#### optimization (finish) / exceptions

#### last time

#### removing redundant operations

example: compiler often can't tell if function call produces same result each time

#### vector/SIMD instructions

extra wide registers can hold small (fixed-size) array of values instructions that perform operation (e.g. add) on several pairs of values typical implementation: extra wide ALU typical implementation: extra wide data cache accesses

vector instrinsics

#### vector exercise (2)

long A[1024], B[1024];

(casts omitted below to reduce clutter:)

```
for (int i = 0; i < 1024; i += 4) {</pre>
    A part = mm256 loadu si256(&A[i]);
    Bi part = mm256 loadu si256(&B[i]);
    for (int j = 0; j < 1024; /* BLANK 1 */) {
        Bj_part = _mm256_/* BLANK 2 */;
        A_part = _mm256_add_epi64(A_part,
            _mm256_mullo_epi64(Bi_part, Bj_part));
    }
    _mm256_storeu_si256(&A[i], A_part);
}
What goes in BLANK 1 and BLANK 2?
A. j += 1, loadu_si256(&B[j]) B. j += 4, loadu_si256(&B[j])
C. i += 1, set1 epi64(B[i])
                            D_i += 4, set1 epi64(B[i])
```

3

#### vector exercise 2 explanation

```
for (int i = 0; i < 1024; i += 1)
    for (int j = 0; j < 1024; j += 1)
        A[i] += B[i] * B[j];
/* -- transformed into -- */
for (int i = 0; i < 1024; i += 4)
    for (int j = 0; j < 1024; j += 1) {
        A[i+0] += B[i+0] * B[i];
        A[i+1] += B[i+1] * B[i];
        A[i+2] += B[i+2] * B[i];
        A[i+3] += B[i+3] * B[i];
    }
/* not the much harder to vectorize: */
for (int i = 0; i < 1024; i += 1)</pre>
    for (int j = 0; j < 1024; j += 4) {
```

A[i] += B[i] \* B[j+0]; A[i] += B[i] \* B[j+1]; A[i] += B[i] \* B[j+2]; A[i] += B[i] \* B[j+3];

}

#### other vector instructions features

more flexible vector instruction features: invented in the 1990s often present in GPUs and being rediscovered by modern ISAs

reasonable conditional handling

better variable-length vectors

ability to load/store non-contiguous values

some of these features in  $\mathsf{AVX2}/\mathsf{AVX512}$ 

#### alternate vector interfaces

intrinsics functions/assembly aren't the only way to write vector code

- e.g. GCC vector extensions: more like normal C code types for each kind of vector write + instead of \_mm\_add\_epi32
- e.g. CUDA (GPUs): looks like writing multithreaded code, but each thread is vector "lane"

#### optimizing real programs

ask your compiler to try first

spend effort where it matters

e.g. 90% of program time spent reading files, but optimize computation?

e.g. 90% of program time spent in routine A, but optimize B?

#### profilers

first step — tool to determine where you spend time

tools exist to do this for programs

example on Linux: perf

## example

Samples: 37K of event 'cycles', Event count (approx.): 37367555513					
	Children	Self	Command	Shared Object	Symbol
+	100.00%	0.00%	hclrs-with-debu	hclrs-with-debuginfo	[.] _start
+	100.00%	0.00%	hclrs-with-debu	libc-2.31.so	[.]libc_start_main
+	100.00%	0.00%	hclrs-with-debu		[.] main
+	100.00%	0.00%	hclrs-with-debu		[.] std::sys_common::backtrace::rust_begin_short_backt
+	100.00%	0.00%	hclrs-with-debu	hclrs-with-debuginfo	[.] hclrs::main
+	99.99%	9.75%	hclrs-with-debu	hclrs-with-debuginfo	<pre>[.] hclrs::program::RunningProgram::run</pre>
+	60.37%	31.67%	hclrs-with-debu	hclrs-with-debuginfo	<pre>[.] hclrs::ast::SpannedExpr::evaluate</pre>
+	41.34%	23.29%	hclrs-with-debu	hclrs-with-debuginfo	[.] hashbrown::map::make_hash
+	18.08%	18.07%	hclrs-with-debu	hclrs-with-debuginfo	[.] <std::collections::hash::map::defaulthasher as="" core:<="" th=""></std::collections::hash::map::defaulthasher>
+	16.33%	0.68%	hclrs-with-debu	hclrs-with-debuginfo	<pre>[.] hclrs::program::Program::process_register_banks</pre>
+	9.54%	3.15%	hclrs-with-debu	hclrs-with-debuginfo	[.] std::collections::hash::map::HashMap <k,v,s>::get</k,v,s>
+	9.10%	9.09%	hclrs-with-debu	libc-2.31.so	[.] memcmp avx2 movbe
+	6.11%	2.10%	hclrs-with-debu	hclrs-with-debuginfo	<pre>[.] hashbrown::map::HashMap<k,v,s>::get mut</k,v,s></pre>
+	2.32%	0.88%	hclrs-with-debu	hclrs-with-debuginfo	[.] std::collections::hash::map::HashMap <k,v,s>::get</k,v,s>
+	1.45%	0.52%	hclrs-with-debu	hclrs-with-debuginfo	<pre>[.] hashbrown::map::HashMap<k,v,s>::insert</k,v,s></pre>
	0.37%	0.11%	hclrs-with-debu	hclrs-with-debuginfo	[.] <alloc::string::string as="" core::clone::clone="">::clone</alloc::string::string>
	0.19%	0.19%	hclrs-with-debu	libc-2.31.so	[.] malloc

#### an infinite loop

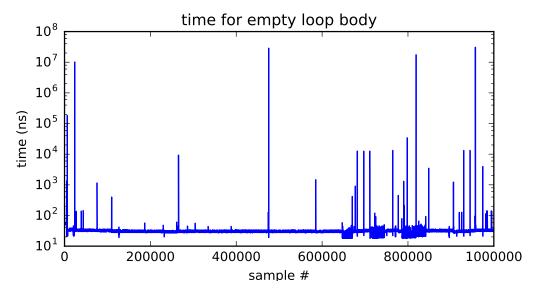
```
int main(void) {
    while (1) {
        /* waste CPU time */
    }
}
```

If I run this on a shared department machine, can you still use it? ... if the machine only has one core?

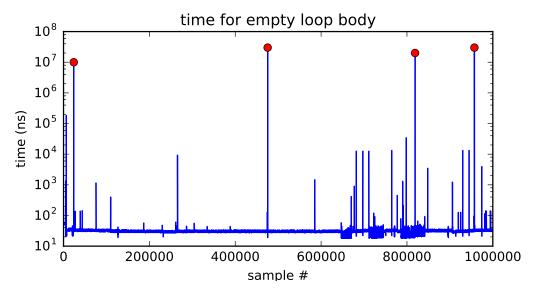
# timing nothing

```
long times[NUM TIMINGS];
int main(void) {
    for (int i = 0; i < N; ++i) {</pre>
         long start, end;
         start = get_time();
        /* do nothing */
         end = get_time();
         times[i] = end - start;
    }
    output_timings(times);
same instructions — same difference each time?
```

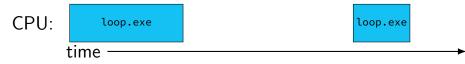
#### doing nothing on a busy system

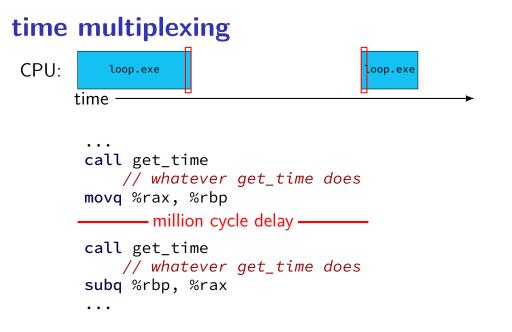


#### doing nothing on a busy system

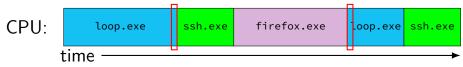


#### time multiplexing





#### time multiplexing



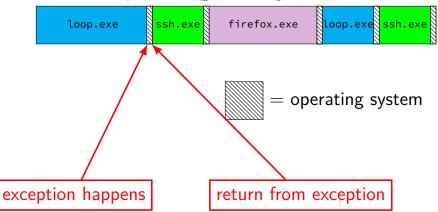
call get\_time
 // whatever get\_time does
movq %rax, %rbp
 million cycle delay
call get\_time
 // whatever get\_time does
subq %rbp, %rax

. . .

#### time multiplexing really

loop.exe	ssh.exe	firefox.exe	loop.exe	ssh.exe
----------	---------	-------------	----------	---------

#### time multiplexing really



#### OS and time multiplexing

starts running instead of normal program mechanism for this: exceptions (later)

saves old program counter, registers somewhere

sets new registers, jumps to new program counter

called context switch

saved information called context

#### context

all registers values %rax %rbx, ..., %rsp, ...

condition codes

program counter

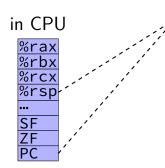
i.e. all visible state in your CPU except memory

#### context switch pseudocode

```
context_switch(last, next):
    copy_preexception_pc last->pc
    mov rax,last->rax
    mov rcx, last->rcx
    mov rdx, last->rdx
    ...
    mov next->rdx, rdx
    mov next->rcx, rcx
    mov next->rax, rax
    jmp next->pc
```

# contexts (A running)

in Memory



Process A memory: code, stack, etc.

Process B memory: code, stack, etc.

OS memory: %raxSF

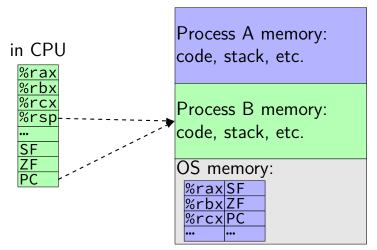
...

#### %rbxZF %rcxPC

...

## contexts (B running)

in Memory



#### memory protection

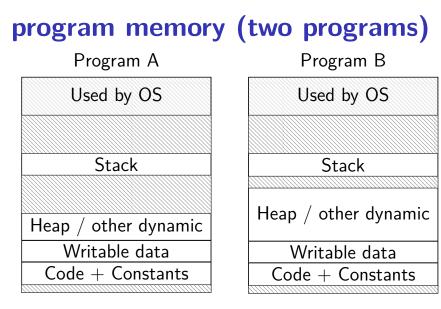
reading from another program	5
Program A	Program B
0x10000: .word 42 // // do work // movq 0x10000, %rax	// while A is working: movq \$99, %rax movq %rax, 0x10000 

#### memory protection

reading from another program Program A	n's memory? Program B				
0x10000: .word 42 // // do work // movq 0x10000, %rax	// while A is working: movq \$99, %rax movq %rax, 0x10000 				
result: %rax is A. 42 B. 99 C. 0x10000 D. 42 or 99 (depending on timing/program layout/etc) E. 42 or program might crash (depending on) F. 99 or program might crash (depending on) G. 42 or 99 or program might crash (depending on) H. something else					

#### memory protection

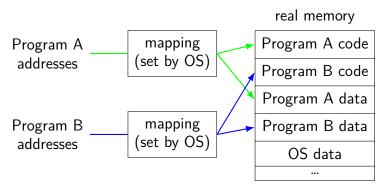
reading from another program's memory?				
Program A	Program B			
0x10000: .word 42 // // do work // movq 0x10000, %rax	// while A is working: movq \$99, %rax movq %rax, 0x10000 			
result: %rax is 42 (always)	result: might crash			

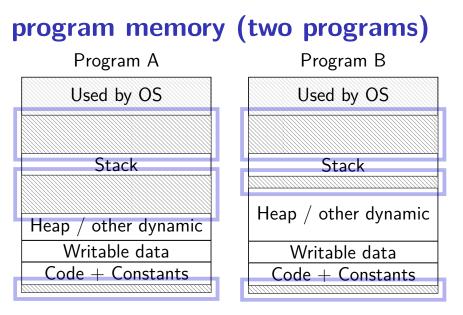


#### address space

programs have illusion of own memory

called a program's address space

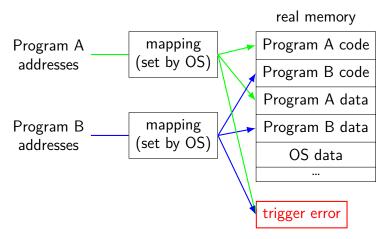




#### address space

programs have illusion of own memory

called a program's address space



#### address space mechanisms

- topic after exceptions
- called virtual memory
- mapping called page tables
- mapping part of what is changed in context switch

#### context

all registers values %rax %rbx, ..., %rsp, ...

condition codes

program counter

i.e. all visible state in your CPU except memory

address space: map from program to real addresses

#### **The Process**

process = thread(s) + address space

illusion of dedicated machine:

 $\label{eq:constraint} \begin{array}{l} \mbox{thread} = \mbox{illusion of own CPU} \\ \mbox{address space} = \mbox{illusion of own memory} \end{array}$ 

## types of exceptions

interrupts — externally-triggered timer — keep program from hogging CPU I/O devices — key presses, hard drives, networks, ...

aborts — hardware is broken

traps — intentionally triggered exceptions system calls — ask OS to do something

faults — errors/events in programs memory not in address space ("Segmentation fault") privileged instruction divide by zero invalid instruction asynchronous not triggered by running program

synchronous triggered by current program

#### types of exceptions

interrupts — externally-triggered timer — keep program from hogging CPU I/O devices — key presses, hard drives, networks, ...

aborts — hardware is broken

traps — intentionally triggered exceptions system calls — ask OS to do something

faults — errors/events in programs memory not in address space ("Segmentation fault") privileged instruction divide by zero invalid instruction asynchronous not triggered by running program

synchronous triggered by current program

## types of exceptions

interrupts — externally-triggered timer — keep program from hogging CPU I/O devices — key presses, hard drives, networks, ...

aborts — hardware is broken

traps — intentionally triggered exceptions system calls — ask OS to do something

faults — errors/events in programs
 memory not in address space ("Segmentation fault")
 privileged instruction
 divide by zero
 invalid instruction

asynchronous not triggered by running program

synchronous triggered by current program

## timer interrupt

(conceptually) external timer device (usually on same chip as processor)

OS configures before starting program

sends signal to CPU after a fixed interval

# types of exceptions

interrupts — externally-triggered timer — keep program from hogging CPU I/O devices — key presses, hard drives, networks, ...

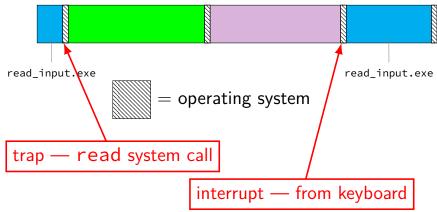
aborts — hardware is broken

traps — intentionally triggered exceptions system calls — ask OS to do something

faults — errors/events in programs memory not in address space ("Segmentation fault") privileged instruction divide by zero invalid instruction asynchronous not triggered by running program

synchronous triggered by current program

## keyboard input timeline



# types of exceptions

interrupts — externally-triggered timer — keep program from hogging CPU I/O devices — key presses, hard drives, networks, ...

aborts — hardware is broken

traps — intentionally triggered exceptions system calls — ask OS to do something

faults — errors/events in programs memory not in address space ("Segmentation fault") privileged instruction divide by zero invalid instruction asynchronous not triggered by running program

synchronous triggered by current program

## exception implementation

detect condition (program error or external event)

save current value of PC somewhere

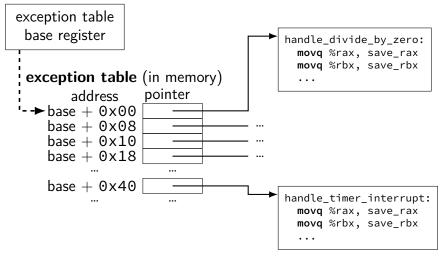
jump to exception handler (part of OS) jump done without program instruction to do so

## exception implementation: notes

I/textbook describe a simplified version

real x86/x86-64 is a bit more complicated (mostly for historical reasons)

# locating exception handlers



## running the exception handler

hardware saves the old program counter (and maybe more)

identifies location of exception handler via table

then jumps to that location

OS code can save anything else it wants to , etc.

new instruction: set exception table base

new logic: jump based on exception table may need to cancel partially completed instructions before jumping

new logic: save the old PC (and maybe more) to special register or to memory

new instruction: set exception table base

new logic: jump based on exception table may need to cancel partially completed instructions before jumping

new logic: save the old PC (and maybe more) to special register or to memory

new instruction: set exception table base

new logic: jump based on exception table may need to cancel partially completed instructions before jumping

new logic: save the old PC (and maybe more) to special register or to memory

new instruction: set exception table base

new logic: jump based on exception table may need to cancel partially completed instructions before jumping

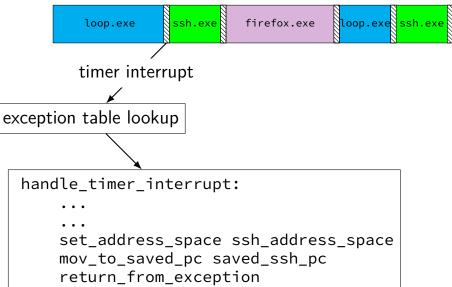
new logic: save the old PC (and maybe more) to special register or to memory

## exception handler structure

- 1. save process's state somewhere
- 2. do work to handle exception
- 3. restore a process's state (maybe a different one)
- 4. jump back to program

```
handle_timer_interrupt:
    mov_from_saved_pc save_pc_loc
    movq %rax, save_rax_loc
    ... // choose new process to run here
    movq new_rax_loc, %rax
    mov_to_saved_pc new_pc
    return_from_exception
```

## exceptions and time slicing



# defeating time slices?

```
my_exception_table:
...
my_handle_timer_interrupt:
    // HA! Keep running me!
    return_from_exception
main:
    set_exception_table_base my_exception_table
```

loop:

jmp loop

# defeating time slices?

wrote a program that tries to set the exception table:
my\_exception\_table:
...

```
main:
    // "Load Interrupt
    // Descriptor Table"
    // x86 instruction to set exception table
    lidt my_exception_table
    ret
```

result: Segmentation fault (exception!)

# types of exceptions

interrupts — externally-triggered timer — keep program from hogging CPU I/O devices — key presses, hard drives, networks, ...

aborts — hardware is broken

traps — intentionally triggered exceptions system calls — ask OS to do something

faults — errors/events in programs memory not in address space ("Segmentation fault") privileged instruction divide by zero invalid instruction asynchronous not triggered by running program

synchronous triggered by current program

## privileged instructions

can't let any program run some instructions

allows machines to be shared between users (e.g. lab servers)

examples:

...

```
set exception table
set address space
talk to I/O device (hard drive, keyboard, display, ...)
```

processor has two modes:

kernel mode — privileged instructions work user mode — privileged instructions cause exception instead

## kernel mode

extra one-bit register: "are we in kernel mode"

exceptions enter kernel mode

return from exception instruction leaves kernel mode

# types of exceptions

interrupts — externally-triggered timer — keep program from hogging CPU I/O devices — key presses, hard drives, networks, ...

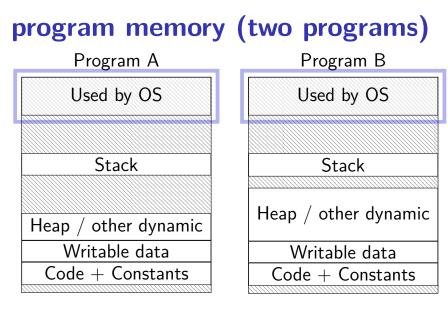
aborts — hardware is broken

traps — intentionally triggered exceptions system calls — ask OS to do something

faults — errors/events in programs memory not in address space ("Segmentation fault") privileged instruction divide by zero invalid instruction asynchronous not triggered by running program

synchronous triggered by current program

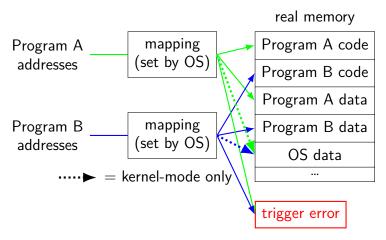
## what about editing exception table?



## address space

programs have illusion of own memory

called a program's address space



## protection fault

when program tries to access memory it doesn't own

e.g. trying to write to OS address

when program tries to do other things that are not allowed

- e.g. accessing I/O devices directly
- e.g. changing exception table base register

OS gets control — can crash the program or more interesting things

# types of exceptions

interrupts — externally-triggered timer — keep program from hogging CPU I/O devices — key presses, hard drives, networks, ...

aborts — hardware is broken

traps — intentionally triggered exceptions system calls — ask OS to do something

faults — errors/events in programs memory not in address space ("Segmentation fault") privileged instruction divide by zero invalid instruction asynchronous not triggered by running program

synchronous triggered by current program

## which requires kernel mode?

which operations are likely to fail (trigger an exception to run the OS instead) if attempted in user mode?

A. reading data on disk by running special instructions that communicate with the hard disk device

- B. changing a program's address space to allocate it more memory
- C. returning from a standard library function
- D. incrementing the stack pointer

## kernel services

- allocating memory? (change address space)
- reading/writing to file? (communicate with hard drive)
- read input? (communicate with keyborad)
- all need privileged instructions!
- need to run code in kernel mode

## Linux x86-64 system calls

special instruction: syscall

triggers trap (deliberate exception)

## Linux syscall calling convention

before syscall:

%rax — system call number

%rdi, %rsi, %rdx, %r10, %r8, %r9 — args

after syscall:

%rax — return value

on error: %rax contains -1 times "error number"

almost the same as normal function calls

## Linux x86-64 hello world

```
.globl start
.data
hello_str: .asciz "Hello, World!\n"
.text
start:
  movg $1, %rax # 1 = "write"
  movq $1, %rdi # file descriptor 1 = stdout
  movg $hello_str, %rsi
  movg $15, %rdx # 15 = strlen("Hello, World!\n")
  syscall
  movq $60, %rax # 60 = exit
  movq $0, %rdi
  syscall
```

#### approx. system call handler

```
sys_call_table:
    .quad handle_read_syscall
    .quad handle_write_syscall
    // ...
```

handle\_syscall: ... // save old PC, etc. pushq %rcx // save registers pushq %rdi ... call \*sys\_call\_table(,%rax,8) ... popq %rdi popq %rcx return\_from\_exception

## Linux system call examples

mmap, brk — allocate memory

fork — create new process

execve — run a program in the current process

\_exit — terminate a process

open, read, write — access files terminals, etc. count as files, too

## system call wrappers

can't write C code to generate syscall instruction

solution: call "wrapper" function written in assembly

# which of these require exceptions? context switches?

- A. program calls a function in the standard library
- B. program writes a file to disk
- C. program A goes to sleep, letting program B run
- D. program exits
- E. program returns from one function to another function
- F. program pops a value from the stack

# a note on terminology (1)

real world: inconsistent terms for exceptions

we will follow textbook's terms in this course

the real world won't

you might see:

'interrupt' meaning what we call 'exception' (x86) 'exception' meaning what we call 'fault' 'hard fault' meaning what we call 'abort' 'trap' meaning what we call 'fault' ... and more

# a note on terminology (2)

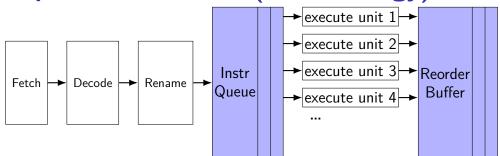
we use the term "kernel mode"

some additional terms:

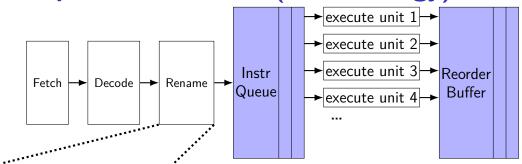
supervisor mode privileged mode ring 0

some systems have multiple levels of privilege different sets of priviliged operations work

exceptions and OOO (one strategy)

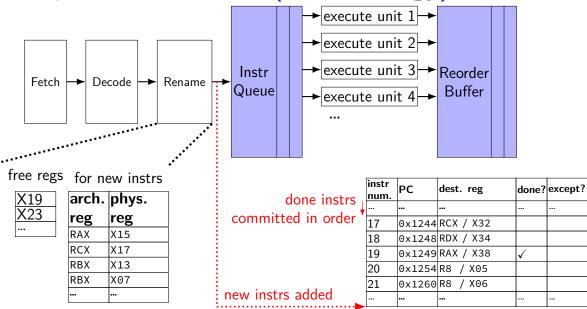


exceptions and OOO (one strategy)

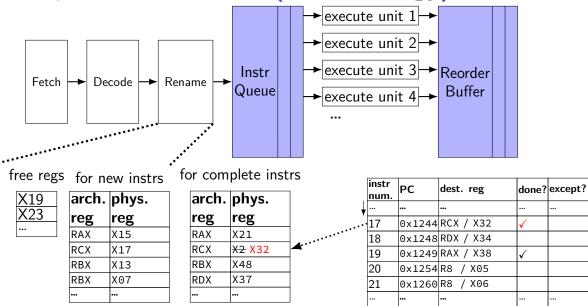


free regs for new instrs

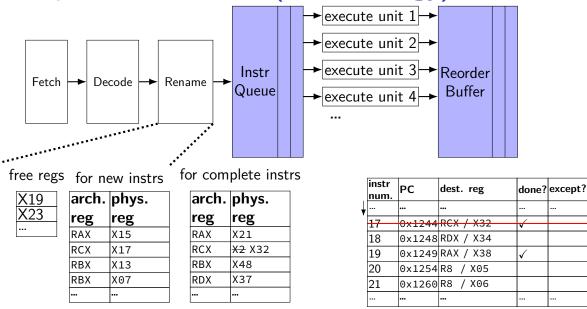
X19	arch.	phys.
X23	reg	reg
	RAX	X15
	RCX	X17
	RBX	X13
	RBX	X07

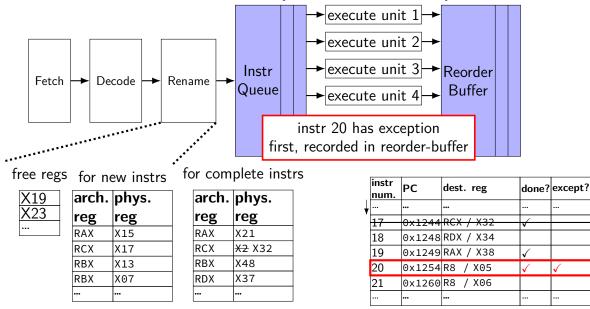


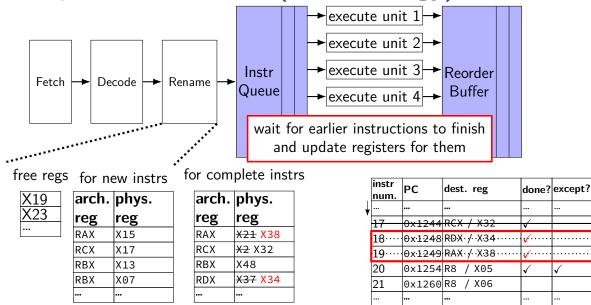
exceptions and OOO (one strategy)



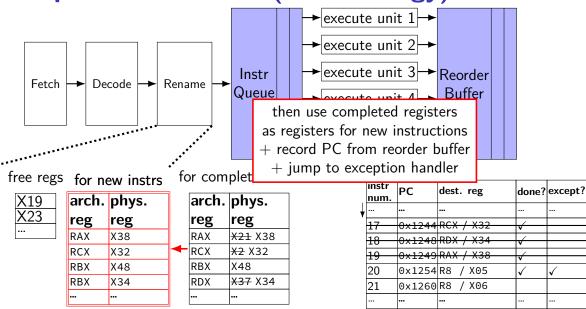
exceptions and OOO (one strategy)



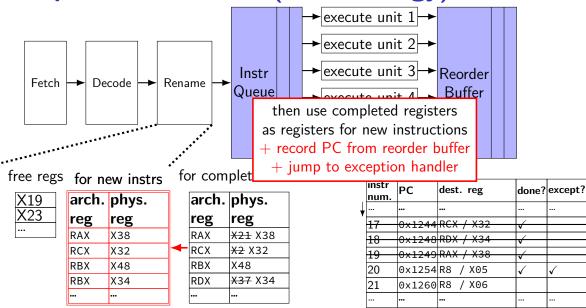




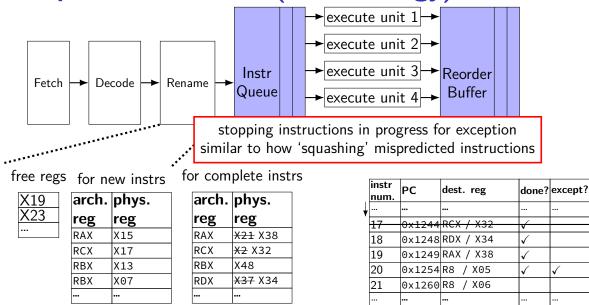
exceptions and OOO (one strategy)



exceptions and OOO (one strategy)

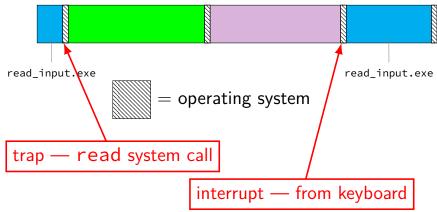


### exceptions and OOO (one strategy) execute unit 1 execute unit 2 execute unit 3 → Reorder Instr Fetch Decode Rename Queue Buffer ►execute unit 4 variation: could store architectual reg. values ..... instead of mapping for completed instrs. (and copy values instead of mapping on exception) free regs for complete instrs for new instrs instr PC done? except? dest. reg X19 arch. phys. num. arch. value ... X23 reg reg reg 17 0x1244 RCX / X32 ... RAX X15 RAX 0x12343 18 0x1248 RDX / X34 ~ RCX X17 RCX 0x234543 19 0x1249 RAX / X38 $\checkmark$ RBX X13 0x56782 RBX 20 0x1254 R8 X05 $\checkmark$ RBX X07 RDX 0xF83A4 21 0x1260 R8 / X06 ••• ... ••• .... ••• ... ...



# backup slides

### keyboard input timeline



# backup slides