

Performance

Changelog

Changes made in this version not seen in first lecture:

26 October 2017: slide 28: remove extraneous text from code

locality exercise (1)

```
/* version 1 */  
for (int i = 0; i < N; ++i)  
    for (int j = 0; j < N; ++j)  
        A[i] += B[j] * C[i * N + j]  
  
/* version 2 */  
for (int j = 0; j < N; ++j)  
    for (int i = 0; i < N; ++i)  
        A[i] += B[j] * C[i * N + j];
```

exercise: which has better temporal locality in A? in B? in C?
how about spatial locality?

a transformation

```
for (int kk = 0; kk < N; kk += 2)
    for (int k = kk; k < kk + 2; ++k)
        for (int i = 0; i < N; i += 2)
            for (int j = 0; j < N; ++j)
                B[i*N+j] += A[i*N+k] * A[k*N+j];
```

split the loop over k — should be exactly the same
(assuming even N)

a transformation

```
for (int kk = 0; kk < N; kk += 2)
    for (int k = kk; k < kk + 2; ++k)
        for (int i = 0; i < N; i += 2)
            for (int j = 0; j < N; ++j)
                B[i*N+j] += A[i*N+k] * A[k*N+j];
```

split the loop over k — should be exactly the same
(assuming even N)

simple blocking

```
for (int kk = 0; kk < N; kk += 2)
    /* was here: for (int k = kk; k < kk + 2; ++k) */
    for (int i = 0; i < N; i += 2)
        for (int j = 0; j < N; ++j)
            /* load Aik, Aik+1 into cache and process: */
            for (int k = kk; k < kk + 2; ++k)
                B[i*N+j] += A[i*N+k] * A[k*N+j];
```

now **reorder** split loop — same calculations

simple blocking

```
for (int kk = 0; kk < N; kk += 2)
    /* was here: for (int k = kk; k < kk + 2; ++k) */
    for (int i = 0; i < N; i += 2)
        for (int j = 0; j < N; ++j)
            /* load Aik, Aik+1 into cache and process: */
            for (int k = kk; k < kk + 2; ++k)
                B[i*N+j] += A[i*N+k] * A[k*N+j];
```

now **reorder** split loop — same calculations

now handle B_{ij} for $k + 1$ right after B_{ij} for k

(previously: $B_{i,j+1}$ for k right after B_{ij} for k)

simple blocking

```
for (int kk = 0; kk < N; kk += 2)
    /* was here: for (int k = kk; k < kk + 2; ++k) */
    for (int i = 0; i < N; i += 2)
        for (int j = 0; j < N; ++j)
            /* load Aik, Aik+1 into cache and process: */
            for (int k = kk; k < kk + 2; ++k)
                B[i*N+j] += A[i*N+k] * A[k*N+j];
```

now **reorder** split loop — same calculations

now handle B_{ij} for $k + 1$ right after B_{ij} for k

(previously: $B_{i,j+1}$ for k right after B_{ij} for k)

simple blocking – expanded

```
for (int kk = 0; kk < N; kk += 2) {  
    for (int i = 0; i < N; i += 2) {  
        for (int j = 0; j < N; ++j) {  
            /* process a "block" of 2 k values: */  
            B[i*N+j] += A[i*N+kk+0] * A[(kk+0)*N+j];  
            B[i*N+j] += A[i*N+kk+1] * A[(kk+1)*N+j];  
        }  
    }  
}
```

simple blocking – expanded

```
for (int kk = 0; kk < N; kk += 2) {  
    for (int i = 0; i < N; i += 2) {  
        for (int j = 0; j < N; ++j) {  
            /* process a "block" of 2 k values: */  
            B[i*N+j] += A[i*N+kk+0] * A[(kk+0)*N+j];  
            B[i*N+j] += A[i*N+kk+1] * A[(kk+1)*N+j];  
        }  
    }  
}
```

Temporal locality in B_{ij} s

simple blocking – expanded

```
for (int kk = 0; kk < N; kk += 2) {  
    for (int i = 0; i < N; i += 2) {  
        for (int j = 0; j < N; ++j) {  
            /* process a "block" of 2 k values: */  
            B[i*N+j] += A[i*N+kk+0] * A[(kk+0)*N+j];  
            B[i*N+j] += A[i*N+kk+1] * A[(kk+1)*N+j];  
        }  
    }  
}
```

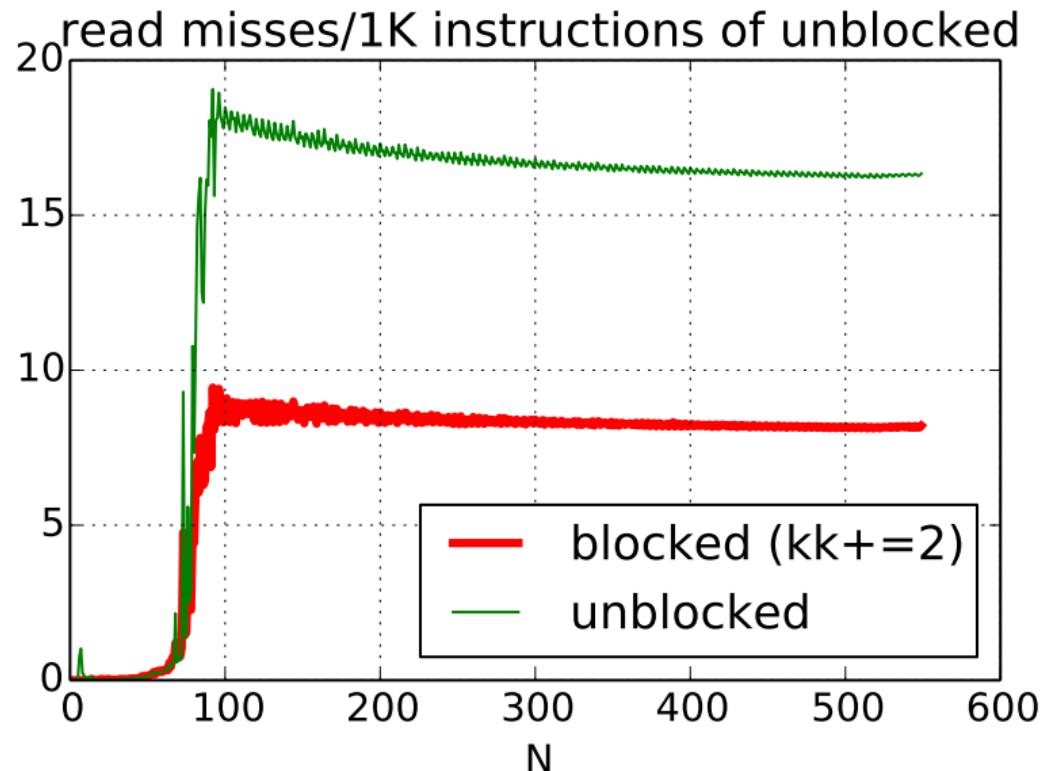
More spatial locality in A_{ik}

simple blocking – expanded

```
for (int kk = 0; kk < N; kk += 2) {  
    for (int i = 0; i < N; i += 2) {  
        for (int j = 0; j < N; ++j) {  
            /* process a "block" of 2 k values: */  
            B[i*N+j] += A[i*N+kk+0] * A[(kk+0)*N+j];  
            B[i*N+j] += A[i*N+kk+1] * A[(kk+1)*N+j];  
        }  
    }  
}
```

Still have good spatial locality in A_{kj} , B_{ij}

improvement in read misses



simple blocking (2)

same thing for i in addition to k ?

```
for (int kk = 0; kk < N; kk += 2) {  
    for (int ii = 0; ii < N; ii += 2) {  
        for (int j = 0; j < N; ++j) {  
            /* process a "block": */  
            for (int k = kk; k < kk + 2; ++k)  
                for (int i = 0; i < ii + 2; ++i)  
                    B[i*N+j] += A[i*N+k] * A[k*N+j];  
    }  
}
```

simple blocking — expanded

```
for (int k = 0; k < N; k += 2) {  
    for (int i = 0; i < N; i += 2) {  
        /* load a block around Aik */  
        for (int j = 0; j < N; ++j) {  
            /* process a "block": */  
             $B_{i+0,j} += A_{i+0,k+0} * A_{k+0,j}$   
             $B_{i+0,j} += A_{i+0,k+1} * A_{k+1,j}$   
             $B_{i+1,j} += A_{i+1,k+0} * A_{k+0,j}$   
             $B_{i+1,j} += A_{i+1,k+1} * A_{k+1,j}$   
        }  
    }  
}
```

simple blocking — expanded

```
for (int k = 0; k < N; k += 2) {  
    for (int i = 0; i < N; i += 2) {  
        /* load a block around Aik */  
        for (int j = 0; j < N; ++j) {  
            /* process a "block": */  
            Bi+0,j += Ai+0,k+0 * Ak+0,j  
            Bi+0,j += Ai+0,k+1 * Ak+1,j  
            Bi+1,j += Ai+1,k+0 * Ak+0,j  
            Bi+1,j += Ai+1,k+1 * Ak+1,j  
        }  
    }  
}
```

Now A_{kj} reused in inner loop — more calculations per load!

generalizing cache blocking

```
for (int kk = 0; kk < N; kk += K) {  
    for (int ii = 0; ii < N; ii += I) {  
        with I by K block of A hopefully cached:  
        for (int jj = 0; jj < N; jj += J) {  
            with K by J block of A, I by J block of B cached:  
            for i in ii to ii+I:  
                for j in jj to jj+J:  
                    for k in kk to kk+K:  
                        B[i * N + j] += A[i * N + k]  
                            * A[k * N + j];
```

B_{ij} used K times for one miss — N^2/K misses

A_{ik} used J times for one miss — N^2/J misses

A_{kj} used I times for one miss — N^2/I misses

catch: $IK + KJ + IJ$ elements must **fit in cache**

generalizing cache blocking

```
for (int kk = 0; kk < N; kk += K) {  
    for (int ii = 0; ii < N; ii += I) {  
        with I by K block of A hopefully cached:  
        for (int jj = 0; jj < N; jj += J) {  
            with K by J block of A, I by J block of B cached:  
            for i in ii to ii+I:  
                for j in jj to jj+J:  
                    for k in kk to kk+K:  
                        B[i * N + j] += A[i * N + k]  
                            * A[k * N + j];
```

B_{ij} used K times for one miss — N^2/K misses

A_{ik} used J times for one miss — N^2/J misses

A_{kj} used I times for one miss — N^2/I misses

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generalizing cache blocking

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for (int kk = 0; kk < N; kk += K) {  
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        with I by K block of A hopefully cached:  
        for (int jj = 0; jj < N; jj += J) {  
            with K by J block of A, I by J block of B cached:  
            for i in ii to ii+I:  
                for j in jj to jj+J:  
                    for k in kk to kk+K:  
                        B[i * N + j] += A[i * N + k]  
                            * A[k * N + j];
```

B_{ij} used K times for one miss — N^2/K misses

A_{ik} used J times for one miss — N^2/J misses

A_{kj} used I times for one miss — N^2/I misses

catch: $IK + KJ + IJ$ elements must fit in cache

generalizing cache blocking

```
for (int kk = 0; kk < N; kk += K) {  
    for (int ii = 0; ii < N; ii += I) {  
        with I by K block of A hopefully cached:  
        for (int jj = 0; jj < N; jj += J) {  
            with K by J block of A, I by J block of B cached:  
            for i in ii to ii+I:  
                for j in jj to jj+J:  
                    for k in kk to kk+K:  
                        B[i * N + j] += A[i * N + k]  
                            * A[k * N + j];
```

B_{ij} used K times for one miss — N^2/K misses

A_{ik} used J times for one miss — N^2/J misses

A_{kj} used I times for one miss — N^2/I misses

catch: $IK + KJ + IJ$ elements must fit in cache

view 2: divide and conquer

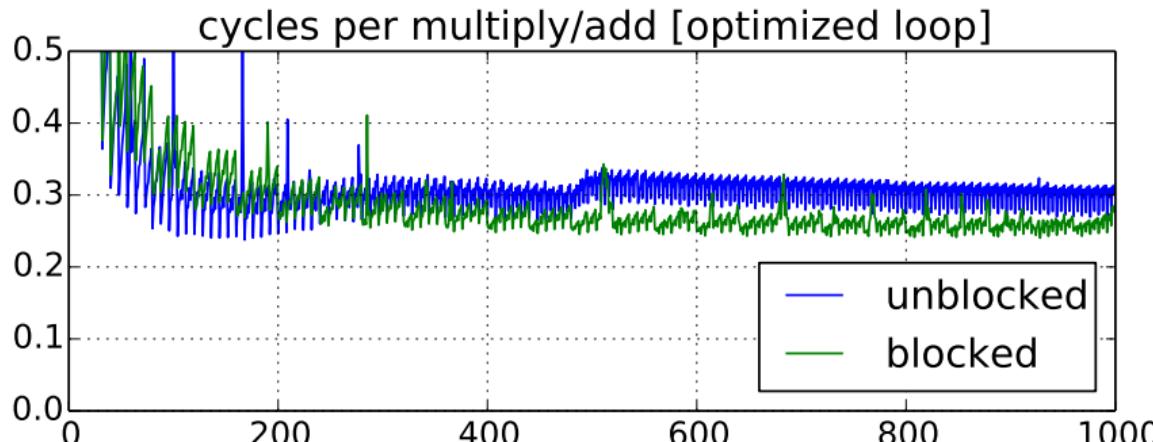
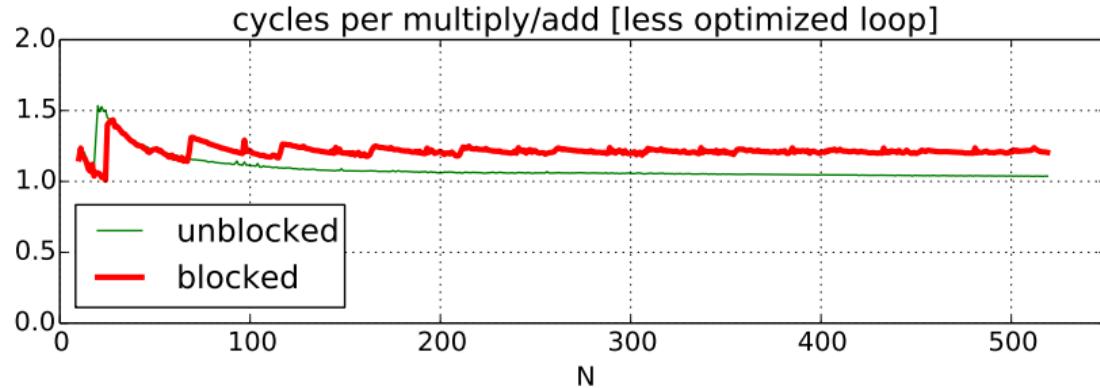
```
partial_square(float *A, float *B,
              int startI, int endI, ... ) {
    for (int i = startI; i < endI; ++i) {
        for (int j = startJ; j < endJ; ++j) {
            ...
        }
    }
}

square(float *A, float *B, int N) {
    for (int ii = 0; ii < N; ii += BLOCK)
        ...
    /* segment of A, B in use fits in cache! */
    partial_square(
        A, B,
        ii, ii + BLOCK,
        jj, jj + BLOCK, ... );
}
```

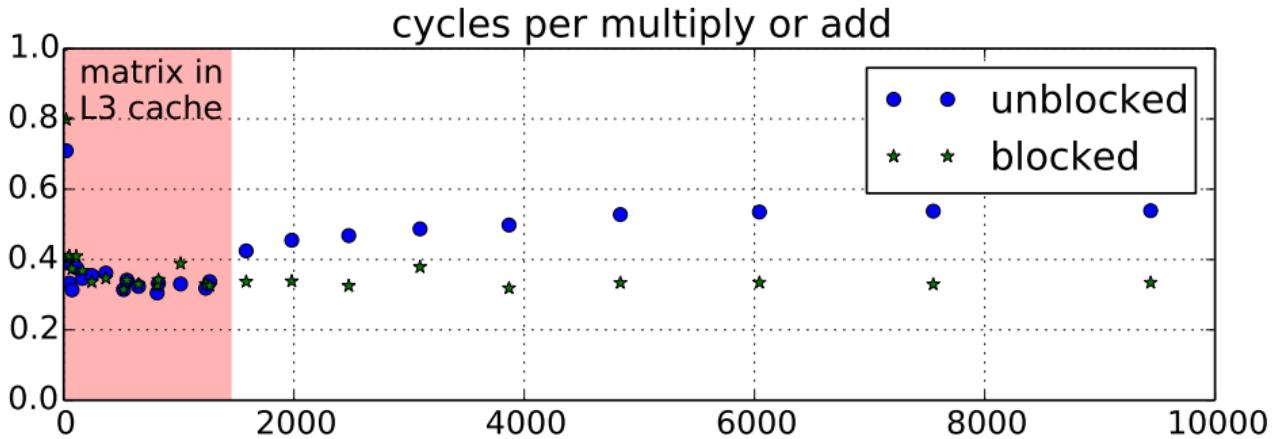
cache blocking and miss rate



what about performance?



performance for big sizes



optimized loop???

performance difference wasn't visible at small sizes
until I optimized **arithmetic** in the loop
(mostly by supplying better options to GCC)

- 1: reducing number of loads
- 2: doing adds/multiplies/etc. with less instructions
- 3: simplifying address computations

optimized loop???

performance difference wasn't visible at small sizes

until I optimized **arithmetic** in the loop

(mostly by supplying better options to GCC)

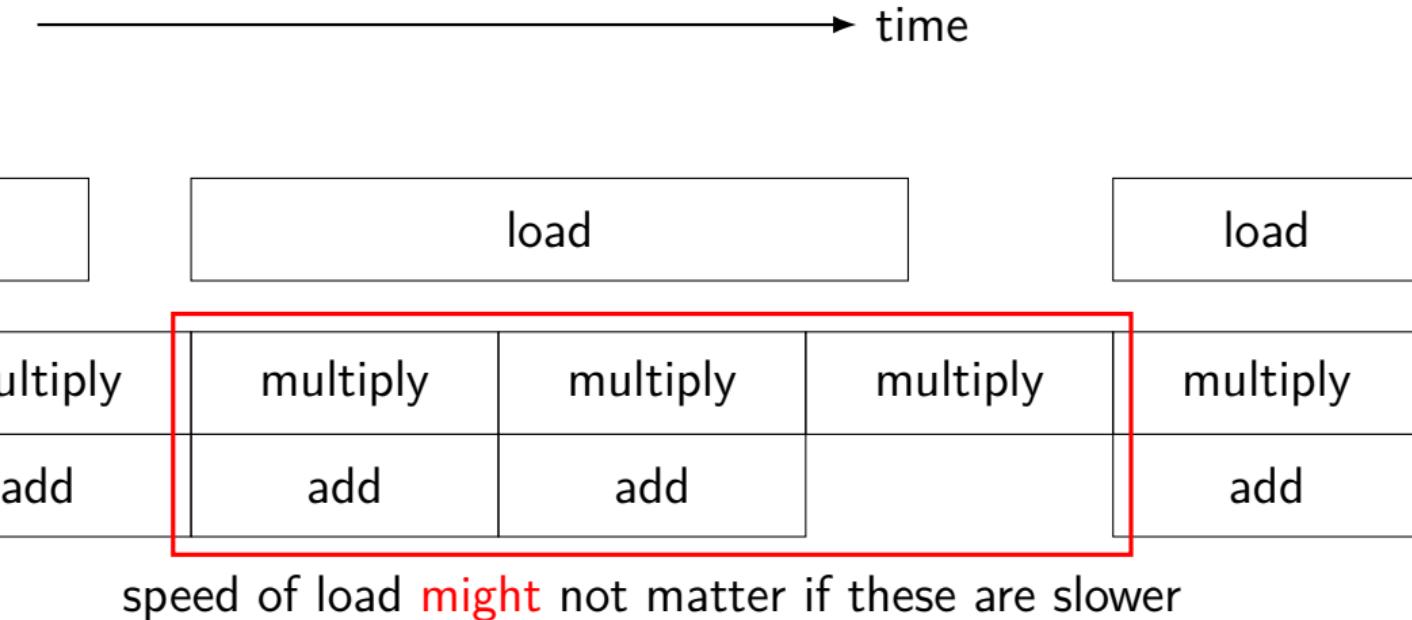
1: reducing number of loads

2: doing adds/multiplies/etc. with less instructions

3: simplifying address computations

but... how can that make cache blocking better???

overlapping loads and arithmetic



optimization and bottlenecks

arithmetic/loop efficiency was the **bottleneck**

after fixing this, cache performance was the bottleneck

common theme when optimizing:

X may not matter until Y is optimized

example assembly (unoptimized)

```
long sum(long *A, int N) {
    long result = 0;
    for (int i = 0; i < N; ++i)
        result += A[i];
    return result;
}

sum:    ...
the_loop:
...
    leaq    0(%rax,8), %rdx // offset ← i * 8
    movq    -24(%rbp), %rax // get A from stack
    addq    %rdx, %rax     // add offset
    movq    (%rax), %rax   // get *(A+offset)
    addq    %rax, -8(%rbp) // add to sum, on stack
    addl    $1, -12(%rbp)  // increment i
condition:
    movl    -12(%rbp), %eax
    cmpl    -28(%rbp), %eax
    jl     the_loop
```

example assembly (gcc 5.4 -Os)

```
long sum(long *A, int N) {
    long result = 0;
    for (int i = 0; i < N; ++i)
        result += A[i];
    return result;
}

sum:
    xorl    %edx, %edx
    xorl    %eax, %eax
the_loop:
    cmpl    %edx, %esi
    jle     done
    addq    (%rdi,%rdx,8), %rax
    incq    %rdx
    jmp     the_loop
done:
    ret
```

example assembly (gcc 5.4 -O2)

```
long sum(long *A, int N) {
    long result = 0;
    for (int i = 0; i < N; ++i)
        result += A[i];
    return result;
}
sum:
    testl    %esi, %esi
    jle     return_zero
    leal    -1(%rsi), %eax
    leaq    8(%rdi,%rax,8), %rdx // rdx=end of A
    xorl    %eax, %eax
the_loop:
    addq    (%rdi), %rax // add to sum
    addq    $8, %rdi      // advance pointer
    cmpq    %rdx, %rdi
    jne     the_loop
    rep ret
return_zero:   ...
```

optimizing compilers

these usually make your code fast

often not done by default

compilers and humans are good at **different kinds** of optimizations

compiler limitations

needs to generate code that does the same thing...

...even in corner cases that “obviously don’t matter”

often doesn’t ‘look into’ a method

 needs to assume it might do anything

can’t predict what inputs/values will be

 e.g. lots of loop iterations or few?

can’t understand code size versus speed tradeoffs

compiler limitations

needs to generate code that does the same thing...

...even in corner cases that “obviously don’t matter”

often doesn't ‘look into’ a method

 needs to assume it might do anything

can't predict what inputs/values will be

 e.g. lots of loop iterations or few?

can't understand code size versus speed tradeoffs

aliasing

```
void twiddle(long *px, long *py) {  
    *px += *py;  
    *px += *py;  
}
```

the compiler **cannot** generate this:

```
twiddle: // BROKEN // %rsi = px, %rdi = py  
        movq    (%rdi), %rax // rax ← *py  
        addq    %rax, %rax   // rax ← 2 * *py  
        addq    %rax, (%rsi) // *px ← 2 * *py  
        ret
```

aliasing problem

```
void twiddle(long *px, long *py) {  
    *px += *py;  
    *px += *py;  
    // NOT the same as *px += 2 * *py;  
}  
...  
long x = 1;  
twiddle(&x, &x);  
// result should be 4, not 3
```

```
twiddle: // BROKEN // %rsi = px, %rdi = py  
    movq    (%rdi), %rax // rax ← *py  
    addq    %rax, %rax   // rax ← 2 * *py  
    addq    %rax, (%rsi) // *px ← 2 * *py  
    ret
```

non-contrived aliasing

```
void sumRows1(int *result, int *matrix, int N) {  
    for (int row = 0; row < N; ++row) {  
        result[row] = 0;  
        for (int col = 0; col < N; ++col)  
            result[row] += matrix[row * N + col];  
    }  
}
```

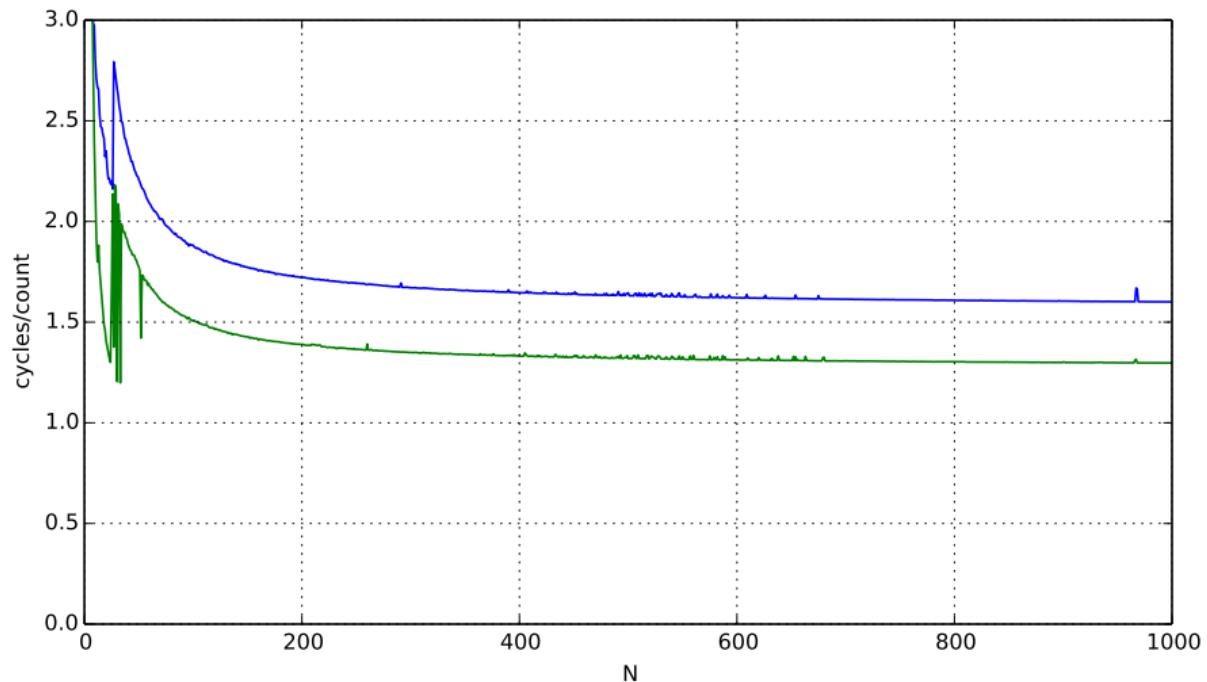
```
void sumRows2(int *result, int *matrix, int N) {  
    for (int row = 0; row < N; ++row) {  
        int sum = 0;  
        for (int col = 0; col < N; ++col)  
            sum += matrix[row * N + col];  
        result[row] = sum;  
    }  
}
```

non-contrived aliasing

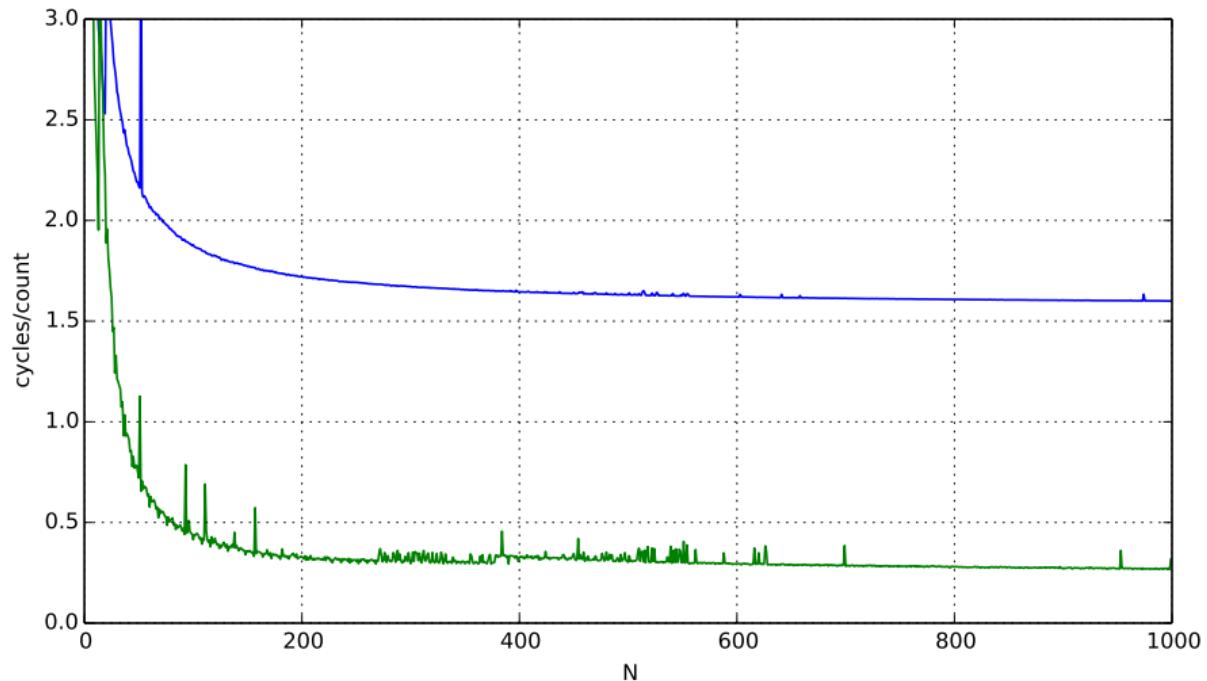
```
void sumRows1(int *result, int *matrix, int N) {  
    for (int row = 0; row < N; ++row) {  
        result[row] = 0;  
        for (int col = 0; col < N; ++col)  
            result[row] += matrix[row * N + col];  
    }  
}
```

```
void sumRows2(int *result, int *matrix, int N) {  
    for (int row = 0; row < N; ++row) {  
        int sum = 0;  
        for (int col = 0; col < N; ++col)  
            sum += matrix[row * N + col];  
        result[row] = sum;  
    }  
}
```

aliasing and performance (1) / GCC 5.4 -O2



aliasing and performance (2) / GCC 5.4 -O3



automatic register reuse

Compiler would need to generate overlap check:

```
if (result > matrix + N * N || result < matrix) {  
    for (int row = 0; row < N; ++row) {  
        int sum = 0; /* kept in register */  
        for (int col = 0; col < N; ++col)  
            sum += matrix[row * N + col];  
        result[row] = sum;  
    }  
} else {  
    for (int row = 0; row < N; ++row) {  
        result[row] = 0;  
        for (int col = 0; col < N; ++col)  
            result[row] += matrix[row * N + col];  
    }  
}
```

aliasing and cache optimizations

```
for (int k = 0; k < N; ++k)
    for (int i = 0; i < N; ++i)
        for (int j = 0; j < N; ++j)
            B[i*N+j] += A[i * N + k] * A[k * N + j];
```

```
for (int i = 0; i < N; ++i)
    for (int j = 0; k < N; ++j)
        for (int k = 0; k < N; ++k)
            B[i*N+j] += A[i * N + k] * A[k * N + j];
```

B = A? B = &A[10]?

compiler can't generate same code for both

“register blocking”

```
for (int k = 0; k < N; ++k) {  
    for (int i = 0; i < N; i += 2) {  
        float Ai0k = A[(i+0)*N + k];  
        float Ai1k = A[(i+1)*N + k];  
        for (int j = 0; j < N; j += 2) {  
            float Akj0 = A[k*N + j+0];  
            float Akj1 = A[k*N + j+1];  
            B[(i+0)*N + j+0] += Ai0k * Akj0;  
            B[(i+1)*N + j+0] += Ai1k * Akj0;  
            B[(i+0)*N + j+1] += Ai0k * Akj1;  
            B[(i+1)*N + j+1] += Ai1k * Akj1;  
        }  
    }  
}
```

avoiding redundant loads summary

move repeated load outside of loop

create variable — tell compiler “not aliased”

aside: the restrict hint

C has a keyword ‘restrict’ for pointers

“I promise this pointer doesn’t alias another”

(if it does — undefined behavior)

maybe will help compiler do optimization itself?

```
void square(float * restrict B, float * restrict A) {  
    ...  
}
```

compiler limitations

needs to generate code that does the same thing...

...even in corner cases that “obviously don’t matter”

often doesn't ‘look into’ a method

needs to assume it might do anything

can't predict what inputs/values will be

e.g. lots of loop iterations or few?

can't understand code size versus speed tradeoffs

loop with a function call

```
int addWithLimit(int x, int y) {  
    int total = x + y;  
    if (total > 10000)  
        return 10000;  
    else  
        return total;  
}  
...  
int sum(int *array, int n) {  
    int sum = 0;  
    for (int i = 0; i < n; i++)  
        sum = addWithLimit(sum, array[i]);  
    return sum;  
}
```

loop with a function call

```
int addWithLimit(int x, int y) {  
    int total = x + y;  
    if (total > 10000)  
        return 10000;  
    else  
        return total;  
}  
...  
int sum(int *array, int n) {  
    int sum = 0;  
    for (int i = 0; i < n; i++)  
        sum = addWithLimit(sum, array[i]);  
    return sum;  
}
```

function call assembly

```
movl (%rbx), %esi // mov array[i]
movl %eax, %edi   // mov sum
call addWithLimit
```

extra instructions executed: two moves, a call, and a ret

manual inlining

```
int sum(int *array, int n) {  
    int sum = 0;  
    for (int i = 0; i < n; i++) {  
        sum = sum + array[i];  
        if (sum > 10000)  
            sum = 10000;  
    }  
    return sum;  
}
```

inlining pro/con

avoids call, ret, extra move instructions

allows compiler to **use more registers**

no caller-saved register problems

but not always faster:

worse for instruction cache

(more copies of function body code)

compiler inlining

compilers will inline, but...

will usually **avoid making code much bigger**

heuristic: inline if function is small enough

heuristic: inline if called exactly once

will usually **not inline across .o files**

some compilers allow hints to say “please inline/do not inline this function”

remove redundant operations (1)

```
char number_of_As(const char *str) {  
    int count = 0;  
    for (int i = 0; i < strlen(str); ++i) {  
        if (str[i] == 'a')  
            count++;  
    }  
    return count;  
}
```

remove redundant operations (1, fix)

```
int number_of_As(const char *str) {  
    int count = 0;  
    int length = strlen(str);  
    for (int i = 0; i < length; ++i) {  
        if (str[i] == 'a')  
            count++;  
    }  
    return count;  
}
```

call strlen once, not once per character!

Big-Oh improvement!

remove redundant operations (1, fix)

```
int number_of_As(const char *str) {  
    int count = 0;  
    int length = strlen(str);  
    for (int i = 0; i < length; ++i) {  
        if (str[i] == 'a')  
            count++;  
    }  
    return count;  
}
```

call `strlen` once, not once per character!

Big-Oh improvement!

remove redundant operations (2)

```
int shiftArray(int *source, int *dest, int N, int amount) {  
    for (int i = 0; i < N; ++i) {  
        if (i + amount < N)  
            dest[i] = source[i + amount];  
        else  
            dest[i] = source[N - 1];  
    }  
}
```

compare $i + amount$ to N many times

remove redundant operations (2, fix)

```
int shiftArray(int *source, int *dest, int N, int amount) {  
    int i;  
    for (i = 0; i + amount < N; ++i) {  
        dest[i] = source[i + amount];  
    }  
    for (; i < N; ++i) {  
        dest[i] = source[N - 1];  
    }  
}
```

eliminate comparisons

compiler limitations

needs to generate code that does the same thing...

...even in corner cases that “obviously don’t matter”

often doesn't ‘look into’ a method

needs to assume it might do anything

can't predict what inputs/values will be

e.g. lots of loop iterations or few?

can't understand code size versus speed tradeoffs

loop unrolling (ASM)

loop:

```
    cmpl    %edx, %esi
    jle     endOfLoop
    addq    (%rdi,%rdx,8), %rax
    incq    %rdx
    jmp
```

endOfLoop:

loop:

```
    cmpl    %edx, %esi
    jle     endOfLoop
    addq    (%rdi,%rdx,8), %rax
    addq    8(%rdi,%rdx,8), %rax
    addq    $2, %rdx
    jmp     loop
    // plus handle leftover?
```

endOfLoop:

loop unrolling (ASM)

loop:

```
    cmpl    %edx, %esi
    jle     endOfLoop
    addq    (%rdi,%rdx,8), %rax
    incq    %rdx
    jmp
```

endOfLoop:

loop:

```
    cmpl    %edx, %esi
    jle     endOfLoop
    addq    (%rdi,%rdx,8), %rax
    addq    8(%rdi,%rdx,8), %rax
    addq    $2, %rdx
    jmp     loop
    // plus handle leftover?
```

endOfLoop:

loop unrolling (C)

```
for (int i = 0; i < N; ++i)
    sum += A[i];
```

```
int i;
for (i = 0; i + 1 < N; i += 2) {
    sum += A[i];
    sum += A[i+1];
}
// handle leftover, if needed
if (i < N)
    sum += A[i];
```

more loop unrolling (C)

```
int i;
for (i = 0; i + 4 <= N; i += 4) {
    sum += A[i];
    sum += A[i+1];
    sum += A[i+2];
    sum += A[i+3];
}
// handle leftover, if needed
for (; i < N; i += 1)
    sum += A[i];
```

automatic loop unrolling

loop unrolling is easy for compilers

...but often not done or done very much

why not?

automatic loop unrolling

loop unrolling is easy for compilers

...but often not done or done very much

why not?

slower if small number of iterations

larger code — could exceed instruction cache space

loop unrolling performance

on my laptop with 992 elements (fits in L1 cache)

times unrolled	cycles/element	instructions/element
1	1.33	4.02
2	1.03	2.52
4	1.02	1.77
8	1.01	1.39
16	1.01	1.21
32	1.01	1.15

instruction cache/etc. overhead

1.01 cycles/element — **latency bound**

interlude: real CPUs

modern CPUs:

execute **multiple instructions at once**

execute instructions **out of order** — whenever **values available**

beyond pipelining: out-of-order

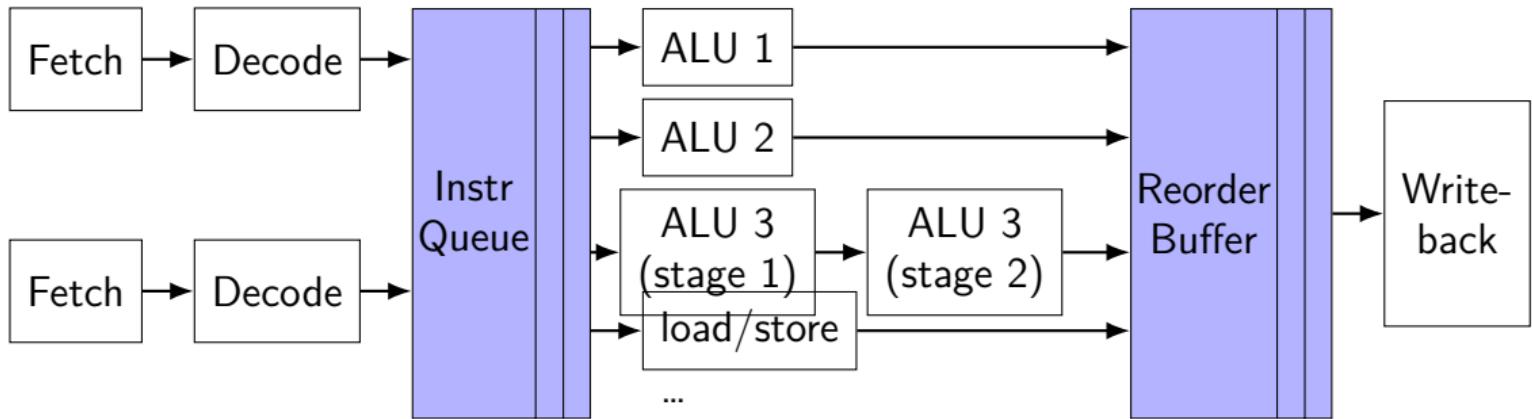
find later instructions to do instead of stalling

lists of available instructions in pipeline registers
take any instruction with available values

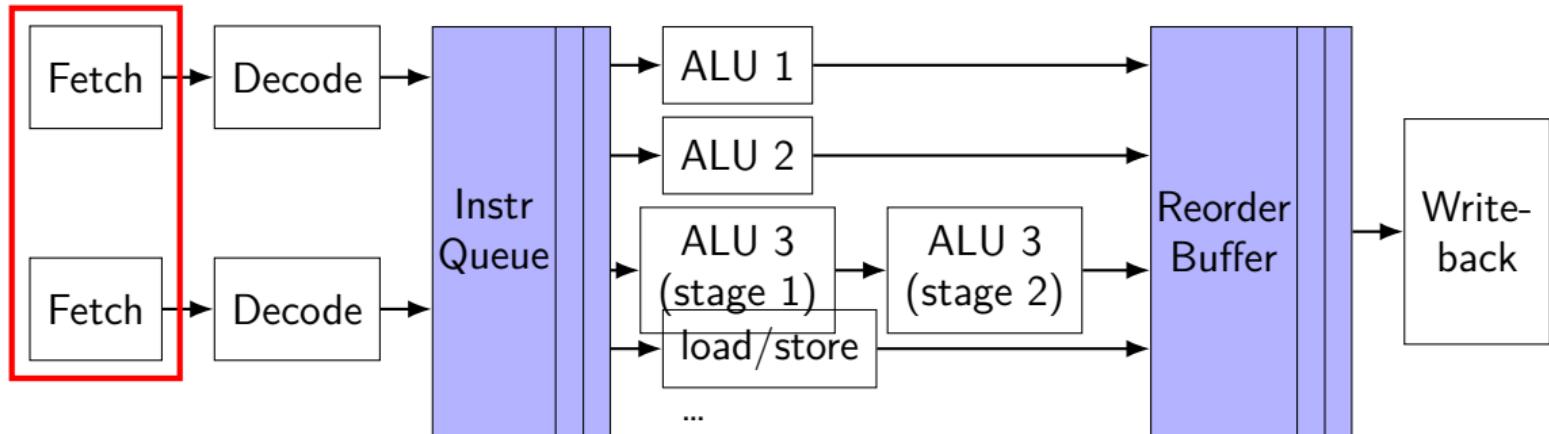
provide illusion that work is still done in order
much more complicated hazard handling logic

	cycle #	0	1	2	3	4	5	6	7	8
mrmovq 0(%rbx), %r8		F	D	E	M	M	M	W		
subq %r8, %r9			F					D	E	W
addq %r10, %r11				F	D	E				W
xorq %r12, %r13					F	D	E			W
...										

modern CPU design (instruction flow)

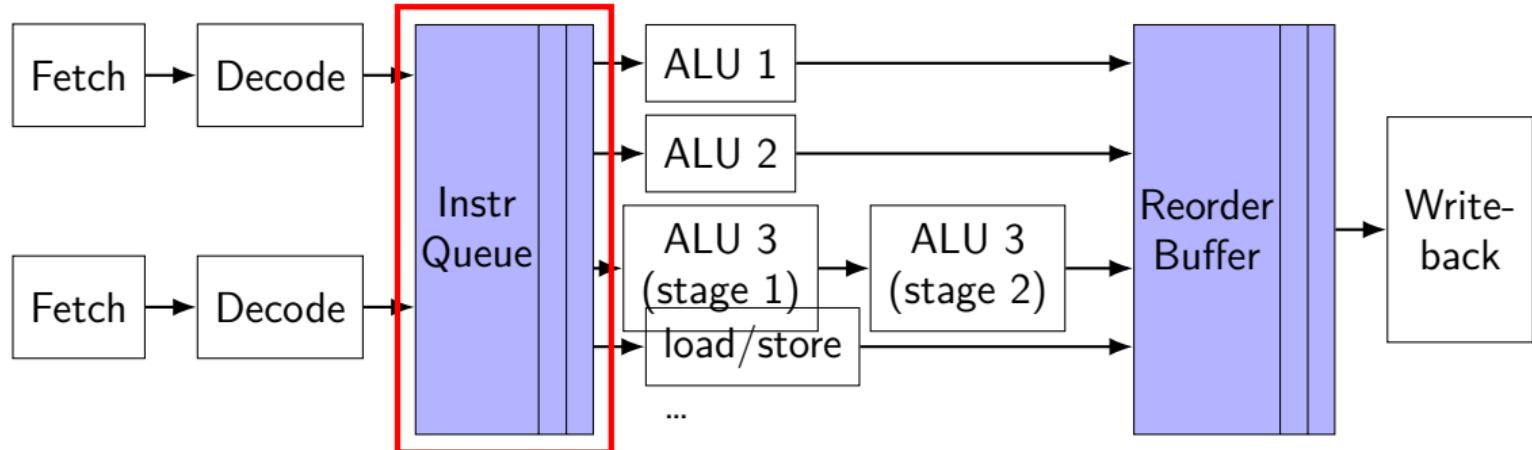


modern CPU design (instruction flow)



fetch multiple instructions/cycle

modern CPU design (instruction flow)

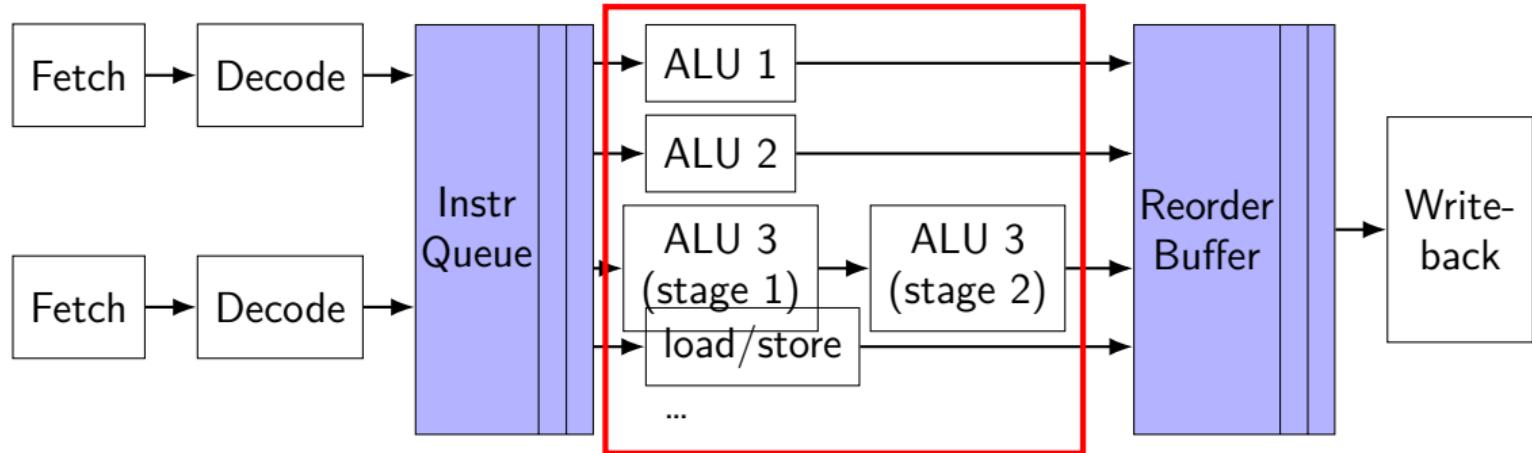


keep list of **pending instructions**

run instructions from list **when operands available**

forwarding handled here

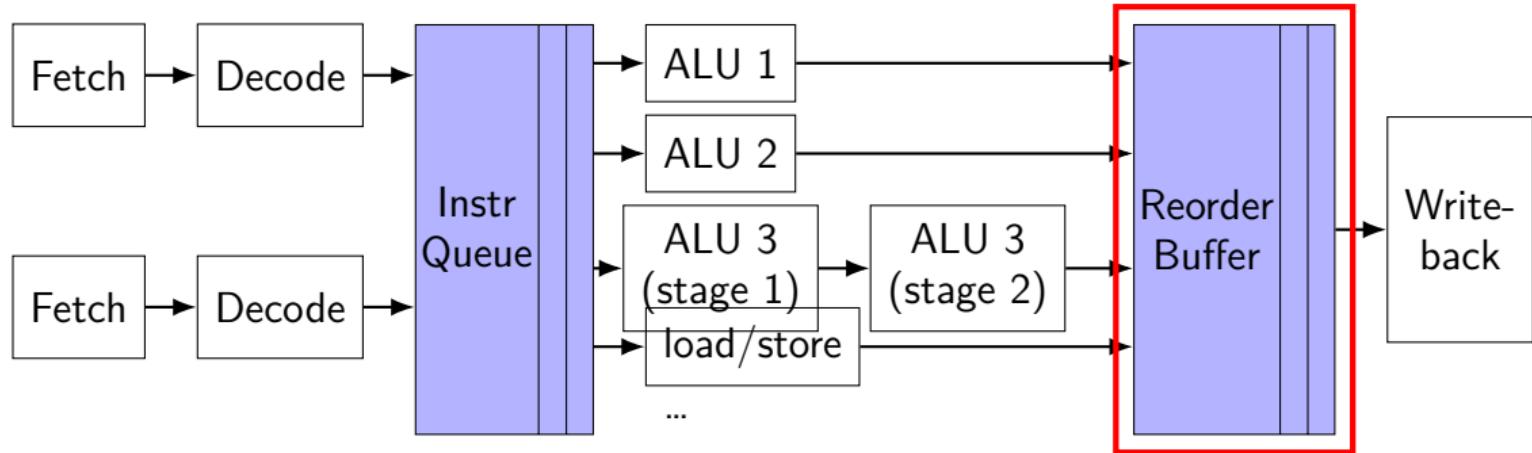
modern CPU design (instruction flow)



multiple “execution units” to run instructions
e.g. possibly many ALUs

sometimes pipelined, sometimes not

modern CPU design (instruction flow)



collect results of finished instructions

helps with forwarding, squashing

instruction queue operation

#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	ready
2	addq %rbx, %rdx	waiting for 1
3	addq %rcx, %rdx	waiting for 2
4	cmpq %r8, %rdx	waiting for 3
5	jne ...	waiting for 4
6	addq %rax, %rdx	waiting for 3
7	addq %rbx, %rdx	waiting for 6
8	addq %rcx, %rdx	waiting for 7
9	cmpq %r8, %rdx	waiting for 8

...

...

<i>execution unit</i>
ALU 1
ALU 2

...

instruction queue operation

#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	<i>running</i>
2	addq %rbx, %rdx	waiting for 1
3	addq %rcx, %rdx	waiting for 2
4	cmpq %r8, %rdx	waiting for 3
5	jne ...	waiting for 4
6	addq %rax, %rdx	waiting for 3
7	addq %rbx, %rdx	waiting for 6
8	addq %rcx, %rdx	waiting for 7
9	cmpq %r8, %rdx	waiting for 8

...

...

<i>execution unit</i>	<i>cycle# 1</i>	...
ALU 1	1	...
ALU 2	—	

instruction queue operation

#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	done
2	addq %rbx, %rdx	ready
3	addq %rcx, %rdx	waiting for 2
4	cmpq %r8, %rdx	waiting for 3
5	jne ...	waiting for 4
6	addq %rax, %rdx	waiting for 3
7	addq %rbx, %rdx	waiting for 6
8	addq %rcx, %rdx	waiting for 7
9	cmpq %r8, %rdx	waiting for 8

...

...

<i>execution unit</i>	<i>cycle#</i>	1	...
ALU 1		1	
ALU 2		—	

instruction queue operation

#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	done
2	addq %rbx, %rdx	<i>running</i>
3	addq %rcx, %rdx	waiting for 2
4	cmpq %r8, %rdx	waiting for 3
5	jne ...	waiting for 4
6	addq %rax, %rdx	waiting for 3
7	addq %rbx, %rdx	waiting for 6
8	addq %rcx, %rdx	waiting for 7
9	cmpq %r8, %rdx	waiting for 8

...

...

<i>execution unit</i>	<i>cycle#</i>	1	2	...
ALU 1		1	2	
ALU 2		—	—	

instruction queue operation

#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	done
2	addq %rbx, %rdx	done
3	addq %rcx, %rdx	<i>running</i>
4	cmpq %r8, %rdx	waiting for 3
5	jne ...	waiting for 4
6	addq %rax, %rdx	waiting for 3
7	addq %rbx, %rdx	waiting for 6
8	addq %rcx, %rdx	waiting for 7
9	cmpq %r8, %rdx	waiting for 8

...

...

<i>execution unit</i>	<i>cycle#</i>	1	2	3	...
ALU 1		1	2	3	
ALU 2		—	—	—	

instruction queue operation

#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	done
2	addq %rbx, %rdx	done
3	addq %rcx, %rdx	done
4	cmpq %r8, %rdx	ready
5	jne ...	waiting for 4
6	addq %rax, %rdx	ready
7	addq %rbx, %rdx	waiting for 6
8	addq %rcx, %rdx	waiting for 7
9	cmpq %r8, %rdx	waiting for 8

...

...

<i>execution unit</i>	<i>cycle#</i>	1	2	3	...
ALU 1		1	2	3	
ALU 2		—	—	—	

instruction queue operation

#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	done
2	addq %rbx, %rdx	done
3	addq %rcx, %rdx	done
4	cmpq %r8, %rdx	<i>running</i>
5	jne ...	waiting for 4
6	addq %rax, %rdx	<i>running</i>
7	addq %rbx, %rdx	waiting for 6
8	addq %rcx, %rdx	waiting for 7
9	cmpq %r8, %rdx	waiting for 8

...

...

<i>execution unit</i>	<i>cycle#</i>	1	2	3	4	...
ALU 1		1	2	3	4	
ALU 2		—	—	—	6	

instruction queue operation

#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	done
2	addq %rbx, %rdx	done
3	addq %rcx, %rdx	done
4	cmpq %r8, %rdx	done
5	jne ...	ready
6	addq %rax, %rdx	done
7	addq %rbx, %rdx	ready
8	addq %rcx, %rdx	waiting for 7
9	cmpq %r8, %rdx	waiting for 8

...

...

<i>execution unit</i>	<i>cycle#</i>	1	2	3	4	...
ALU 1		1	2	3	4	
ALU 2		—	—	—	6	

instruction queue operation

#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	done
2	addq %rbx, %rdx	done
3	addq %rcx, %rdx	done
4	cmpq %r8, %rdx	done
5	jne ...	done
6	addq %rax, %rdx	done
7	addq %rbx, %rdx	<i>running</i>
8	addq %rcx, %rdx	waiting for 7
9	cmpq %r8, %rdx	waiting for 8

...

...

<i>execution unit</i>	<i>cycle#</i>	1	2	3	4	5	...
ALU 1		1	2	3	4	5	
ALU 2		—	—	—	6	7	

instruction queue operation

#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	done
2	addq %rbx, %rdx	done
3	addq %rcx, %rdx	done
4	cmpq %r8, %rdx	done
5	jne ...	done
6	addq %rax, %rdx	done
7	addq %rbx, %rdx	done
8	addq %rcx, %rdx	<i>running</i>
9	cmpq %r8, %rdx	waiting for 8

...

...

<i>execution unit</i>	<i>cycle#</i>	1	2	3	4	5	6	...
ALU 1		1	2	3	4	5	8	
ALU 2		—	—	—	6	7	—	

instruction queue operation

#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	done
2	addq %rbx, %rdx	done
3	addq %rcx, %rdx	done
4	cmpq %r8, %rdx	done
5	jne ...	done
6	addq %rax, %rdx	done
7	addq %rbx, %rdx	done
8	addq %rcx, %rdx	done
9	cmpq %r8, %rdx	<i>running</i>

...

...

<i>execution unit</i>	<i>cycle#</i>	1	2	3	4	5	6	7	...
ALU 1		1	2	3	4	5	8	9	
ALU 2		—	—	—	6	7	—	...	

instruction queue operation

#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	done
2	addq %rbx, %rdx	done
3	addq %rcx, %rdx	done
4	cmpq %r8, %rdx	done
5	jne ...	done
6	addq %rax, %rdx	done
7	addq %rbx, %rdx	done
8	addq %rcx, %rdx	done
9	cmpq %r8, %rdx	done

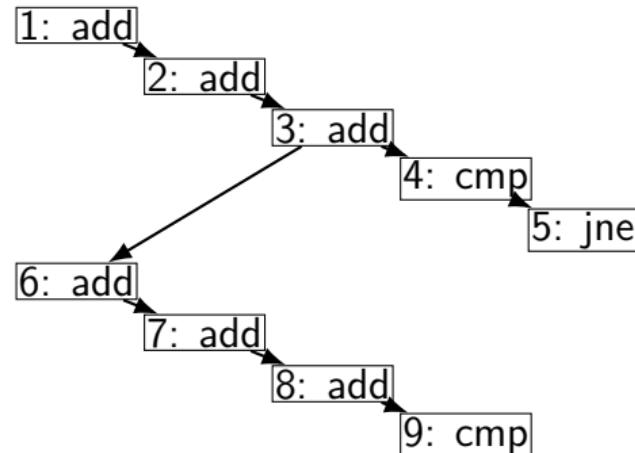
...

...

<i>execution unit</i>	<i>cycle#</i>	1	2	3	4	5	6	7	...
ALU 1		1	2	3	4	5	8	9	
ALU 2		—	—	—	6	7	—	...	

data flow

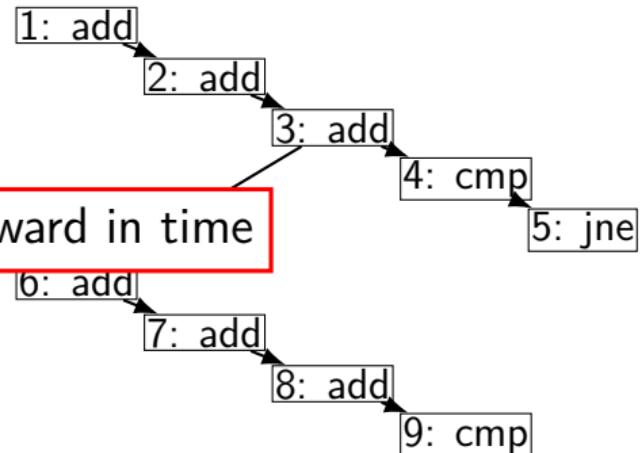
#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	done
2	addq %rbx, %rdx	done
3	addq %rcx, %rdx	done
4	cmpq %r8, %rdx	done
5	jne ...	done
6	addq %rax, %rdx	done
7	addq %rbx, %rdx	done
8	addq %rcx, %rdx	done
9	cmpq %r8, %rdx	done
...	...	



<i>execution unit</i>	<i>cycle#</i>	1	2	3	4	5	6	7	...
ALU 1		1	2	3	4	5	8	9	
ALU 2		—	—	—	6	7	—	...	

data flow

#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	done
2	addq %rbx, %rdx	done
3	addq %rcx, %rdx	done
4	cmpq %r8, %rdx	done
5	jne ...	rule: arrows must go forward in time
6	addq %rax, %rax	done
7	addq %rbx, %rdx	done
8	addq %rcx, %rdx	done
9	cmpq %r8, %rdx	done
...	...	

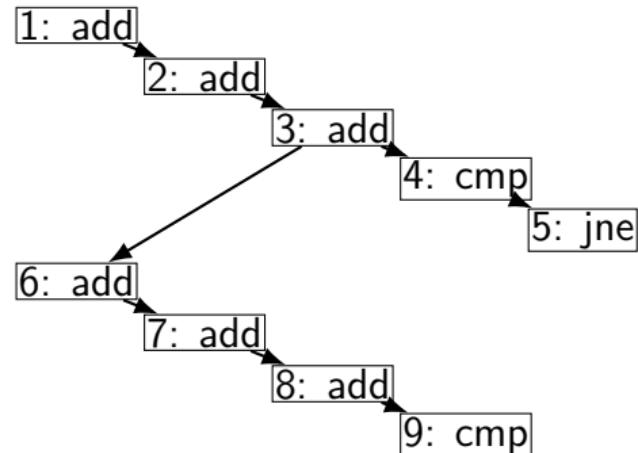


<i>execution unit</i>	cycle# 1	2	3	4	5	6	7	...
ALU 1	1	2	3	4	5	8	9	
ALU 2	—	—	—	6	7	—	...	

data flow

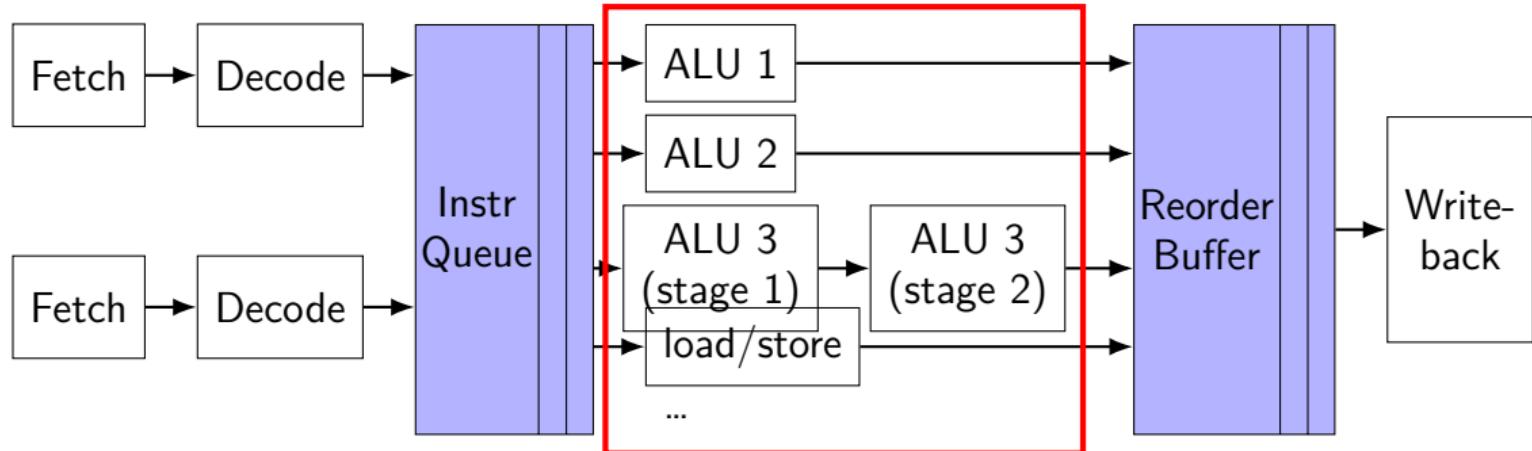
#	<i>instruction</i>	<i>status</i>
1	addq %rax, %rdx	done
2	addq %rbx, %rdx	done
3	addq %rcx, %rdx	done
4	cmpq %r8, %rdx	done
5	jne ...	done
6	ad	longest path determines speed
7	addq %rdx, %rax	done
8	addq %rcx, %rdx	done
9	cmpq %r8, %rdx	done

... ...



<i>execution unit</i>	<i>cycle#</i>	1	2	3	4	5	6	7	...
ALU 1		1	2	3	4	5	8	9	
ALU 2		—	—	—	6	7	—	...	

modern CPU design (instruction flow)



multiple “execution units” to run instructions
e.g. possibly many ALUs

sometimes pipelined, sometimes not

constant multiplies/divides (1)

```
unsigned int fiveEights(unsigned int x) {  
    return x * 5 / 8;  
}
```

```
fiveEights:  
    leal    (%rdi,%rdi,4), %eax  
    shr    $3, %eax  
    ret
```

constant multiplies/divides (2)

```
int oneHundredth(int x) { return x / 100; }
```

oneHundredth:

```
    movl    %edi, %eax
    movl    $1374389535, %edx
    sarl    $31, %edi
    imull   %edx
    sarl    $5, %edx
    movl    %edx, %eax
    subl    %edi, %eax
    ret
```

$$\frac{1374389535}{2^{37}} \approx \frac{1}{100}$$

constant multiplies/divides

compiler is very good at handling

...but need to actually use constants

addressing efficiency

```
for (int i = 0; i < N; ++i) {  
    for (int j = 0; j < N; ++j) {  
        float Bij = B[i * N + j];  
        for (int k = kk; k < kk + 2; ++k) {  
            Bij += A[i * N + k] * A[k * N + j];  
        }  
        B[i * N + j] = Bij;  
    }  
}
```

tons of multiplies by N??

isn't that slow?

addressing transformation

```
for (int kk = 0; k < N; kk += 2 )  
    for (int i = 0; i < N; ++i) {  
        for (int j = 0; j < N; ++j) {  
            float Bij = B[i * N + j];  
            float *Akj_pointer = &A[kk * N + j];  
            for (int k = kk; k < kk + 2; ++k) {  
                // Bij += A[i * N + k] * A[k * N + j~];  
                Bij += A[i * N + k] * Akj_pointer;  
                Akj_pointer += N;  
            }  
            B[i * N + j] = Bij;  
        }  
    }
```

transforms loop to iterate with pointer

compiler will usually do this!

increment/decrement by N ($\times \text{sizeof(float)}$)

addressing transformation

```
for (int kk = 0; k < N; kk += 2 )  
    for (int i = 0; i < N; ++i) {  
        for (int j = 0; j < N; ++j) {  
            float Bij = B[i * N + j];  
            float *Akj_pointer = &A[kk * N + j];  
            for (int k = kk; k < kk + 2; ++k) {  
                // Bij += A[i * N + k] * A[k * N + j~];  
                Bij += A[i * N + k] * Akj_pointer;  
                Akj_pointer += N;  
            }  
            B[i * N + j] = Bij;  
        }  
    }
```

transforms loop to iterate with pointer

compiler will usually do this!

increment/decrement by N ($\times \text{sizeof}(\text{float})$)

addressing efficiency

compiler will **usually** eliminate slow multiplies

doing transformation yourself often slower if so

```
i * N; ++i into i_times_N; i_times_N += N
```

way to check: see if assembly uses lots multiplies in loop

if it doesn't — do it yourself

cache blocking ugliness — fringe

```
for (int kk = 0; kk < N; kk += K) {  
    for (int ii = 0; ii < N; ii += I) {  
        for (int jj = 0; jj < N; jj += J) {  
            for (int k = kk; k < min(kk + K, N) ; ++k) {  
                // ...  
            }  
        }  
    }  
}
```

cache blocking ugliness — fringe

```
for (kk = 0; kk + K <= N; kk += K) {  
    for (ii = 0; ii + I <= N; ii += I) {  
        for (jj = 0; jj + J <= N; ii += J) {  
            // ...  
        }  
        for (; jj < N; ++jj) {  
            // handle remainder  
        }  
    }  
    for (; ii < N; ++ii) {  
        // handle remainder  
    }  
}  
for (; kk < N; ++kk) {  
    // handle remainder  
}
```

avoiding conflict misses

problem — array is scattered throughout memory

observation: 32KB cache can store 32KB contiguous array

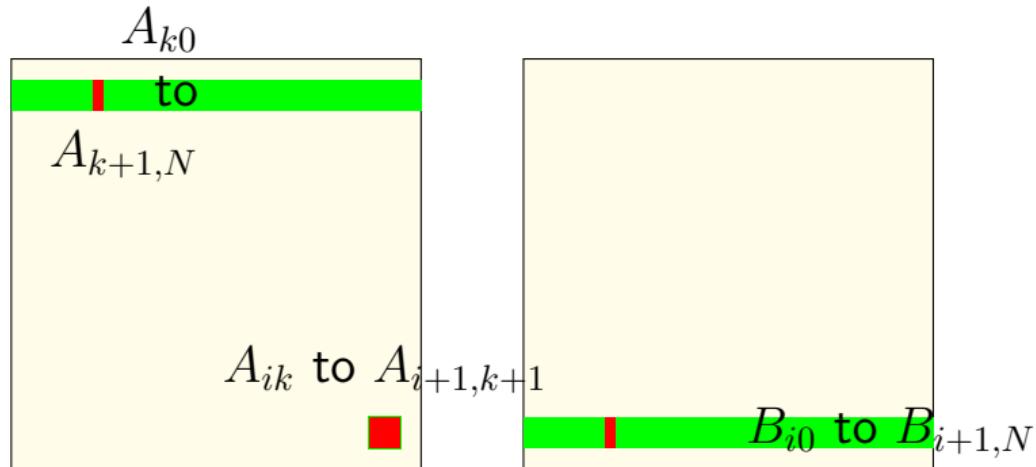
contiguous array is **split evenly** among sets

solution: **copy block into contiguous array**

avoiding conflict misses (code)

```
process_block(ii, jj, kk) {  
    float B_copy[I * J];  
    /* pseudocode for loop to save space */  
    for i = ii to ii + I, j = jj to jj + J:  
        B_copy[i * J + j] = B[i * N + j];  
    for i = ii to ii + I, j = jj to jj + J, k:  
        B_copy[i * J + j] += A[k * N + j] * A[i * N + k];  
    for all i, j:  
        B[i * N + j] = B_copy[i * J + j];  
}
```

array usage (better)



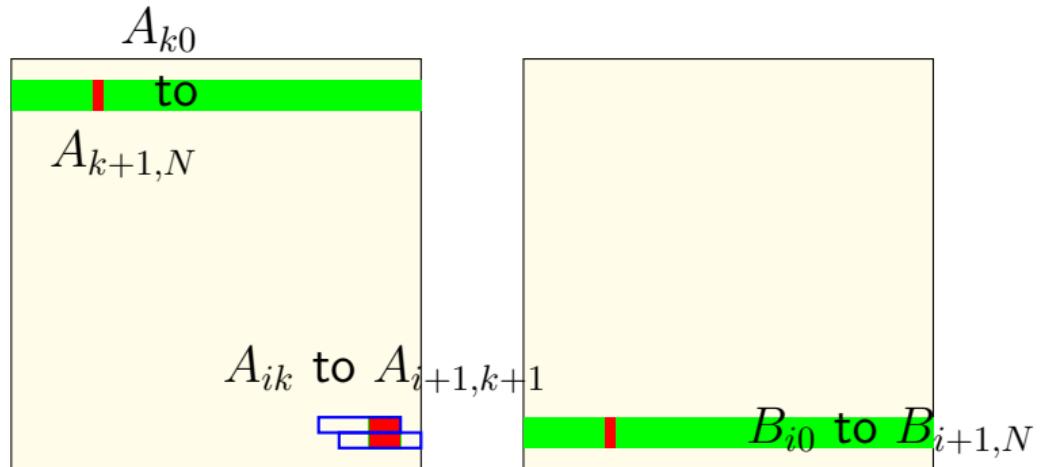
more **temporal** locality:

N calculations for each A_{ik}

2 calculations for each B_{ij} (for $k, k + 1$)

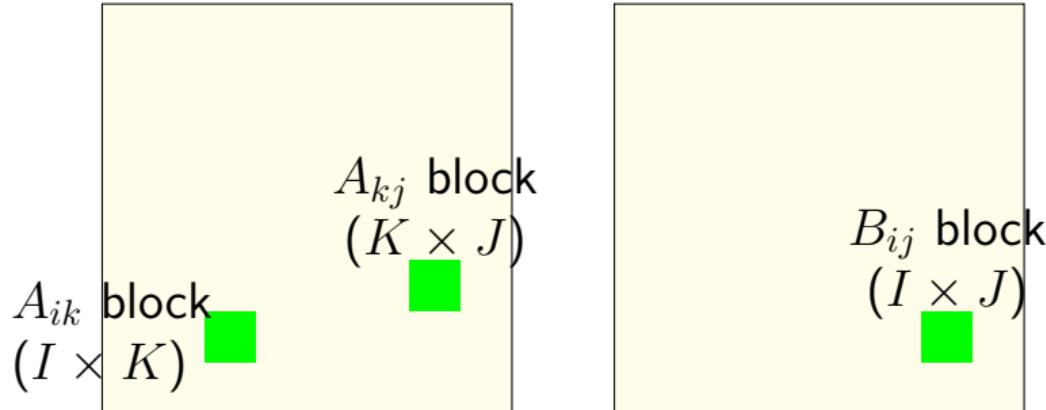
2 calculations for each A_{kj} (for $k, k + 1$)

array usage (better)



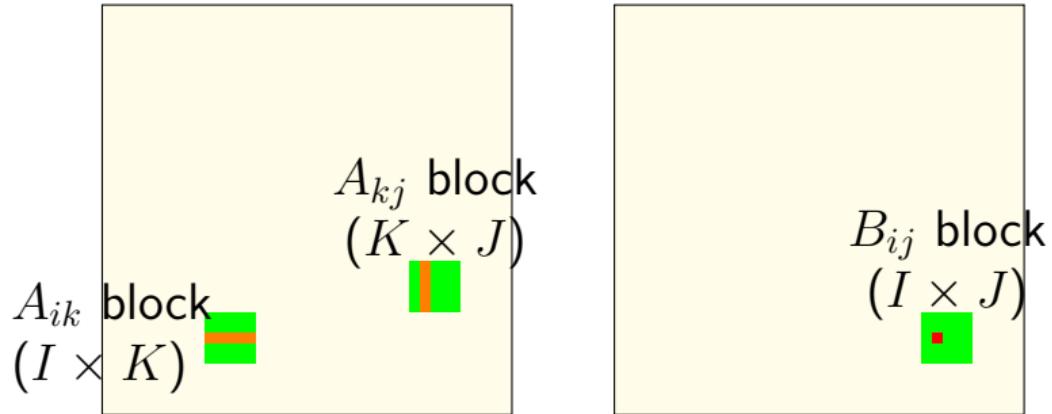
more **spatial** locality:
calculate on each $A_{i,k}$ and $A_{i,k+1}$ together
both in same cache block — same amount of cache loads

array usage: block



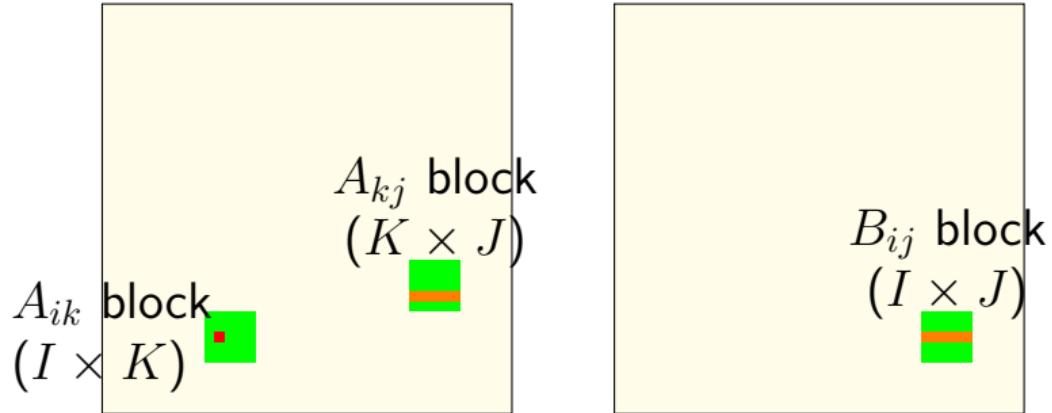
inner loop keeps “blocks” from A , B in cache

array usage: block



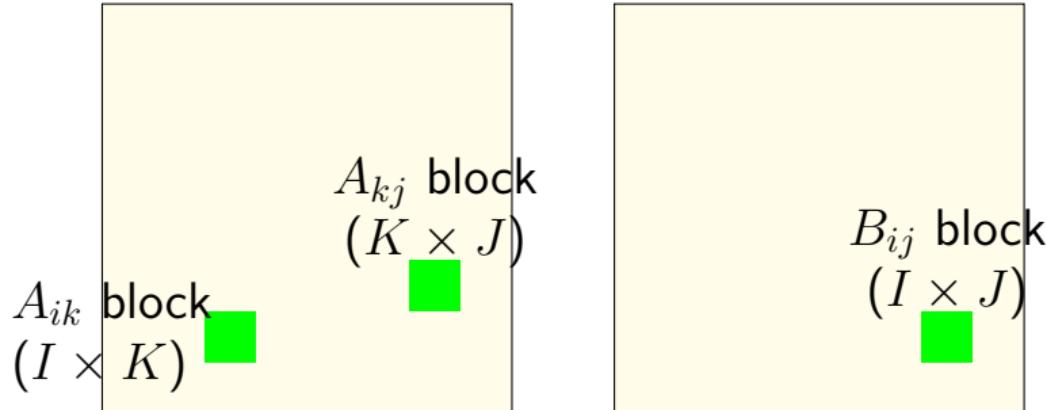
B_{ij} calculation uses strips from A
 K calculations for one load (cache miss)

array usage: block



A_{ik} calculation uses strips from A , B
 J calculations for one load (cache miss)

array usage: block



(approx.) KIJ fully cached calculations
for $KI + IJ + KJ$ loads
(assuming everything stays in cache)

cache blocking efficiency

load $I \times K$ elements of A_{ik} :

do $> J$ multiplies with each

load $K \times J$ elements of A_{kj} :

do I multiplies with each

load $I \times J$ elements of B_{ij} :

do K adds with each

bigger blocks — more work per load!

catch: $IK + KJ + IJ$ elements must fit in cache

cache blocking rule of thumb

fill the most of the cache with useful data

and do as much work as possible from that

example: my desktop 32KB L1 cache

$I = J = K = 48$ uses $48^2 \times 3$ elements, or 27KB.

assumption: conflict misses aren't important

register reuse

```
for (int k = 0; k < N; ++k)
    for (int i = 0; i < N; ++i)
        for (int j = 0; j < N; ++j)
            B[i*N+j] += A[i*N+k] * A[k*N+j];
// optimize into:
for (int k = 0; k < N; ++k)
    for (int i = 0; i < N; ++i) {
        float Aik = A[i*N+k]; // hopefully keep in register!
                                // faster than even cache hit!
        for (int j = 0; j < N; ++j)
            B[i*N+j] += Aik * A[k*N+j];
    }
}
```

can compiler do this for us?

can compiler do register reuse?

Not easily — What if $A=B$? What if $A=\&B[10]$

```
for (int k = 0; k < N; ++k)
    for (int i = 0; i < N; ++i) {
        // want to preload A[i*N+k] here!
        for (int j = 0; j < N; ++j) {
            // but if A = B, modifying here!
            B[i*N+j] += A[i*N+k] * A[k*N+j];
        }
    }
}
```