

pipelining 3: branch prediction / implementing
stalling+forwarding

last time

hazard — pipeline doesn't work as is

data hazard — hazard because wrong version of data
pipelining changed order of reads+writes (e.g. of registers)

stalling to resolve hazard

stall — insert nop instead of advancing instruction

forwarding to resolve data hazards

observation: value may be computed by not stored yet

exercise: forwarding paths

	cycle #	0	1	2	3	4	5	6	7	8
addq %r8, %r9		F	D	E	M	W				
subq %r8, %r10			F	D	E	M	W			
xorq %r8, %r9				F	D	E	M	W		
andq %r9, %r8					F	D	E	M	W	

in subq, %r8 is _____ addq.

in xorq, %r9 is _____ addq.

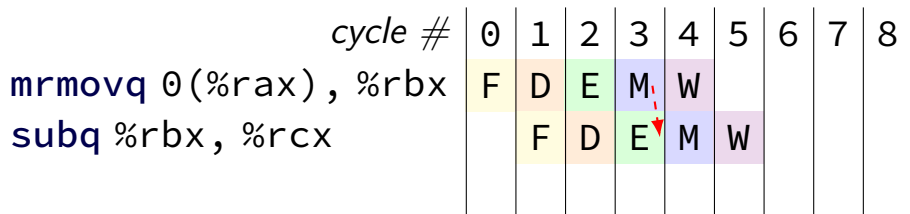
in andq, %r9 is _____ addq.

in andq, %r9 is _____ xorq.

A: not forwarded from

B-D: forwarded to decode from {execute,memory,writeback} stage of

unsolved problem



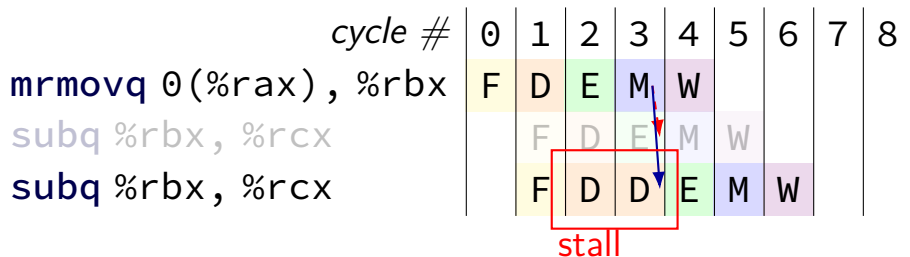
combine stalling and forwarding to resolve hazard

assumption in diagram: hazard detected in `subq`'s decode stage
(since easier than detecting it in fetch stage)

typically what you'll implement

intuition: try to forward, but detect that it won't work

unsolved problem



combine stalling and forwarding to resolve hazard

assumption in diagram: hazard detected in `subq`'s decode stage
(since easier than detecting it in fetch stage)

typically what you'll implement

intuition: try to forward, but detect that it won't work

solveable problem

	<i>cycle #</i>									
	0	1	2	3	4	5	6	7	8	
<code>mrmovq 0(%rax), %rbx</code>	F	D	E	M	W					
<code>rmmovq %rbx, 0(%rcx)</code>		F	D	E	M	W				

common for real processors to do this
but our textbook only forwards to the end of decode

aside: forwarding timings

forwarding: adds MUXes for forwarding to critical path
might slightly increase cycle time, considered acceptable

should not add much more to critical path:

example: can't use value read from memory in ALU in same cycle

pipeline with different hazards

example: 4-stage pipeline:

fetch/decode/execute+memory/writeback

		<i>// 4 stage</i>	<i>// 5 stage</i>
<code>addq %rax, %r8</code>		<i>//</i>	<i>// W</i>
<code>subq %rax, %r9</code>		<i>// W</i>	<i>// M</i>
<code>xorq %rax, %r10</code>		<i>// EM</i>	<i>// E</i>
<code>andq %r8, %r11</code>		<i>// D</i>	<i>// D</i>

pipeline with different hazards

example: 4-stage pipeline:

fetch/decode/execute+memory/writeback

	<i>// 4 stage</i>	<i>// 5 stage</i>
<code>addq %rax, %r8</code>	<i>//</i>	<i>// W</i>
<code>subq %rax, %r9</code>	<i>// W</i>	<i>// M</i>
<code>xorq %rax, %r10</code>	<i>// EM</i>	<i>// E</i>
<code>andq %r8, %r11</code>	<i>// D</i>	<i>// D</i>

`addq/andq` is hazard with 5-stage pipeline

`addq/andq` is **not** a hazard with 4-stage pipeline

exercise: different pipeline

split execute into two stages: F/D/E1/E2/M/W

result only available near end of second execute stage

where does forwarding, stalls occur?

	<i>cycle #</i>	0	1	2	3	4	5	6	7	8
(1) addq %rcx, %r9		F	D	E1	E2	M	W			
(2) addq %r9, %rbx										
(3) addq %rax, %r9										
(4) rmmovq %r9, (%rbx)										
(5) rrmovq %rcx, %r9										

exercise: different pipeline

split execute into two stages: F/D/E1/E2/M/W

	<i>cycle #</i>	0	1	2	3	4	5	6	7	8
<code>addq %rcx, %r9</code>		F	D	E1	E2	M	W			
<code>addq %r9, %rbx</code>										
<code>addq %rax, %r9</code>										
<code>rmmovq %r9, (%rbx)</code>										

exercise: different pipeline

split execute into two stages: F/D/E1/E2/M/W

	cycle #	0	1	2	3	4	5	6	7	8
<code>addq %rcx, %r9</code>		F	D	E1	E2	M	W			
<code>addq %r9, %rbx</code>			F	D	E1	E2	M	W		

`addq %rax, %r9` r9 not available yet — can't forward here
so try stalling in addq's decode...

<code>rmmovq %r9, (%rbx)</code>					F	D	E1	E2	M	W
---------------------------------	--	--	--	--	---	---	----	----	---	---

exercise: different pipeline

split execute into two stages: F/D/E1/E2/M/W

	cycle #	0	1	2	3	4	5	6	7	8	
addq %rcx, %r9		F	D	E1	E2	M	W				
addq %r9, %rbx			F	D	E1	E2	M	W			
addq %r9, %rbx			F	D	D	E1	E2	M	W		
addq %rax, %r9											
addq %rax, %r9				F	F	D	E1	E2	M	W	
rmmovq %r9, (%rbx)					F	D	E1	E2	M	W	
rmmovq %r9, (%rbx)						F	D	E1	E2	M	W

after stalling once, now we can forward

exercise: different pipeline

split execute into two stages: F/D/E1/E2/M/W

	<i>cycle #</i>	0	1	2	3	4	5	6	7	8	
addq %rcx, %r9		F	D	E1	E2	M	W				
addq %r9, %rbx			F	D	E1	E2	M	W			
addq %r9, %rbx			F	D	D	E1	E2	M	W		
addq %rax, %r9				F	D	E1	E2	M	W		
addq %rax, %r9				F	F	D	E1	E2	M	W	
rmmovq %r9, (%rbx)					F	D	E1	E2	M	W	
rmmovq %r9, (%rbx)						F	D	E1	E2	M	W

exercise: different pipeline

split execute into two stages: F/D/E1/E2/M/W

	cycle #	0	1	2	3	4	5	6	7	8		
addq %rcx, %r9		F	D	E1	E2	M	W					
addq %r9, %rbx			F	D	E1	E2	M	W				
addq %r9, %rbx			F	D	D	E1	E2	M	W			
addq %rax, %r9				F	D	E1	E2	M	W			
addq %rax, %r9				F	F	D	E1	E2	M	W		
rmmovq %r9, (%rbx)					F	D	E1	E2	M	W		
rmmovq %r9, (%rbx)						F	D	E1	E2	M	W	
rrmovq %rcx, %r9							F	D	E1	E2	M	W

control hazard

```
subq %r8, %r9
je    0xFFFF
addq %r10, %r11
```

	fetch		fetch→decode		decode→execute			execute→writeback	
cycle	PC	SF/ZF	rA	rB	R[srcA]	R[srcB]	dstE	next R[dstE]	dstE
0	0x0	0/1							
1	0x2	0/1	8	9					
2	???	0/1	0xF	0xF	800	900	9		

control hazard

```
subq %r8, %r9
je    0xFFFF
addq %r10, %r11
```

	fetch		fetch→decode		decode→execute			execute→writeback	
cycle	PC	SF/ZF	rA	rB	R[srcA]	R[srcB]	dstE	next R[dstE]	dstE
0	0x0	0/1							
1	0x2	0/1	8	9					
2	???	0/1	0xF	0xF	800	900	9		

0xFFFF if R[8] = R[9]; 0x12 otherwise

control hazard: stall

```
addq %r8, %r9
```

```
// insert two nops
```

```
je    0xFFFF
```

```
addq %r10, %r11
```

cycle	fetch		fetch→decode		decode→execute			execute→writeback	
	PC	SF/ZF	rA	rB	R[srcA]	R[srcB]	dstE	next R[dstE]	dstE
0	0x0	0/1							
1	0x2*	0/1	8	9					
2	0x2*	0/1	0xF	0xF	800	900	9		
3	0x2	0/0	0xF	0xF	---	---	0xF	1700	9
4	0x10	0/0	0xF	0xF	---	---	0xF	---	0xF
5			10	11	---	---	0xF	---	0xF
6					1000	1100	11	---	0xF

control hazard: stall

```
addq %r8, %r9
// insert two nops
je    0xFFFF
addq %r10, %r11
```

	fetch	fetch→decode	decode→execute	execute→writeback					
cycle	PC	wait for two cycles for addq to update SF/ZF							
0	0x0	0/1							
1	0x2*	0/1	8	9					
2	0x2*	0/1	0xF	0xF	800	900	9		
3	0x2	0/0	0xF	0xF	---	---	0xF	1700	9
4	0x10	0/0	0xF	0xF	---	---	0xF	---	0xF
5			10	11	---	---	0xF	---	0xF
6					1000	1100	11	---	0xF

control hazard: stall

```
addq %r8, %r9
```

```
// insert two nops
```

```
je    0xFFFF
```

```
addq %r10, %r11
```

cycle	fetch	fetch→decode		decode→execute			execute→writeback		
	PC	SF/ZF	rA	rB	R[srcA]	R[srcB]	dstE	next R[dstE]	dstE
0	0x0	0/1							
1	0x2*	execute je instruction (use SF/ZF)							
2	0x2*	0/1	0xF	0xF	800	900	9		
3	0x2	0/0	0xF	0xF	---	---	0xF	1700	9
4	0x10	0/0	0xF	0xF	---	---	0xF	---	0xF
5			10	11	---	---	0xF	---	0xF
6					1000	1100	11	---	0xF

stalling costs

with only stalling:

extra 3 cycles (total 4) for every ret

extra 2 cycles (total 3) for conditional jmp

up to 3 extra cycles for data dependencies

ex.: dependencies and hazards (2)

```
mrmovq    0(%rax) %rbx
```

```
addq     %rbx    %rcx
```

```
jne     foo
```

```
foo:    addq     %rcx    %rdx
```

```
mrmovq   (%rdx)  %rcx
```

where are dependencies?

which are hazards in our pipeline?

which are resolved with forwarding?

when do instructions change things?

... other than pipeline registers/PC:

stage	changes
fetch	(none)
decode	(none)
execute	condition codes
memory	memory writes
writeback	register writes/stat changes

when do instructions change things?

... other than pipeline registers/PC:

stage	changes
fetch	(none)
decode	(none)
execute	condition codes
memory	memory writes
writeback	register writes/stat changes

to “undo” instruction during fetch/decode:

forget everything in **pipeline registers**

making guesses

```
subq    %rcx, %rax  
jne     LABEL  
xorq    %r10, %r11  
xorq    %r12, %r13
```

...

```
LABEL:  addq    %r8, %r9  
        rmmovq %r10, 0(%r11)
```

speculate: **jne** will goto LABEL

right: 2 cycles faster!

wrong: forget before execute finishes

jXX: speculating right

```
subq %r8, %r8  
jne LABEL  
...
```

```
LABEL: addq %r8, %r9  
rmmovq %r10, 0(%r11)  
irmovq $1, %r11
```

time	fetch	decode	execute	memory	writeback
1	subq				
2	jne	subq			
3	addq [?]	jne	subq (set ZF)		
4	rmmovq [?]	addq [?]	jne (use ZF)	OPq	
5	irmovq	rmmovq	addq	jne (done)	OPq

jXX: speculating right

```
subq %r8, %r8
jne LABEL
...
```

```
LABEL: addq %r8, %r9
        rmmovq %r10, 0(%r11)
        irmovq $1, %r11
```

time	fetch	decode	execute	memory	writeback
1	subq				
2	jne	subq			
3	addq [?]	jne	subq (set ZF)		
4	rmmovq [?]	addq [?]	j were waiting/nothing		
5	irmovq	rmmovq	addq	jne (done)	OPq

jXX: speculating wrong

```
subq %r8, %r8
jne LABEL
xorq %r10, %r11
...
```

```
LABEL: addq %r8, %r9
       rmmovq %r10, 0(%r11)
```

time	fetch	decode	execute	memory	writeback
1	subq				
2	jne	subq			
3	addq [?]	jne	subq (set ZF)		
4	rmmovq [?]	addq [?]	jne (use ZF)	OPq	
5	xorq	nothing	nothing	jne (done)	OPq

jXX: speculating wrong

```
subq %r8, %r8
jne LABEL
xorq %r10, %r11
...
```

```
LABEL: addq %r8, %r9
       rmmovq %r10, 0(%r11)
```

time	fetch	decode	execute	memory	writeback
1	subq				
2	jne	"squash" wrong guesses			
3	addq [?]	jne	subq (set ZF)		
4	rmmovq [?]	addq [?]	jne (use ZF)	OPq	
5	xorq	nothing	nothing	jne (done)	OPq

jXX: speculating wrong

```
subq %r8, %r8
jne LABEL
xorq %r10, %r11
...
```

```
LABEL: addq %r8, %r9
        rmmovq %r10, 0(%r11)
```

time	fetch	decode	execute	memory	writeback
1	subq				
2	jne	subq			
3	addq [?]	j			
4	rmmovq [?]	addq [?]	jne (use 2)		
5	xorq	nothing	nothing	jne (done)	OPq

fetch correct next instruction

performance

hypothetical instruction mix

kind	portion	cycles (predict)	cycles (stall)
not-taken jXX	3%	3	3
taken jXX	5%	1	3
ret	1%	4	4
others	91%	1*	1*

performance

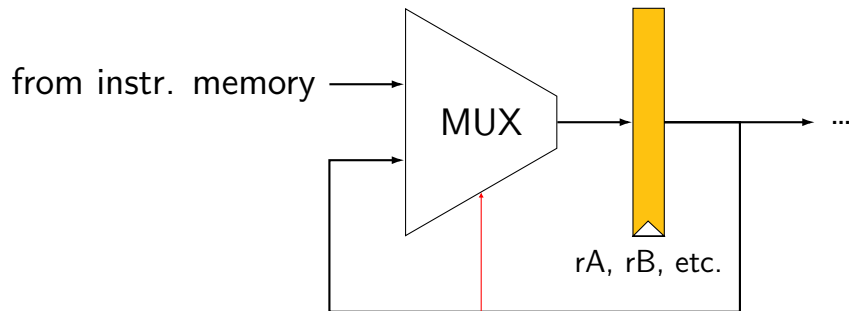
hypothetical instruction mix

kind	portion	cycles (predict)	cycles (stall)
not-taken jXX	3%	3	3
taken jXX	5%	1	3
ret	1%	4	4
others	91%	1*	1*

$$\text{predict: } 3 \times .03 + 1 \times .05 + 4 \times .01 + 1 \times .91 = 1.09 \text{ cycles/instr.}$$

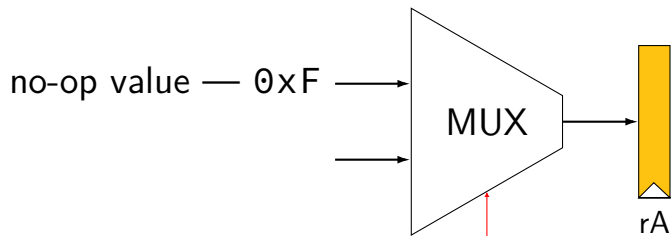
$$\text{stall: } 3 \times .03 + 3 \times .05 + 4 \times .01 + 1 \times .91 = 1.19 \text{ cycles/instr. } (1.19 \div 1.09 \approx 1.09\text{x faster})$$

fetch/decode logic — advance or not



should we stall?

fetch/decode logic — bubble or not



should we send
no-op value (“bubble”)?

HCLRS signals

```
register aB {  
    ...  
}
```

HCLRS: every register bank has these MUXes built-in

`stall_B`: keep **old value** for all registers

register input \leftarrow register output

pipeline: keep same instruction in this stage next cycle

`bubble_B`: use **default value** for all registers

register input \leftarrow default value

pipeline: put no-operation in this stage next cycle

exercise

```
register aB {  
    value : 8 = 0xFF;  
}  
...
```

stall: keep old value bubble: store default value
--

time	a_value	B_value	stall_B	bubble_B
0	0x01	0xFF	0	0
1	0x02	???	1	0
2	0x03	???	0	0
3	0x04	???	0	1
4	0x05	???	0	0
5	0x06	???	0	0
6	0x07	???	1	0
7	0x08	???	1	0
8		???		

exercise result

```
register aB {  
    value : 8 = 0xFF;  
}
```

...

time	a_value	B_value	stall_B	bubble_B
0	0x01	0xFF	0	0
1	0x02	0x01	1	0
2	0x03	0x01	0	0
3	0x04	0x03	0	1
4	0x05	0xFF	0	0
5	0x06	0x05	0	0
6	0x07	0x06	1	0
7	0x08	0x06	1	0
8		0x06		

backup slides

stalling for conditional jmps

```
subq %r8, %r8  
je label
```

```
label: irmovq ...
```

time	fetch	decode	execute	memory	writeback
1	OPq				
2	jCC	OPq			
3	wait for jCC	jCC	OPq (set ZF)		
4	wait for jCC	nothing	jCC (use ZF)	OPq	
5	irmovq	nothing	nothing	jCC (done)	OPq

stalling for conditional jmps

```
subq %r8, %r8  
je label
```

```
label: irmovq ...
```

time	fetch	decode	execute	memory	writeback
1	OPq				
2	jCC	OPq			
3	wait for jCC	jCC	OPq (set ZF)		
4	wait for jCC	nothing	jCC (use ZF)	OPq	
5	irmovq	nothing	nothing	jCC (done)	OPq

stalling for conditional jmps

```
subq %r8, %r8  
je label
```

```
label: irmovq ...
```

time	fetch	decode	execute	memory	writeback
1	OPq				
2	jCC	OPq			
3	wait for jCC	jCC	OPq (set ZF)		
4	wait for jCC	nothing	jCC (use ZF)	OPq	
5	irmovq	nothing	nothing	jCC (done)	OPq

ZF sent via register

stalling for conditional jmps

```
subq %r8, %r8  
je label
```

```
label: irmovq ...
```

time	fetch	decode	execute	memory	writeback
1	OPq				
2	jCC	OPq			
3	wait for jCC	jCC	OPq (set ZF)		
4	wait for jCC	nothing	jCC (use ZF)	OPq	
5	irmovq	nothing	nothing	jCC (done)	OPq

“taken” sent from execute to fetch

stalling for ret

```
call empty  
addq %r8, %r9
```

```
empty:    ret
```

time	fetch	decode	execute	memory	writeback
1	call				
2	ret	call			
3	wait for ret	ret	call		
4	wait for ret	nothing	ret	call (store)	
5	wait for ret	nothing	nothing	ret (load)	call
6	addq	nothing	nothing	nothing	ret

stalling for ret

```
call empty
addq %r8, %r9
```

```
empty:    ret
```

time	fetch	decode	execute	memory	writeback
1	call				
2	ret	call			
3	wait for ret	ret	call		
4	wait for ret	nothing	ret	call (store)	
5	wait for ret	nothing	nothing	ret (load)	call
6	addq	nothing	nothing	nothing	ret

return address stored here

stalling for ret

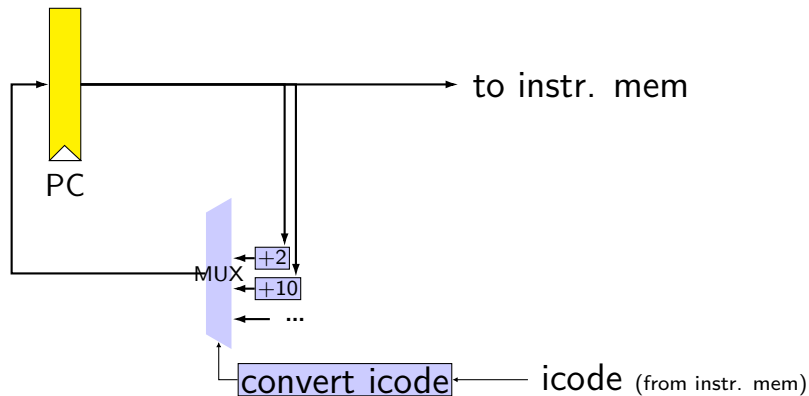
```
call empty
addq %r8, %r9
```

```
empty:  ret
```

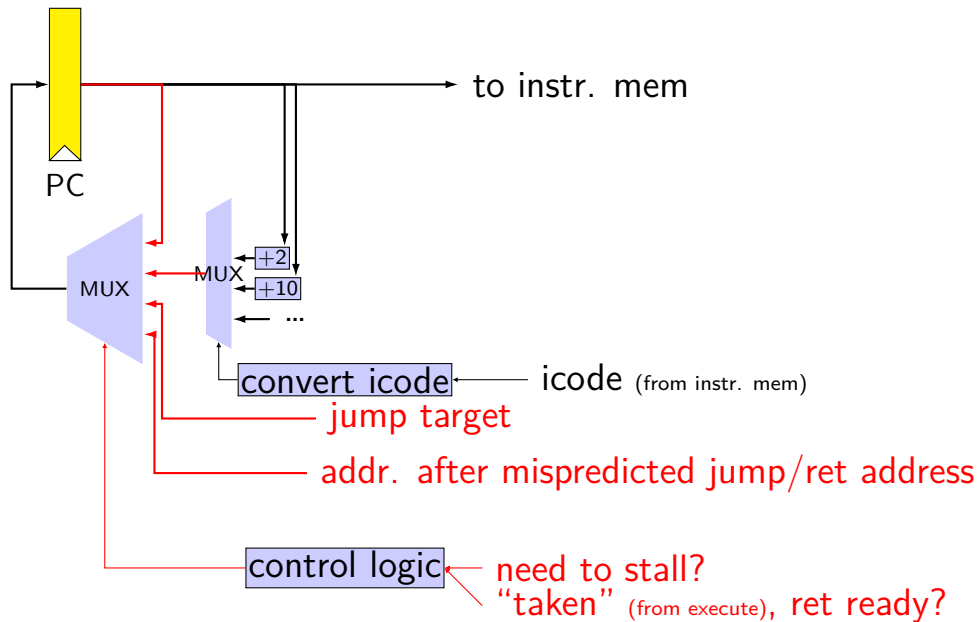
time	fetch	decode	execute	memory	writeback
1	call				
2	ret	call			
3	wait for ret	ret	call		
4	wait for ret	nothing	ret	call (store)	
5	wait for ret	nothing	nothing	ret (load)	call
6	addq	nothing	nothing	nothing	ret

return address loaded here

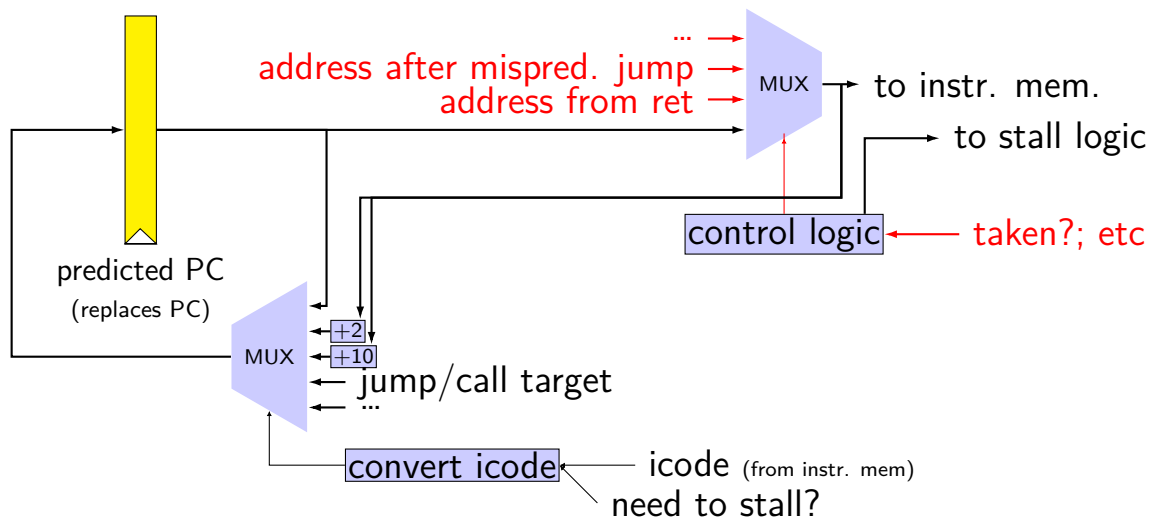
PC update (adding prediction, stall)



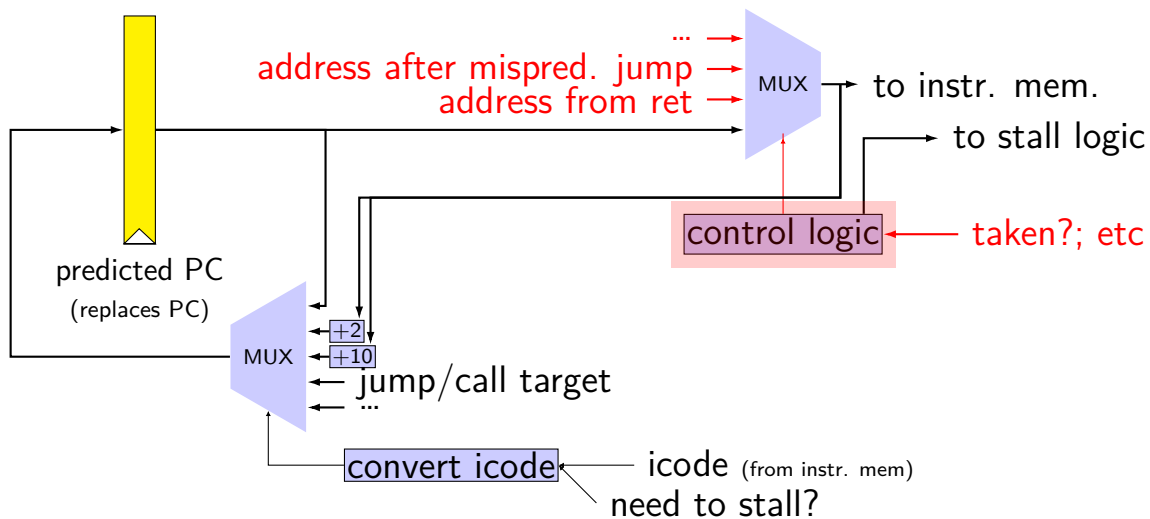
PC update (adding prediction, stall)



PC update (rearranged)

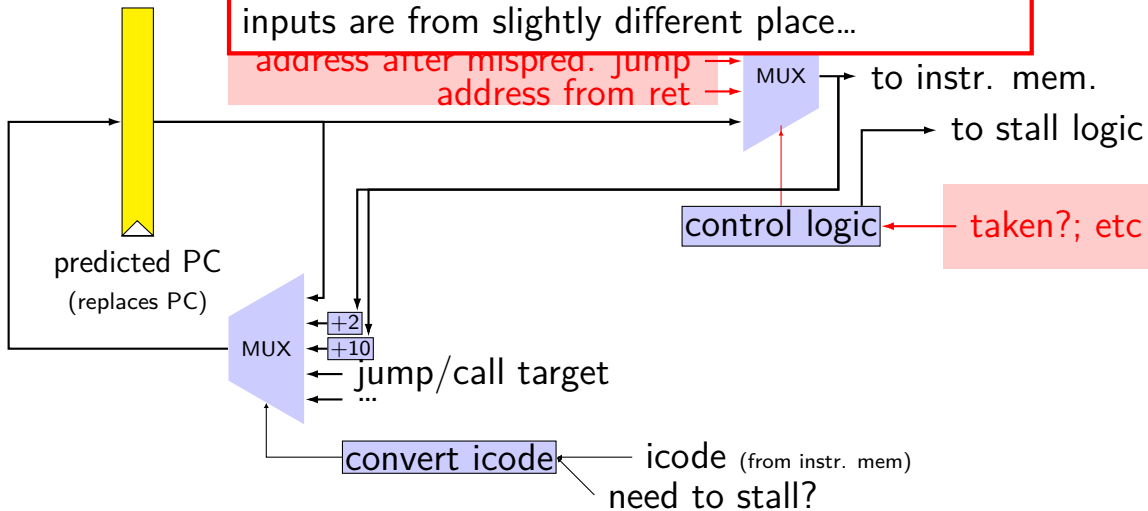


PC update (rearranged)

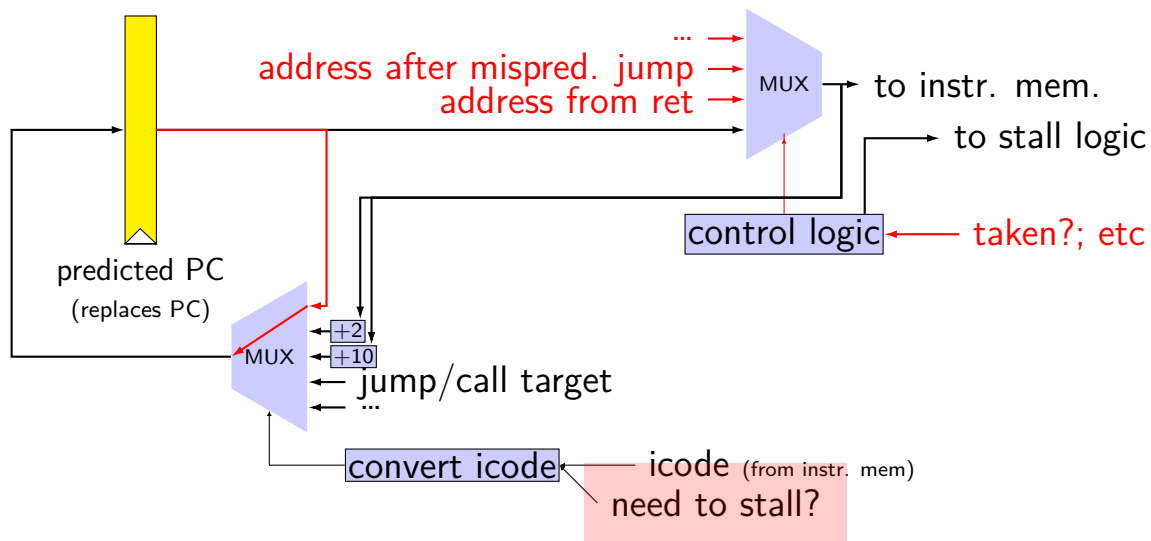


PC update (rearranged)

same logic as before — but happens in next cycle
inputs are from slightly different place...



PC update (rearranged)



rearranged PC update in HCL

```
/* replacing the PC register: */
register fF {
    predictedPC: 64 = 0;
}

/* actual input to instruction memory */
pc = [
    conditionCodesSaidNotTaken : jumpValP;
    /* from later in pipeline */
    ...
    1: F_predictedPC;
];
```

why rearrange PC update?

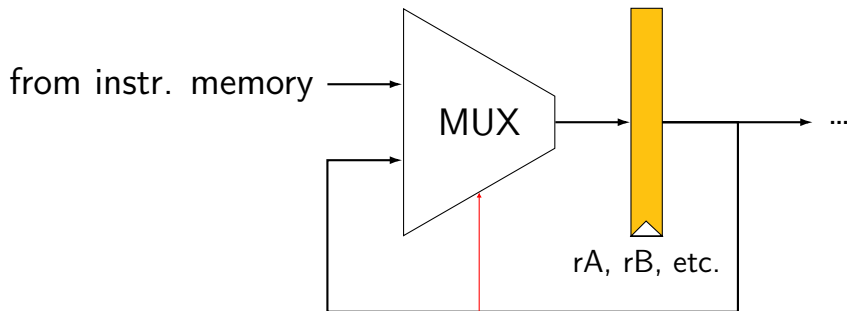
either works

- correct PC at beginning or end of cycle?

- still some time in cycle to do so...

maybe easier to think about branch prediction this way?

fetch/decode logic — advance or not



should we stall?

ex.: dependencies and hazards (1)

addq %rax, %rbx

subq %rax, %rcx

irmovq \$100, %rcx

addq %rcx, %r10

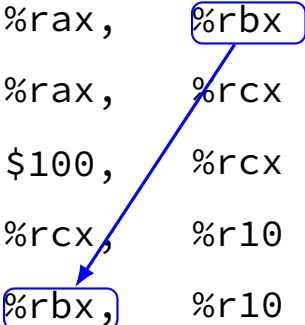
addq %rbx, %r10

where are dependencies?

which are hazards in our pipeline?

ex.: dependencies and hazards (1)

<code>addq</code>	<code>%rax,</code>	<code>%rbx</code>
<code>subq</code>	<code>%rax,</code>	<code>%rcx</code>
<code>irmovq</code>	<code>\$100,</code>	<code>%rcx</code>
<code>addq</code>	<code>%rcx,</code>	<code>%r10</code>
<code>addq</code>	<code>%rbx,</code>	<code>%r10</code>



where are dependencies?
which are hazards in our pipeline?

ex.: dependencies and hazards (1)

```
addq    %rax, %rbx
subq    %rax, %rcx
irmovq  $100, %rcx
addq    %rcx, %r10
addq    %rbx, %r10
```

The diagram illustrates data dependencies between instructions. A blue box highlights the `%rbx` register in the first instruction. A red box highlights the `%rcx` register in the third instruction. A red arrow points from the `%rcx` box to the `%rcx` operand in the second instruction, indicating a data hazard. A blue arrow points from the `%rbx` box to the `%rbx` operand in the fifth instruction, indicating a data dependency.

where are dependencies?
which are hazards in our pipeline?

ex.: dependencies and hazards (1)

addq	%rax,	%rbx
subq	%rax,	%rcx
irmovq	\$100,	%rcx
addq	%rcx,	%r10
addq	%rbx,	%r10

where are dependencies?
which are hazards in our pipeline?