

Synchronization 4: Deadlock, Misc Lock Issues

Changelog

Changes made in this version not seen in first lecture:

4 October: livelock: move slides earlier (next to abort discussion)

4 October: revocable locks, Linux OOM killer: move slides earlier (next to steal discussion)

4 October: event-based programming: some single-threaded code: fix broken slide

4 October: add backup slides on dining philosopher ordering/abort

5 October: deadlock detection with variable resources: iterate over threads with owned/requested resources only; not all threads

last time (1)

monitor intuition:

- mutex locked before touching anything

- find reasons to wait

- condition variable for each

- broadcast (or maybe signal) when changing condition

reader/writer lock

- many readers at a time

- one writer

last time (2)

reader-priority/writer-priority

want writers to go before readers? count writers

change wait conditions to account for who else is waiting

choosing priorities generally

can track whatever you want, wait while not true

worst case: own queue with boolean + one condition variable/semaphore
per waiter

(probably duplicates internal queue of mutex/cond var)

bounded buffer producer/consumer

```
pthread_mutex_t lock;  
pthread_cond_t data_ready; pthread_cond_t space_ready;  
BoundedQueue buffer;
```

```
Produce(item) {  
    pthread_mutex_lock(&lock);  
    while (buffer.enqueue(item) == false) {  
        pthread_cond_wait(&space_ready, &lock);  
    }  
    pthread_mutex_unlock(&lock);  
}
```

```
Consume() {  
    pthread_mutex_lock(&lock);  
    while (buffer.dequeue() == false) {  
        pthread_cond_wait(&data_ready, &lock);  
    }  
    item = buffer.dequeue();  
    pthread_cond_signal(&space_ready);  
    pthread_mutex_unlock(&lock);  
    return item;  
}
```

error last time:

if (buffer.size() == buffer.capacity() - 1)

pthread_cond_signal(&space_ready);

what if two waiting producers and

two consumers run right after each other

problem: only one woken up



potential fixes

unconditionally signal

each consume allows one produce to go
rely on condition variable knowing if no one is waiting

broadcast if buffer changed from full to not-full

every thread waiting because it was full could go buffer it becomes full again

explicitly count number of waiting producers — buffer not full and waiter

how could I have avoided this?

question: who might be waiting when condition changes

almost always multiple threads!

if not broadcasting, **explain why each waiting thread gets to go**

my implicit non-explanation: queue will be full again first

not actually true: can keep consuming before producers go

how could I have avoided this?

question: who might be waiting when condition changes

almost always multiple threads!

if not broadcasting, **explain why each waiting thread gets to go**

my implicit non-explanation: queue will be full again first

not actually true: can keep consuming before producers go

alternate view: consuming causes what threads to go?

not just when the buffer was full

since if I empty the buffer by consuming...

last week's quiz

“after one processor finishes updating a value, another processor could still have an old version of the value cached”

invalid state → can never read it

generally, called “not cached”

from comments, significant number of people did not interpret it this way

life HW notes

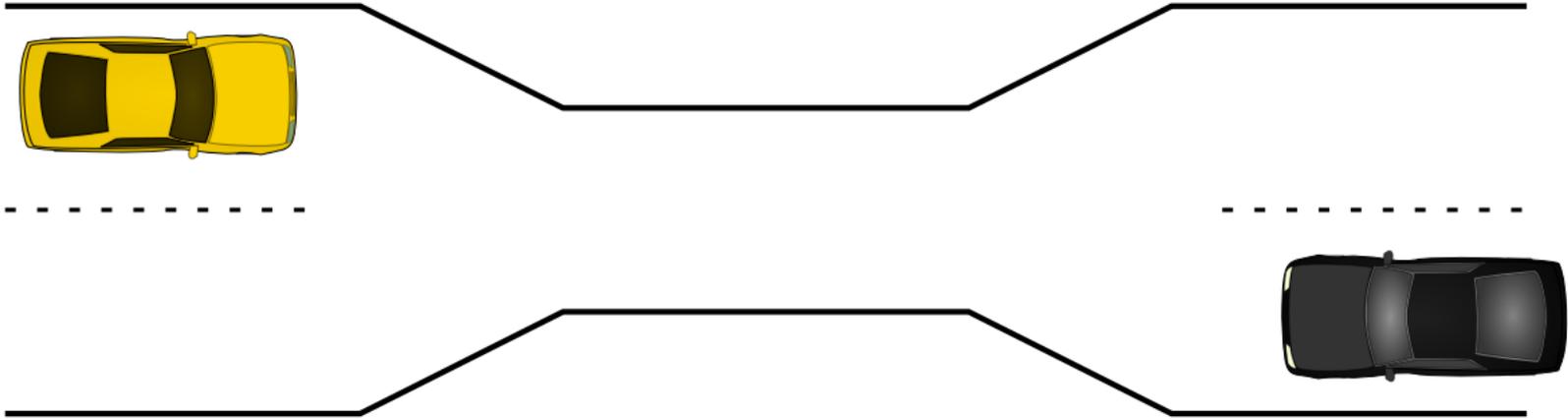
some common ways students seem to get confused

`LifeBoard my_copy; ... my_copy = state` makes a copy of state

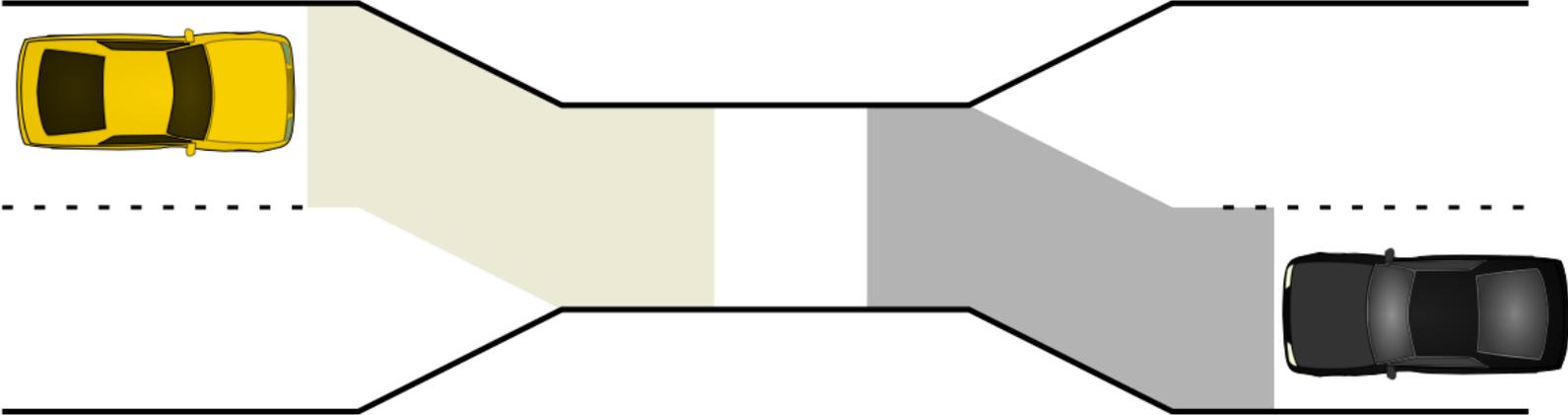
(even if `my_copy` is in a struct, etc.)

the `simulate` function modifies the state reference passed it
you better change that `LifeBoard` to return the result

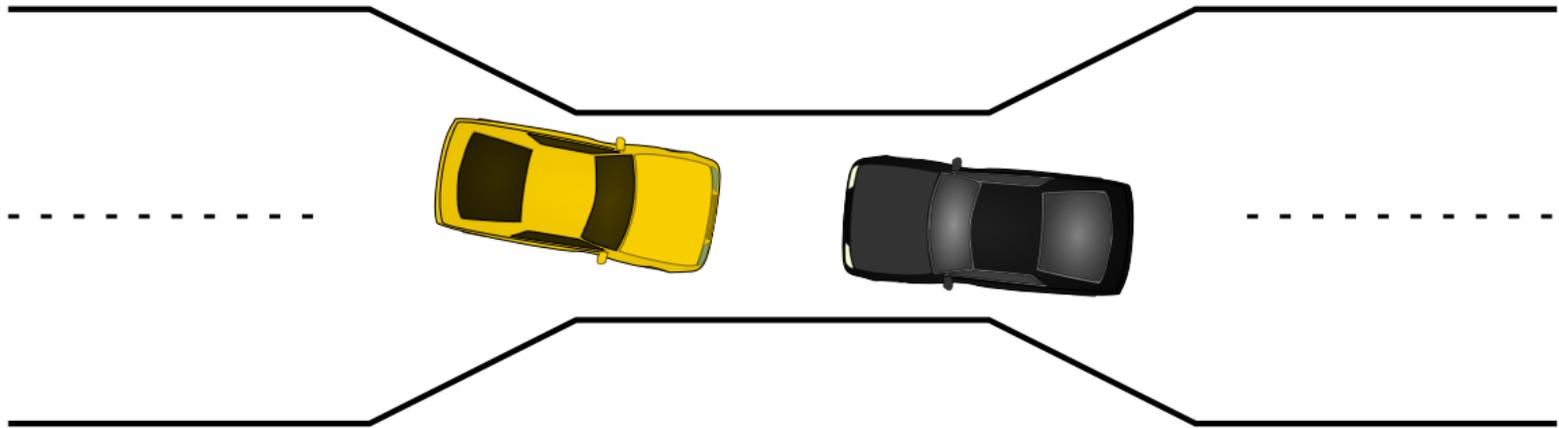
the one-way bridge



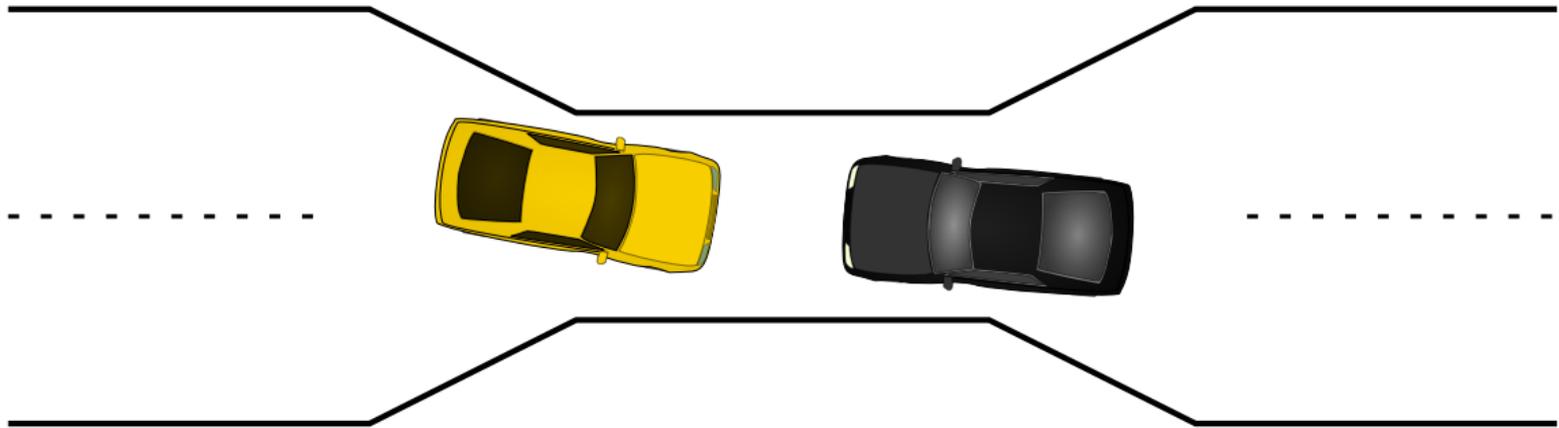
the one-way bridge



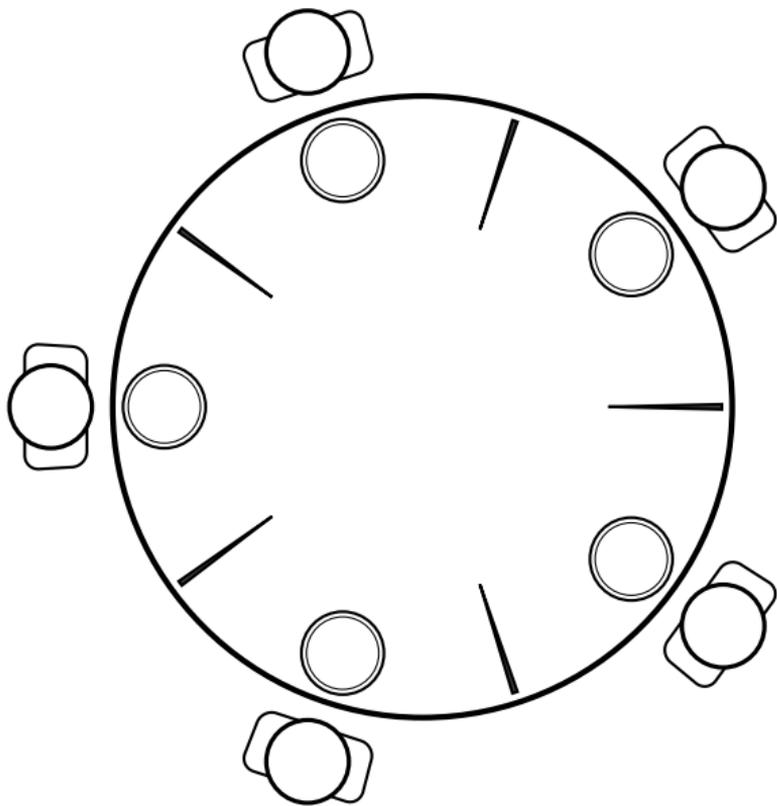
the one-way bridge



the one-way bridge

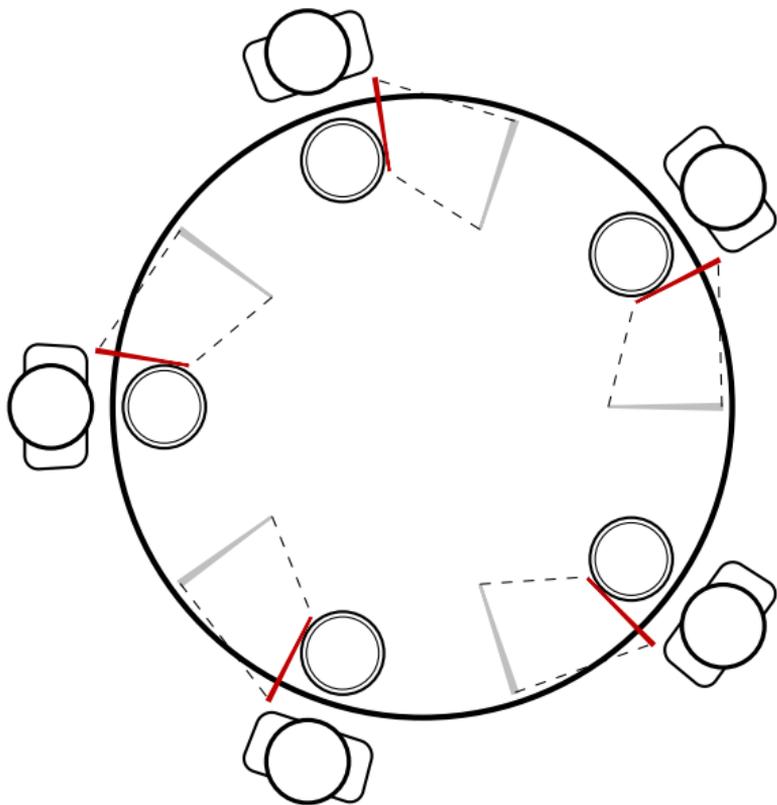


dining philosophers



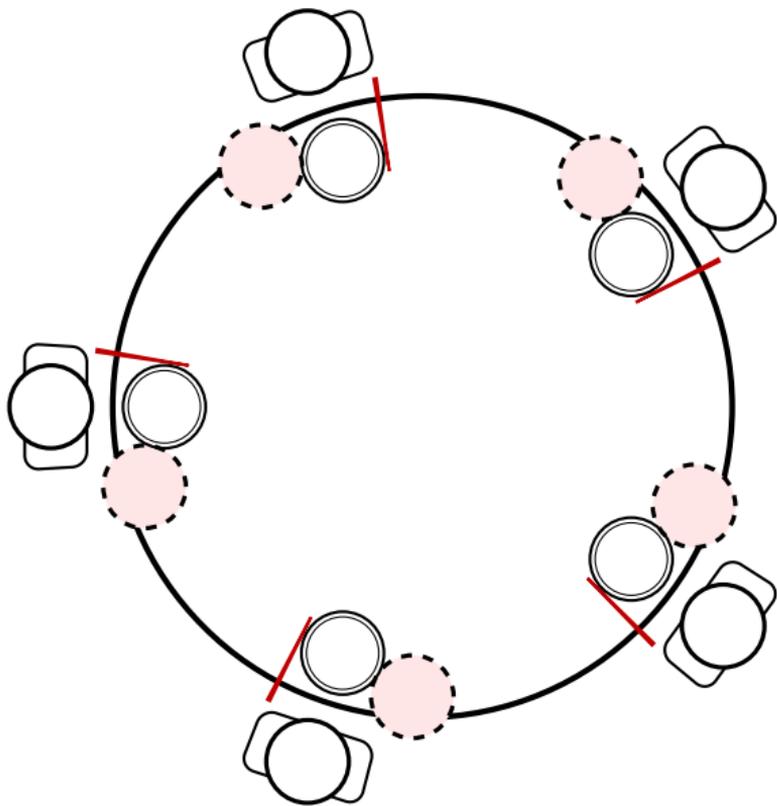
five philosophers either think or eat
to eat, grab chopsticks on either side

dining philosophers



everyone eats at the same time?
grab left chopstick, then...

dining philosophers



everyone eats at the same time?
grab left chopstick, then
try to grab right chopstick, ...
we're at an impasse

pipe() deadlock

BROKEN example:

```
int child_to_parent_pipe[2], parent_to_child_pipe[2];
pipe(child_to_parent_pipe); pipe(parent_to_child_pipe);
if (fork() == 0) {
    /* child */
    write(child_to_parent_pipe[1], buffer, HUGE_SIZE);
    read(parent_to_child_pipe[0], buffer, HUGE_SIZE);
    exit(0);
} else {
    /* parent */
    write(parent_to_child_pipe[1], buffer, HUGE_SIZE);
    read(child_to_parent[0], buffer, HUGE_SIZE);
}
```

This will **hang forever** (if `HUGE_SIZE` is big enough).

deadlock waiting

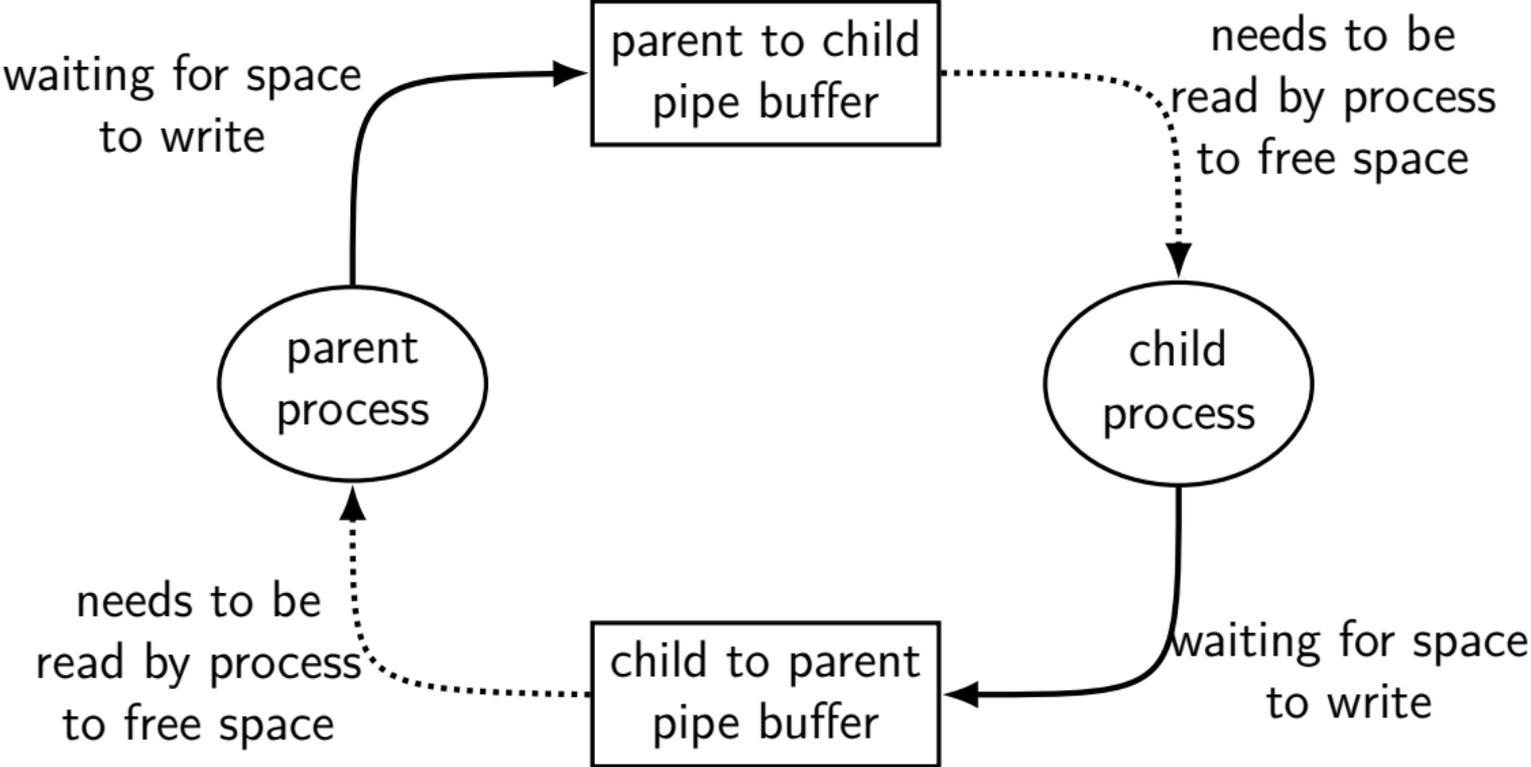
child writing to pipe waiting for free buffer space

...which will not be available until parent reads

parent writing to pipe waiting for free buffer space

...which will not be available until child reads

circular dependency



moving two files

```
struct Dir {
    mutex_t lock; map<string, DirEntry> entries;
};
void MoveFile(Dir *from_dir, Dir *to_dir, string filename) {
    mutex_lock(&from_dir->lock);
    mutex_lock(&to_dir->lock);

    to_dir->entries[filename] = from_dir->entries[filename];
    from_dir->entries.erase(filename);

    mutex_unlock(&to_dir->lock);
    mutex_unlock(&from_dir->lock);
}
```

Thread 1: MoveFile(A, B, "foo")

Thread 2: MoveFile(B, A, "bar")

moving two files: lucky timeline (1)

Thread 1

`MoveFile(A, B, "foo")`

`lock(&A->lock);`

`lock(&B->lock);`

(do move)

`unlock(&B->lock);`

`unlock(&A->lock);`

Thread 2

`MoveFile(B, A, "bar")`

`lock(&B->lock);`

`lock(&A->lock);`

(do move)

`unlock(&B->lock);`

`unlock(&A->lock);`

moving two files: lucky timeline (2)

Thread 1

```
MoveFile(A, B, "foo")
```

```
lock(&A->lock);
```

```
lock(&B->lock);
```

```
(do move)
```

```
unlock(&B->lock);
```

```
unlock(&A->lock);
```

Thread 2

```
MoveFile(B, A, "bar")
```

```
lock(&B->lock...
```

```
(waiting for B lock)
```

```
lock(&B->lock);
```

```
lock(&A->lock...
```

```
lock(&A->lock);
```

```
(do move)
```

```
unlock(&A->lock);
```

```
unlock(&B->lock);
```

moving two files: unlucky timeline

Thread 1

```
MoveFile(A, B, "foo")
```

```
lock(&A->lock);
```

Thread 2

```
MoveFile(B, A, "bar")
```

```
lock(&B->lock);
```

moving two files: unlucky timeline

Thread 1

```
MoveFile(A, B, "foo")
```

```
lock(&A->lock);
```

```
lock(&B->lock... stalled
```

```
(waiting for lock on B)
```

```
(waiting for lock on B)
```

Thread 2

```
MoveFile(B, A, "bar")
```

```
lock(&B->lock);
```

```
lock(&A->lock... stalled
```

```
(waiting for lock on A)
```

moving two files: unlucky timeline

Thread 1

MoveFile(A, B, "foo")

lock(&A->lock);

lock(&B->lock... **stalled**

(waiting for lock on B)

(waiting for lock on B)

~~(do move)~~ **unreachable**

~~unlock(&B->lock);~~ **unreachable**

~~unlock(&A->lock);~~ **unreachable**

Thread 2

MoveFile(B, A, "bar")

lock(&B->lock);

lock(&A->lock... **stalled**

(waiting for lock on A)

~~(do move)~~ **unreachable**

~~unlock(&A->lock);~~ **unreachable**

~~unlock(&B->lock);~~ **unreachable**

moving two files: unlucky timeline

Thread 1

```
MoveFile(A, B, "foo")
```

```
lock(&A->lock);
```

```
lock(&B->lock... stalled
```

```
(waiting for lock on B)
```

```
(waiting for lock on B)
```

```
(do move) unreachable
```

```
unlock(&B->lock); unreachable
```

```
unlock(&A->lock); unreachable
```

Thread 2

```
MoveFile(B, A, "bar")
```

```
lock(&B->lock);
```

```
lock(&A->lock... stalled
```

```
(waiting for lock on A)
```

```
(do move) unreachable
```

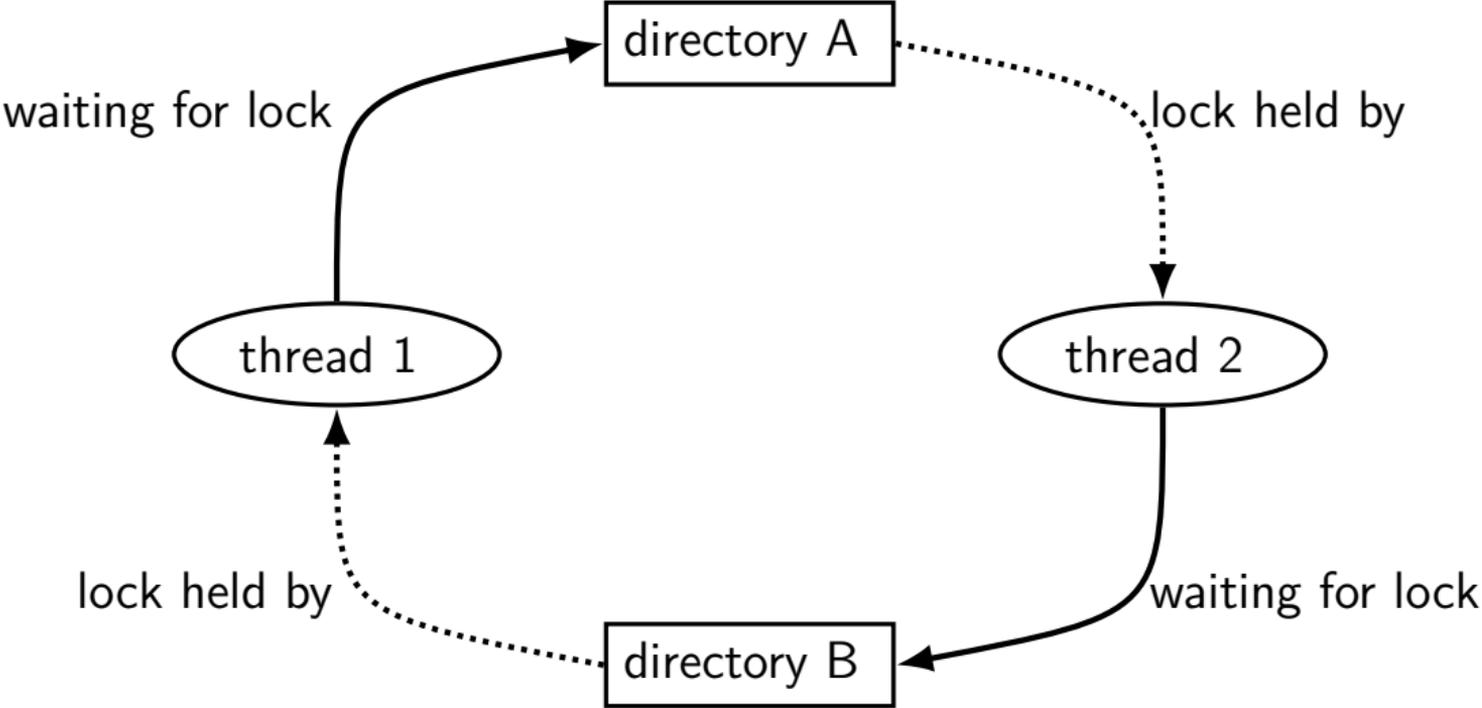
```
unlock(&A->lock); unreachable
```

```
unlock(&B->lock); unreachable
```

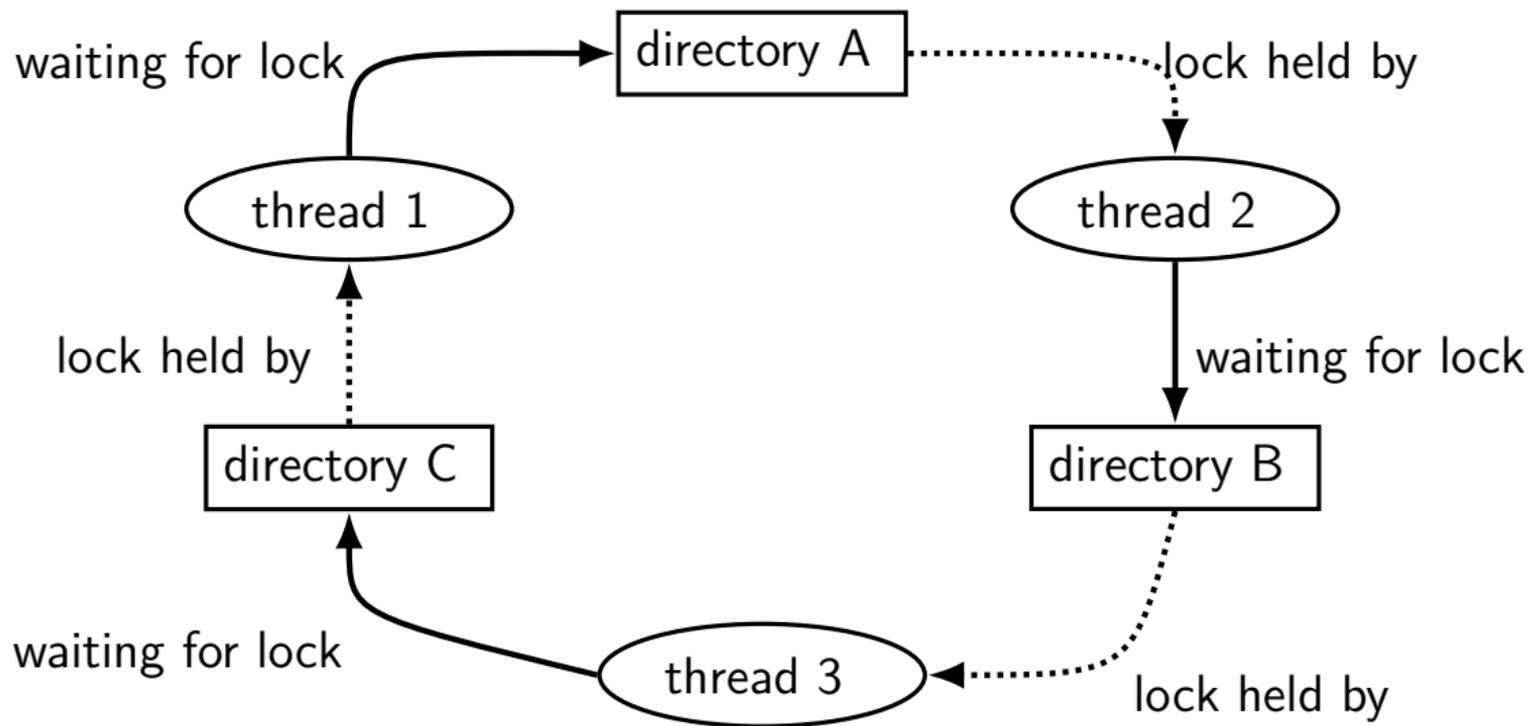
Thread 1 holds A lock, waiting for Thread 2 to release B lock

Thread 2 holds B lock, waiting for Thread 1 to release A lock

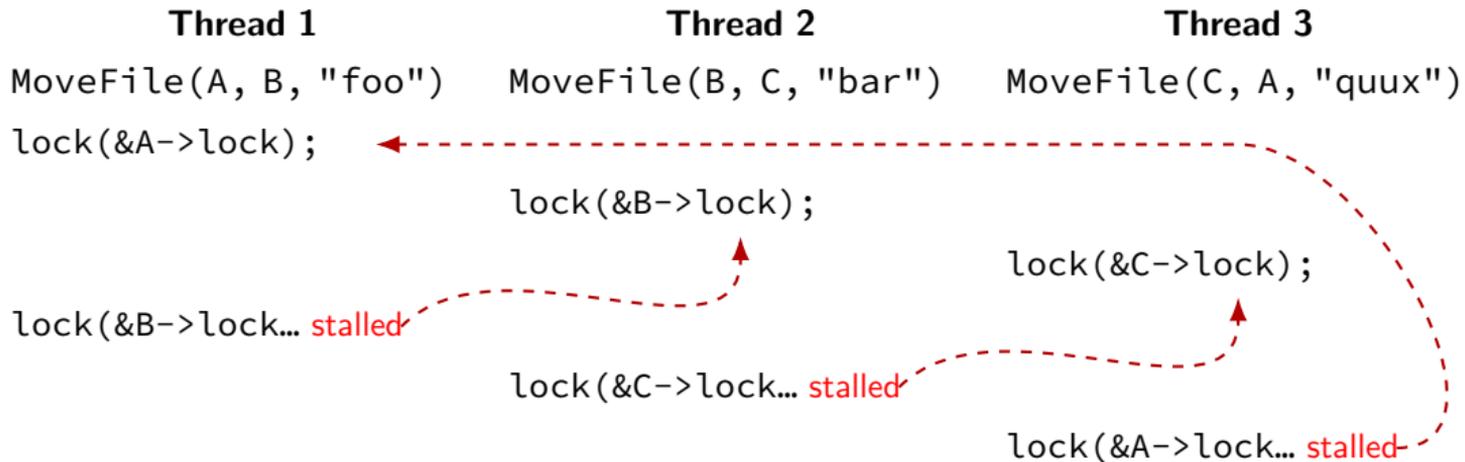
moving two files: dependencies



moving three files: dependencies



moving three files: unlucky timeline



deadlock with free space

Thread 1

```
AllocateOrWaitFor(1 MB)
AllocateOrWaitFor(1 MB)
(do calculation)
Free(1 MB)
Free(1 MB)
```

Thread 2

```
AllocateOrWaitFor(1 MB)
AllocateOrWaitFor(1 MB)
(do calculation)
Free(1 MB)
Free(1 MB)
```

2 MB of space — deadlock possible with unlucky order

deadlock with free space (unlucky case)

Thread 1

AllocateOrWaitFor(1 MB)

AllocateOrWaitFor(1 MB... stalled

Thread 2

AllocateOrWaitFor(1 MB)

AllocateOrWaitFor(1 MB... stalled

deadlock with free space (lucky case)

Thread 1

```
AllocateOrWaitFor(1 MB)
AllocateOrWaitFor(1 MB)
(do calculation)
Free(1 MB);
Free(1 MB);
```

Thread 2

```
AllocateOrWaitFor(1 MB)
AllocateOrWaitFor(1 MB)
(do calculation)
Free(1 MB);
Free(1 MB);
```

deadlock

deadlock — circular waiting for resources

resource = something needed by a thread to do work

- locks

- CPU time

- disk space

- memory

- ...

often non-deterministic in practice

most common example: **when acquiring multiple locks**

deadlock

deadlock — circular waiting for **resources**

resource = something needed by a thread to do work

- locks

- CPU time

- disk space

- memory

- ...

often non-deterministic in practice

most common example: **when acquiring multiple locks**

deadlock versus starvation

starvation: one+ unlucky (no progress), one+ lucky (yes progress)

example: low priority threads versus high-priority threads

deadlock: no one involved in deadlock makes progress

deadlock versus starvation

starvation: one+ unlucky (no progress), one+ lucky (yes progress)

example: low priority threads versus high-priority threads

deadlock: no one involved in deadlock makes progress

starvation: once starvation happens, taking turns will resolve

low priority thread just needed a chance...

deadlock: once it happens, taking turns won't fix

deadlock requirements

mutual exclusion

one thread at a time can use a resource

hold and wait

thread holding a resources waits to acquire *another* resource

no preemption of resources

resources are only released voluntarily

thread trying to acquire resources can't 'steal'

circular wait

there exists a set $\{T_1, \dots, T_n\}$ of waiting threads such that

T_1 is waiting for a resource held by T_2

T_2 is waiting for a resource held by T_3

...

T_n is waiting for a resource held by T_1

deadlock prevention techniques

infinite resources

or at least enough that never run out

no mutual exclusion

no shared resources

no mutual exclusion

no waiting (e.g. abort and retry)
“busy signal”

*no hold and wait/
preemption*

acquire resources in **consistent order**

no circular wait

request **all resources at once**

no hold and wait

deadlock prevention techniques

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acquire resources in **consistent order**

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request **all resources at once**

no hold and wait

AllocateOrFail

Thread 1

AllocateOrFail(1 MB)

AllocateOrFail(1 MB) **fails!**

Free(1 MB) **(cleanup after failure)**

Thread 2

AllocateOrFail(1 MB)

AllocateOrFail(1 MB) **fails!**

Free(1 MB) **(cleanup after failure)**

okay, now what?

give up?

both try again? — maybe this will keep happening? (called **livelock**)

try one-at-a-time? — gaurenteed to work, but tricky to implement

AllocateOrSteal

Thread 1

AllocateOrSteal(1 MB)

AllocateOrSteal(1 MB)

(do work)

Thread 2

AllocateOrSteal(1 MB)

Thread killed to free 1MB

problem: can one actually implement this?

problem: can one kill thread and keep system in consistent state?

fail/steal with locks

pthread provides `pthread_mutex_trylock` — “lock or fail”

some databases implement *revocable locks*

do equivalent of throwing exception in thread to ‘steal’ lock
need to carefully arrange for operation to be cleaned up

livelock

abort-and-retry

how many times will you retry?

moving two files: abort-and-retry

```
struct Dir {
    mutex_t lock; map<string, DirEntry> entries;
};
void MoveFile(Dir *from_dir, Dir *to_dir, string filename) {
    while (mutex_trylock(&from_dir->lock) == LOCKED) {
        if (mutex_trylock(&to_dir->lock) == LOCKED) break;
        mutex_unlock(&from_dir->lock);
    }

    to_dir->entries[filename] = from_dir->entries[filename];
    from_dir->entries.erase(filename);

    mutex_unlock(&to_dir->lock);
    mutex_unlock(&from_dir->lock);
}
```

Thread 1: MoveFile(A, B, "foo")

Thread 2: MoveFile(B, A, "bar")

moving two files: lots of bad luck?

Thread 1

MoveFile(A, B, "foo")

trylock(&A->lock) → LOCKED

trylock(&B->lock) → FAILED

unlock(&A->lock)

trylock(&A->lock) → LOCKED

trylock(&B->lock) → FAILED

unlock(&A->lock)

Thread 2

MoveFile(B, A, "bar")

trylock(&B->lock) → LOCKED

trylock(&A->lock) → FAILED

unlock(&B->lock)

trylock(&B->lock) → LOCKED

trylock(&A->lock) → FAILED

unlock(&B->lock)

livelock

like deadlock — no one's making progress
potentially forever

unlike deadlock — threads are trying

...but keep aborting and retrying

preventing livelock

make schedule random — e.g. random waiting after abort

make threads run one-at-a-time if lots of aborting

other ideas?

stealing locks???

how do we make stealing locks possible

revokable locks

```
try {  
    AcquireLock();  
    use shared data  
} catch (LockRevokedException le) {  
    undo operation hopefully?  
} finally {  
    ReleaseLock();  
}
```

Linux out-of-memory killer

Linux by default *overcommits* memory

tell processes they have **more memory than is available**
(some recommend disabling this feature)

problem: what if wrong?

could wait for program to finish, free memory...
but could be waiting forever because of deadlock

solution: kill a process

(and try to choose one that's not important)

database transactions

databases operations organized into *transactions*

happens **all at once or not at all**

until transaction is *committed*, not finalized

code to **undo** transaction in case it's not okay

database deadlock solution: invoke undo transaction code

...then rerun transaction later

deadlock prevention techniques

infinite resources

or at least enough that never run out

no mutual exclusion

no shared resources

no mutual exclusion

no waiting (e.g. abort and retry)
“busy signal”

*no hold and wait/
preemption*

acquire resources in **consistent order**

no circular wait

request **all resources at once**

no hold and wait

acquiring locks in consistent order (1)

```
MoveFile(Dir* from_dir, Dir* to_dir, string filename) {  
    if (from_dir->path < to_dir->path) {  
        lock(&from_dir->lock);  
        lock(&to_dir->lock);  
    } else {  
        lock(&to_dir->lock);  
        lock(&from_dir->lock);  
    }  
    ...  
}
```

acquiring locks in consistent order (1)

```
MoveFile(Dir* from_dir, Dir* to_dir, string filename) {  
    if (from_dir->path < to_dir->path) {  
        lock(&from_dir->lock);  
        lock(&to_dir->lock);  
    } else {  
        lock(&to_dir->lock);  
        lock(&from_dir->lock);  
    }  
    ...  
}
```

any ordering will do
e.g. compare pointers

acquiring locks in consistent order (2)

often by convention, e.g. Linux kernel comments:

```
/*
 * ...
 * Lock order:
 *     contex.ldt_usr_sem
 *     mmap_sem
 *     context.lock
 */
```

```
/*
 * ...
 * Lock order:
 * 1. slab_mutex (Global Mutex)
 * 2. node->list_lock
 * 3. slab_lock(page) (Only on some arches and for debugging)
 * ...
 */
```

deadlock prevention techniques

infinite resources

or at least enough that never run out

no *mutual exclusion*

no shared resources

no *mutual exclusion*

no waiting (e.g. abort and retry)
“busy signal”

no *hold and wait*/
preemption

acquire resources in **consistent order**

no *circular wait*

request **all resources at once**

no *hold and wait*

allocating all at once?

for resources like disk space, memory

figure out maximum allocation **when starting thread**

“only” need conservative estimate

only start thread if those resources are available

okay solution for embedded systems?

deadlock detection

idea: search for cyclic dependencies

detecting deadlocks on locks

let's say I want to detect deadlocks that only involve mutexes
goal: help programmers debug deadlocks

...by modifying my threading library:

```
struct Thread {  
    ... /* stuff for implementing thread */  
    /* what extra fields go here? */  
  
};  
  
struct Mutex {  
    ... /* stuff for implementing mutex */  
    /* what extra fields go here? */  
  
};
```

deadlock detection

idea: search for cyclic dependencies

need:

- list of all contended resources
- what thread is waiting for what?
- what thread 'owns' what?

aside: deadlock detection in reality

instrument all contended resources?

- add tracking of who locked what

- modify every lock implementation — no simple spinlocks?

- some tricky cases: e.g. what about counting semaphores?

doing something useful on deadlock?

- want way to “undo” partially done operations

...but done for some applications

common example: for locks in a database

- database typically has customized locking code

- “undo” exists as side-effect of code for handling power/disk failures

resource allocation graphs

nodes: resources or threads

edge thread→resource: thread waiting for resource

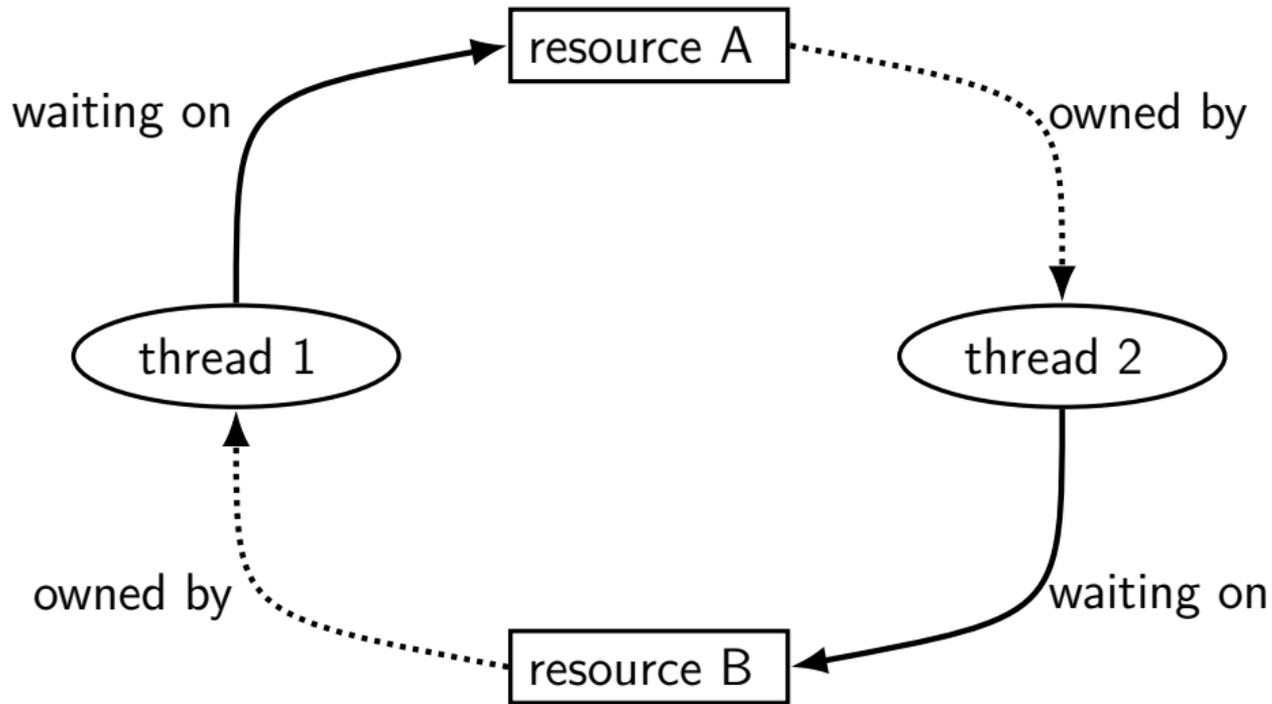
edge resource→thread: resource is “owned” by thread

holds lock on

will be deallocated by

...

resource allocate graphs



searching for cycles

cycle → deadlock happened!

finding cycles: recall 2150 topological sort (maybe???)

divided resources

what about resources like memory?

allocating 1MB of memory:

- thread 'owns' the 1MB, but...

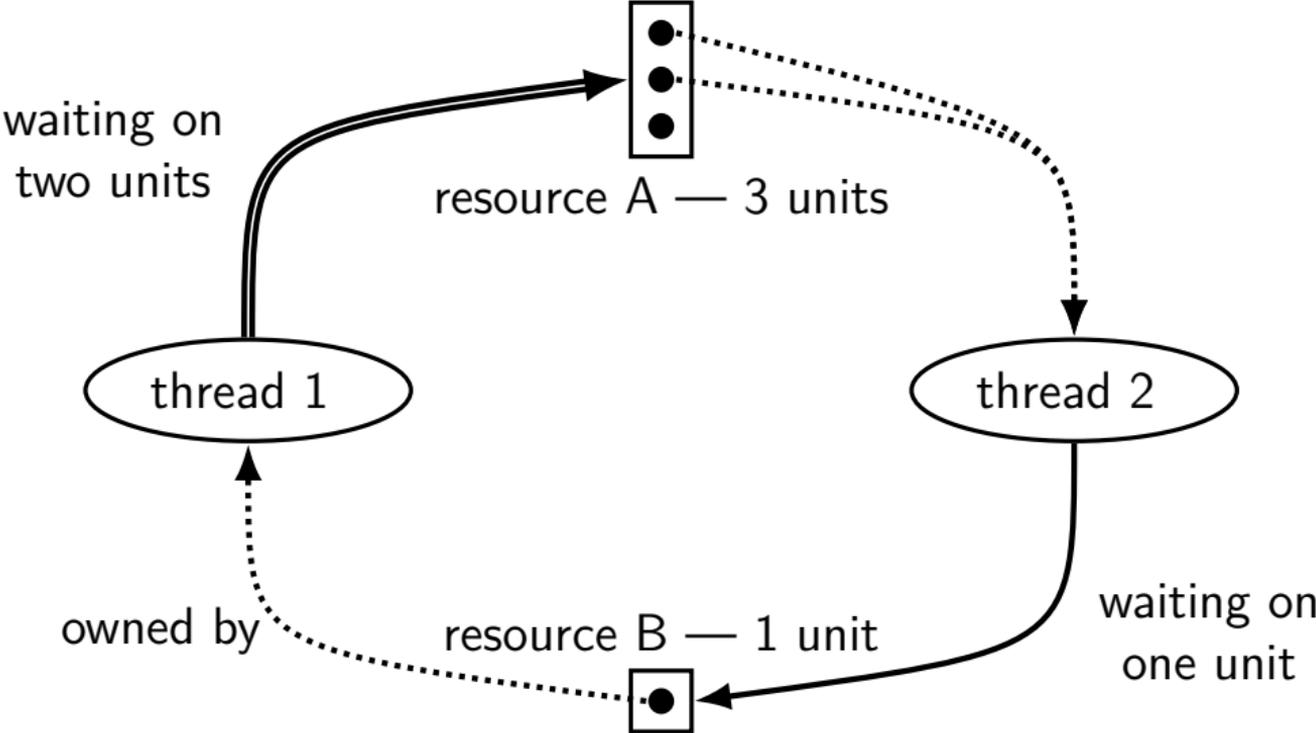
- another thread can use any other 1MB

want to track all of memory together

“partial ownership”

- locked half the memory

dividable/interchangeable resources



deadlock detection

cycle-finding not enough

new idea: try to simulate progress

- anything not waiting releases resources (as it finishes)

- anything waiting on only free resources no one else wants takes resources

see if everything gets resources eventually

deadlock detection (with variable resources)

(pseudocode)

```
class Resources { map<ResourceType, int> amounts; ... };
Resources free_resources;
map<Thread, Resources> requested;
map<Thread, Resources> owned;
```

deadlock detection (with variable resources)

(pseudocode)

```
class Resources { map<ResourceType, int> amounts; ... };
Resources free_resources;
map<Thread, Resources> requested;
map<Thread, Resources> owned;

...
do { done = true;
  for (Thread t : all threads with owned or requested resources) {
    // if everything requested is free, finish
    if (requested[t] <= free_resources ) {
      requested[t] = no_resources;
      free_resources += owned[t];
      owned[t] = no_resources;
      done = false;
    }
  }
} while (!done);
if (owned.size() > 0) { DeadlockDetected() }
```

deadlock detection (with variable resources)

(pseudocode)

```
class Resources { map<ResourceType, int> amounts; ... };
Resources free_resources;
map<Thread, Resources> requested;
map<Thread, Resources> owned;
```

```
...
do { done =
  for (Thread t) {
    // if everything requested is free, finish
    if (requested[t] <= free_resources) {
      requested[t] = no_resources;
      free_resources += owned[t];
      owned[t] = no_resources;
      done = false;
    }
  }
} while (!done);
if (owned.size() > 0) { DeadlockDetected() }
```

\leq — free resources include *everything* being requested
(enough memory, disk, each lock requested, etc.)
note: not requesting anything right now? — always true

deadlock detection (with variable resources)

(pseudocode)

```
class Resources { map<ResourceType, int> amounts; ... };
Resources free_resources;
map<Thread, Resources> requested;
map<Thread, Resources> owned;
```

```
...
do { done = true;
  for (Thread t : all (resources) {
    // if everything requested is free, finish
    if (requested[t] <= free_resources ) {
      requested[t] = no_resources;
      free_resources += owned[t];
      owned[t] = no_resources;
      done = false;
    }
  }
} while (!done);
if (owned.size() > 0) { DeadlockDetected() }
```

assume requested resources taken
then everything taken released

deadlock detection (with variable resources)

(pseudocode)

```
class Resources { map<ResourceType, int> amounts; ... };
Resources free_resources;
map<Thread, Resources> requested;
map<Thread, Resources> owned;

...
do { done = true;
  for (Thread t : all threads with owned or requested resources) {
    // if everything requested is free, finish
    if (requested[t] <= free_resources ) {
      requested[t] = no_resources;
      owned[t] = no_resources;
      done = false;
    }
  }
} while (!done);
if (owned.size() > 0) { DeadlockDetected() }
```

using deadlock detection for prevention

suppose you know the *maximum resources* a process could request
make decision **when starting process** (“*admission control*”)

using deadlock detection for prevention

suppose you know the *maximum resources* a process could request

make decision **when starting process** (“*admission control*”)

ask “what if every process was waiting for maximum resources”
including the one we’re starting

would it cause deadlock? then **don’t let it start**

called Baker’s algorithm

recovering from deadlock?

what if it's too late?

kill a thread involved in the deadlock?
hopefully won't mess things up???

tell owner to release a resource
need code written to do this???

same concept as **locks you can steal**

additional threading topics (if time)

queuing spinlocks: ticket spinlocks?

Linux kernel support for user locks: futexes?

fast synchronization for read-mostly data: read-copy-update?

threads are hard

get synchronization wrong? weird things happen

...and only sometimes

are there better ways to handle the same problems?

concurrency — multiple things at once

parallelism — same thing, use more cores/etc.

beyond threads: event based programming

writing server that servers multiple clients?

e.g. multiple web browsers at a time

maybe don't really need multiple processors/cores

one network, not that fast

idea: one thread handles multiple connections

beyond threads: event based programming

writing server that servers multiple clients?

e.g. multiple web browsers at a time

maybe don't really need multiple processors/cores

one network, not that fast

idea: one thread handles multiple connections

issue: read from/write to multiple streams at once?

event loops

```
while (true) {  
    event = WaitForNextEvent();  
    switch (event.type) {  
    case NEW_CONNECTION:  
        handleNewConnection(event); break;  
    case CAN_READ_DATA_WITHOUT_WAITING:  
        connection = LookupConnection(event.fd);  
        handleRead(connection);  
        break;  
    case CAN_WRITE_DATA_WITHOUT_WAITING:  
        connection = LookupConnection(event.fd);  
        handleWrite(connection);  
        break;  
        ...  
    }  
}
```

some single-threaded processing code

```
void ProcessRequest(int fd) {
    while (true) {
        char command[1024] = {};
        size_t command_length = 0;
        do {
            ssize_t read_result =
                read(fd, command + command_length,
                    sizeof(command) - command_length);
            if (read_result <= 0) handle_error();
            command_length += read_result;
        } while (command[command_length - 1] != '\n');
        if (IsExitCommand(command)) { return; }
        char response[1024];
        computeResponse(response, command);
        size_t total_written = 0;
        while (total_written < sizeof(response)) {
            ...
        }
    }
}
```

```
class Connection {
    int fd;
    char command[1024];
    size_t command_length;
    char response[1024];
    size_t total_written;
    ...
};
```

some single-threaded processing code

```
void ProcessRequest(int fd) {
    while (true) {
        char command[1024] = {};
        size_t command_length = 0;
        do {
            ssize_t read_result =
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        } while (command[command_length - 1] != '\n');
        if (IsExitCommand(command)) { return; }
        char response[1024];
        computeResponse(response, command);
        size_t total_written = 0;
        while (total_written < sizeof(response)) {
            ...
        }
    }
}
```

```
class Connection {
    int fd;
    char command[1024];
    size_t command_length;
    char response[1024];
    size_t total_written;
    ...
};
```

as event code

```
handleRead(Connection *c) {
    ssize_t read_result =
        read(fd, c->command + command_length,
             sizeof(command) - c->command_length);
    if (read_result <= 0) handle_error();
    c->command_length += read_result;

    if (c->command[c->command_length - 1] == '\\n') {
        computeResponse(c->response, c->command);
        if (IsExitCommand(command)) {
            FinishConnection(c);
        }
        StopWaitingToRead(c->fd);
        StartWaitingToWrite(c->fd);
    }
}
```

as event code

```
handleRead(Connection *c) {
    ssize_t read_result =
        read(fd, c->command + command_length,
             sizeof(command) - c->command_length);
    if (read_result <= 0) handle_error();
    c->command_length += read_result;

    if (c->command[c->command_length - 1] == '\\n') {
        computeResponse(c->response, c->command);
        if (IsExitCommand(command)) {
            FinishConnection(c);
        }
        StopWaitingToRead(c->fd);
        StartWaitingToWrite(c->fd);
    }
}
```

POSIX support for event loops

select and poll functions

take list(s) of file descriptors to read and to write
wait for them to be read/writeable without waiting
(or for new connections associated with them, etc.)

many OS-specific extensions/improvements/alternatives:

examples: Linux epoll, Windows IO completion ports

better ways of managing list of file descriptors

do read/write when ready instead of just returning when reading/writing
is okay

message passing

instead of having variables, locks between threads...

send messages between threads/processes

what you need anyways between machines

big 'supercomputers' = really many machines together

arguably an easier model to program

can't have locking issues

message passing API

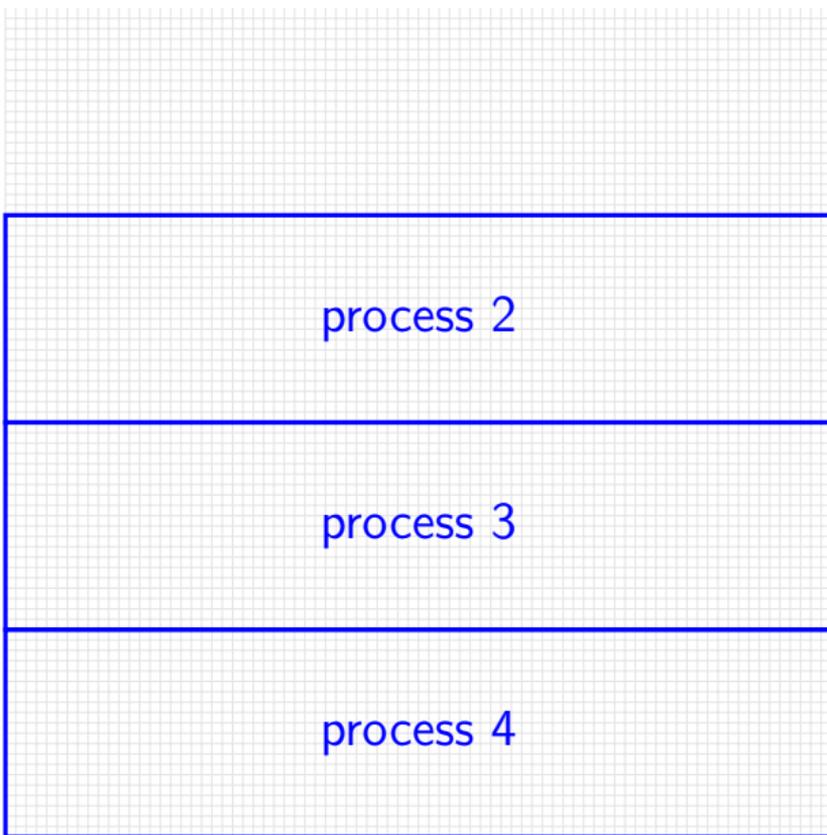
core functions: Send(toId, data)/Recv(fromId, data)

simplest version: functions wait for other processes/threads

extensions: send/recv at same time, multiple messages at once, don't wait, etc.

```
if (thread_id == 0) {
  for (int i = 1; i < MAX_THREAD; ++i) {
    Send(i, getWorkForThread(i));
  }
  for (int i = 1; i < MAX_THREAD; ++i) {
    WorkResult result;
    Recv(i, &result);
    handleResultForThread(i, result);
  }
} else {
  WorkInfo work;
  Recv(0, &work);
  Send(0, ComputeResultFor(work));
}
```

message passing game of life



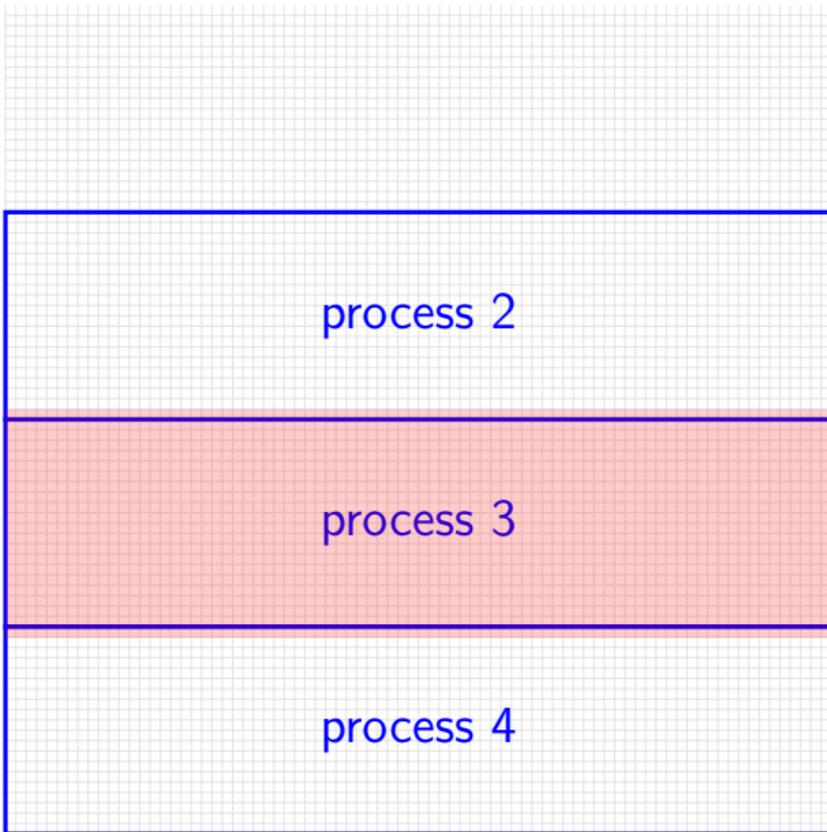
divide grid

like you would for normal threads

each process **stores cells**
in that part of grid

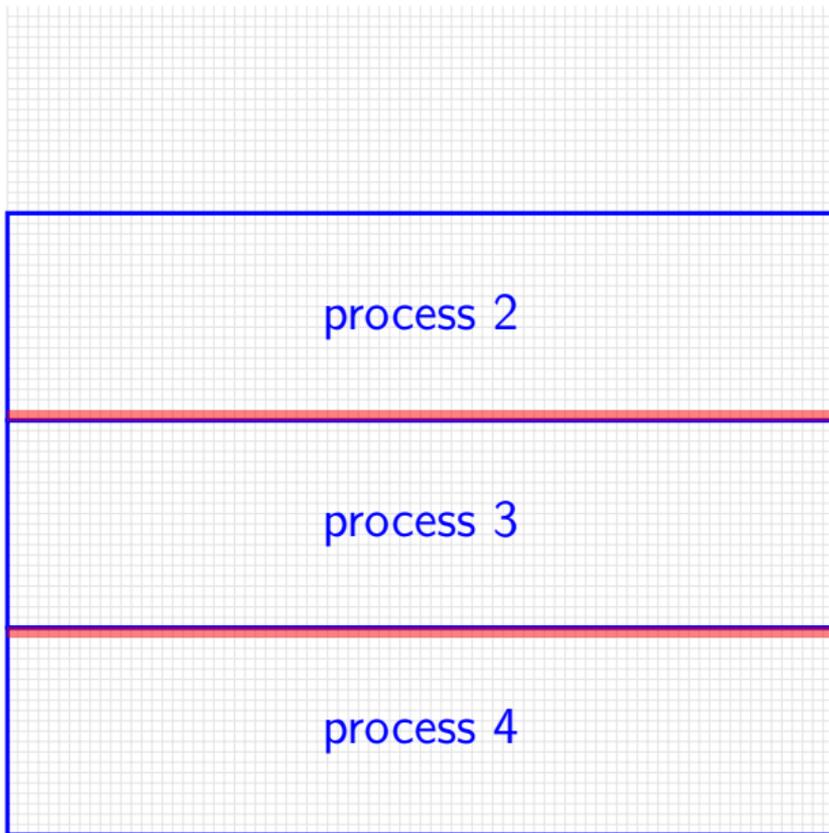
(no shared memory!)

message passing game of life



process 3 only needs values of cells around its area (values of cells adjacent to the ones it computes)

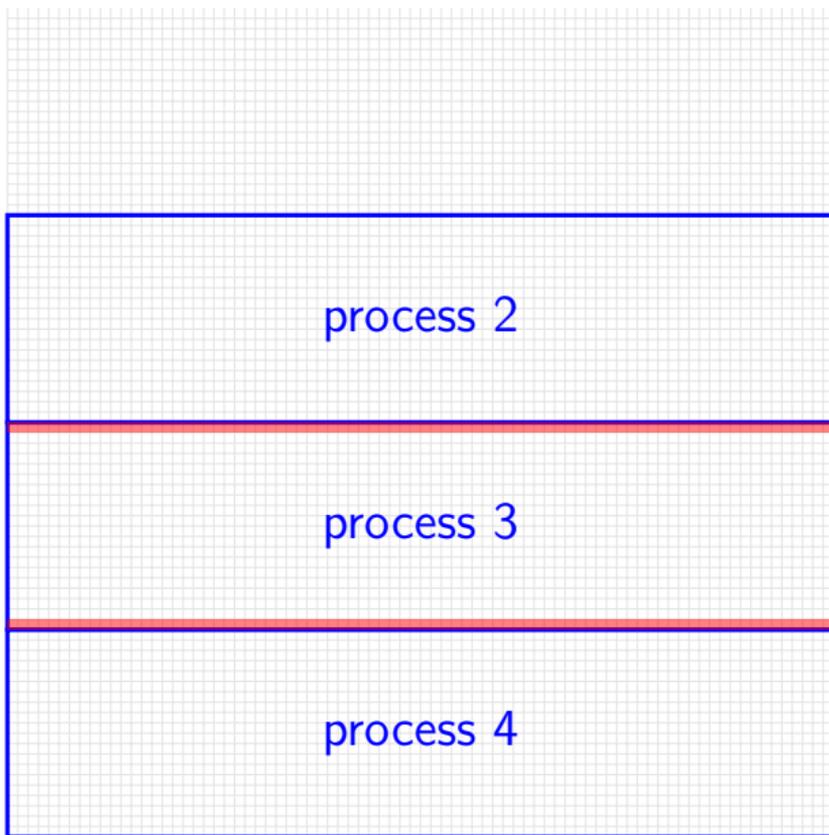
message passing game of life



small slivers of
other process's cells needed

solution: process 2, 4
send messages with cells every iterat

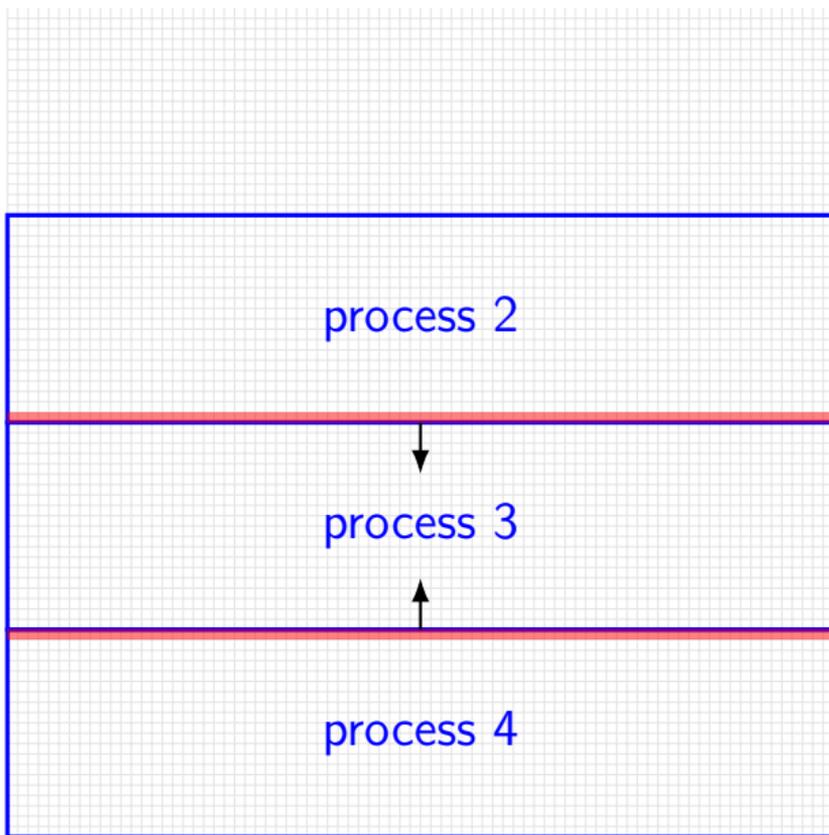
message passing game of life



some of process 3's cells
also needed by process 2/4

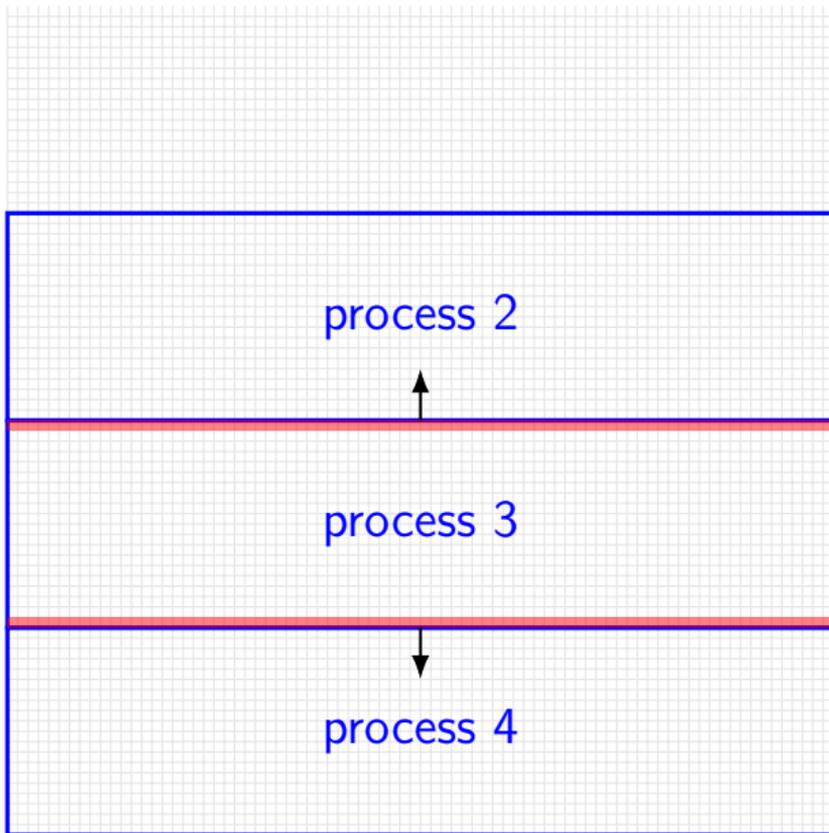
so process 3 also sends messages

message passing game of life



one possible pseudocode:
all **even processes send messages**
(while odd receives), then
all odd processes send messages
(while even receives)

message passing game of life



one possible pseudocode:
all even processes send messages
(while odd receives), then
all **odd processes send messages**
(while even receives)

backup slides

fairer spinlocks

so far — everything on spinlocks

mutexes, condition variables — built with spinlocks

spinlocks are pretty 'unfair'

where fair = get lock if waiting longest

last CPU that held spinlock more likely to get it again

already has the lock in its cache...

but there are many other ways to spinlocks...

ticket spinlocks

```
unsigned int serving_number;  
unsigned int next_number;
```

```
Lock() {  
    // "take a number"  
    unsigned int my_number = atomic_read_and_increment(&next_number);  
    // wait until "now serving" that number  
    while (atomic_read(&serving_number) != my_number)  
        /* do nothing */  
    }  
    // MISSING: code to prevent reordering reads/writes  
}
```

```
Unlock() {
```

ticket spinlocks and cache contention

still have contention to write `next_number`

...but no retrying writes!

should limit 'ping-ponging'?

threads loop performing a read repeatedly while waiting

value will be broadcasted to all processors

'free' if using a bus

not-so-free if another way of connecting CPUs

beyond ticket spinlocks

Linux kernel used to use ticket spinlocks

now uses variant of MCS spinlocks — locks have linked-list queue!
careful use of atomic operations to modify queue

still try

goal: even less contention

unlocking value doesn't require broadcasting to all CPUs
each processor waits on its own cache block

Linux futexes

futex — **f**ast **u**space **m**utex

goal: implement waiting like 'proper' mutexes, but...

don't enter kernel mode most of the time

challenge: can't acquire lock to call scheduler from user mode

futex operations

```
futex(&lock_value, FUTEX_WAIT, expected_value, ...);
```

check if `lock_value` is `expected_value`

if not — return immediately

otherwise, sleep until it `futex(..., FUTEX_WAKE` is called

```
futex(&lock_value, FUTEX_WAKE, num_processes);
```

wakeup up to `num_processes` which called `FUTEX_WAIT`

mutexes with futexes

```
int lock_value; // UNLOCKED or LOCKED_NO_WAITERS or LOCKED_WAITERS
Lock() {
retry:
    if (CompareAndSwap(&lock_value, UNLOCKED, LOCKED_NO_WAITERS) ==
        /* acquired lock */)
        return;
    } else if (CompareAndSwap(&lock_value, LOCKED_NO_WAITERS, LOCKED_WAITERS) ==
        futex(&lock_value, FUTEX_WAIT, LOCKED_WAITERS, ...));
    }
    goto retry;
}
Unlock() {
    if (CompareAndSwap(&lock_value, LOCKED_NO_WAITERS, UNLOCKED) ==
        return;
    } else {
        lock_value = UNLOCKED;
        futex(&lock_value, FUTEX_WAKE, 1, ...);
    }
}
```

implementing `futex_wait`

hashtable: address \rightarrow queue of waiting threads

use hashtable to look-up queue

lock queue

check value hasn't changed

if so abort, releasing lock

add thread to queue

set thread as WAITING (not runnable)

unlock queue

call scheduler

read-copy-update (high-level overview)

idea: read-mostly data structure

when reading:

read normally **via shared pointer**

when writing:

make a copy

atomically update the **shared pointer**

delete the old version **eventually**

tricky part: when is it safe to delete old version

implementation: **scheduler integration**

RCU operations

read lock — record: “I am reading now”

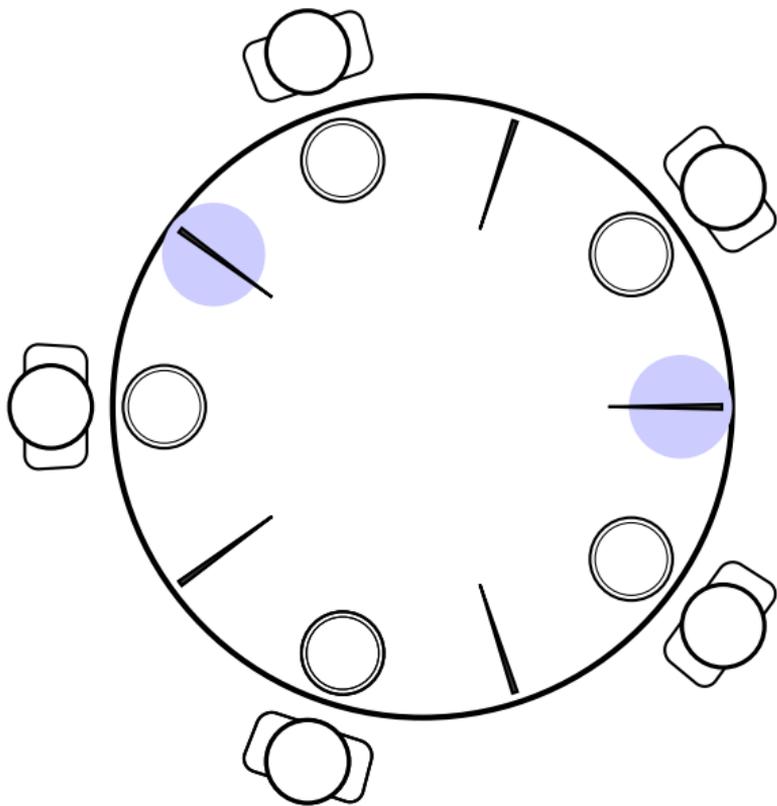
read unlock — record: “I am done reading now”

publish — atomically update pointer

after publish: wait until

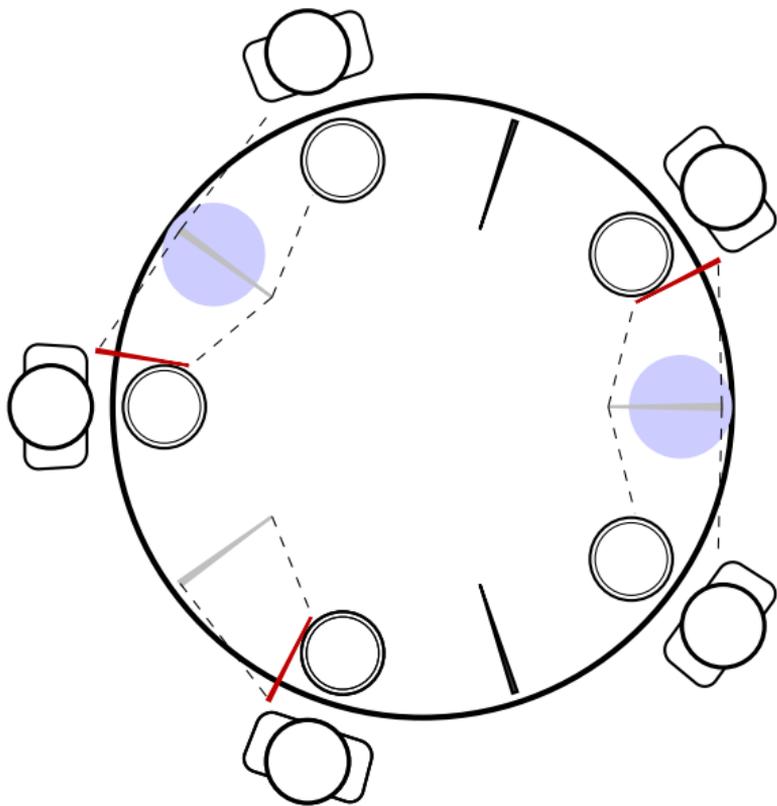
- all threads currently running have context switched
- ...and none of them set the “I am reading now” bit

dining philosophers — ordering



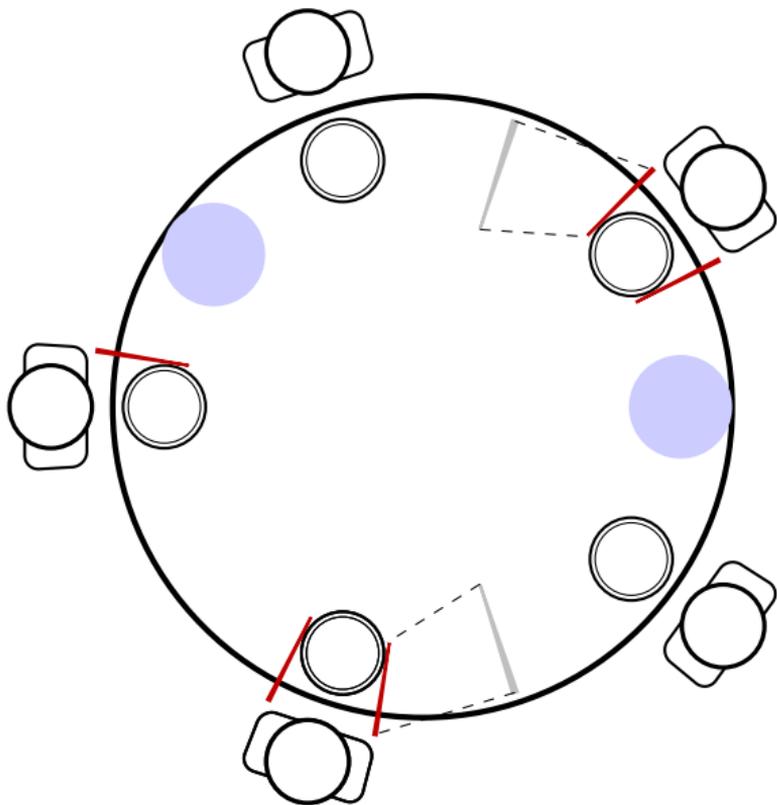
mark some chopsticks places
rule: grab from marked place first
only grab other chopstick after that

dining philosophers — ordering



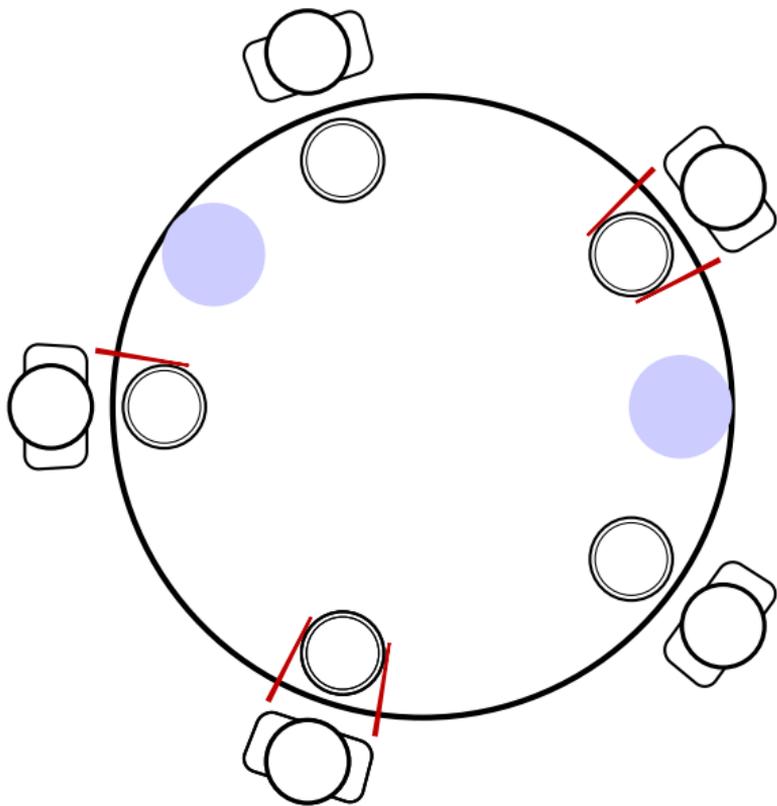
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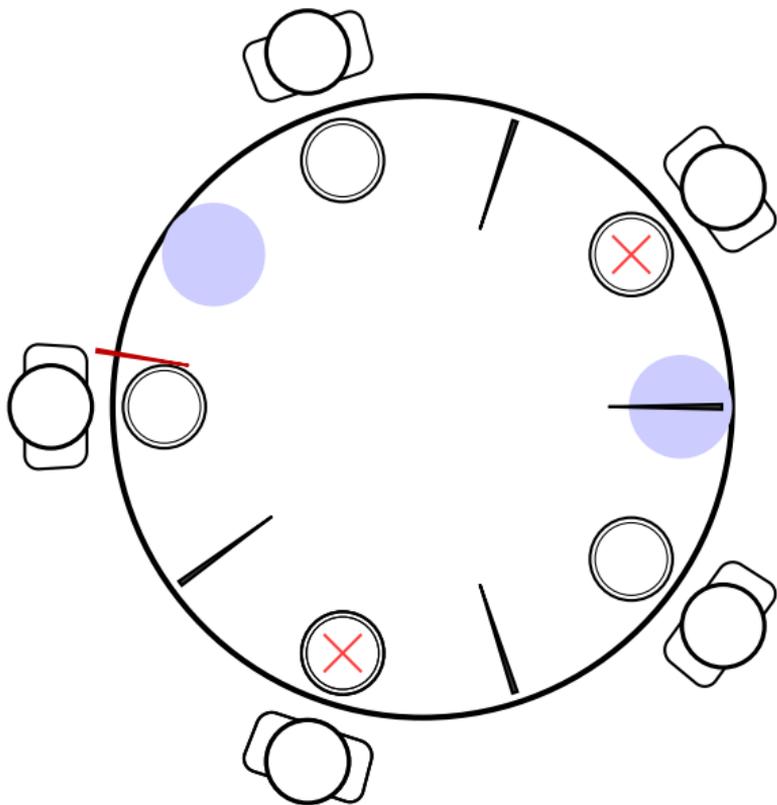
dining philosophers — ordering



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avoids circular dependency,
means everyone else
eventually gets a turn

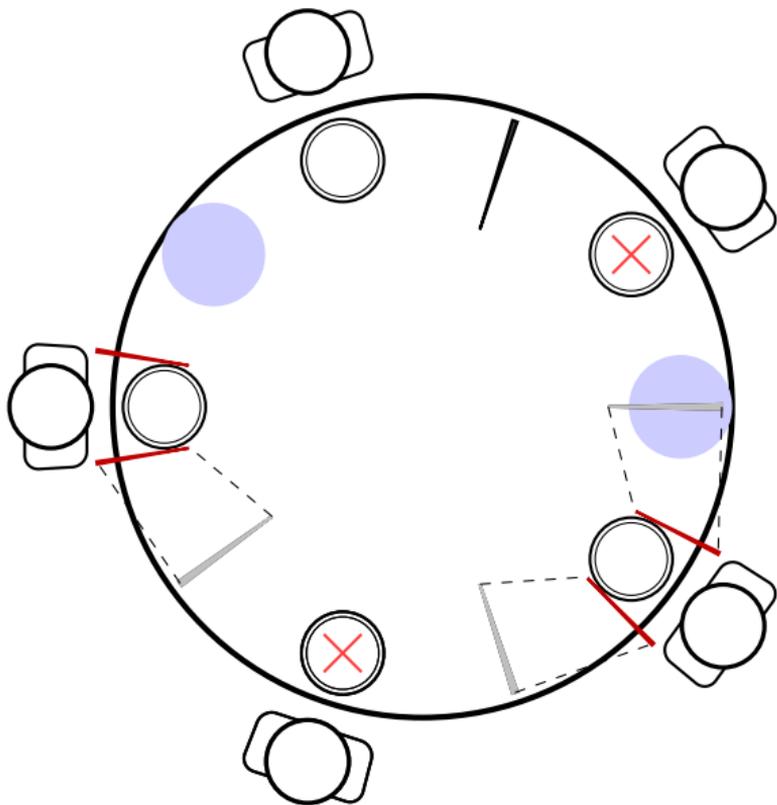
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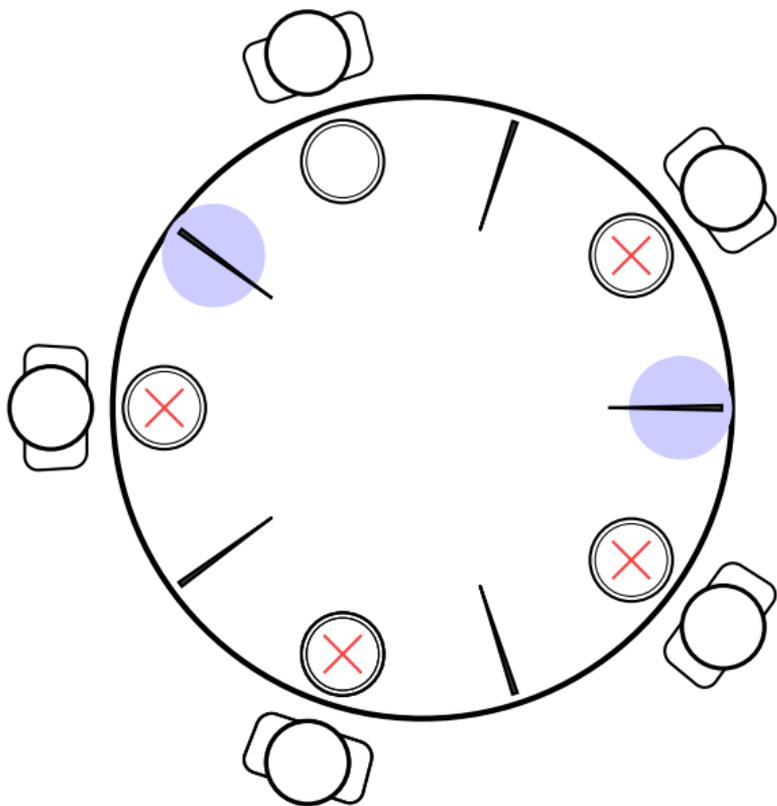
dining philosophers — ordering



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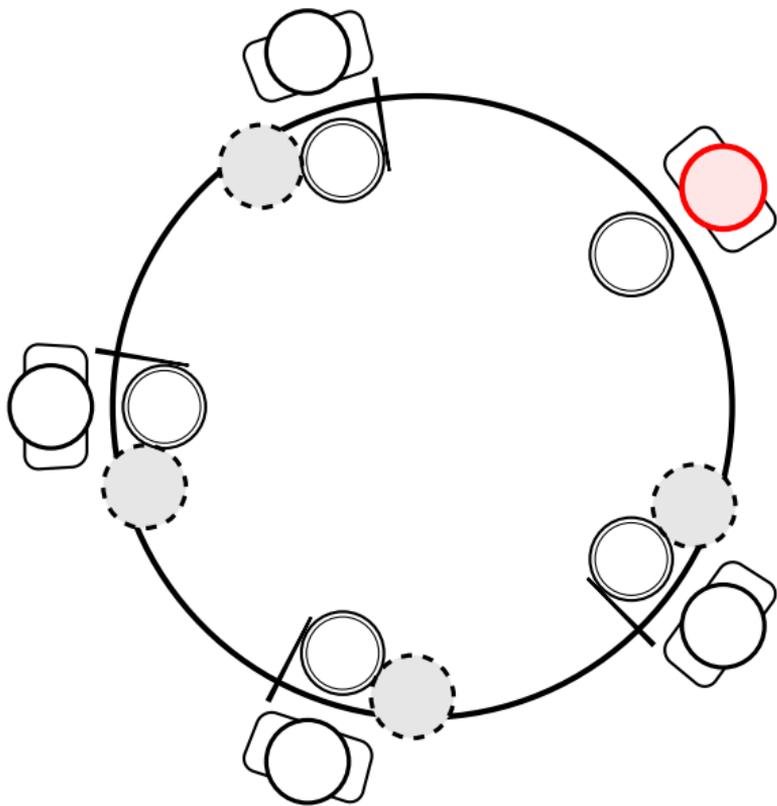
dining philosophers — ordering



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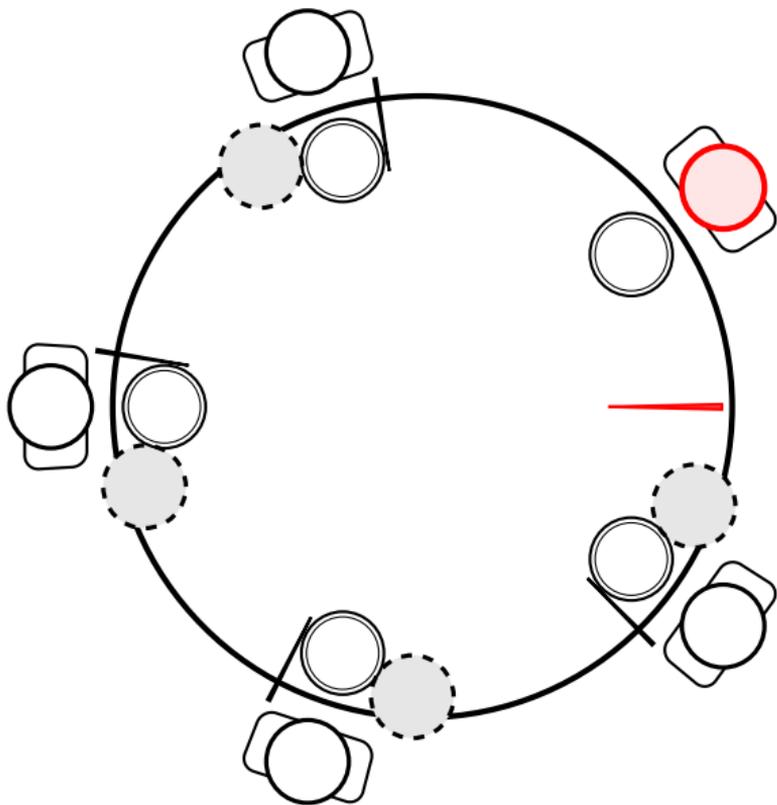
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dining philosophers — aborting



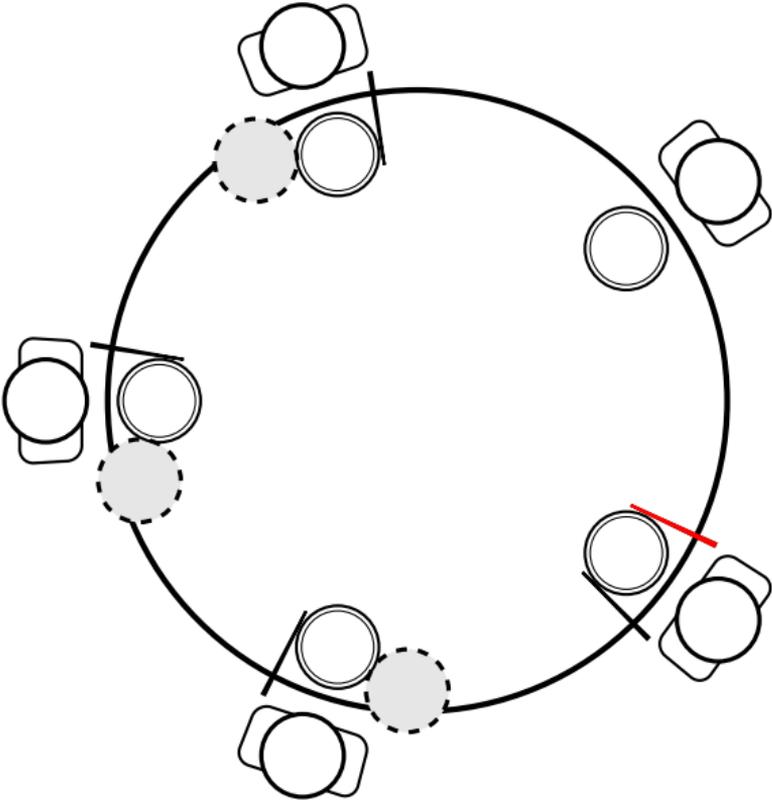
dining philosopher
what if someone's impatient
just gives up instead of waiting

dining philosophers — aborting



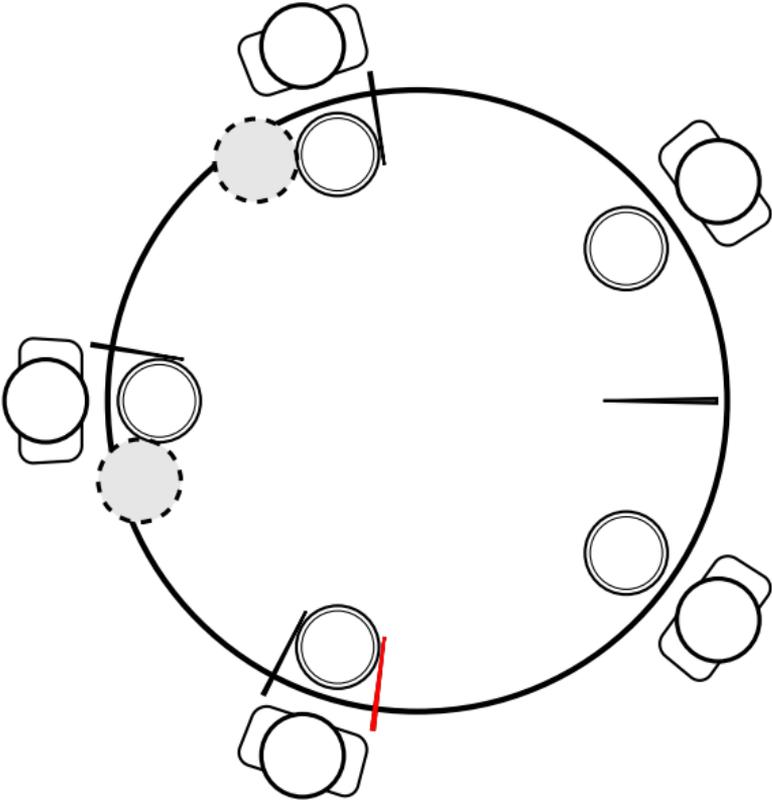
dining philosopher
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just gives up instead of waiting

dining philosophers — aborting



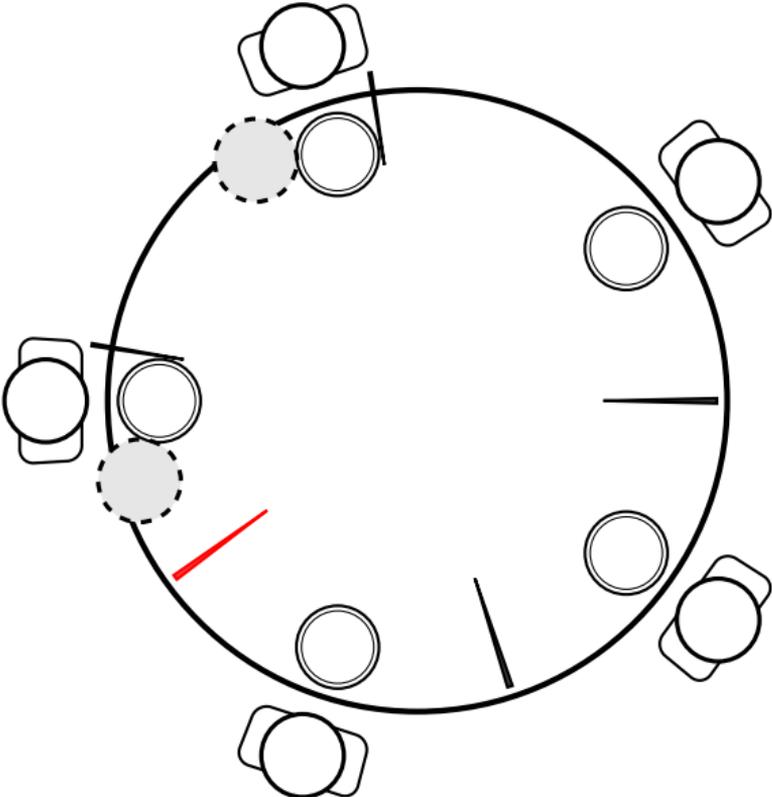
now everyone else can eat

dining philosophers — aborting



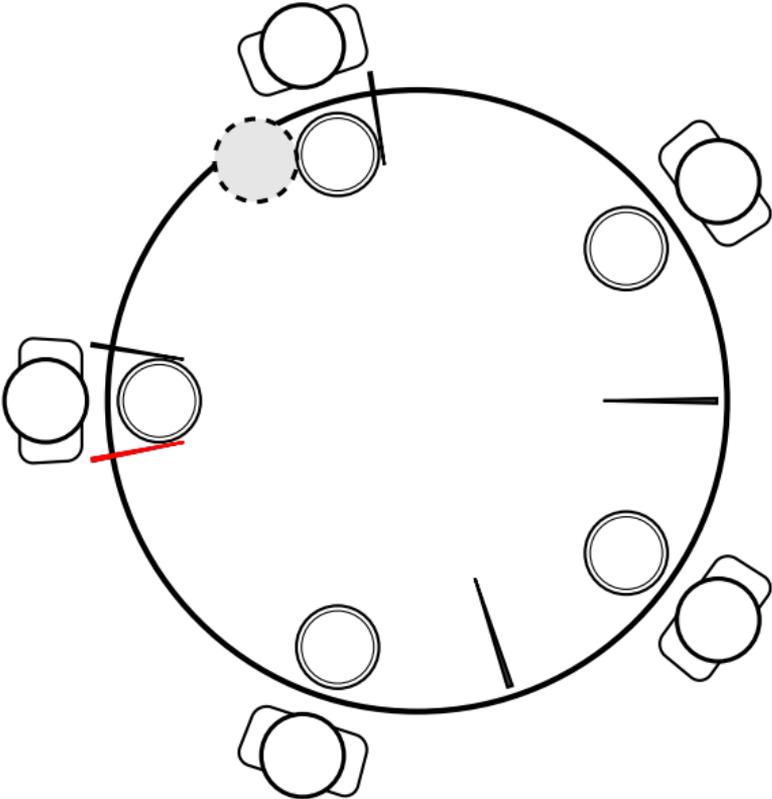
now everyone else can eat

dining philosophers — aborting



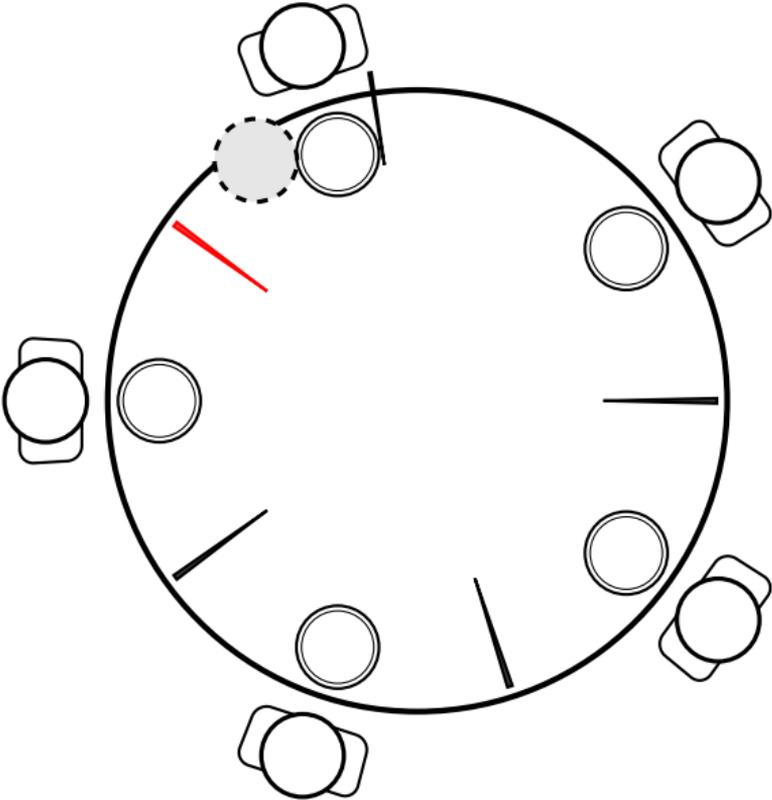
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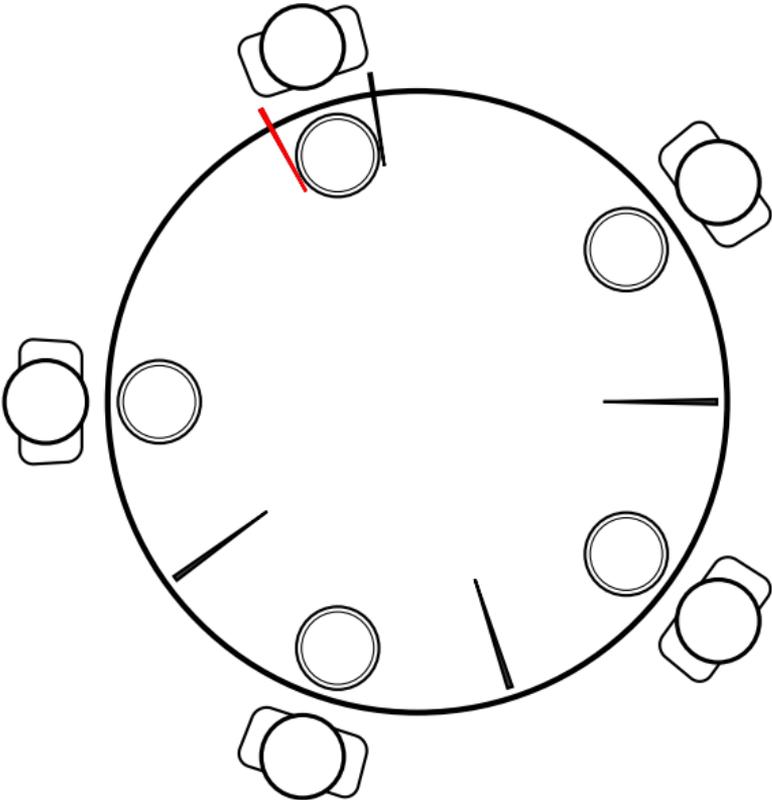
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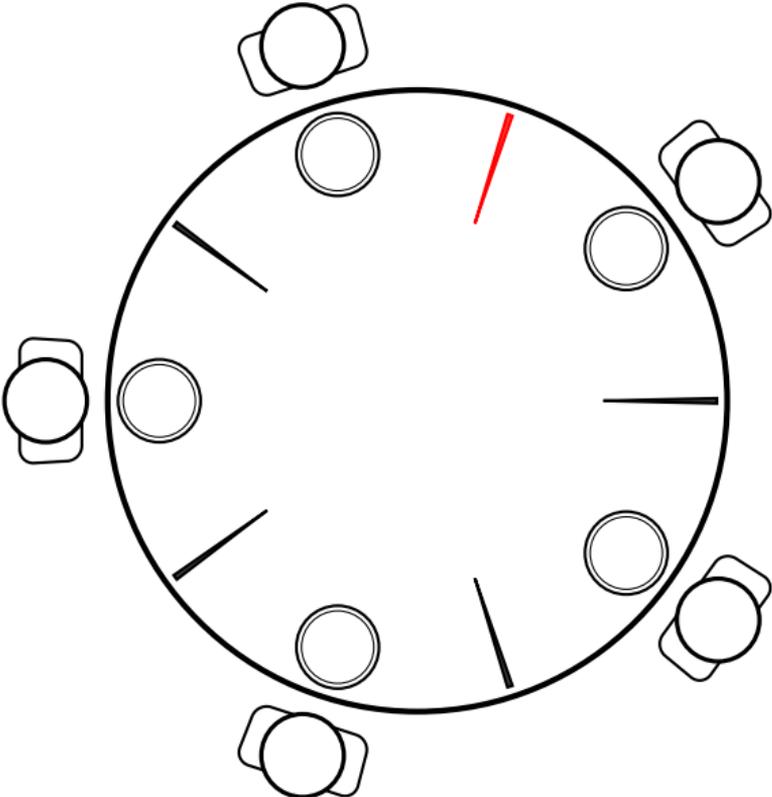
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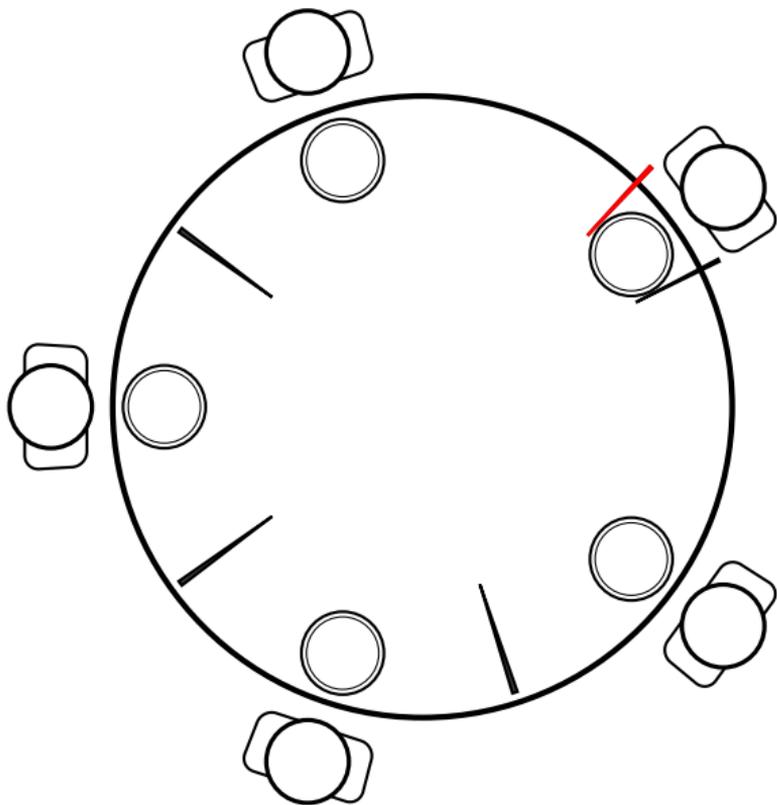
now everyone else can eat

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now everyone else can eat

dining philosophers — aborting



and person who gave up
might succeed later