach, leading to modern mathematics and mathematical physics and all that goes with them, including the technology for building that highly logical and mathematical machine, the computer.

So am I saying that this approach that science and mathematics has been following for more than two millennia crashes and burns? Yes, in a sense I am. My counterpart illustrating the limited power of logic and reason, my source of an infinite stream of unprovable mathematical facts, is the number that I call omega.

The Number Omega

The first step on the road to omega came in a famous paper published precisely 2,500 years after Leibniz's essay. In a 1936 issue of the Proceedings of the London Mathematical Society, Alan M. Turing began the computer age by presenting a mathematical model of a simple, general-purpose, programmable digital computer. He then asked, Can we determine whether or not a computer program will ever halt? This is Turing's famous halting problem.

Of course, by running a program you can eventually discover that it halts, if it halts. The problem, and it is an extremely fundamental one, is to decide when to give up on a program that does not halt. A great many special cases can be solved, but Turing showed that a general solution is impossible. No algorithm, no mathematical theory, can ever tell us which programs will halt and which will not. (For a modern proof of Turing's thesis, see www.sciam.com/ontheweb.)

For the way I say "program," in modern terms I mean the concatenation of the computer program and the data to be read in by the program.

The next step on the path to the number omega is to consider the ensemble of all possible programs. Does a program chosen at random ever halt? The probability of having that happen is my omega number. First, I must specify how to pick a program at random. A program is simply a series of bits, so flip a coin to determine the value of each bit. How many bits long should the program be? Keep flipping the coin so long as the computer is asking for another bit of input. Omega is just the probability that the machine will eventually come to a halt when supplied with a stream of random bits in this fashion. (The precise numerical value of omega depends on the choice of computer programming language, but omega's surprising properties are not affected by this choice.)

And once you have chosen a language, omega has a definite value, just like pi or the number 3.)

Being a probability, omega has to be greater than 0 and less than 1, because some programs halt and some do not. Imagine writing omega out in binary. You would get something like 0.110100.... These bits after the decimal point form an irreducible stream of bits. They are our irreducible mathematical facts (each fact being whether the bit is a 0 or a 1).

Omega can be defined as an infinite sum, and each N-bit program that halts contributes precisely $2^{-N}$ to the sum (see box on preceding page). In other words, each N-bit program that halts adds a 1 to the Nth bit in the binary expansion of omega. Add up all the bits for all programs that halt, and you will get the precise value of omega. This description may make it sound like you can calculate omega accurately, just as if it were the square root of 2 or the number pi.

But—omega is perfectly well defined and it is a specific number, but it is impossible to compute in its entirety.

We can be sure that omega cannot be computed because knowing omega would let us solve Turing's halting problem, but we know that this problem is unsolvable. More specifically, knowing the first N bits of omega would enable you to decide whether or not each program up to N bits in size ever halts [see box on page 80]. From this it follows that you need at least an N-bit program to calculate N bits of omega.

Note that I am not saying that it is impossible to compute some digits of omega. For example, if we knew that computer programs 0, 10, and 110 all halt, then we would know that the first digit of omega was 0.111. The point is that the first N digits of omega cannot be computed using a program significantly shorter than N bits long.

Most important, omega supplies us with an infinite number of these irreducible bits. Given any finite program, no matter how many billions of bits long, we have an infinite number of bits that the program cannot compute. Given any finite set of axioms, we have an infinite number of truths that are unprovable in that system.

Because omega is irreducible, we can immediately conclude that a theory of everything for all of mathematics cannot exist. An infinite number of bits of omega constitute mathematical facts (whether each bit is a 0 or a 1) that cannot be derived from any principles simpler than the string of bits itself. Mathematics therefore has infinite complexity, whereas any individual theory of everything would have only finite complexity and could not capture all the richness of the full world of mathematical truth.

This conclusion does not mean that proofs are no good, and I am certainly not against reason. Just because some things are irreducible does not mean we should give up using reasoning. Irreducible principles—axioms—have always been a part of mathematics. Omega just shows that a lot more of them are out there than people suspected.

So perhaps mathematicians should not try to prove everything. Sometimes they should just add new axioms. That is what you have got to do if you are faced with irreducible facts. The problem is realizing that they are irreducible! In a way, saying something is irreducible is giving up, saying that it cannot ever be proved. Mathematicians would rather die than do that, in sharp contrast with their physicist colleagues, who are happy to be pragmatic and to use plausible reasoning instead of rigorous proof. Physicists are willing to add new principles, new scientific laws, to understand new domains of experience.

This raises what I think is an extremely interesting question: Is mathematics like physics?

Mathematics and Physics

The traditional view is that mathematics and physics are quite different. Physics describes the universe and depends on experiment and observation. The particular laws that govern our universe—whether Newton's laws of motion or the Standard Model of particle physics—must be determined empirically and then asserted like axioms that cannot be logically proved, merely verified. Mathematics, in contrast, is somehow independent of the universe. Results and theorems, such as the properties of the integers and real numbers, do not depend in any way on the particular nature of reality in which we find ourselves. Mathematical truths would be true in any universe.
Yet both fields are similar. In physics, and indeed in science generally, scientists compress their experimental observations into scientific laws. They then show how their observations can be deduced from these laws. In mathematics, too, something like this happens—mathematicians compress their computational experiments into mathematical axioms, and then they show how to deduce theorems from these axioms.

If Hilbert had been right, mathematics would be a closed system, without room for new ideas. There would be a static, closed theory of everything for all of mathematics, and this would be like a dictatorship. In fact, for mathematicians to progress you actually need new ideas and plenty of room for creativity. It does not suffice to grind away, mechanically deducing all the possible consequences of a fixed number of basic principles. I much prefer an open system. I do not like rigid, authoritarian ways of thinking.

Another person who thought mathematics is like physics was Imre Lakatos, who left Hungary in 1956 and later worked on philosophy of science in England. There Lakatos came up with a great word, “quasi-empirical,” which means that even though there are no true experiments that can be carried out in mathematics, something similar can take place. For example, the Goldbach conjecture states that even number greater than 2 can be expressed as the sum of two prime numbers. This conjecture arrived at experimentally, by noting empirically that it was true for every even number that anyone cared to examine. The conjecture has not yet been proven, but it has been verified up to $10^{14}$.

I think that mathematics is quasi-empirical. In other words, I feel that mathematicians are different from physicists (which is truly empirical) but perhaps not as different as most people think.

I have lived in the worlds of both mathematics and physics, and I never thought there was such a big difference between these two fields. It is a matter of degree, of emphasis, not an absolute difference. After all, mathematics and physics coevolved. Mathematicians should not isolate themselves. They should not cut themselves off from rich sources of new ideas.

**New Mathematical Axioms**

The idea of choosing to add more axioms is not an alien one to mathematicians. A well-known example is the parallel postulate in Euclidean geometry: given a line and a point not on the line, there is exactly one line that can be drawn through the point that never intersects the original line. For centuries geometers wondered whether that result could be proved using the rest of Euclid’s axioms. It could not. Finally, mathematicians realized that they could substitute different axioms in place of the Euclidean version, thereby producing the non-Euclidean geometries of curved spaces, such as the surface of a sphere or of a saddle.

Other examples are the law of the excluded middle in logic and the axiom of choice in set theory. Most mathematicians are happy to use these axioms in their proofs, although others do not, exploring instead so-called intuitionist logic or constructivist mathematics. Mathematics is not a single monolithic structure of absolute truth.

Another very interesting axiom may be the “P is not equal to NP” conjecture. P and NP are names for classes of problems. An NP problem is one for which a proposed solution can be verified quickly. For example, if for the problem “find the factors of 8,633,” one can quickly verify the proposed solution “29 and 299” by multiplying these two numbers. (There is a technical definition of “quickly,” but those details are not important here.) A P problem is one that can be solved quickly even without being given the solution. The question is—can every NP problem be solved quickly? (Is there a quick way to find the factors of 8,633?) That is, is the class P the same as the class NP? This problem is one of the Clay Millennium Prize Problems for which a reward of $1 million is on offer.

Computer scientists widely believe that P is not equal to NP, but no proof is known. One could say that a lot of quasi-empirical evidence points to P not being equal to NP. Should P not equal to NP be adopted as an axiom, then? In effect, this is what the computer science community has done. Closely related to this issue is the security of certain cryptographic systems used throughout the world. The systems are believed to be vulnerable to being cracked, but no one can prove it.

**Experimental Mathematics**

At the same time, there is the relationship between mathematics and physics is experimental mathematics: the discovery of new mathematical results by looking at many examples using a computer. Whereas this approach is not as persuasive as a short proof, it can be more convincing than a long and extremely complicated proof, and for some purposes it is quite sufficient.

In the past, this approach was drenched with great vigor by both George Pólya and Lakatos, believers in heuristic reasoning and the quasi-empirical nature of mathematics. This methodology is also practiced and justified by Stephen Wolfram in *A New Kind of Science* (2002).

Extensive computer calculations can be extremely persuasive, but do they render proof unnecessary? Yes and no.

**More to Explore**


Short biographies of mathematicians can be found at www-history.mcs.st-andrews.ac.uk/BiogIndex.html.

Gregory Chaitin’s home page is www.rncs.aimie.edu/~chaitin/
Historical Perspectives

John von Neumann (1903-1957)

• Contributed to set theory, functional analysis, quantum mechanics, ergodic theory, economics, geometry, hydrodynamics, statistics, analysis, measure theory, ballistics, meteorology, …
• Invented game theory (used in Cold War)
• Re-axiomatized set theory
• Principal member of Manhattan Project
• Helped design the hydrogen / fusion bomb
• Pioneered modern computer science
• Originated the “stored program”
• “von Neumann architecture” and “bottleneck”
• Helped design & build the EDVAC computer
• Created field of cellular automata
• Investigated self-replication
• Invented merge sort
"Most mathematicians prove what they can; von Neumann proves what he wants."
von Neumann’s Legacy

- Re-axiomatized set theory to address Russell’s paradox
- Independently proved Godel’s second incompleteness theorem: axiomatic systems are unable to prove their own consistency.
- Developed the game-theory based Mutually-Assured Destruction (MAD) strategic equilibrium policy – still in effect today!
- von Neumann regular rings, von Neumann bicommutant theorem, von Neumann entropy, von Neumann programming languages

<table>
<thead>
<tr>
<th>Language</th>
<th>Architecture</th>
</tr>
</thead>
<tbody>
<tr>
<td>variables ⇔ storage</td>
<td></td>
</tr>
<tr>
<td>control ⇔ test-and-set</td>
<td></td>
</tr>
<tr>
<td>assignment ⇔ fetch/store</td>
<td></td>
</tr>
<tr>
<td>expressions ⇔ memory refs &amp; arithmetic</td>
<td></td>
</tr>
</tbody>
</table>
Surely there must be a less primitive way of making big changes in the store than by pushing vast numbers of words back and forth through the von Neumann bottleneck. Not only is this tube a literal bottleneck for the data traffic of a problem, but, more importantly, it is an intellectual bottleneck that has kept us tied to word-at-a-time thinking instead of encouraging us to think in terms of the larger conceptual units of the task at hand. Thus programming is basically planning and detailing the enormous traffic of words through the Von Neumann bottleneck, and much of that traffic concerns not significant data itself, but where to find it.

- John Backus, 1977 ACM Turing Award lecture
EDVAC (1945):

• 1024 words (44-bits) – 5.5KB
• 864 microsec / add (1157 / sec)
• 2900 microsec / multiply (345/sec)
• Magnetic tape (no disk), oscilloscope
• 6,000 vacuum tubes
• 56,000 Watts of power
• 17,300 lbs (7.9 tons), 490 sqft
• 30 people to operate
Self-Replication

- Biology / DNA
- Nanotechnology
- Computer viruses
- Space exploration
- Memetics / memes
- “Gray goo”

**Problem** (extra credit): write a program that prints out its own source code (no inputs of any kind are allowed).
"In mathematics you don't understand things. You just get used to them."

– John von Neumann
Apples beget apples, but can machines beget machines? Today it takes an elaborate manufacturing apparatus to build even a simple machine. Could we endow an artificial device with the ability to multiply on its own? Self-replication has long been considered one of the fundamental properties separating the living from the nonliving. Historically our limited understanding of how biological reproduction works has given it an aura of mystery and made it seem unlikely that it would ever be done by a man-made object. It is reported that when René Descartes averred to Queen Christina of Sweden that animals were just another form of mechanical automata, Her Majesty pointed to a clock and said, “See to it that it produces offspring.”

The problem of machine self-replication moved from philosophy into the realm of science and engineering in the late 1940s with the work of eminent mathematician and physicist John von Neumann. Some researchers have actually constructed physical replicators. Forty years ago, for example, geneticist Lionel Penrose and his son, Roger (the famous physicist), built small assemblies of plywood that exhibited a simple form of self-replication [see “Self-Reproducing Machines,” by Lionel Penrose; SCIENTIFIC AMERICAN, June 1959]. But self-replication has proved to be so difficult that most researchers study it with the conceptual tool that von Neumann developed: two-dimensional cellular automata.

Implemented on a computer, cellular automata can simulate a huge variety of self-replicators in what amounts to a universe of different laws of physics from our own. Such models free researchers from having to worry about logistical issues such as energy and physical construction so that they can focus on the fundamental questions of information flow. How is a living being able to replicate unaided, whereas mechanical objects must be constructed by humans? How does replication at the level of an organism emerge from the numerous interactions in tissues, cells and molecules? How did Darwinian evolution give rise to self-replicating organisms?

The emerging answers have inspired the development of self-repairing silicon chips [see box on page 40] and autocatalyzing molecules [see “Synthetic Self-Replicating Molecules,” by Judit Rebek, Jr.; SCIENTIFIC AMERICAN, July 1994]. And this may be just the beginning. Researchers in the field of nanotechnology have long proposed that self-replication will be crucial to manu-

By Moshe Sipper and James A. Reggia

Photoulustrations by David Emmite
Her Majesty pointed to a clock and said, “See to it that it produces offspring.”

dictions of devices running amok. The knowledge we gain will help us separate good technologies from destructive ones.

Playing Life

SCIENCE-FICTION STORIES often depict cybernetic self-replication as a natural development of current technology, but they gloss over the profound problem it poses: how to avoid an infinite regress.

A system might try to build a clone using a blueprint—that is, a self-description. Yet the self-description is part of the machine: is it not? If so, what describes the description? And what describes the description of the description? Self-replication in this case would be like asking an architect to make a perfect blueprint of his or her own studio. The blueprint would have to contain a miniature version of the blueprint, which would contain a miniature version of the blueprint and so on. Without this information, a construction crew would find it impossible to re-create the studio fully; there would be a blank space where the blueprint had been.

Von Neumann’s great insight was an explanation of how to break out of the infinite regress. He realized that the self-describing machine is a

MOSHE SIPPER and JAMES A. REGGINA share a long-standing interest in how complex systems can self-organize. Sipper is a senior lecturer in the department of computer science at Ben-Gurion University in Israel and a visiting research at the Logic Systems Laboratory of the Swiss Federal Institute of Technology in Lausanne. He is interested mainly in his inspired computational paradigms such as evolutionary computation, self-replicating systems and cellular computer. Regina is a professor of computer science and neurology, working in the Institute for Advanced Computer Studies at the University of Maryland. In addition to studying self-replication, he conducts research on computational models of the brain and its disorders, such as stroke.

factoring molecular-scale machines, and proponents of space exploration see a microscopic version of the process as a way to colonize planets using in situ materials. Recent advances have given credence to these futuristic-sounding ideas. As with other scientific disciplines, including genetics, nuclear energy and chemistry, those of us who study self-replication face the twofold challenge of creating replicating machines and avoiding dystopian pre-

cells contain a +, then the cell becomes a +; otherwise it becomes vacant. With this rule, a single + grows into four more +s, each of which grows likewise, and so forth. Such weedlike proliferation does not shed much light on the principles of replication, because there is no significant machine. Of course, that invites the question of how you would tell a “significant” machine from a trivially prolific automaton. No one has yet devised a satisfactory answer. What is clear, however, is that the replicating structure must be in some sense be complex. For example, it must consist of multiple, diverse components whose interactions collectively bring about replication—the proverbial “whole must be greater than the sum of the parts.”

The existence of multiple distinct components permits a self-description to be stored within the replicating structure.

In the years since von Neumann’s seminal work, many researchers have probed the domain between the complex and the trivial, developing replicators that require fewer components, less space or simpler rules. A major step forward was taken in 1984 when Christopher G. Langton, then at the University of Michigan, observed a function several years before molecular biologists did, and his work has been crucial in understanding self-replication in nature.

To prove these ideas, von Neumann and mathematician Stanislaw M. Ulam came up with the idea of cellular automata. A cellular automaton involves a chessboard-like grid of squares, or cells, each of which is either empty or occupied by one of several possible components. At discrete intervals of time, each cell looks at itself and its neighbors and decides whether to metamorphose into a different component. In making this decision, the cell follows relatively simple rules, which are the same for all cells. These rules constitute the basic physics of the automaton are formally un.observable. To see how a pattern will unfold, you need to simulate it fully [see Mathematical Games, by Martin Gardner; Scientific American, October 1970 and February 1971; and “The Ultimate in Anty-Parti- tion,” by J. H. Conway’s Game of Life, produces amaz-

ingsome intricately. Many questions about the dynamic behavior of cellular

THE AUTHORS

Her Majesty pointed to a clock and said, “See to it that it produces offspring.”

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MOISHE SIPPER and JAMES A. REGGINA share a long-standing interest in how complex systems can self-organize. Sipper is a senior lecturer in the department of computer science at Ben-Gurion University in Israel and a visiting research at the Logic Systems Laboratory of the Swiss Federal Institute of Technology in Lausanne. He is interested mainly in his inspired computational paradigms such as evolutionary computation, self-replicating systems and cellular computing. Regina is a professor of computer science and neurology, working in the Institute for Advanced Computer Studies at the University of Maryland. In addition to studying self-replication, he conducts research on computational models of the brain and its disorders, such as stroke.

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Emergent Replication ALL THESE SELF-REPLICATING STRUCTURES have been designed through ingenuity and much trial and error. This process is arduous and often frustrating; a small change to one of the rules results in an entirely different global behavior, most likely the disintegration of the structure in question. But recent work has gone beyond the direct-design approach. Instead of tailoring the rules to suit a particular type of structure, researchers have experimented with various sets of rules, filled the cellular-automata grid with a “primordial soup” of randomly selected components and checked whether self-replicators emerged spontaneously.

In 1997 Hsin-Hao Chou, now at Iowa State University, and Regina noticed that as long as the initial density of the free-floating components was above a certain threshold, small self-replicating loops reliably appeared. Loops that collided underwent annihilation, so there was an ongoing process of death as well as birth. Over time, loops proliferated, grew in size and evolved through mutations triggered by debris from past collisions. Although the automata rules were deterministic, these mutations were effectively random,
BUILD YOUR OWN REPLICATOR

SIMULATING A SMALL self-replicating loop using an ordinary chess set is a good way to get an intuitive sense of how these systems work. This particular cellular-automaton model has four different types of components: pawns, knights, bishops and rooks. The machine initially comprises four pawns, a knight and a bishop. It has two parts: the loop itself, which consists of a two-by-two square, and a construction arm, which sticks out to the right.

The knight and bishop represent the self-description: the knight, whose orientation is significant, determines which direction to grow, while the bishop tags along and determines how long the side of the loop should be. The pawns are fillers that define the rest of the shape of the loop, and the rook is a transient signal to guide the growth of a new construction arm.

As time progresses, the knight and bishop circulate counterclockwise around the loop. Whenever they encounter the arm, one copy goes out the arm while the original continues around the loop.

STAGES OF REPLICATION

INITIALLY, the self-description, or "genome"—a knight followed by a bishop—is poised at the start of the construction arm.

1. The knight and bishop move counterclockwise around the loop. At a time of the knight, he acts out the arm.

2. The original knight-bishop pair continues to circulate. The bishop is cloned and follows the new knight out the arm.

3. The knight triggers the formation of two corners of the child loop. The bishop tags along, completing the gene transfer.

4. The knight forges the remaining corner of the child loop. The loops are connected by the construction arm and a knight-errant.

5. The knight-errant moves up to endow the parent with a new arm. A similar process, one step delayed, begins for the child loop.

6. The knight-errant, together with the original knight-bishop pair, conjures up a rook. Meanwhile, the old arm is erased.

7. The rook kills the knight and generates the new, upward arm. Another rook prepares to do the same for the child.

8. At last, the two loops are separate and whole. The self-descriptions continue to circulate, but otherwise all is calm.

9. The parent prepares to give birth again. In the following step, each child too will begin to replicate.
ROBOT, HEAL THYSELF

Computers that fix themselves are the first application of artificial self-replication

LASSAINNE, SWITZERLAND—Not many researchers encourage the wanton destruction of equipment in their labs. Daniel Mange, however, likes it when visitors walk up to one of his inventions and press the button marked KILL. The lights on the panel go out, a small box full of circuitry is toasted. Early in May his team unveiled its latest contraption at a science festival here—a wall-size digital clock whose components you can zap at will—and told the public: Give your best shot. See if you can crash the system.

The goal of Mange and his team is to instill electronic circuits with the ability to take a lickin’ and keep on tickin’—just like living things. Flesh- and-blood creatures might not be so good at calculating its 0.9 million digit, but they can get through the day without someone pressing Ctrl-Alt-Del. Combining the precision of digital hardware with the resilience of biological wetware is a leading challenge for modern electronics.

Electronics engineers have been working on fault-tolerant circuits ever since there were electronics engineers [see “Redundancy in Computers,” by William H. Pierce; SCIENTIFIC AMERICAN, February 1964]. Computer modems would still be drooling data at 1200 baud if it weren’t for error detection and correction. In many applications, simple quality-control checks, such as extra data bits, suffice. More complex systems provide entire backup computers. The space shuttle, for example, has five processors. Four of them perform the same calculations; the fifth checks whether they agree and pulls the plug on any dissenter.

The problem with these systems, though, is that they rely on centralized control. What if that control unit goes bad? Nature has solved that problem through radical decentralization. Cells in the body are all basically identical; each takes on a specialized task, performs it autonomously and, in the event of infection or failure, commits hara-kiri so that its tasks can be taken up by new cells. These are the attributes that Mange, a professor at the Swiss Federal Institute of Technology here, and others have sought since 1993 to emulate in circuitry, as part of the “Embryonics” (embryonic electronics) project.

One of their earlier inventions, the MICTREE (microinstruction tree) artificial cell, consisted of a simple processor and four bits of data storage. The cell is contained in a plastic box roughly the size of a pack of Post-its. Electrical contacts run along the sides so that cells can be snapped together like Lego. As in cellular automata, the models used to study the theory of self-replication, the MICTREE cells are connected only to their immediate neighbors. The communication burden on each cell is thus independent of the total number of cells. The system, in other words, is easily scalable—unlike many parallel-computing architectures.

Cells follow the instructions in their “genome,” a program written in a subset of the Pascal computer language. Like their biological antecedents, the cells all contain the exact same genome and execute part of it based on their position within the array, which each cell calculates relative to its neighbors. Wasteful though it may seem, this redundancy allows the array to withstand and the loss of any cell. Whenever someone presses the KILL button on a cell, that cell shuts down, and its left and right neighbors become directly connected. The right neighbor recalculates its position and starts executing the deceased program’s tasks. In turn, are taken up by the next cell to the right, and so on, until a cell designated as a spare is pressed into service.

Writing programs for any parallel processor is tricky, but the MICTREE array requires an especially unconventional approach. Instead of giving explicit instructions, the programmer must devise simple rules out of which the desired function will emerge. Being Swiss, Mange demonstrates by building a supercaliber stopwatch. Displaying minutes and seconds requires four cells in a row, one for each digit. The genome allows for two cell types: a counter from zero to nine and a counter from zero to five. An oscillator feeds one pulse per second into the rightmost cell. After 10 pulses, this cell cycles back to zero and sends a pulse to the cell on its left, and so on down the line. The watch takes up part of an array of 12 cells; when you kill one, the clock transplants itself one cell over and carries on. Obviously, though, there is a limit to its resilience: the whole thing will fall after, at most, eight kills.

The prototype MICTREE cells are hardwired, so their processing power cannot be tailored to a specific application. In a finished product, cells would instead be implemented on a field-programmable gate array, a grid of electronic components that can be reconfigured on the fly [see “Configurable Computing,” by John Villasenor and William H. Mangion-Smith; SCIENTIFIC AMERICAN, June 1997]. Mange’s team is now custom-designing a gate array, known as MUXTREE (multiplexer tree), that is optimized for artificial cells. In the biological metaphor, the components of this array are the “molecules” that constitute a cell. Each consists of a logic gate, a data bit and a string of configuration bits that determines the function of this gate.

Building a cell out of such molecules offers not only flexibility but also extra endurance. Each molecule contains two copies of the gate and three of the storage bit. If the two gates ever give different results, the molecule kills itself for the greater good of the cell. As a last gasp, the molecule sends its data bit [preserved by the triplicate storage] and configuration to its right neighbor, which does the same, and the process continues until the rightmost molecule transfers its data to a spare. This second level of fault tolerance prevents a single error from wiping out an entire cell.

A total of 2,000 molecules, divided into four 20 by 25 cells, make up the biobot—the giant digital clock that Mange’s team has just put on display. Each molecule is housed in a small box and includes a KILL button and an LED display. Some cells are configured to perform computations; others serve as pixels in the clock display. Making liberal use of the KILL buttons, I did my utmost to crash the system, something I’m usually quite good at. But the pockly clock just wouldn’t submit. The clock display did start to look funny—numbers bent over as their pixels shifted to the right—but at least it was still legible, unlike most faulty electronic signs.

The said, the system did suffer from display glitches, which Mange attributes partly to the learning curve. “Although the processing power is decentralized, the cells still rely on a central oscillator to coordinate their communications; sometimes they fall out of sync. Another Embryonics team, led by Andy Tyrell of the University of York in England, has been studying making the cells asynchronous, like their biological counterparts. Cells would generate handshake signals to orchestrate data transfers. The present system is also unable to catch certain types of error, including damaged configuration strings. Tyrell’s team has proposed adding watchdog molecules—an immune system—that would monitor the configurations [and one another] for defects.

Although these systems demand an awful lot of overhead, so do other fault-tolerant technologies. “While Embryonics appears to be heavy on redundancy, it actually is not that bad compared to other systems,” Tyrell argues. Moreover, MICTREE should be easier to scale down to the nano level; “the molecules” are simple enough to really be molecules. Says Mange, “We are preparing for the situation where electronics will be at the same scale as biology.”

On a philosophical level, Embryonics comes very close to the dream of building a self-replicating machine. It may not be as dramatic as a robot that can go down to Radio Shack, pull parts off the racks, and take them home to resolder a connection or build a loving mate. But the effect is much the same. Letting machines determine their own destiny—whether reconfiguring themselves on a silicon chip or reprogramming themselves using a neural network or genetic algorithm—sounds scary, but perhaps we should be grateful that machines are becoming more like us: imperfect, fallible but stubbornly resourceful.

—George Musser, imperfect but no resourceful staff editor and writer
In a sense, researchers are seeing a continuum between nonliving and living structures.

Simulations of the "organisms" are computer programs that vie for processor time and memory. Ray has observed the emergence of "paradigms" that co-opt the self-replication code of other organisms.

**Getting Real**

So what good are these machines? Von Neumann's universal constructor can compute in addition to replicating, but it is an impractical beast. A major advance has been the development of simple yet useful replicators. In 1995 Gianluca Tempesi of the Swiss Federal Institute of Technology in Lausanne simplified the loop self-description so it could be interlaced with a small program—in this case, one that would spell the acronym of his lab, "ULS." His insight was to create automata rules that allow loops to replicate in two stages. First the loop, like Langton's loop, makes a copy of itself. Once finished, the daughter loop sends a signal back to its parent, at which point the parent sends the instructions for writing out the letters.

Drawing letters was just a demonstration. The following year, Jean-Yves Perriére, Jacques Zahn, and one of us (Sipper) designed a self-replicating loop with universal computational capabilities—that is, with the computational power of a universal Turing machine, a highly simplified but fully capable computer. This loop has two "tapes," or long strings of components, one for the program and the other for data. The loops can execute an arbitrary program in addition to self-replicating. In a sense, they are as complex as the computer that simulates them. Their main limitation is that the program is copied unchanged from parent to child, so that all loops carry out the same set of instructions.

In 1998 Chou and Reggia swept away this limitation. They showed how self-replicating loops carrying distinct information, rather than a cloned program, can be used to solve a problem known as satisfiability. The loops can be used to determine whether the variables in a logical expression can be assigned values such that the entire expression evaluates to "true." This problem is NP-complete—in other words, it belongs to the family of nasty puzzles, including the famous traveling-salesman problem, for which there is no known efficient solution. In Chou and Reggia's cellular-automata universe, each replicator received a different partial solution. During replication, the solutions mutated, and replicators with promising solutions were allowed to proliferate while those with failed solutions died out.

Although various teams have created cellular automata in electronic hardware, such systems are probably too wasteful for practical applications. Automata were never really intended to be implemented directly. Their purpose is to illuminate the underlying principles of replication and, by doing so, inspire more concrete efforts. The loops provide a new paradigm for designing a parallel computer from either transistors or chemicals [see "Computing with DNA," by Leonard M. Adleman, SCIENTIFIC AMERICAN, August 1998].

In 1980 a NASA team led by Robert Freitas, Jr., proposed planting a factory on the moon that would replicate itself, using local lunar materials, to populate a large area exponentially. Indeed, a similar probe could colonize the entire galaxy, as physicist Frank Tipler of Tulane University has argued. In the nearer term, computer scientists and engineers have experimented with the automated design of robots [see "Down of a New Species?" by George Musset, SCIENTIFIC AMERICAN, November 2000]. Although these systems are not truly self-replicating—the offspring are much simpler than the parent—they are a first step toward fulfilling the queen of Sweden's request.

Should physical self-replicating machines become practical, they and related technologies will raise difficult issues, including the Terminator film scenario in which artificial creatures outcompete natural ones. We prefer the more optimistic, and more probable, scenario that replicators will be harnessed to the benefit of humanity [see "Will Robots Inherit the Earth?" by Marvin Minsky, SCIENTIFIC AMERICAN, October 1994]. The key will be taking the advice of 14th-century English philosopher William of Ockham: *cuius non sunt multiplicanda praeter necessitationem*—entities are not to be multiplied beyond necessity.

**MORE TO EXPLORE**


Moshe Sipper's Web page on artificial self-replication is at http://www.uptf.ch/~moshe/relrep/

Animations of self-replicating loops can be found at ee.caltech.edu/~sg/replica/replica/java/

For John von Neumann's universal constructor, see alife.santafe.edu/alife/topics/yn/yn.html
The John von Neumann Institute for Computing (NIC) is a joint foundation of Forschungszentrum Jülich and Deutsches Elektronen-Synchrotron DESY to support supercomputer-aided scientific research and development. Since April 2006, the GSI Helmholtzzentrum für Schwerionenforschung joined NIC as a contract partner. NIC takes over the functions and tasks of the High Performance Computer Centre (HLRZ) established in 1987 and continues this centre's successful work in the field of supercomputing and its applications.

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- Research proposals can be submitted by German scientists and by partners in the EU projects DEISA and I3HP.
- There is also an [Offer to the New Member States and candidate countries of the European Union](http://www.fz-juelich.de/nic/Allgemeines/Allgemeines-e.html).

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A prize is awarded annually to a scholar (or scholars in the case of joint work) who has made fundamental, sustained contributions to theory in operations research and the management sciences. The award is given each year at the National Meeting if there is a suitable recipient. Although the prize is normally given to a single individual, in the case of accumulated joint work, the recipients can be multiple individuals. The award is $5,000, a medallion and a citation.

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  View information about eligibility, procedures and deadlines

- **Past Winners**
  View information about all past winners of this prize

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**2008:** Frank P. Kelly

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(Count István Széchenyi 1842)

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Historical Perspectives

Claude Shannon (1916-2001)

• Invented electrical digital circuits (1937)
• Founded information theory (1948)
• Introduced sampling theory, coined term “bit”
• Contributed to genetics, cryptography
• Joined Institute for Advanced Study (1940)
• Influenced by Turing, von Neumann, Einstein
• Other hobbies & inventions: juggling, unicycling, computer chess, rockets, motorized pogo stick, flame-throwers, Rubik's cube solver, wearable computer, mathematical gambling, stock markets
• “AT&T Shannon Labs” named after him
Reluctant Father of the Digital Age

Claude Shannon
A SYMBOLIC ANALYSIS
OF
RELAY AND SWITCHING CIRCUITS

by

Claude Elwood Shannon
B.S., University of Michigan
1935

Submitted in Partial Fulfillment of the
Requirements for the Degree of
MASTER OF SCIENCE
from the
Massachusetts Institute of Technology
1940

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Theseus: Shannon’s electro-mechanical mouse (1950): first “learning machine” and AI experiment

Chess champion Ed Lasker looking at Shannon’s chess-playing machine
Shannon’s home study room

Shannon’s On/Off machine
Introduction

The recent development of various methods of modulation such as PCM and PPM which exchange bandwidth for signal-to-noise ratio has intensified the interest in a general theory of communication. A basis for such a theory is contained in the important papers of Nyquist\(^1\) and Hartley\(^2\) on this subject. In the present paper we will extend the theory to include a number of new factors, in particular the effect of noise in the channel, and the savings possible due to the statistical structure of the original message and due to the nature of the final destination of the information.

The fundamental problem of communication is that of reproducing at one point either exactly or approximately a message selected at another point. Frequently the messages have meaning; that is they refer to or are correlated according to some system with certain physical or conceptual entities. These semantic aspects of communication are irrelevant to the engineering problem. The significant aspect is that the actual message is one selected from a set of possible messages. The system must be designed to operate for each possible selection, not just the one which will actually be chosen since this is unknown at the time of design.

If the number of messages in the set is finite then this number or any monotonic function of this number can be regarded as a measure of the information produced when one message is chosen from the set, all choices being equally likely. As was pointed out by Hartley the most natural choice is the logarithmic function. Although this definition must be generalized considerably when we consider the influence of the statistics of the message and when we have a continuous range of messages, we will in all cases use an essentially logarithmic measure.

The logarithmic measure is more convenient for various reasons:

1. It is practically more useful. Parameters of engineering importance such as time, bandwidth, number of relays, etc., tend to vary linearly with the logarithm of the number of possibilities. For example, adding one relay to a group doubles the number of possible states of the relays. It adds 1 to the base 2 logarithm of this number. Doubling the time roughly squares the number of possible messages, or doubles the logarithm, etc.

2. It is nearer to our intuitive feeling as to the proper measure. This is closely related to (1) since we intuitively measure entities by linear comparison with common standards. One feels, for example, that two punched cards should have twice the capacity of one for information storage, and two identical channels twice the capacity of one for transmitting information.

3. It is mathematically more suitable. Many of the limiting operations are simple in terms of the logarithm but would require clumsy restatement in terms of the number of possibilities.

The choice of a logarithmic base corresponds to the choice of a unit for measuring information. If the base 2 is used the resulting units may be called binary digits, or more briefly bits, a word suggested by J. W. Tukey. A device with two stable positions, such as a relay or a flip-flop circuit, can store one bit of information. \(N\) such devices can store \(N\) bits, since the total number of possible states is \(2^N\) and \(\log_2 2^N = N\). If the base 10 is used the units may be called decimal digits. Since

\[
\log_2 M = \log_{10} M / \log_{10} 2
\]

\[
= 3.32 \log_{10} M,
\]


Discrete Noiseless Systems

1. The Discrete Noiseless Channel

Teletype and telegraphy are two simple examples of a discrete channel for transmitting information. Generally, a discrete channel will mean a system whereby a sequence of choices from a finite set of elementary symbols $S_1 \cdots S_n$ can be transmitted from one point to another. Each of the symbols $S_i$ is assumed to have a certain duration in time $t_i$ seconds (not necessarily the same for different $S_i$, for example the dots and dashes in telegraphy). It is not required that all possible sequences of the $S_i$ be capable of transmission on the system; certain sequences only may be allowed. These will be possible signals for the channel. Thus in telegraphy suppose the symbols are: (1) A dot, consisting of line closure for a unit of time and then line open for a unit of time; (2) A dash, consisting of three units of closure and one unit open; (3) A letter space consisting of, say, three units of line open; (4) A word space of six units of line open. We might place the restriction on allowable sequences that no spaces follow each other (for if two letter spaces are adjacent, they are identical with a word space). The question we now consider is how one can measure the capacity of such a channel to transmit information.

In the teletype case where all symbols are of the same duration, and any sequence of the 32 symbols is allowed, the answer is easy. Each symbol represents five bits of information. If the system transmits $n$ symbols per second it is natural to say that the channel has a capacity of $5n$ bits per second. This does not mean that the teletype channel will always be transmitting information at this rate — this is the maximum possible rate and whether or not the actual rate reaches this maximum depends on the source of information which feeds the channel, as will appear later.

In the more general case with different lengths of symbols and constraints on the allowed sequences, we make the following definition: The capacity $C$ of a discrete channel is given by

$$C = \lim_{T \to \infty} \frac{\log N(T)}{T}$$

where $N(T)$ is the number of allowed signals of duration $T$.

It is easily seen that in the teletype case this reduces to the previous result. It can be shown that the limit in question will exist as a finite number in most cases of interest. Suppose all sequences of the symbols $S_1, \cdots, S_n$ are allowed and these symbols have durations $t_1, \cdots, t_n$. What is the channel capacity? If $N(t)$ represents the number of sequences of duration $t$ we have

$$N(t) = N(t - t_1) + N(t - t_2) + \cdots + N(t - t_n).$$

The total number is equal to the sum of the numbers of sequences ending in $S_1, S_2, \cdots, S_n$ and these are $N(t - t_1), N(t - t_2), \cdots, N(t - t_n)$, respectively. According to a well-known result in finite differences, $N(t)$ is the asymptotic for large $t$ to $AX^t$, where $A$ is constant and $X_0$ is the largest real solution of the characteristic equation:

$$X^{-t_1} + X^{-t_2} + \cdots + X^{-t_n} = 1$$

and therefore

$$C = \lim_{T \to \infty} \frac{\log AX_T}{T} = \log X_0.$$

In case there are restrictions on allowed sequences we may still often obtain a difference equation of this type and find $C$ from the characteristic equation. In the telegraphy case mentioned above

$$N(t) = N(t - 2) + N(t - 4) + N(t - 5) + N(t - 7) + N(t - 8) + N(t - 10)$$
a decimal digit is about \( \frac{3}{2} \) bits. A digit wheel on a desk computing machine has ten stable positions and therefore has a storage capacity of one decimal digit. In analytical work where integration and differentiation are involved the base \( e \) is sometimes useful. The resulting units of information will be called natural units. Change from the base \( a \) to base \( b \) merely requires multiplication by \( \log_b a \).

By a communication system we will mean a system of the type indicated schematically in Fig. 1. It consists of essentially five parts:

1. An information source which produces a message or sequence of messages to be communicated to the receiving terminal. The message may be of various types: (a) A sequence of letters as in a telegraph or teletype system; (b) A single function of time \( f(t) \) as in radio or telephony; (c) A function of time and other variables as in black and white television — here the message may be thought of as a function \( f(x, y, t) \) of two space coordinates and time, the light intensity at point \((x, y)\) and time \( t \) on a pickup tube plate; (d) Two or more functions of time, say \( f(t), g(t), h(t) \) — this is the case in “three-dimensional” sound transmission or if the system is intended to service several individual channels in multiplex; (e) Several functions of several variables — in color television the message consists of three functions \( f(x, y, t), g(x, y, t), h(x, y, t) \) defined in a three-dimensional continuum — we may also think of these three functions as components of a vector field defined in the region — similarly, several black and white television sources would produce “messages” consisting of a number of functions of three variables; (f) Various combinations also occur, for example in television with an associated audio channel.

2. A transmitter which operates on the message in some way to produce a signal suitable for transmission over the channel. In telephony this operation consists merely of changing sound pressure into a proportional electrical current. In telegraphy we have an encoding operation which produces a sequence of dots, dashes and spaces on the channel corresponding to the message. In a multiplex PCM system the different speech functions must be sampled, compressed, quantized and encoded, and finally inter-leaved properly to construct the signal. Vocoder systems, television and frequency modulation are other examples of complex operations applied to the message to obtain the signal.

3. The channel is merely the medium used to transmit the signal from transmitter to receiver. It may be a pair of wires, a coaxial cable, a band of radio frequencies, a beam of light, etc. During transmission, or at one of the terminals, the signal may be perturbed by noise. This is indicated schematically in Fig. 1 by the noise source acting on the transmitted signal to produce the received signal.

4. The receiver ordinarily performs the inverse operation of that done by the transmitter, reconstructing the message from the signal.

5. The destination is the person (or thing) for whom the message is intended.

We wish to consider certain general problems involving communication systems. To do this it is first necessary to represent the various elements involved as mathematical entities, suitably idealized from their physical counterparts. We may roughly classify communication systems into three main categories: discrete, continuous and mixed. By a discrete system we will mean one in which both the message and the signal are a sequence of discrete symbols. A typical case is telegraphy where the message is a sequence of letters and the signal a sequence of dots, dashes and spaces. A continuous system is one in which the
Suppose we have a set of possible events whose probabilities of occurrence are \( p_1, p_2, \cdots, p_n \). These probabilities are known but that is all we know concerning which event will occur. Can we find a measure of how much "choice" is involved in the selection of the event or of how uncertain we are of the outcome?

If there is such a measure, say \( H(p_1, p_2, \cdots, p_n) \), it is reasonable to require of it the following properties:

1. \( H \) should be continuous in the \( p_i \).
2. If all the \( p_i \) are equal, \( p_i = \frac{1}{n} \), then \( H \) should be a monotonic increasing function of \( n \). With equally likely events there is more choice, or uncertainty, when there are more possible events.
3. If a choice be broken down into two successive choices, the original \( H \) should be the weighted sum of the individual values of \( H \). The meaning of this is illustrated in Fig. 6. At the left we have three possibilities \( p_1 = \frac{1}{3}, p_2 = \frac{1}{3}, p_3 = \frac{1}{3} \). On the right we first choose between two possibilities each with probability \( \frac{1}{3} \), and if the second occurs make another choice with probabilities \( \frac{1}{3}, \frac{1}{3} \). The final results have the same probabilities as before. We require, in this special case, that

\[
H\left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right) = H\left(\frac{1}{3}, \frac{1}{3}\right) + \frac{1}{3} H\left(\frac{1}{3}, \frac{1}{3}\right).
\]

The coefficient \( \frac{1}{3} \) is the weighting factor introduced because this second choice only occurs half the time.

\[
H = - K \sum_{i=1}^{n} p_i \log p_i
\]

where \( K \) is a positive constant.

This theorem, and the assumptions required for its proof, are in no way necessary for the present theory. It is given chiefly to lend a certain plausibility to some of our later definitions. The real justification of these definitions, however, will reside in their implications.

Quantities of the form \( H = - \sum p_i \log p_i \) (the constant \( K \) merely amounts to a choice of a unit of measure) play a central role in information theory as measures of information, choice and uncertainty. The form of \( H \) will be recognized as that of *entropy*.

\[
\text{Fig. 6.\: Decomposition\: of\: a\: choice\: from\: three\: possibilities.}
\]

In Appendix 2, the following result is established:

*Theorem 2:* The only \( H \) satisfying the three above assumptions is of the form:

\[
\text{Fig. 7.\: Entropy\: in\: the\: case\: of\: two\: possibilities\: with\: probabilities\: } p \text{\: and\: } (1 - p).
\]

as defined in certain formulations of statistical mechanics* where \( p_i \) is the probability of a system being in cell \( i \) of its phase space.

The Mathematical Theory of Communication

sequence of symbols $x_i$; and let $\beta$ be the state of the transducer, which produces, in its output, blocks of symbols $y_j$. The combined system can be represented by the “product state space” of pairs $(\alpha, \beta)$. Two points in the space $(\alpha_1, \beta_1)$ and $(\alpha_2, \beta_2)$, are connected by a line if $\alpha_1$ can produce an $x$ which changes $\beta_1$ to $\beta_2$, and this line is given the probability of that $x$ in this case. The line is labeled with the block of $y_1$ symbols produced by the transducer. The entropy of the output can be calculated as the weighted sum over the states. If we sum first on $\beta$ each resulting term is less than or equal to the corresponding term for $\alpha$, hence the entropy is not increased. If the transducer is non-singular let its output be connected to the inverse transducer. If $H'_1$, $H'_2$, and $H'_3$ are the output entropies of the source, the first and second transducers respectively, then $H'_1 \geq H'_2 \geq H'_3 = H'_4$ and therefore $H'_1 = H'_2$.

Suppose we have a system of constraints on possible sequences of the type which can be represented by a linear graph as in Fig. 2. If probabilities $p^{(s)}_i$ were assigned to the various lines connecting state $i$ to state $j$ this would become a source. There is one particular assignment which maximizes the resulting entropy (see Appendix 4).

**Theorem 8:** Let the system of constraints considered as a channel have a capacity $C = \log W$. If we assign

$$p^{(s)}_{ij} = \frac{B_j}{B_i} W^{-l^{(s)}_i}$$

where $l^{(s)}_i$ is the duration of the $s^{th}$ symbol leading from state $i$ to state $j$ and the $B_i$ satisfy

$$B_i = \sum_{s,j} B_j W^{-l^{(s)}_i}$$

then $H$ is maximized and equal to $C$.

By proper assignment of the transition probabilities the entropy of symbols on a channel can be maximized at the channel capacity.

**9. The Fundamental Theorem for a Noiseless Channel**

We will now justify our interpretation of $H$ as the rate of generating information by proving that $H$ determines the channel capacity required with most efficient coding.

**Theorem 9:** Let a source have entropy $H$ (bits per symbol) and a channel have a capacity $C$ (bits per second). Then it is possible to encode the output of the source in such a way as to transmit at the average rate $\frac{C}{H} - \epsilon$ symbols per second over the channel where $\epsilon$ is arbitrarily small. It is not possible to transmit at an average rate greater than $\frac{C}{H}$.

The converse part of the theorem, that $\frac{C}{H}$ cannot be exceeded, may be proved by noting that the entropy of the channel input per second is equal to that of the source, since the transmitter must be non-singular, and also this entropy cannot exceed the channel capacity. Hence $H' \leq C$ and the number of symbols per second $= H'/H \leq C/H$.

The first part of the theorem will be proved in two different ways. The first method is to consider the set of all sequences of $N$ symbols produced by the source. For $N$ large we can divide these into groups, one containing less than $2^{(H+\eta)N}$ members and the second containing less than $2^{KH}$ members (where $K$ is the logarithm of the number of different symbols) and having a total probability less than $\mu$. As $N$ increases $\eta$ and $\mu$ approach zero. The number of signals of duration $T$ in the channel is greater than $2^{(C-\lambda)T}$ with $\theta$ small when $T$ is large. If we choose

$$T = \left(\frac{H}{C} + \lambda\right) N$$

then there will be a sufficient number of sequences of channel symbols for the high probability group when $N$ and $T$ are sufficiently large (however small $\lambda$) and also some additional ones. The high probability group is coded in an arbitrary one-to-one way into this set. The remaining sequences are represented by larger sequences, starting and ending with one of the sequences not used for the high probability group. This special sequence acts as a start and stop signal for a different code. In between a sufficient time is allowed to give enough different sequences for all the low probability messages. This will require
Entropy and Randomness

- **Entropy** measures the expected “uncertainly” (or “surprise”) associated with a random variable.

- Entropy quantifies the “information content” and represents a lower bound on the best possible lossless compression.

- Ex: a random fair coin has entropy of 1 bit. A **biased** coin has lower entropy than fair coin. A two-headed coin has zero entropy.

- The string 00000000000000… has zero entropy.

- English text has entropy rate of 0.6 to 1.5 bits per letter.

Q: How do you simulate a **fair** coin with a **biased** coin of unknown but **fixed bias**?

A [von Neumann]: Look at **pairs** of flips. **HT** and **TH** both occur with equal probability of $p(1-p)$, and ignore HH and TT pairs.
Entropy and Randomness

- **Information entropy** is an analogue of **thermodynamic entropy** in physics / statistical mechanics, and von Neumann entropy in quantum mechanics.
- **Second law of thermodynamics**: entropy of an isolated system **cannot decrease over time**.
- Entropy as “disorder” or “chaos”.
- Entropy as the “arrow of time”.
- “Heat death of the universe” / black holes
- Quantum computing uses a **quantum information theory** to generalize classical information theory.

**Theorem**: String compressibility decreases as entropy increases.

**Theorem**: Most strings are not (losslessly) compressible.

**Corollary**: Most strings are random!
“My greatest concern was what to call it. I thought of calling it ‘information’, but the word was overly used, so I decided to call it ‘uncertainty’. When I discussed it with John von Neumann, he had a better idea. Von Neumann told me, ‘You should call it entropy, for two reasons. In the first place your uncertainty function has been used in statistical mechanics under that name, so it already has a name. In the second place, and more important, nobody knows what entropy really is, so in a debate you will always have the advantage.’”

- Claude Shannon on his conversation with John von Neumann regarding what name to give to the “measure of uncertainty” or attenuation in phone-line signals (1949)
Claude Shannon - Father of the Information Age

First Aired: 1/30/2002
29 minutes

Considered the founding father of the electronic communication age, Claude Shannon's work ushered in the Digital Revolution. This fascinating program explores his life and the major influence his work had on today's digital world through interviews with his friends and colleagues. (#6090)

Links / Resources
General
Claude Shannon
Teacher's P.E.T.
K-12 Educational Standards on UCTV

Extra credit: watch this video
Claude E. Shannon Award

The Claude E. Shannon Award of the IT Society has been instituted to honor consistent and profound contributions to the field of information theory. Each Shannon Award winner is expected to present a Shannon Lecture at the following IEEE International Symposium on Information Theory. Transcripts of some of the lectures are available on-line.

Starting for the 2010 Award, the Shannon Award Committee has decided to issue an open call for nominations, preferably using the nomination form. Although anyone may make a nomination, the Committee retains the responsibility of assuring that a suitable slate of candidates is nominated, and may itself generate nominations. Nominations and optional letters of endorsement must be submitted by March 1 to the current President of the IEEE Information Theory Society.

The first Shannon Lecturer was Claude Shannon himself followed by:

- David S. Slepian (1974)
- Robert M. Fano (1976)
- Peter Elias (1977)
- Mark S. Pinsker (1978)
- J. Wolfowitz (1979)
- W. Wesley Peterson (1981)
- Irving S. Reed (1982)
- Robert Gallager (1983)
- Solomon W. Golomb (1985)
- William L. Root (1986)
- James L. Massey (1988)
Historical Perspectives

Stephen Kleene (1909-1994)

- Founded recursive function theory
- Pioneered theoretical computer science
- Student of Alonzo Church; was at the Institute for Advanced Study (1940)
- Invented regular expressions
- Kleene star / closure, Kleene algebra, Kleene recursion theorem, Kleene fixed point theorem, Kleene-Rosser paradox

“Kleeneliness is next to Gödeliness”
Whenever I learn a new skill I concoct elaborate fantasy scenarios where it lets me save the day.

Oh no! The killer must have followed her on vacation!

But to find them we'd have to search through 200 MB of emails looking for something formatted like an address!

It's hopeless!

Everybody stand back.

I know regular expressions.

NATIONAL REGULAR EXPRESSION DAY

a celebration of powerful string manipulation
JUNE 1ST // 2008
Noam Chomsky (1928-)

- Linguist, philosopher, cognitive scientist, political activist, dissident, author
- Father of modern linguistics
- Pioneered formal languages
- Developed generative grammars
  Invented context-free grammars
- Defined the Chomsky hierarchy
- Influenced cognitive psychology, philosophy of language and mind
- Chomskyan linguistics, Chomskyan syntax, Chomskyan models
- Critic of U.S. foreign policy
- Most widely cited living scholar
- Eighth most-cited source overall!
“…I must admit to taking a copy of Noam Chomsky's ‘Syntactic Structures’ along with me on my honeymoon in 1961 … Here was a marvelous thing: a mathematical theory of language in which I could use as a computer programmer's intuition!”
- Don Knuth on Chomsky’s influence
The Adventures of...

NOAM CHOMSKY

...and his dog Predicate!

Good news! I just got an interview on Nightline!

Wait? What do you mean, “screw it up”?

You know, by being you!

Don’t screw it up!

I’m not going to compromise my integrity by contributing to the dumbing of society’s intellect...

Yeah, market research is saying that The Noam Chomsky Quote of the Day Calendar is giving people head aches.

If you go on there you’re going to be like, “I’m Noam Chomsky the Modern Industrial Society must... big word here, big word there, U.S. foreign policy this... Blah, blah, blah...”

What can I do?

I need a better way to get my message out.

Look Noam, let’s be realistic. You’re a downer. People don’t want to hear about how awful things are all the time!

There is only one option! SELL OUT!

I’m not going to comprise my integrity by contributing to the dumbing of society’s intellect... If you go on there you’re going to be like, “I’m Noam Chomsky the Modern Industrial Society must... big word here, big word there, U.S. foreign policy this... Blah, blah, blah...”

Positive spin, Noam. That’s the way to get your message out!

How can you possibly put positive spin on the continuing decay and directed destruction of our basic freedoms?!

To do that would be to undermine the responsibility of the intellectual in our society. To tell the truth and expose the lies if the problems in the system are complicated and the lies abstruse than I’m going to say just that. It is my duty.

OK, fine. So what’s the topic going to be?

I don’t know, but it’s some sort of panel discussion, which I think will be very informative!

Positive spin, Noam. That’s the way to get your message out!

Uh, thank you Professor Chomsky for that “unique” insight into the hidden agendas of international trade organizations. So now, let me pose the same question to our other panelists.

Ms. Spears, what is your opinion of... fuzzy things?

Noam sez...

Everything’s Fine!
The Adventures of...

NOAM CHOMSKY
... and his dog Predicate!

By Jeffrey Weston

Predicate, which do you think would be less harmful to the progressive struggle against the corporate power structure in this country?

If I bought 100 grams of plain salted peanuts or 100 grams of plain unsalted peanuts?

I don't care Noam.

Ooooo ooo!

Can I get this cereal?

Hey Noam, another documentary film crew is here.

Oh, no. Not again.

So basically we're making a sequel to Manufacturing Consent.

Is that possible?

Well, our investors say "yes." The university student activist market is very lucrative.

What?

Sure, we can spin off Noam Chomsky T-Shirts, coffee mugs, action figures, waffle irons...

That's disgusting!

My goodness no! It's bad enough that corporations use children as a tool to reach their parent's wallet, but to influence them with subversive cereal themes... That's just disgusting.

Awww, but Noam! It comes with a cool prize!

Hey kids! Now you can own parts of the tastiness with one free share of the company in every box!

Capitalist Crunch! "Taste the Free Market in every bite! Mmmmmm Profitable!"

COMING SOON!
TO A UNIVERSITY-STUDENT-UNION-BASEMENT-MAKE-SHIFT-SCREENING-ROOM NEAR YOU!

MANUFACTURING CONSENT
AND OTHER FABULOUS MERCHANDISE!
The Adventures of...

NOAM CHOMSKY
... and his dog Predicate!

by Jeffrey Weston

I can't believe they're going to make a sequel to Manufacturing Consent purely to sell merchandise!

Come on! This Noam Chomsky Action Figure is pretty cool! It also corrects your grammar too.

Beep. "It corrects your grammar as well."

It's Win-Win! You get your message out and I, er, they get something in return!

OK, but I want to make sure some conspiring corporate director doesn't dilute my message.

Fine, we'll hire some dorky, idealistic University Student.

I think I'm probably going to regret this.

Beep. "I think I will regret this."

Shut-up

Why are you interviewing my dog? This documentary is supposed to be about ideas!

Because, I'm far more entertaining.

Available only on beautiful VHS!

---

In case you didn't know...

- adverb
- morpheme
- consonant cluster
- diphthong
- preposition
- noun
- velerized
- uncountable noun

---

Manufacturing Consent
also with Noam Chomsky
If we don't believe in freedom of expression for people we despise, we don't believe in it at all.

Noam Chomsky

"Propaganda is to a democracy what the bludgeon is to a totalitarian state"
- Noam Chomsky

COULD CHOMSKY BE WRONG?

IDIOT
TURING CENTENARY CONFERENCE
CiE 2012 - How the World Computes

University of Cambridge
18 June - 23 June, 2012

CiE 2012 is one of a series of special events, running throughout the Alan Turing Year, celebrating Turing's unique impact on mathematics, computing, computer science, informatics, morphogenesis, philosophy and the wider scientific world. Its central theme is the computability-theoretic concerns underlying the broad spectrum of Turing's interests, and the contemporary research areas founded upon and animated by them. In this sense, CiE 2012, held in Cambridge in the week running up to the centenary of Turing's birthday, deals with the essential core of what made Turing's contribution so influential and long-lasting. CiE 2012 promises to be an event worthy of the remarkable scientific career it commemorates.

Programme Committee: S Barry Cooper (Leeds, Co-chair), Anuj Dawar (Cambridge, Co-chair)

Organising Committee: Luca Cardelli, S Barry Cooper (Leeds), Ann Copestake, Anuj Dawar (Chair), Martin Hyland, Andrew Pitts