

SEQ part 3

last time

HCLRS built-in register file

- inputs for register indices to read+write

- reads as indices received

- writes occur at rising edge of clock (but setup earlier)

- REG_NONE = 0xF to “not write”

HCLRS built-in data memory

- accesses same data as instruction memory

- read like instruction memory

- writes occur at rising edge of clock (but setup earlier)

- read+write enable signals

processor stages

- conceptual division of processor's work

- actual ordering: components compute as received + write at rising edge

stages: fetch / decode / execute / memory / writeback / PC update

stages and time

fetch / decode / execute / memory / write back / PC update

Order when these events happen pushq %rax instruction:

1. instruction read
2. memory changes
3. %rsp changes
4. PC changes

Hint: recall how registers, register files, memory works

- a. 1; then 2, 3, and 4 in any order
- b. 1; then 2, 3, and 4 at almost the same time
- c. 1; then 2; then 3; then 4
- d. 1; then 3; then 2; then 4
- e. 1; then 2; then 3 and 4 at almost the same time
- f. something else

SEQ: instruction fetch

read instruction memory at PC

split into separate wires:

icode:ifun — opcode

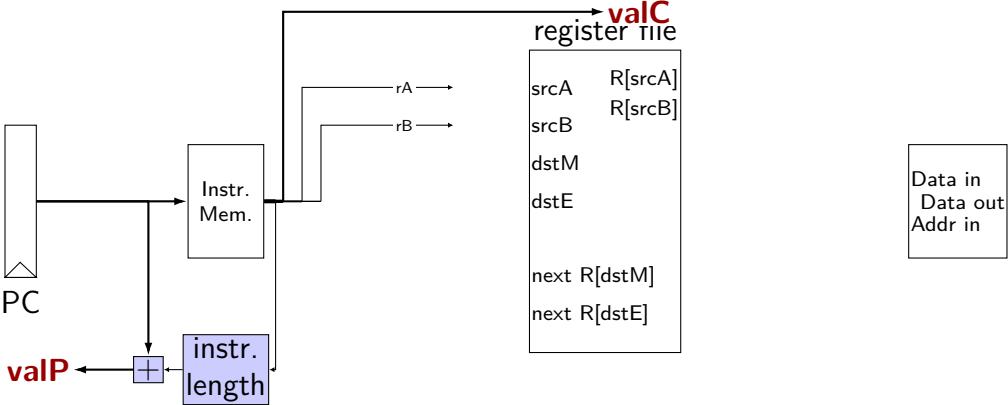
rA, rB — register numbers

valC — call target or mov displacement

compute next instruction address:

valP — $PC + (\text{instr length})$

instruction fetch

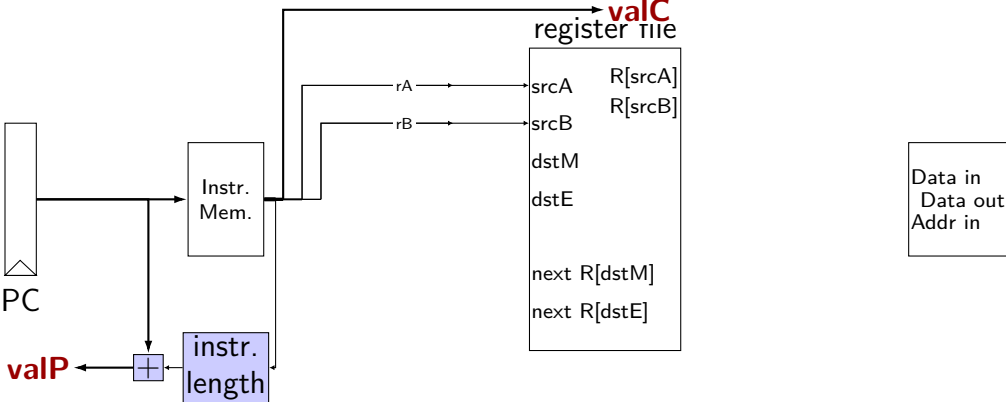


SEQ: instruction “decode”

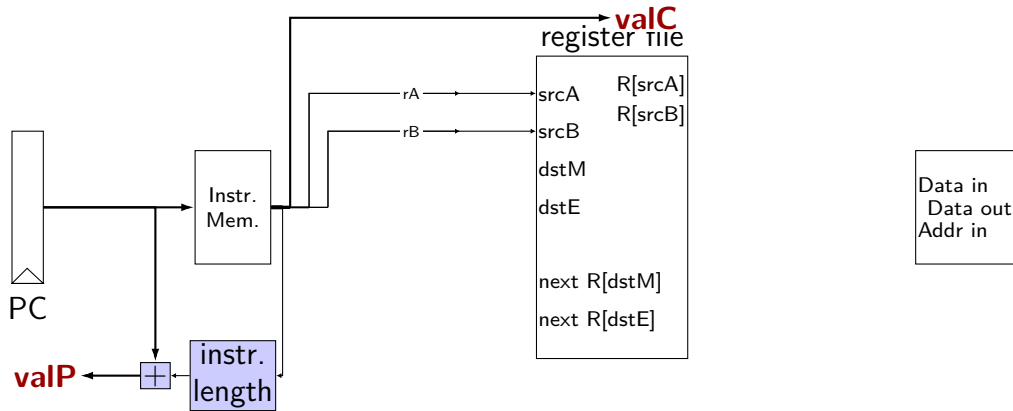
read registers

`valA`, `valB` — register values

instruction decode (1)

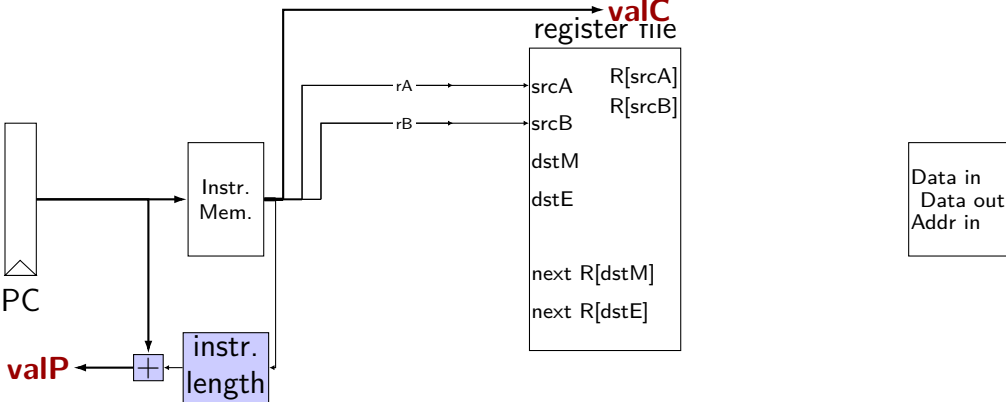


instruction decode (1)



exercise: for which instructions would there be a problem ?
nop, addq, mrmovq, rmmovq, jmp, pushq

instruction decode (1)



SEQ: srcA, srcB

always read rA, rB?

Problems:

- push rA

- pop

- call

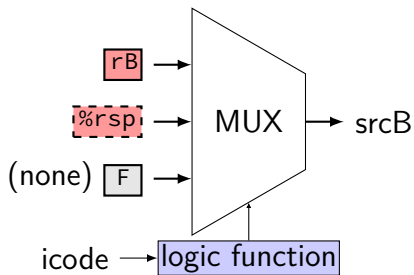
- ret

book: extra signals: srcA, srcB — computed input register

MUX controlled by icode

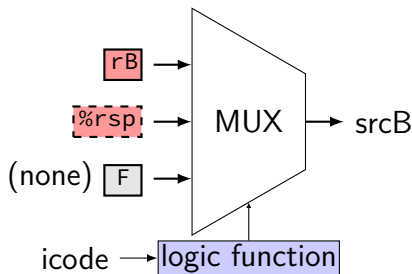
SEQ: possible registers to read

instruction	srcA	srcB
halt, nop, jCC, irmovq	none	none
cmovCC, rrmovq	rA	none
mrmovq	none	rB
rmmovq, OPq	rA	rB
call, ret	none?	%rsp
pushq, popq	rA	%rsp



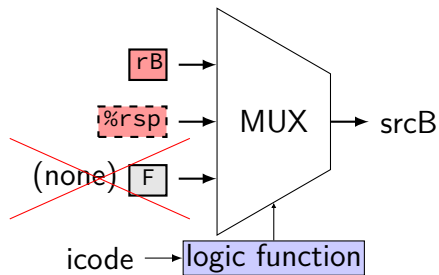
SEQ: possible registers to read

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halt, nop, jCC, irmovq	none	none
cmovCC, rrmovq	rA	none
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rmmovq, OPq	rA	rB
call, ret	none?	%rsp
pushq, popq	rA	%rsp

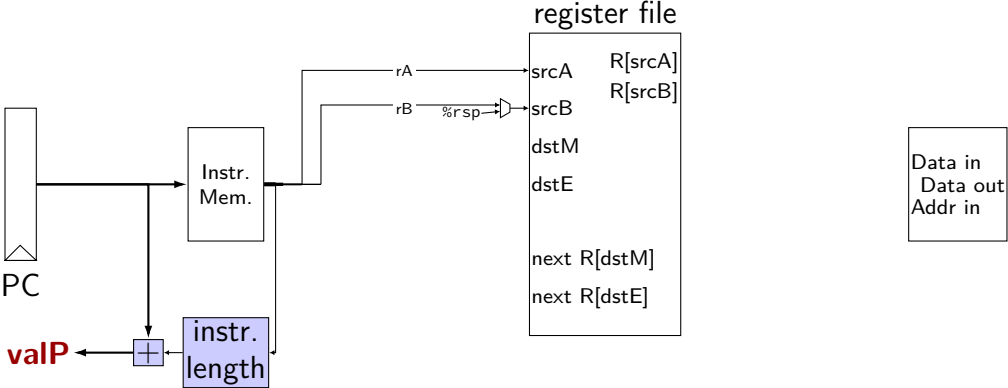


SEQ: possible registers to read

instruction	srcA	srcB
halt, nop, jCC, irmovq	none	none
cmovCC, rrmovq	rA	none
mrmovq	none	rB
rmmovq, OPq	rA	rB
call, ret	none?	%rsp
pushq, popq	rA	%rsp



instruction decode (2)



SEQ: execute

perform ALU operation (add, sub, xor, and)

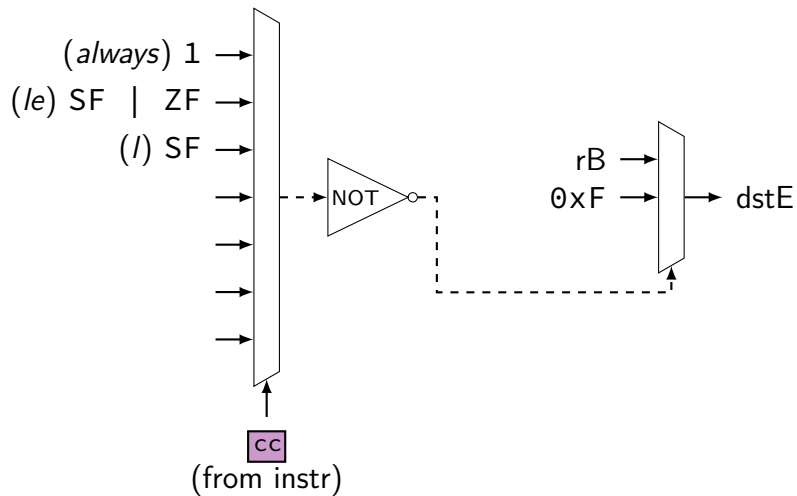
valE — ALU output

read prior condition codes

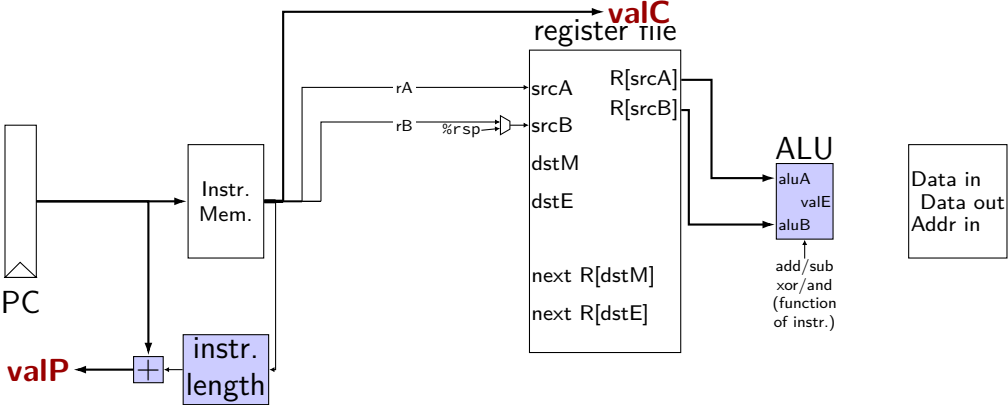
Cnd — condition codes based on ifun (instruction type for jCC/cmouvCC)

write new condition codes

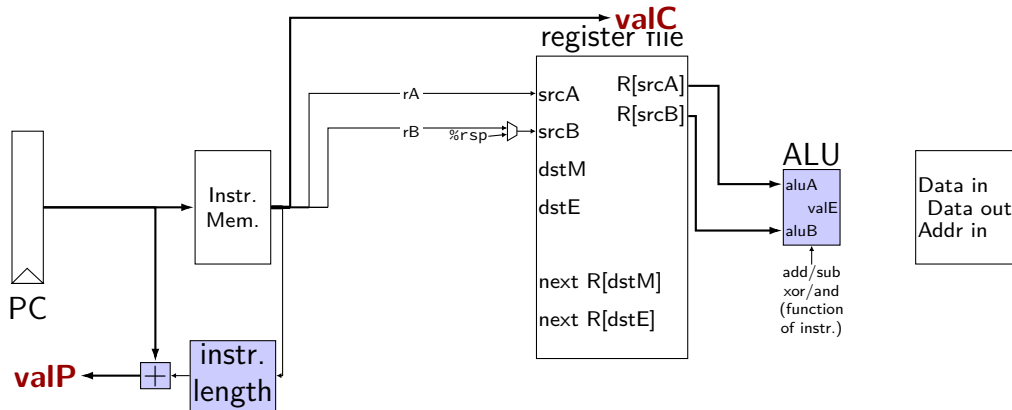
using condition codes: cmov



execute (1)



execute (1)



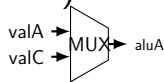
exercise: which of these instructions would there be a problem ?
nop, addq, mrmovq, popq, call,

SEQ: ALU operations?

ALU inputs always **valA**, **valB** (register values)?

no, inputs from instruction: (Displacement + rB)

`mrmovq`
`rmmovq`



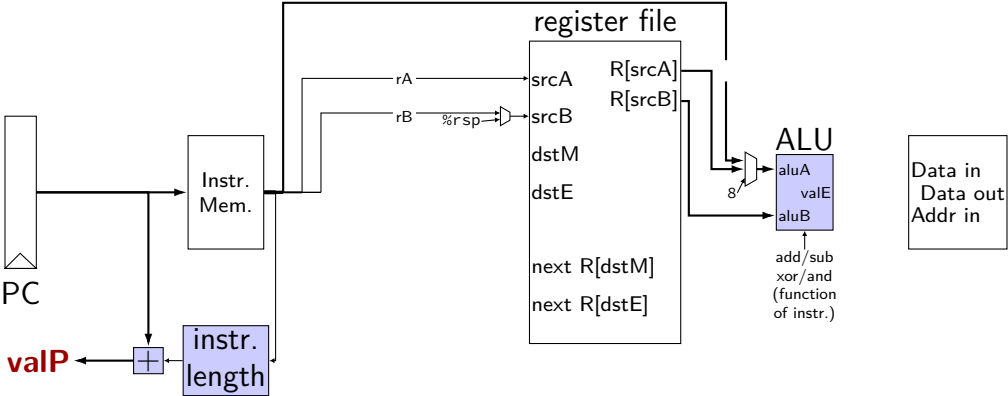
no, constants: (rsp +/- 8)

`pushq`
`popq`
`call`
`ret`

extra signals: **aluA**, **aluB**

computed ALU input values

execute (2)

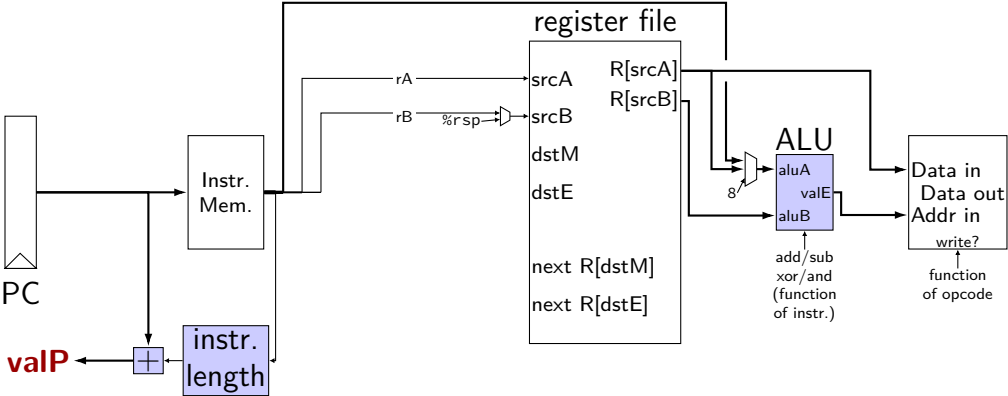


SEQ: Memory

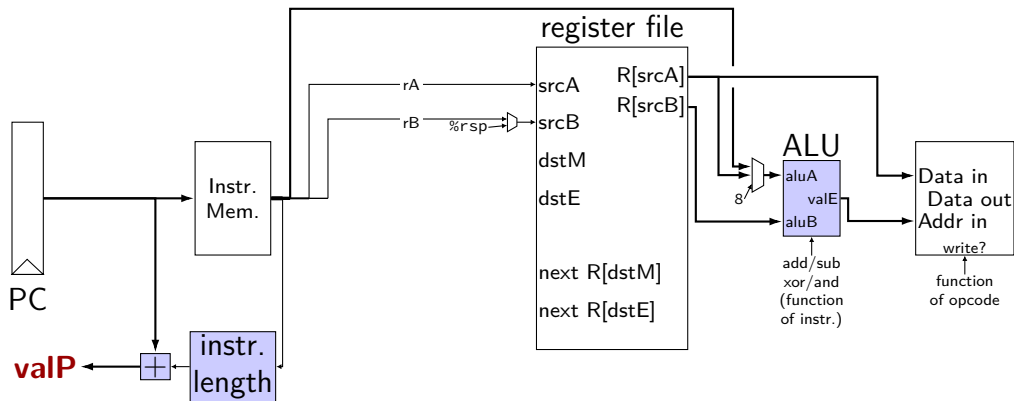
read or write data memory

valM — value read from memory (if any)

memory (1)



memory (1)



exercise: which of these instructions would there be a problem ?
nop, rmmovq, mrmovq, popq, call,

SEQ: control signals for memory

read/write — read enable? write enable?

Addr — address

mostly ALU output

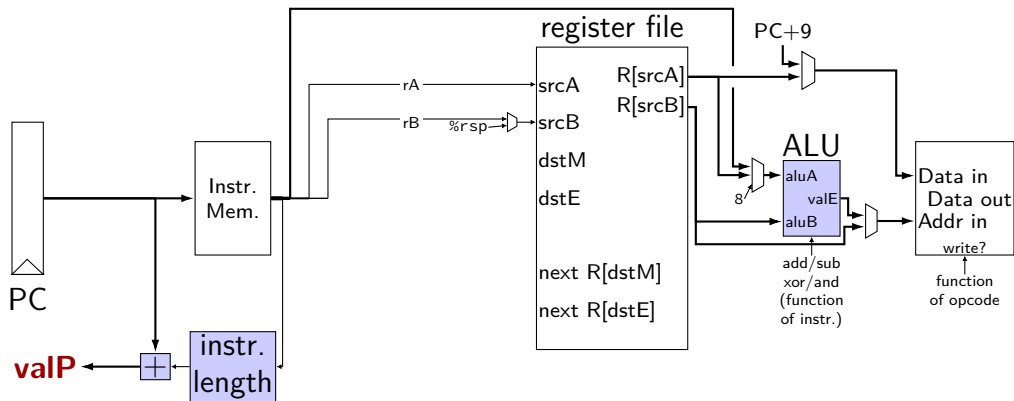
special cases (need extra MUX): `popq`, `ret`

Data — value to write

mostly `valA`

special cases (need extra MUX): `call`

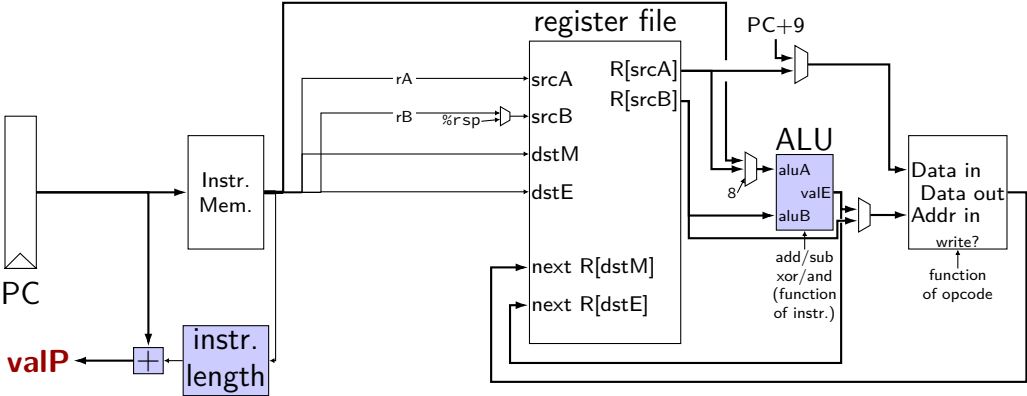
memory (2)



SEQ: write back

write registers

write back (1)



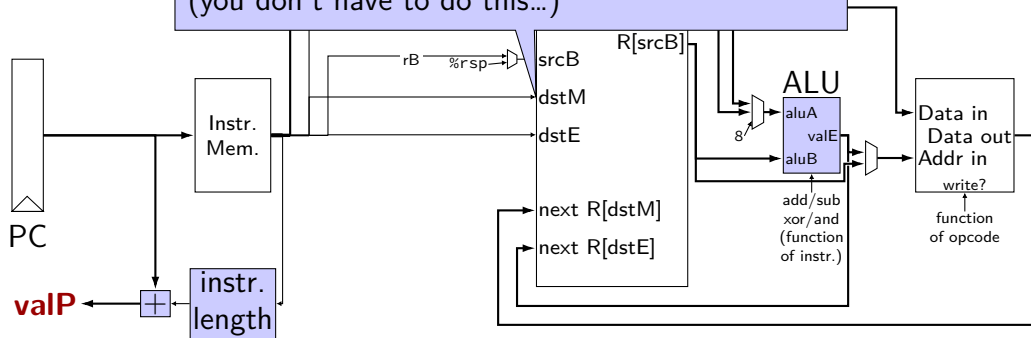
write back (1)

textbook convention:

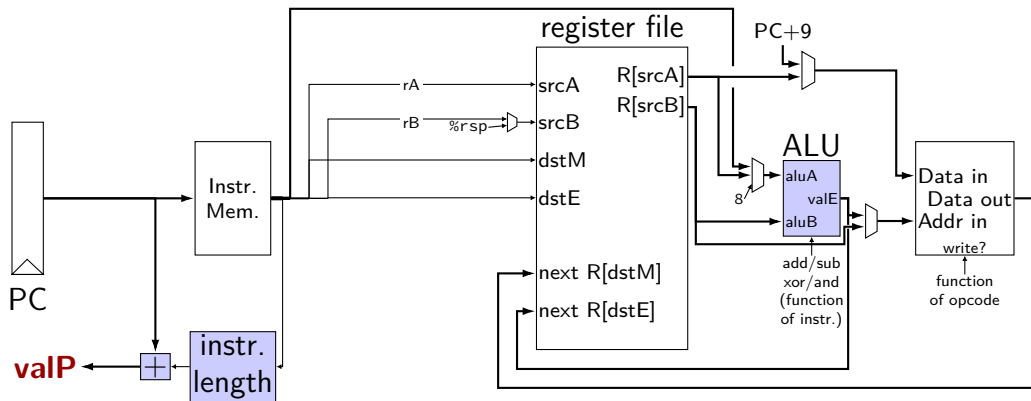
E used for storing ALU results (e.g. add)

M used for storing memory results (e.g. rmmovq)

(you don't have to do this...)



write back (1)



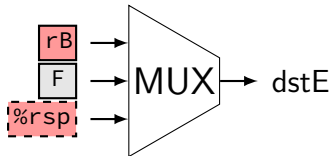
exercise: which of these instructions would there be a problem ?
nop, irmovq, mrmovq, rmmovq, addq, popq

SEQ: control signals for WB

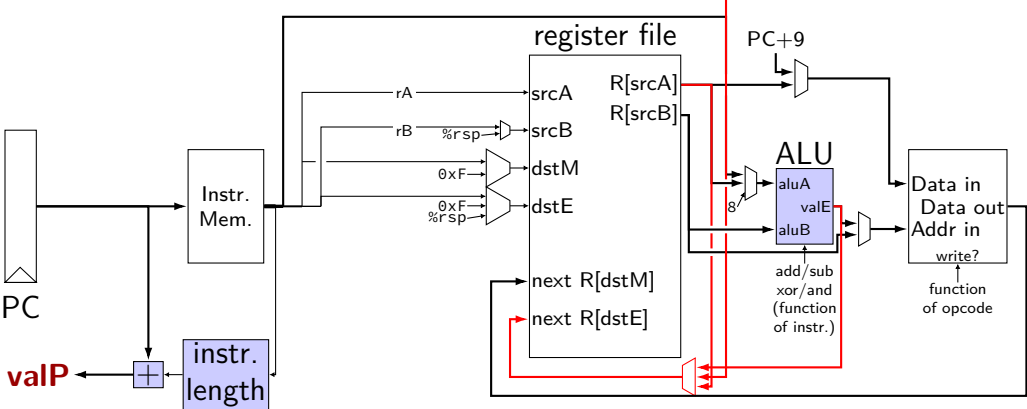
two write inputs — two needed by popq
valM (memory output), valE (ALU output)

two register numbers
dstM, dstE

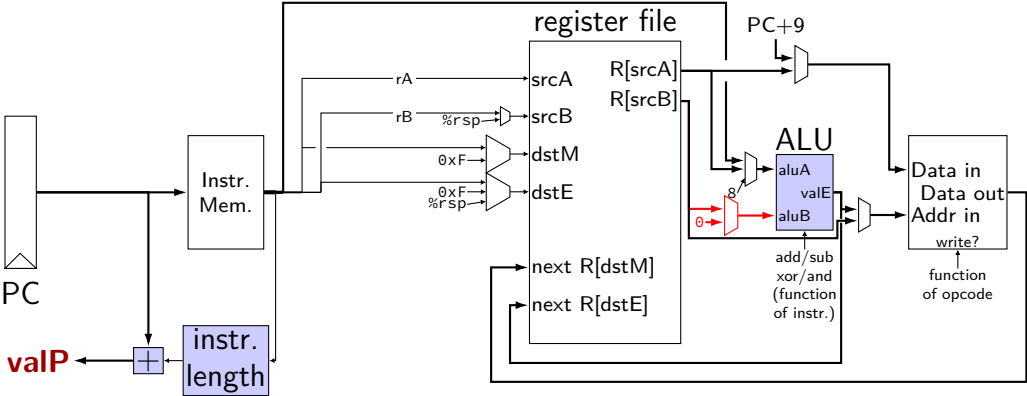
write disable — use dummy register number 0xF



write back (2a)



write back (2b)



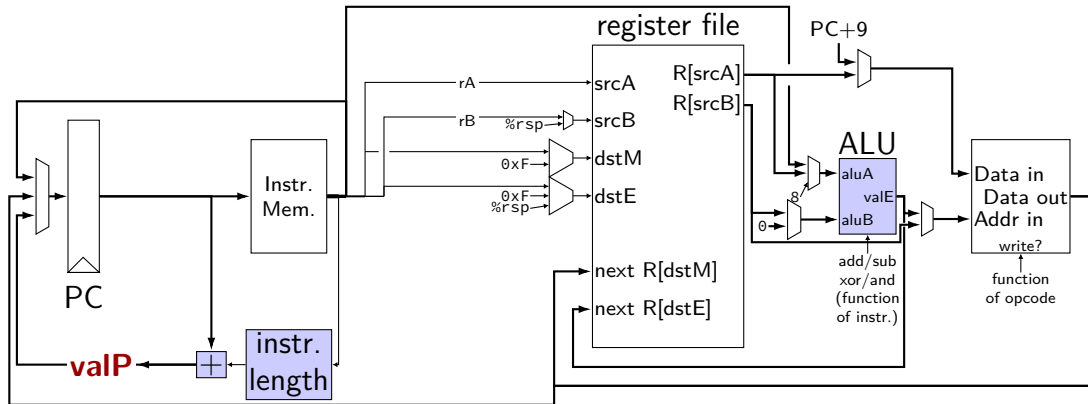
SEQ: Update PC

choose value for PC next cycle (input to PC register)

usually valP (following instruction)

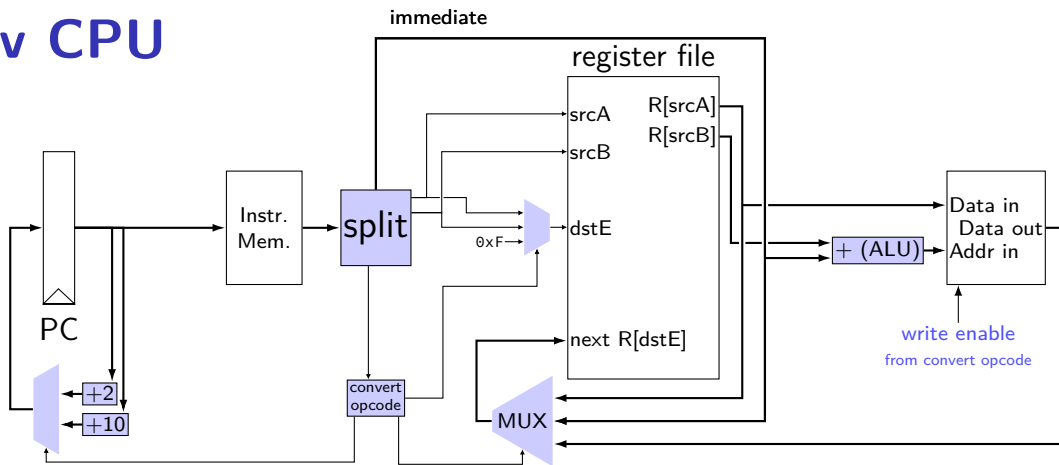
exceptions: `call`, `jCC`, `ret`

PC update



backup slides

mov CPU



mov CPU

