SEQ part 4 / pipelining 0

last time

building processors: add MUX for each decision

single-cycle processor timing

- storage (memory, registers, register file) write at rising edge
- therefore, rising edge changes storage outputs = other circuit inputs
- everything else adjusts as their inputs change
- clock signal long enough to give storage stable inputs (at rising edge)

so-called "stages"

- conceptual division of the processor (later: timing division)
- fetch (read instruction; split into pieces; *compute next instruction addr*)
- 'decode' (read from register file)
- execute (ALU operation; condition codes)
- memory (setup data memory access)
- writeback (setup write to register file)
- PC update (setup next PC value)

SEQ: instruction fetch

read instruction memory at PC

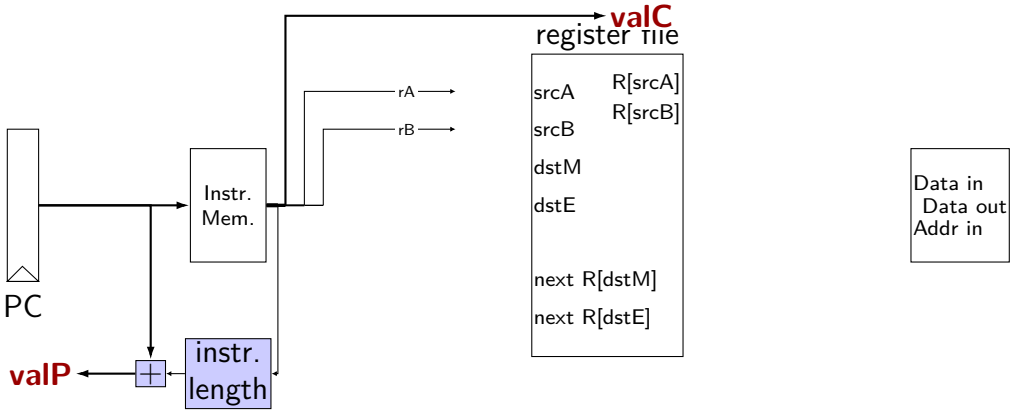
split into seperate wires:

- icode:ifun — opcode
- rA, rB — register numbers
- valC — call target or mov displacement

compute next instruction address:

- valP — PC + (instr length)

instruction fetch

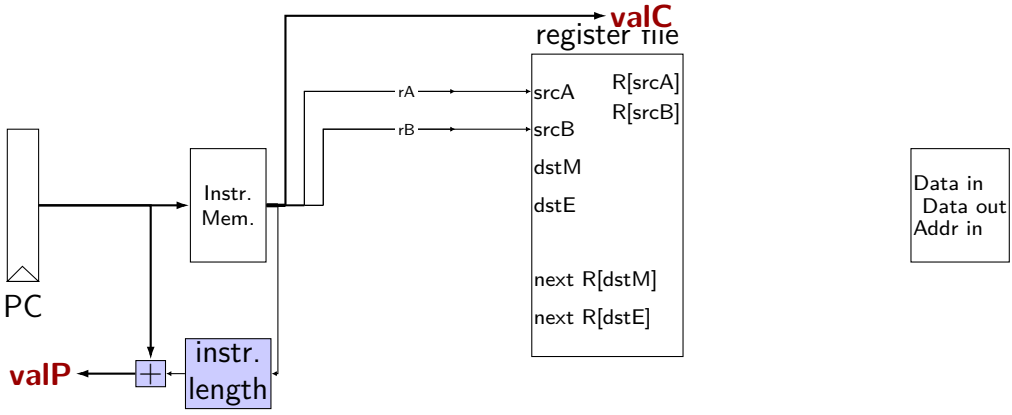


SEQ: instruction “decode”

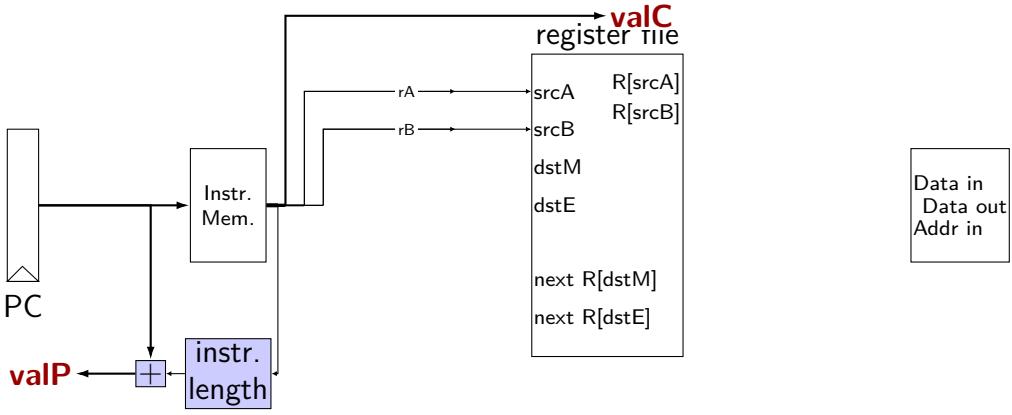
read registers

valA, valB — register values

instruction decode (1)

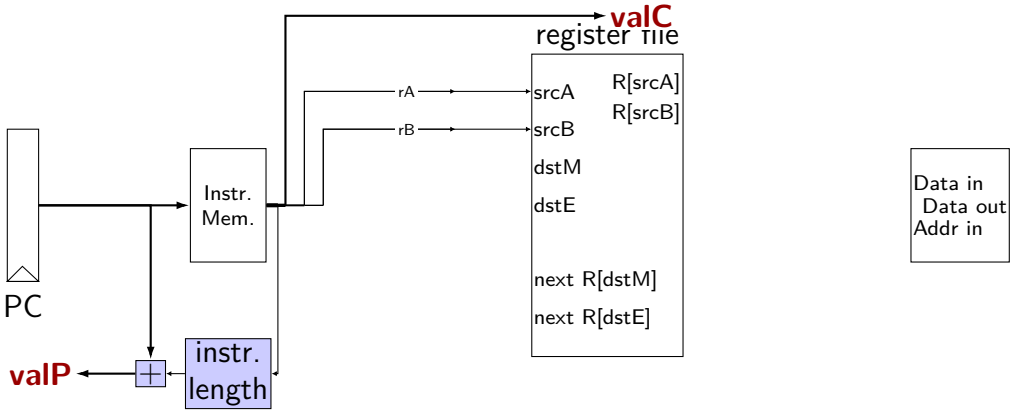


instruction decode (1)



exercise: for which instructions would there be a problem ?
nop, addq, `mrmovq`, `rmmovq`, `jmp`, pushq

instruction decode (1)



SEQ: srcA, srcB

always read rA, rB?

Problems:

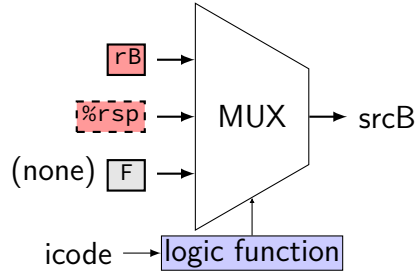
- push rA
- pop
- call
- ret

book: extra signals: srcA, srcB — computed input register

MUX controlled by icode

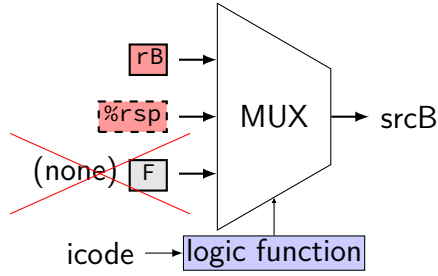
SEQ: possible registers to read

instruction	srcA	srcB
`halt`, `nop`, `j`*CC*, `irmovq`	none	none
`cmovCC`, `rrmovq`	rA	none
`mrmovq`	none	rB
`rmmovq`, *OP*`q`	rA	rB
`call`, `ret`	none?	`%rsp`
`pushq`, `popq`	rA	`%rsp`

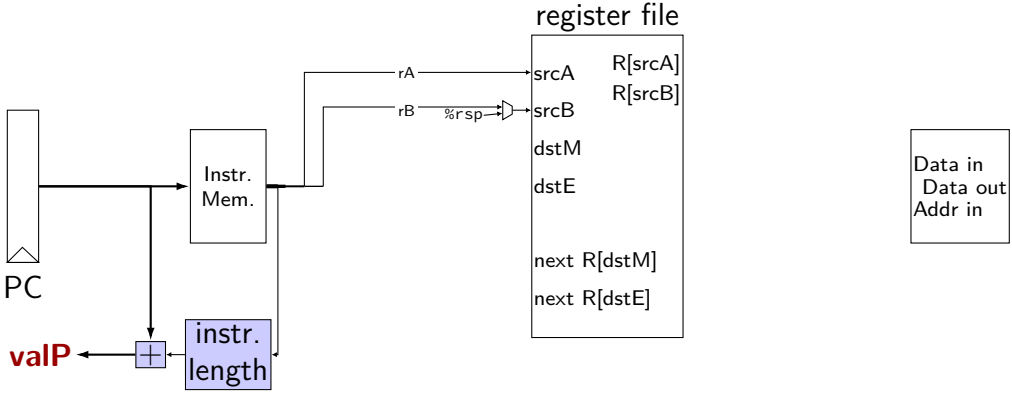


SEQ: possible registers to read

instruction	srcA	srcB
`halt`, `nop`, `j`*CC*, `irmovq`	none	none
`cmovCC`, `rrmovq`	rA	none
`mrmovq`	none	rB
`rmmovq`, *OP*`q`	rA	rB
`call`, `ret`	none?	`%rsp`
`pushq`, `popq`	rA	`%rsp`



instruction decode (2)



SEQ: execute

perform ALU operation (add, sub, xor, and)

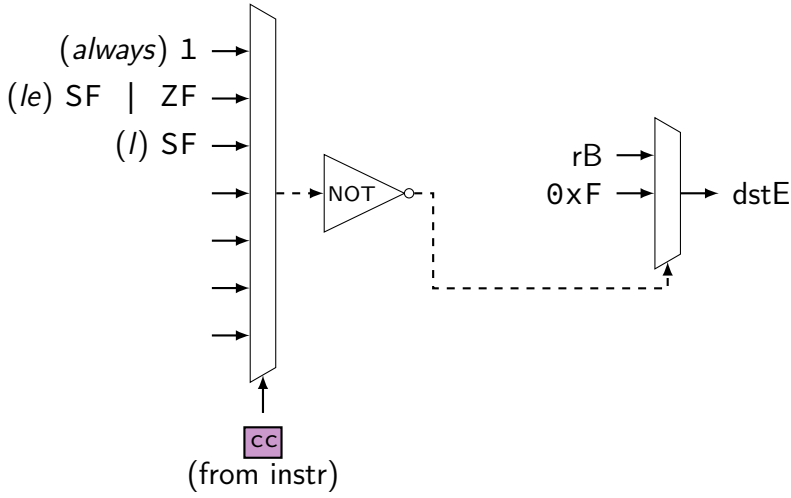
- valE — ALU output

read prior condition codes

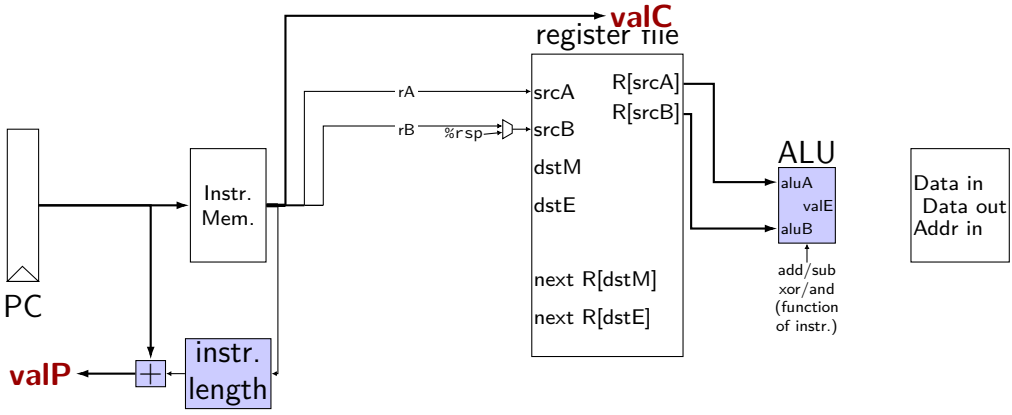
- Cnd — condition codes based on ifun (instruction type for jCC/cmovCC)

write new condition codes

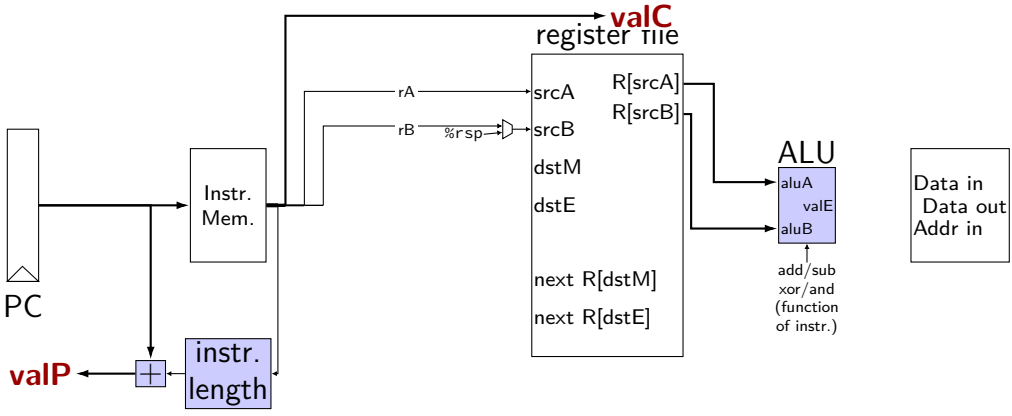
using condition codes: cmov



execute (1)


valC
register file
rA
rB
%rsp
srcA
srcB
dstM
dstE
R[srcA]
R[srcB]
next R[dstM]
next R[dstE]
ALU
aluA
valE
aluB
add/sub
xor/and
(function
of instr.)
Data in
Data out
Addr in
Instr.
Mem.
PC
valP
instr.
length

execute (1)



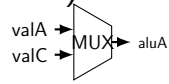
exercise: which of these instructions would there be a problem ?
`nop`, `addq`, `mrmovq`, `popq`, `call`,

SEQ: ALU operations?

ALU inputs always valA, valB (register values)?

no, inputs from instruction: (Displacement + rB)

- `mrmovq`
- `rmmovq`



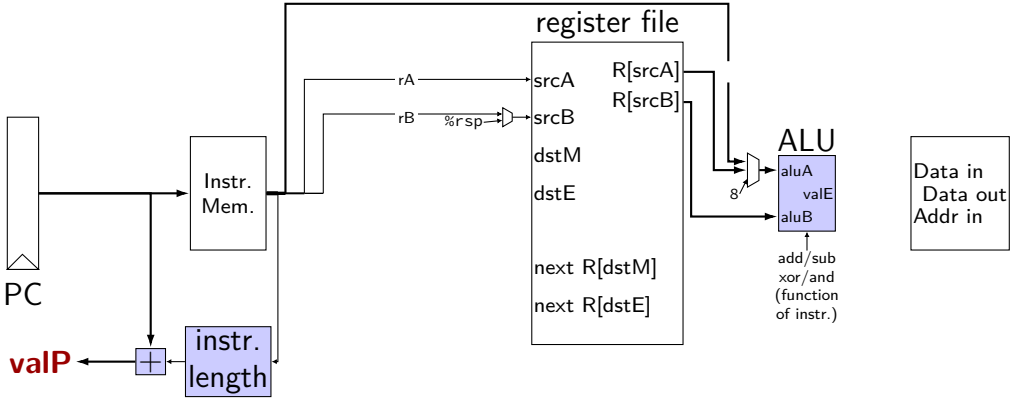
no, constants: (rsp +/- 8)

- `pushq`
- `popq`
- `call`
- `ret`

extra signals: aluA, aluB

computed ALU input values

execute (2)

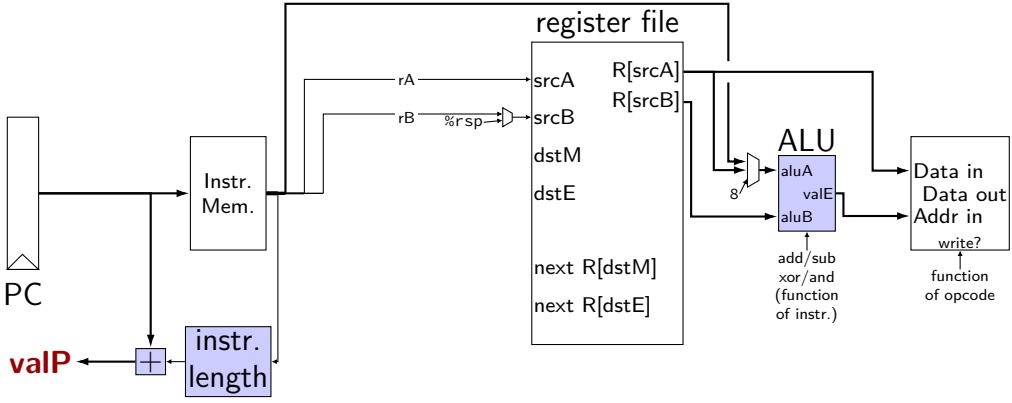

register file
rA
rB
%rsp
srcA
srcB
dstM
dstE
R[srcA]
R[srcB]
next R[dstM]
next R[dstE]
ALU
aluA
valE
aluB
8
add/sub
xor/and
(function
of instr.)
Data in
Data out
Addr in
Instr.
Mem.
PC
valP
instr.
length

SEQ: Memory

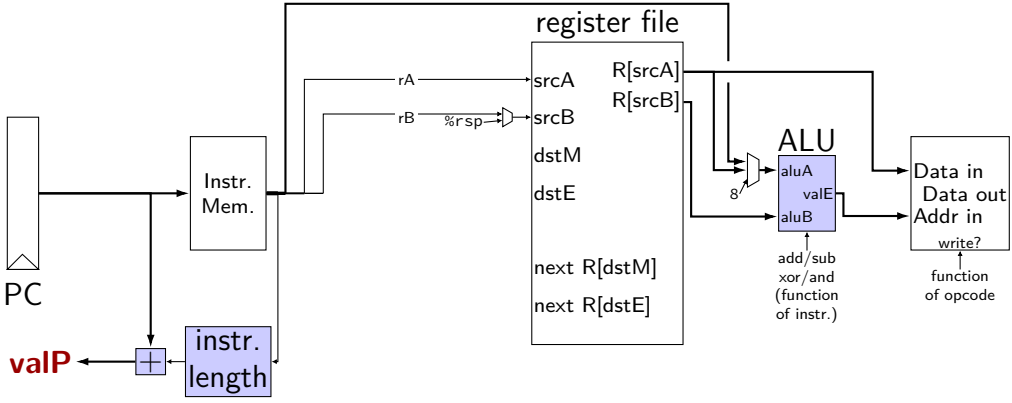
read or write data memory

valM — value read from memory (if any)

memory (1)


register file
rA
rB
%rsp
srcA
srcB
dstM
dstE
R[srcA]
R[srcB]
next R[dstM]
next R[dstE]
ALU
aluA
valE
aluB
8
add/sub
xor/and
(function
of instr.)
Data in
Data out
Addr in
write?
function
of opcode
Instr.
Mem.
PC
valP
instr.
length

memory (1)



exercise: which of these instructions would there be a problem ?
`nop`, `rmmovq`, `mrmovq`, `popq`, `call`,

SEQ: control signals for memory

read/write — read enable? write enable?

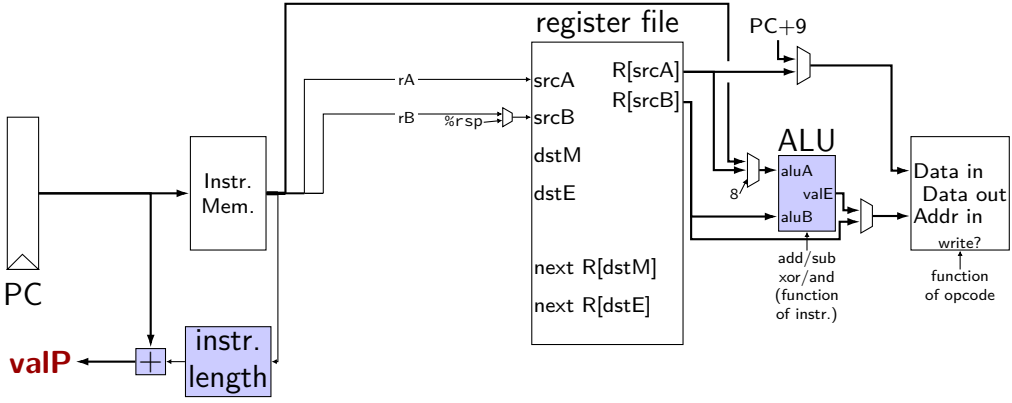
Addr — address

- mostly ALU output
- special cases (need extra MUX): `popq`, `ret`

Data — value to write

- mostly valA
- special cases (need extra MUX): `call`

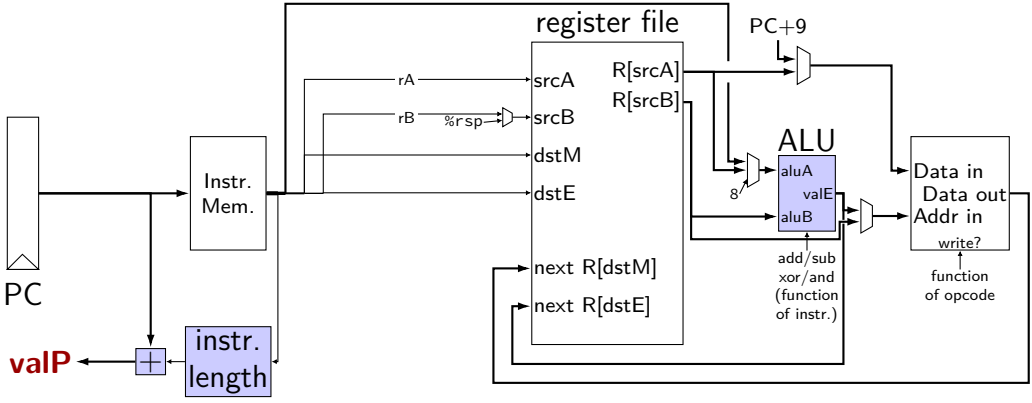
memory (2)


register file
PC+9
rA
rB
%rsp
srcA
srcB
dstM
dstE
R[srcA]
R[srcB]
next R[dstM]
next R[dstE]
ALU
aluA
valE
aluB
8
Data in
Data out
Addr in
write?
add/sub
xor/and
(function
of instr.)
function
of opcode
Instr.
Mem.
PC
valP
instr.
length

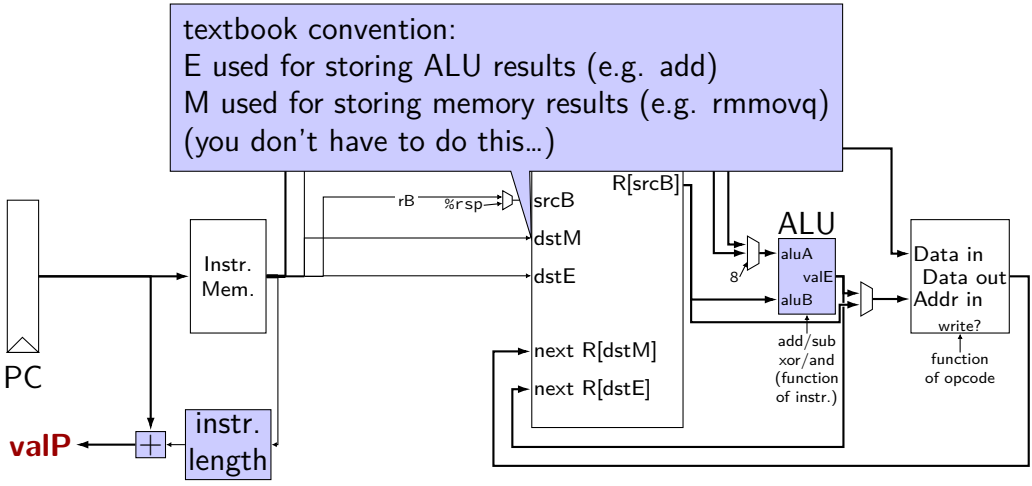
SEQ: write back

write registers

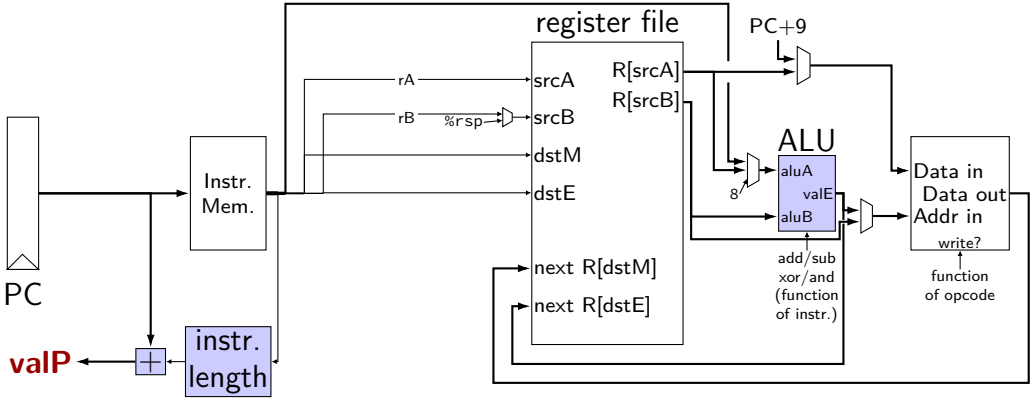
write back (1)


register file
PC+9
rA
rB
%rsp
srcA
srcB
dstM
dstE
R[srcA]
R[srcB]
ALU
aluA
valE
aluB
8
Data in
Data out
Addr in
write?
function
of opcode
add/sub
xor/and
(function
of instr.)
next R[dstM]
next R[dstE]
Instr.
Mem.
PC
valP
instr.
length

write back (1)


textbook convention:
E used for storing ALU results (e.g. add)
M used for storing memory results (e.g. rmmovq)
(you don't have to do this...)
PC
valP
Instr.
Mem.
instr.
length
rB
%rsp
srcB
dstM
dstE
R[srcB]
next R[dstM]
next R[dstE]
ALU
aluA
valE
aluB
8
add/sub
xor/and
(function
of instr.)
Data in
Data out
Addr in
write?
function
of opcode

write back (1)



exercise: which of these instructions would there be a problem ?
nop, `irmovq`, `mrmovq`, `rmmovq`, addq, popq

SEQ: control signals for WB

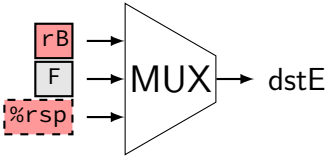
two write inputs — two needed by popq

valM (memory output), valE (ALU output)

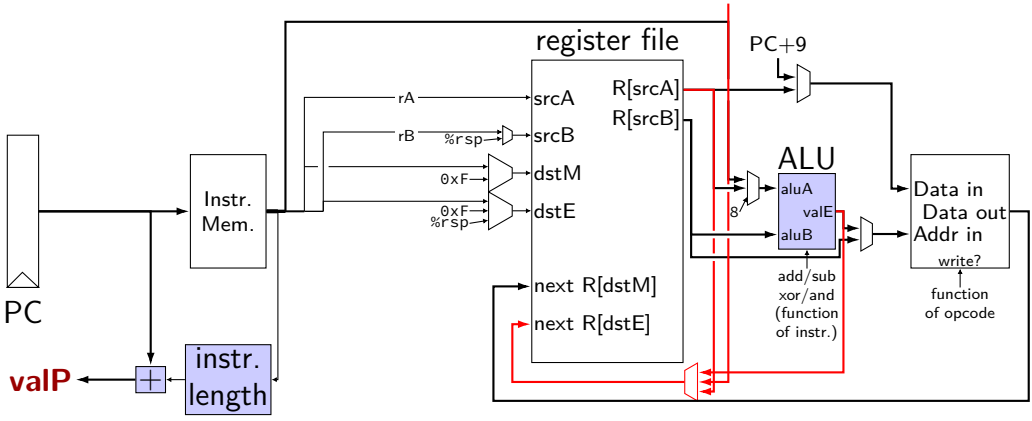
two register numbers

dstM, dstE

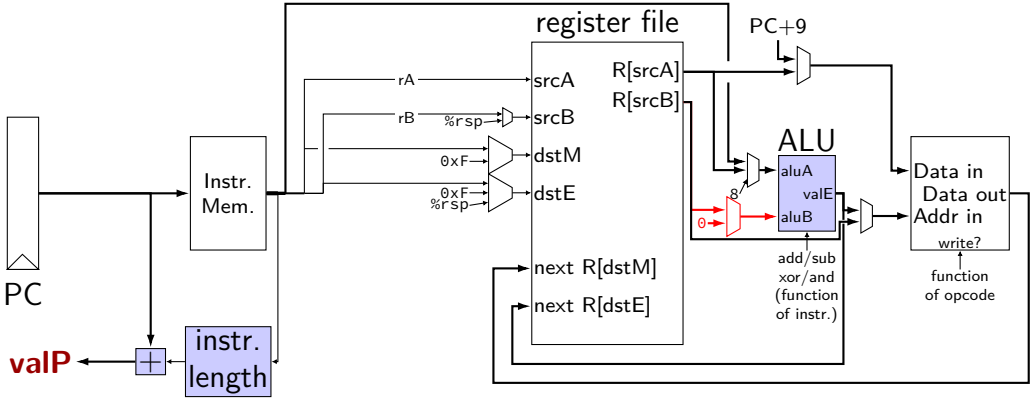
write disable — use dummy register number `0xF`



write back (2a)



write back (2b)

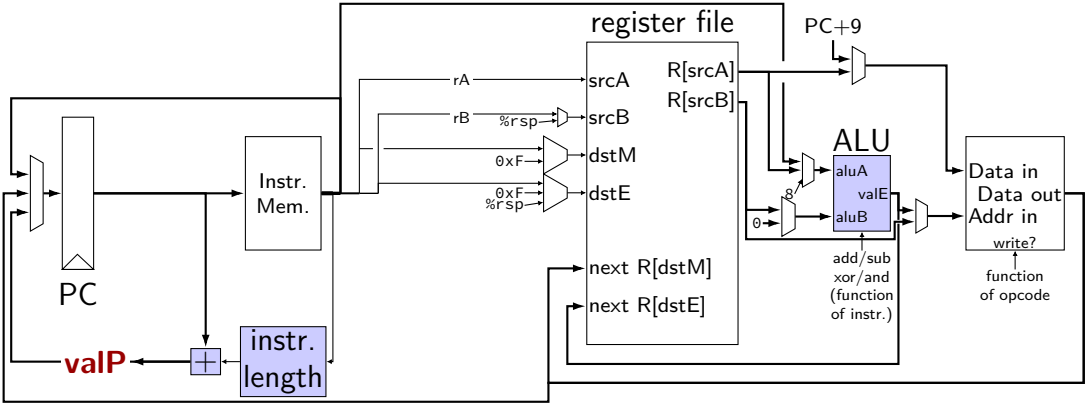


SEQ: Update PC

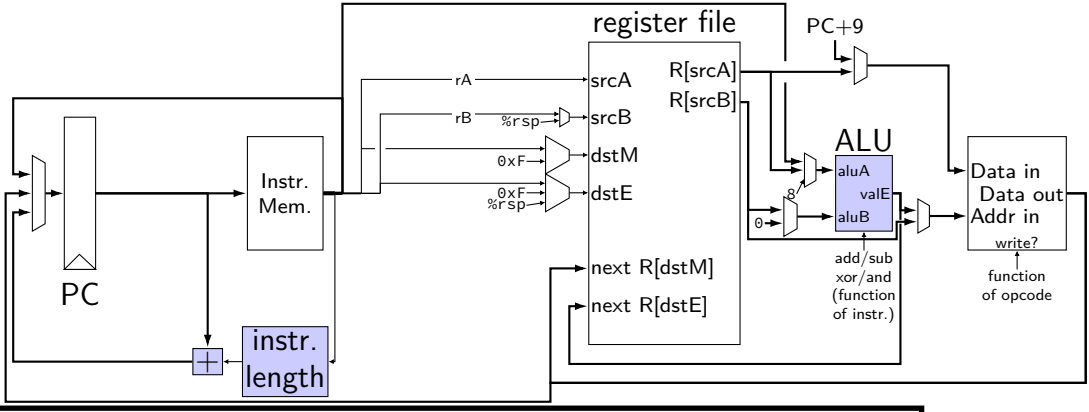
choose value for PC next cycle (input to PC register)

- usually valP (following instruction)
- exceptions: `call`, `j`*CC*, `ret`

PC update


register file
PC+9
rA
rB
%rsp
0xF
0xF
%rsp
srcA
srcB
dstM
dstE
R[srcA]
R[srcB]
next R[dstM]
next R[dstE]
ALU
aluA
valE
aluB
8
0
add/sub
xor/and
(function
of instr.)
Data in
Data out
Addr in
write?
function
of opcode
Instr.
Mem.
PC
valP
instr.
length

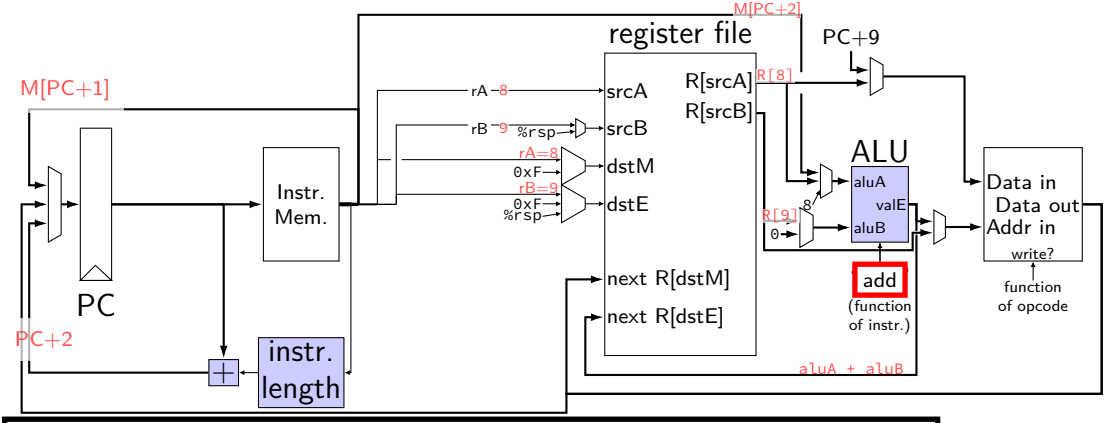
circuit: setting MUXes



MUXes — PC, dstM, dstE, aluA, aluB, dmemIn, dmemAddr, ...

Exercise: what do they select when running `addq %r8, %r9`?

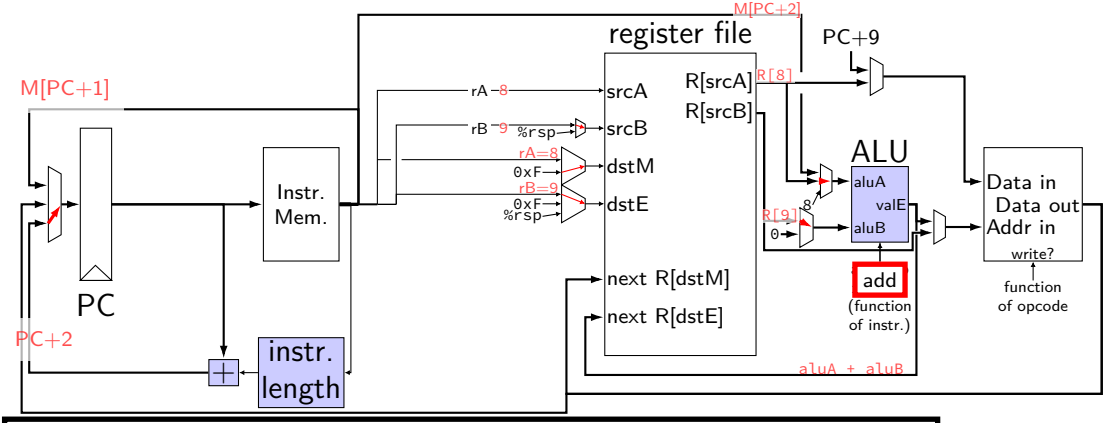
circuit: setting MUXes



MUXes — PC, dstM, dstE, aluA, aluB, dmemIn, dmemAddr, ...

Exercise: what do they select when running `addq %r8, %r9`?

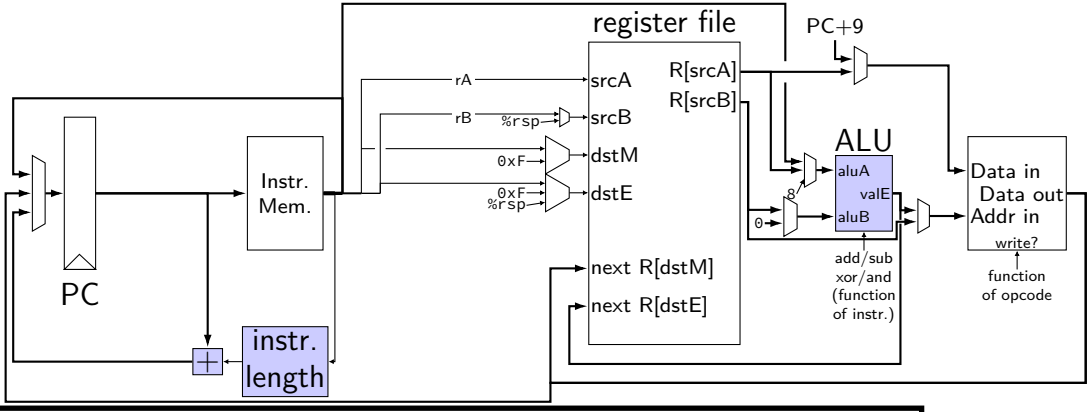
circuit: setting MUXes



MUXes — PC, dstM, dstE, aluA, aluB, dmemIn, dmemAddr, ...

Exercise: what do they select when running `addq %r8, %r9`?

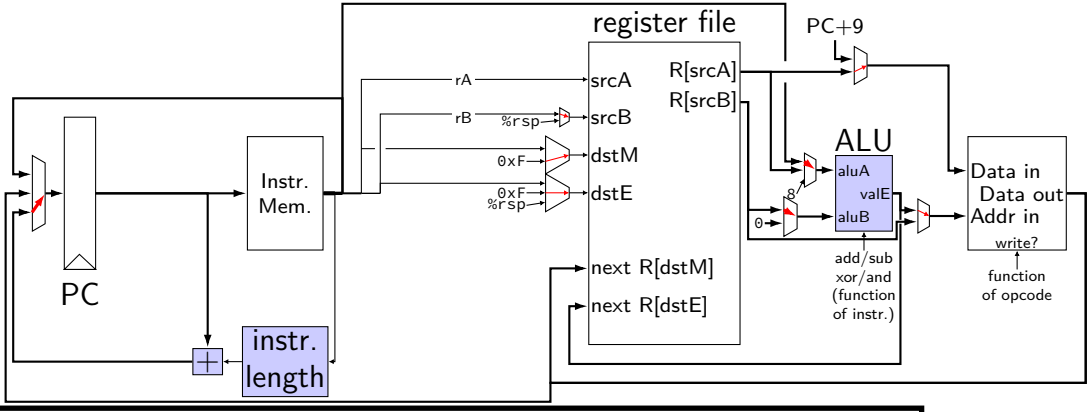
circuit: setting MUXes



MUXes — PC, dstM, dstE, aluA, aluB, dmemIn, dmemAddr, ...

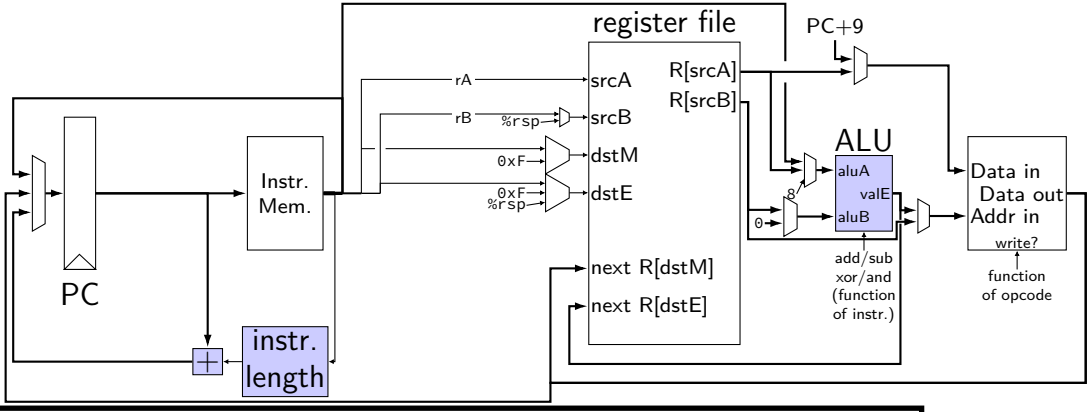
Exercise: what do they select for `rmmovq`?

circuit: setting MUXes



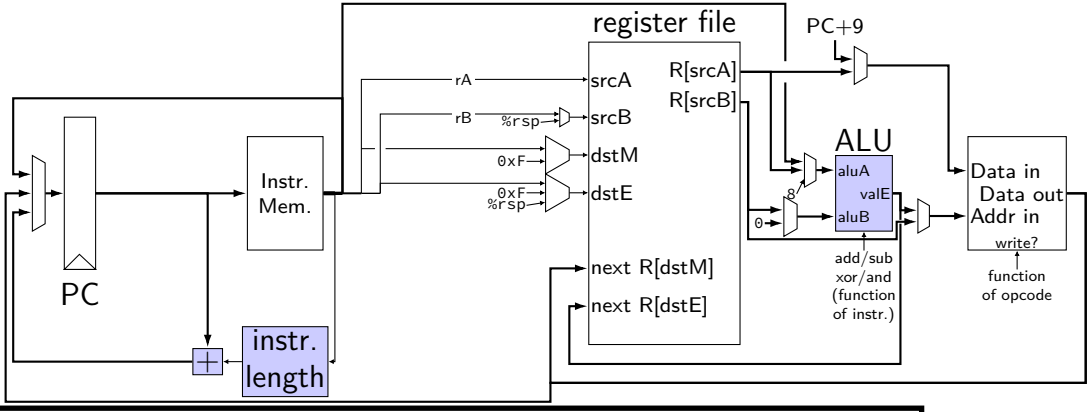
MUXes — PC, dstM, dstE, aluA, aluB, dmemIn, dmemAddr, ...
Exercise: what do they select for `rmmovq`?

circuit: setting MUXes



MUXes — PC, dstM, dstE, aluA, aluB, dmemIn, dmemAddr, ...
Exercise: what do they select for `irmovq`?

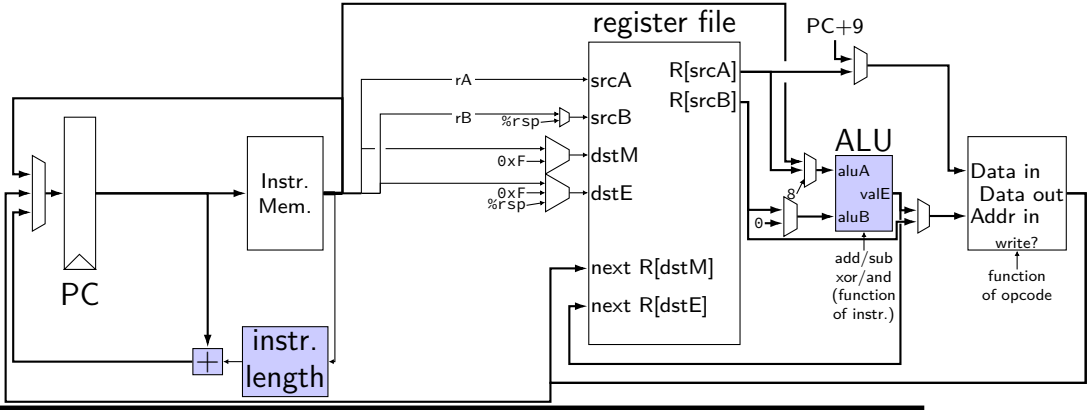
circuit: setting MUXes



MUXes — PC, dstM, dstE, aluA, aluB, dmemIn, dmemAddr, ...

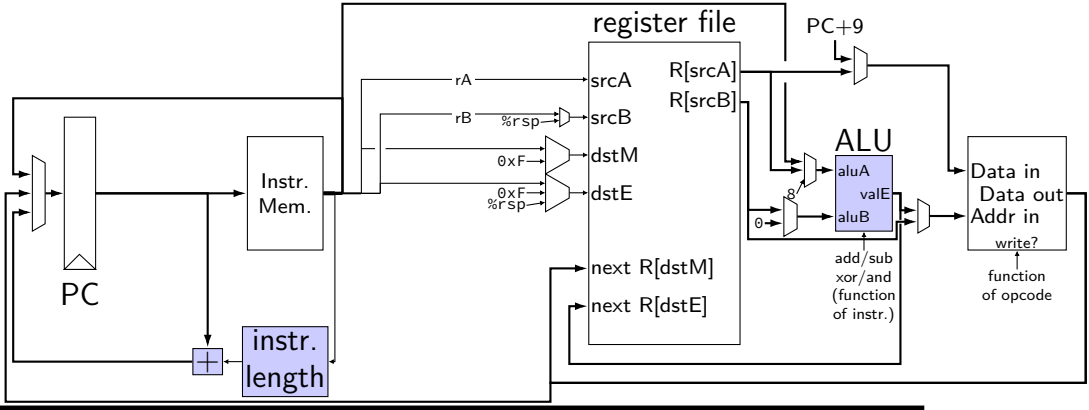
Exercise: what do they select for `mrmovq`?

circuit: setting MUXes



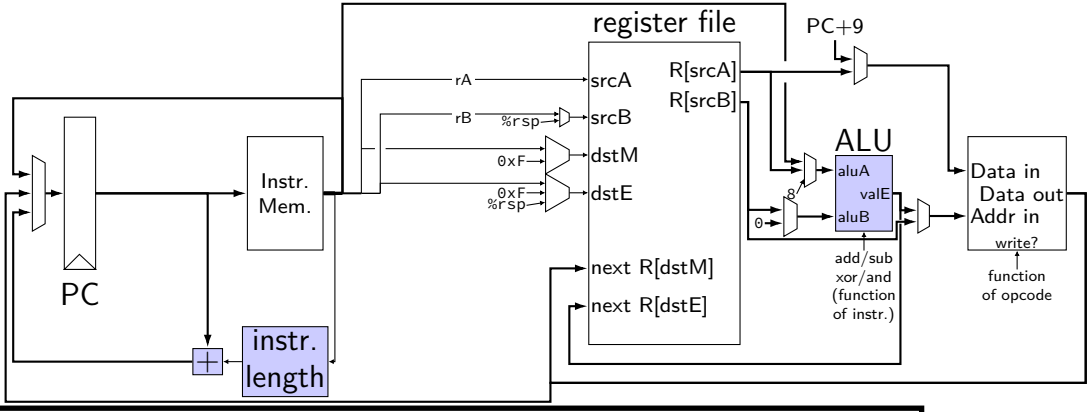
MUXes — PC, dstM, dstE, aluA, aluB, dmemIn, dmemAddr, ...
Exercise: what do they select for `jle`?

circuit: setting MUXes



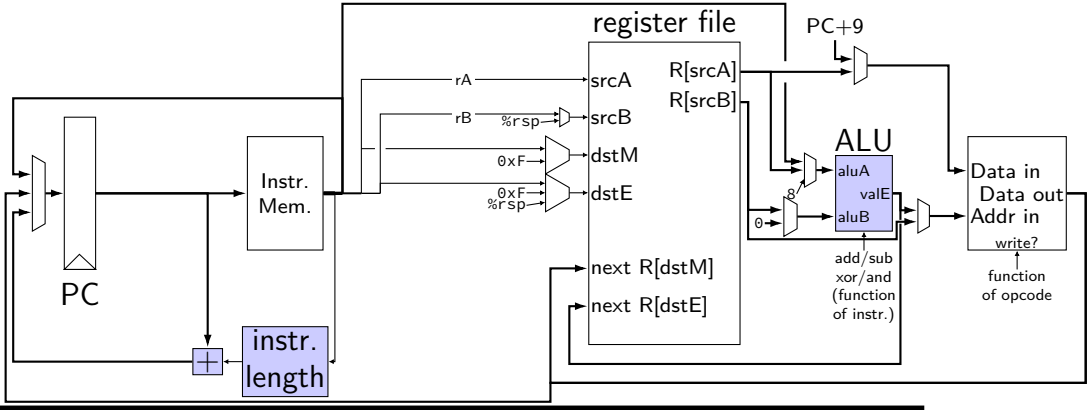
MUXes — PC, dstM, dstE, aluA, aluB, dmemIn, dmemAddr, ...
Exercise: what do they select for `cmovle`?

circuit: setting MUXes



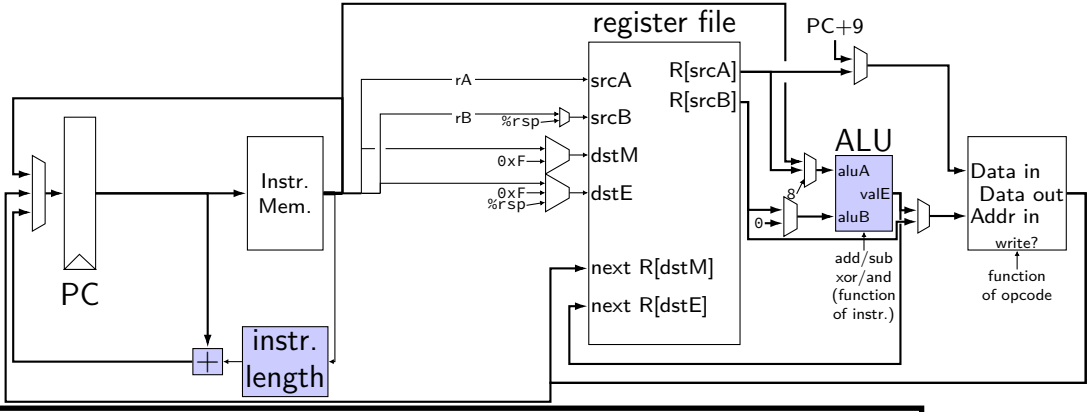
MUXes — PC, dstM, dstE, aluA, aluB, dmemIn, dmemAddr, ...
Exercise: what do they select for `ret`?

circuit: setting MUXes



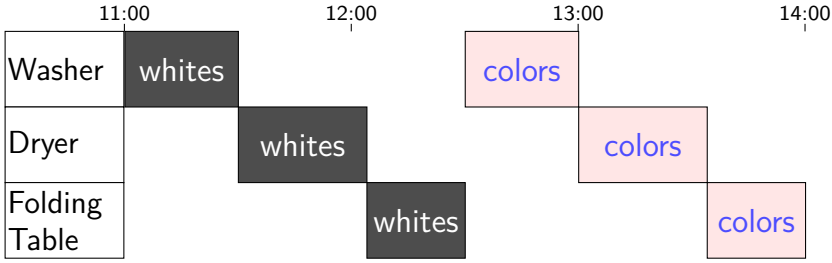
MUXes — PC, dstM, dstE, aluA, aluB, dmemIn, dmemAddr, ...
Exercise: what do they select for **popq**?

circuit: setting MUXes

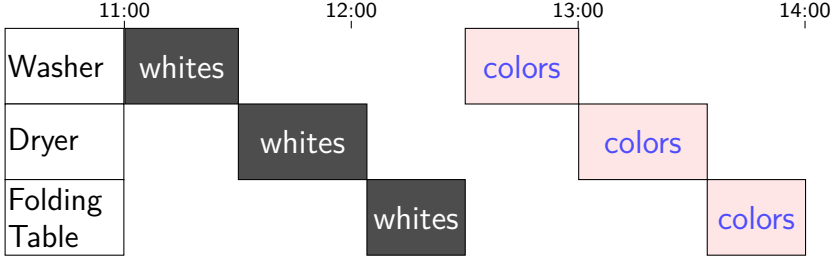


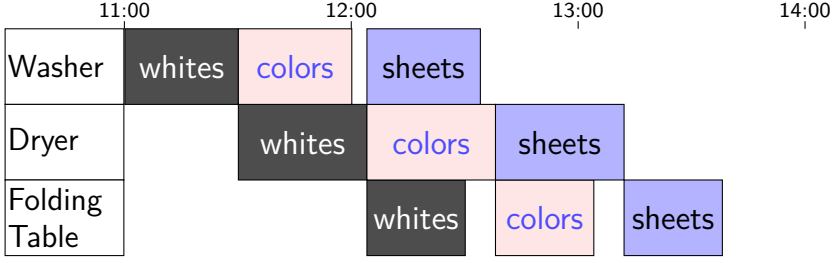
MUXes — PC, dstM, dstE, aluA, aluB, dmemIn, dmemAddr, ...
Exercise: what do they select for `call`?

Human pipeline: laundry

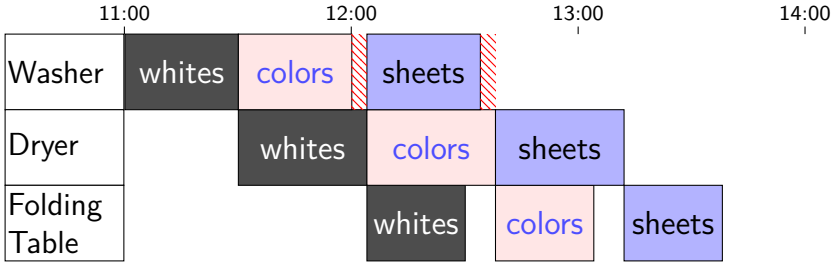


Human pipeline: laundry





Waste (1)


11:00
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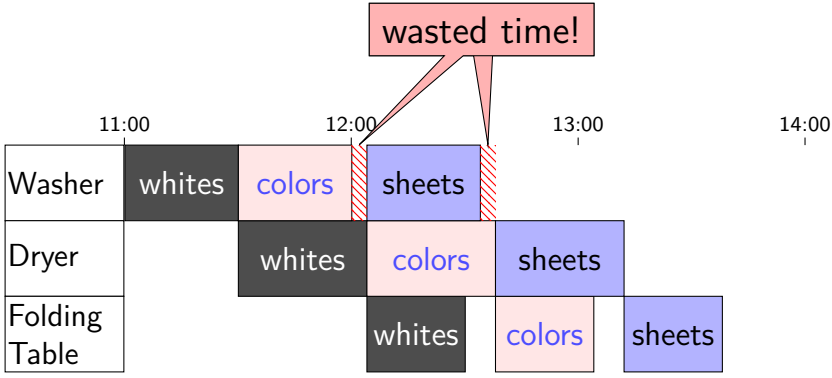
Waste (1)


wasted time!
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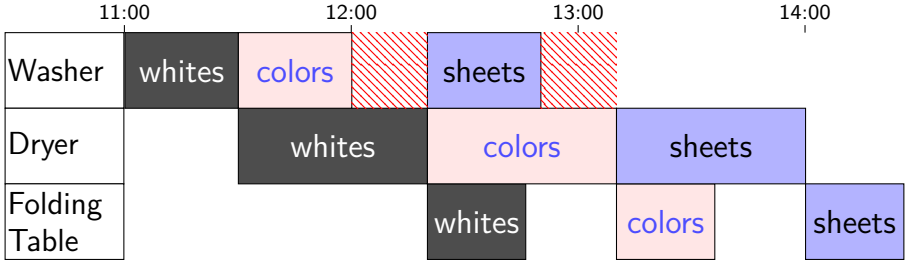
Waste (2)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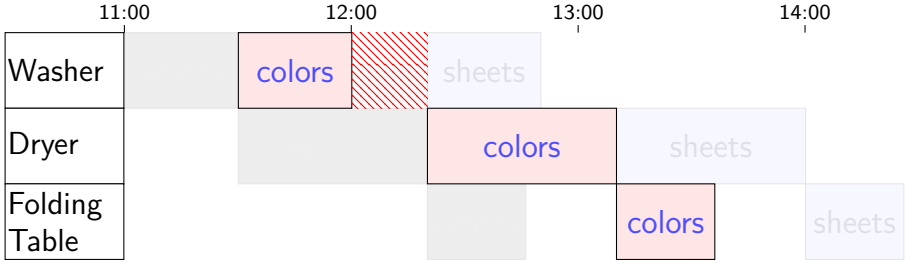
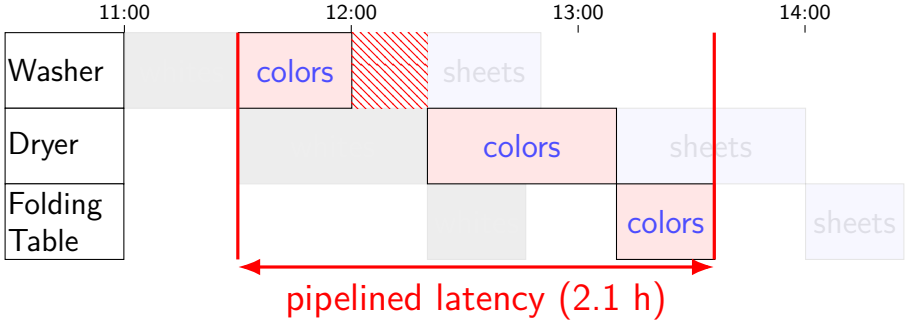
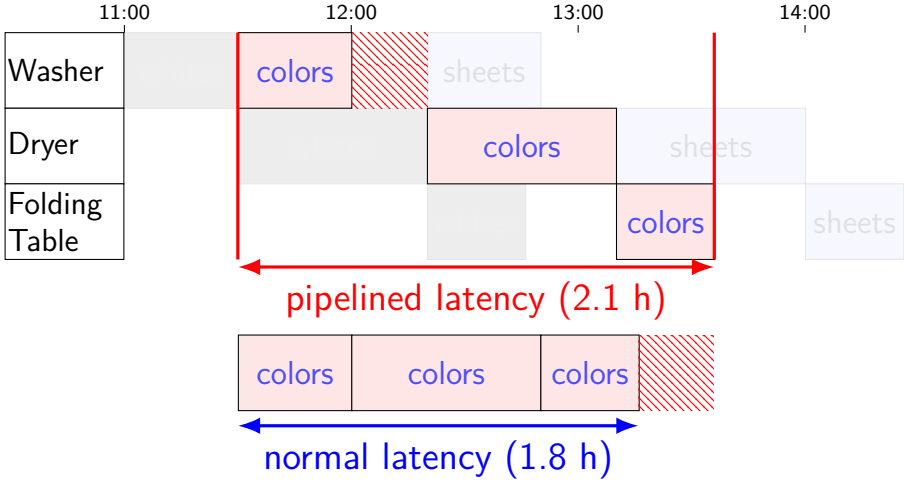
Latency — Time for One



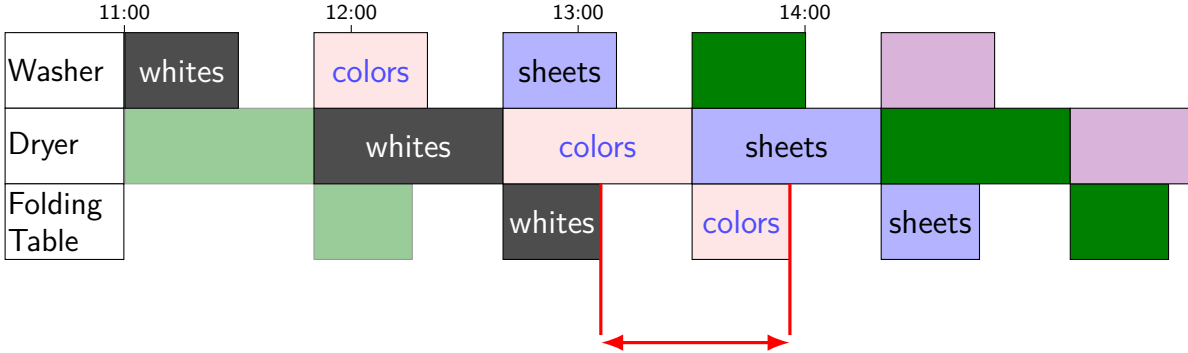
Latency — Time for One



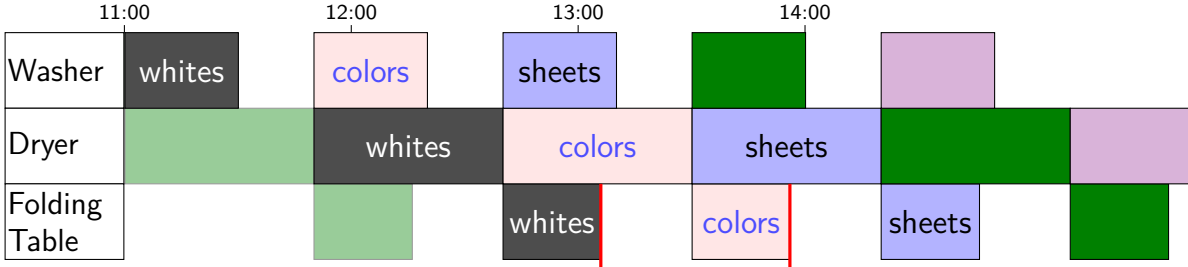
Latency — Time for One



Throughput — Rate of Many

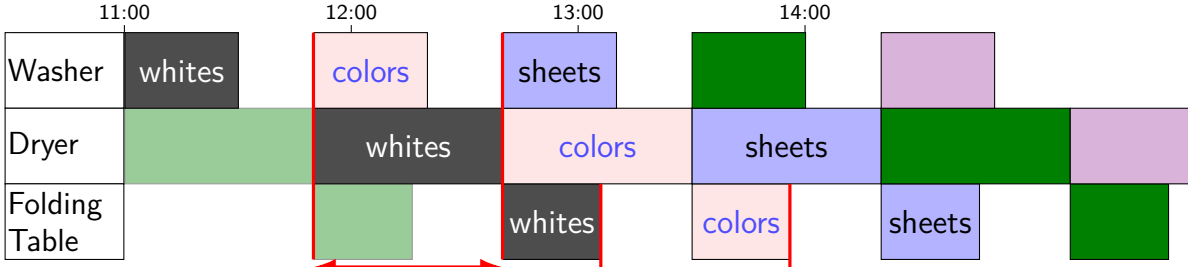


Throughput — Rate of Many



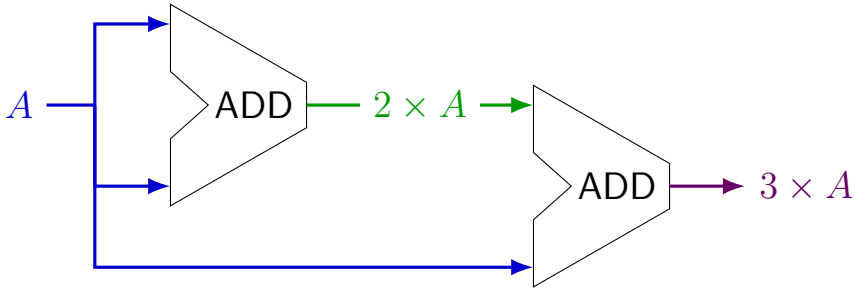
$$\frac{1 \text{ load}}{0.83\text{h}} = 1.2 \text{ loads/h}$$

Throughput — Rate of Many

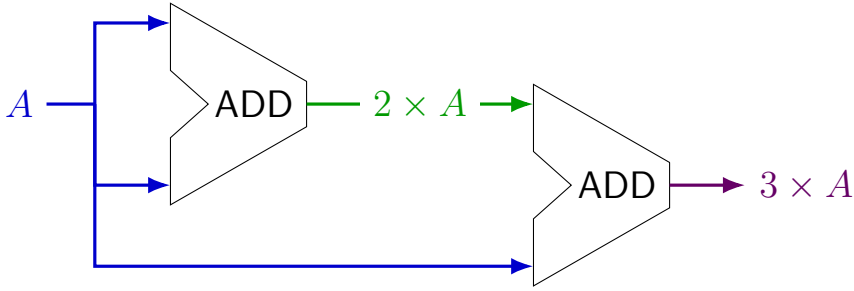


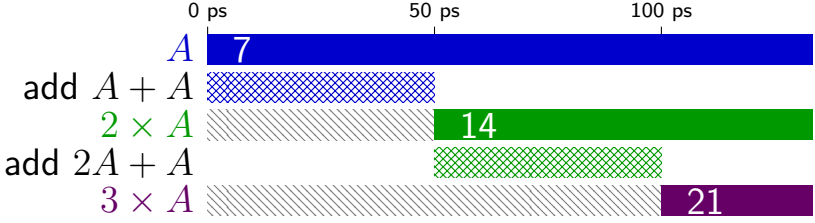
$$\frac{1 \text{ load}}{0.83\text{h}} = 1.2 \text{ loads/h}$$

times three circuit

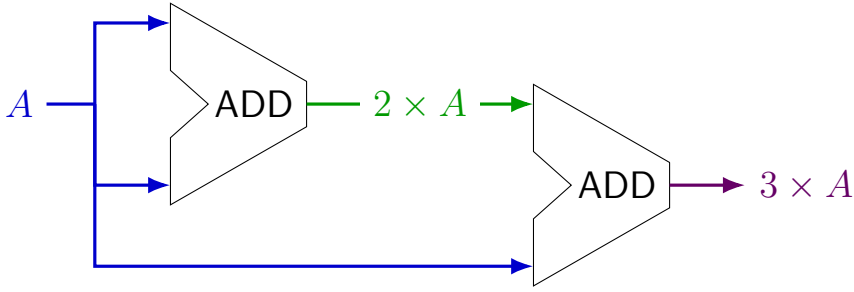


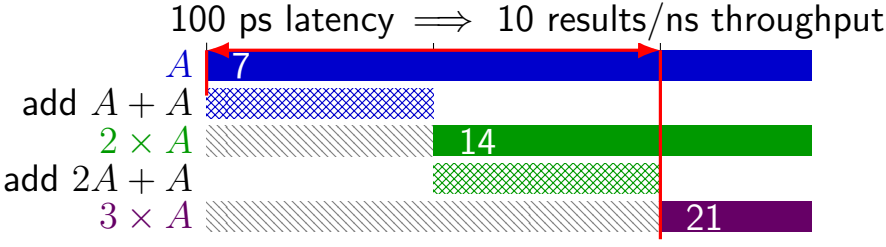
times three circuit



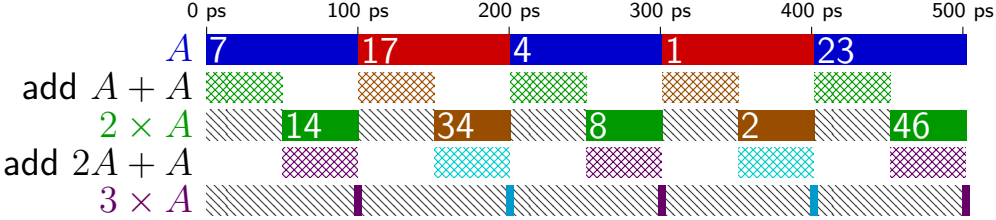


times three circuit

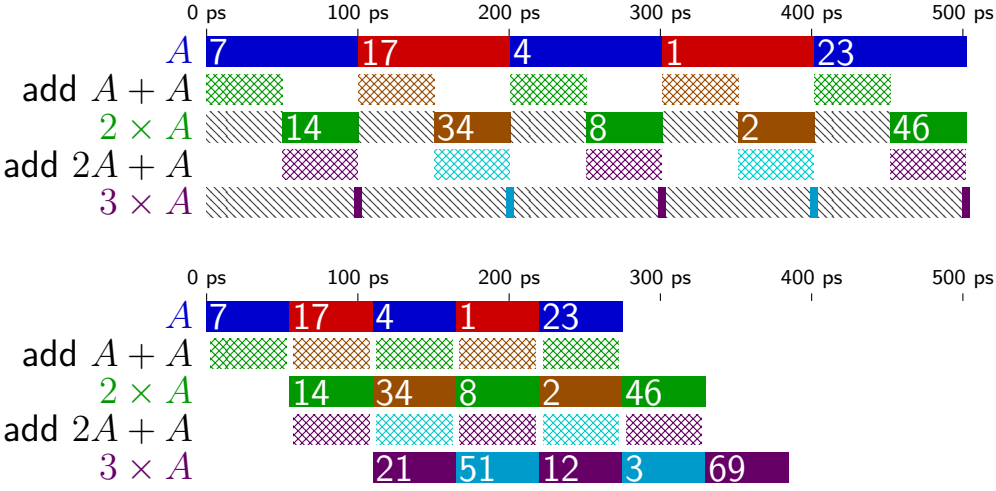




times three and repeat



times three and repeat



backup slides

comparing to yis

```
$ ./hclrs nopjmp_cpu.hcl nopjmp.yo
...
...
+---------------------- (end of halted state) ---------------------------+
Cycles run: 7
$ ./tools/yis nopjmp.yo
Stopped in 7 steps at PC = 0x1e.  Status 'HLT', CC Z=1 S=0 O=0
Changes to registers:

Changes to memory:
```

HCLRS summary

declare/assign values to wires

MUXes with

```
[ test1: value1; test2: value2; 1: default; ]
```

register banks with **`register i0`**:

next value on `i_name`; current value on `0_name`

fixed functionality

register file (15 registers; 2 read + 2 write)
memories (data + instruction)
Stat register (start/stop/error)