







moving two files

```
struct Dir {
  mutex_t lock; HashMap entries;
};
void MoveFile(Dir *from dir, Dir *to dir, string filename) {
  mutex lock(&from dir->lock);
  mutex lock(&to dir->lock);
  Map_put(to_dir->entries, filename,
        Map get(from dir->entries, filename));
  Map erase(from dir->entries. filename):
  mutex unlock(&to dir->lock);
  mutex_unlock(&from_dir->lock);
}
Thread 1: MoveFile(A, B, "foo")
Thread 2: MoveFile(B, A, "bar")
```

moving two files: lucky timeline (1)	
Thread 1	Thread 2
MoveFile(A, B, "foo")	MoveFile(B, A, "bar")
lock(&A->lock);	
lock(&B->lock);	
(do move)	
unlock(&B->lock);	
unlock(&A->lock);	

lock(&B->lock); lock(&A->lock); (do move) unlock(&B->lock); unlock(&A->lock); moving two files: lucky timeline (2) Thread 1 Thread 2 MoveFile(A, B, "foo") MoveFile(B, A, "bar") lock(&A->lock); lock(&B->lock); lock(&B->lock... (do move) (waiting for B lock) unlock(&B->lock); lock(&B->lock): lock(&A->lock... unlock(&A->lock);

lock(&A->lock);
(do move)
unlock(&A->lock);

moving two files: unlucky timeline

Thread 1Thread 2MoveFile(A, B, "foo")MoveFile(B, A, "bar")lock(&A->lock);

lock(&B->lock);

moving two files: unlucky timeline Thread 1 MoveFile(A, B, "foo") lock(&A->lock);

lock(&B->lock);

lock(&B->lock... stalled

(waiting for lock on B) (waiting for lock on B) lock(&A->lock... stalled
(waiting for lock on A)

moving two files: unlucky timeline Thread 1 Thread 2

MoveFile(A, B, "foo")
lock(&A->lock);

lock(&B->lock... stalled

(waiting for lock on B) (waiting for lock on B)

(do move) unreachable
unlock(&B->lock); unreachable
unlock(&A->lock); unreachable

Thread 2 MoveFile(B, A, "bar")

lock(&B->lock);

lock(&A->lock... stalled
(waiting for lock on A)

(do move) unreachable
unlock(&A->lock); unreachable
unlock(&B->lock); unreachable

moving two files: unlucky timeline

MoveFile(A, B, "foo")
lock(&A->lock);

lock(&B->lock... stalled

(waiting for lock on B) (waiting for lock on B)

(do move) unreachable
unlock(&B->lock); unreachable
unlock(&A->lock); unreachable

Thread 2 MoveFile(B, A, "bar")

lock(&B->lock);

lock(&A->lock... stalled
(waiting for lock on A)

(do move) unreachable
unlock(&A->lock); unreachable
unlock(&B->lock); unreachable

Thread 1 holds A lock, waiting for Thread 2 to release B lock





moving three files: unlucky timeline



deadlock with free space

Thread 1

AllocateOrWaitFor(1 MB)
AllocateOrWaitFor(1 MB)

(do calculation)

Free(1 MB)

Free(1 MB)

Thread 2 AllocateOrWaitFor(1 MB) AllocateOrWaitFor(1 MB) (do calculation) Free(1 MB) Free(1 MB)

2 MB of space — deadlock possible with unlucky order

deadlock with free space (unlucky case)Thread 1Thread 2AllocateOrWaitFor(1 MB)

AllocateOrWaitFor(1 MB... stalled

AllocateOrWaitFor(1 MB)

AllocateOrWaitFor(1 MB... stalled

free space: dependency graph



deadlock with free space (lucky case) Thread 1 Thread 2

AllocateOrWaitFor(1 MB) AllocateOrWaitFor(1 MB) (do calculation) Free(1 MB);

Free(1 MB);

AllocateOrWaitFor(1 MB)
AllocateOrWaitFor(1 MB)
(do calculation)
Free(1 MB);
Free(1 MB);

lab next week

applying solutions to deadlock to classic *dining philosphers* problem

dining philosophers



five philosophers either think or eat to eat:

grab chopstick on left, then grab chopstick on right, then then eat, then return chopsticks

dining philosophers



everyone eats at the same time? grab left chopstick, then...

dining philosophers



everyone eats at the same time? grab left chopstick, then try to grab right chopstick, ... we're at an impasse

deadlock

deadlock — circular waiting for resources

resource = something needed by a thread to do work locks CPU time disk space memory

•••

often non-deterministic in practice

most common example: when acquiring multiple locks

deadlock

deadlock — circular waiting for *resources*

resource = something needed by a thread to do work locks CPU time disk space memory

•••

often non-deterministic in practice

most common example: when acquiring multiple locks

deadlock requirements

mutual exclusion

one thread at a time can use a resource

hold and wait

thread holding a resources waits to acquire another resource

no preemption of resources

resources are only released voluntarily thread trying to acquire resources can't 'steal'

circular wait

```
there exists a set \{T_1, \ldots, T_n\} of waiting threads such that T_1 is waiting for a resource held by T_2
T_2 is waiting for a resource held by T_3
...
T_n is waiting for a resource held by T_1
```

how is deadlock possible?

```
Given list: A, B, C, D, E
RemoveNode(LinkedListNode *node) {
    pthread_mutex_lock(&node->lock);
    pthread_mutex_lock(&node->prev->lock);
    pthread_mutex_lock(&node->next->lock);
    node->next->prev = node->prev; node->prev->next = node->next;
    pthread_mutex_unlock(&node->next->lock); pthread_mutex_unlock(&node->prev->next = node->next;
    pthread_mutex_unlock(&node->lock);
}
```

Which of these (all run in parallel) can deadlock?

- A. RemoveNode(B) and RemoveNode(C)
- B. RemoveNode(B) and RemoveNode(D)
- C. RemoveNode(D) and RemoveNode(C) and RemoveNode(D)
- D. A and C E. B and C
- F. all of the above G. none of the above

how is deadlock — solution

Remove B	Remove C
lock B	lock C
lock A (prev)	wait to lock B (prev)
wait to lock C (next)	

With B and D — only overlap in in node C — no circular wait possible (thread can't be waiting while holding something other thread wants)

infinite resources no mutual exclusion or at least enough that never run out no shared resources no mutual exclusion no waiting no hold and wait/ "busy signal" — abort and (maybe) retry preemption revoke/preempt resources acquire resources in consistent order no circular wait request all resources at once no hold and wait

deadlock prevention techniques

"busy signal" — abort and (maybe) retry preemption acquire resources in consistent order no circular wait no hold and wait

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deadlock prevention techniques

infinite resources

or at least enough that never run out

revoke/preempt resources

request all resources at once

no mutual exclusion

no shared resources

no waiting

no mutual exclusion

no hold and wait/

deadlock prevention techniques infinite resources no mutual exclusion or at least enough that never run out no shared resources no mutual exclusion no waiting no hold and wait/ "busy signal" — abort and (maybe) retry preemption revoke/preempt resources acquire resources in consistent order no circular wait request all resources at once no hold and wait

deadlock prevention techniques





deadlock prevention techniques

or at least enough that never run out

no mutual exclusion

no share no waiti "busy signal" — abort and (maybe) retry revoke/preempt resources
"exclusion" exclusion" e

acquire resources in **consistent order** no *circular wait*

request all resources at once no hold and wait

infinite resources no mutual exclusion or at least enough that never run out no shared resources no mutual exclusion no waiting no hold and wait/ "busy signal" — abort and (maybe) retry preemption revoke/preempt resources acquire resources in *consistent order* no circular wait request all resources at once no hold and wait

deadlock prevention techniques

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acquiring locks in consistent order (1)

```
MoveFile(Dir* from_dir, Dir* to_dir, string filename) {
    if (from_dir->path < to_dir->path) {
        lock(&from_dir->lock);
        lock(&to_dir->lock);
    } else {
        lock(&to_dir->lock);
        lock(&from_dir->lock);
        lock(&from_dir->lock);
    }
    ...
```

acquiring locks in consistent order (1)

```
MoveFile(Dir* from_dir, Dir* to_dir, string filename) {
  if (from dir->path < to dir->path) {
    lock(&from dir->lock):
    lock(&to dir->lock);
  } else {
    lock(&to dir->lock);
    lock(&from dir->lock);
  }
                      any ordering will do
                      e.g. compare pointers
```

acquiring locks in consistent order (2)

often by convention, e.g. Linux kernel comments:

```
/*
   lock order:
*
        contex.ldt usr sem
*
          mmap_sem
*
            context.lock
*/
/*
   lock order:
*
   1. slab mutex (Global Mutex)
*
   2. node->list_lock
*
   3. slab_lock(page) (Only on some arches and for debugging)
*
* /
```

infinite resources no mutual exclusion or at least enough that never run out no shared resources no mutual exclusion no waiting no hold and wait/ "busy signal" — abort and (maybe) retry preemption revoke/preempt resources acquire resources in consistent order no circular wait request all resources at once no hold and wait

deadlock prevention techniques

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