

two-phase commit / security (start)

# Changelog

Changes made in this version not seen in first lecture:

- quorum: add note that part of voting is updating other nodes to latest version

# last time (1)

RPC: remote function calls like local

- interface description language compiled into stubs (wrapper functions)
- marshalling (AKA serialization) of arguments/return value into bytes

NFS: file operations into remote procedure calls

NFS is stateless operation

- server uses file IDs — give inode number
- client remembers fd to file ID mapping
- nothing to recover on server failure
- nothing for server to forget on client failure

## last time (2)

close-to-open consistency

check for updates on open, write file on close

idea: inconsistent behavior if two processes open file at once okay

AFS: callbacks on write rather than proactive checks

...but server still needs to know about write to callback

# file locking

so, your program doesn't like conflicting writes

what can you do?

if offline operation, probably not much...

otherwise **file locking**

except **it often doesn't work on NFS, etc.**

# advisory file locking with fcntl

```
int fd = open(...);
struct flock lock_info = {
    .l_type = F_WRLCK, // write lock; RDLOCK also available
    // range of bytes to lock:
    .l_whence = SEEK_SET, l_start = 0, l_len = ...
};
/* set lock, waiting if needed */
int rv = fcntl(fd, F_SETLKW, &lock_info);
if (rv == -1) { /* handle error */ }
/* now have a lock on the file */

/* unlock --- could also close() */
lock_info.l_type = F_UNLCK;
fcntl(fd, F_SETLK, &lock_info);
```

# advisory locks

fcntl is an *advisory* lock

doesn't stop others from accessing the file...

unless they always try to get a lock first

# POSIX file locks are horrible

actually two locking APIs: `fcntl()` and `flock()`

`fcntl`: *not* inherited by `fork`

`fcntl`: closing any `fd` for file release lock  
even if you `dup2`'d it!

`fcntl`: maybe sometimes works over NFS?

`flock`: less likely to work over NFS, etc.

# fcntl and NFS

seems to require extra state at the server

typical implementation: separate *lock server*

not a stateless protocol

# lockfiles

use a separate *lockfile* instead of “real” locks

e.g. convention: use `NOTES.txt.lock` as lock file

lock: create a *lockfile* with `link()` or `open()` with `O_EXCL`

can't lock: `link()/open()` will fail “file already exists”

for current NFSv3: should be single RPC calls that always contact server  
some (old, I hope?) systems: `link()` atomic, `open()` `O_EXCL` not

unlock: remove the lockfile

annoyance: what if program crashes, file not removed?

# failure models

how do machines fail?...

well, lots of ways

# two models of machine failure

## **fail-stop**

failing machines stop responding

or one always detects they're broken and can ignore them

## **Byzantine failures**

failing machines do the worst possible thing

# dealing with machine failure

recover when machine comes back up

does not work for Byzantine failures

rely on a *quorum* of machines working

requires 1 extra machine for fail-stop

requires  $3F + 1$  to handle  $F$  failures with Byzantine failures

# distributed transaction problem

## distributed transaction

two machines both agree to do something *or not do something*

even if *a machine fails*

# distributed transaction example

course database across many machines

machine A and B: student records

machine C: course records

want to make sure machines agree to add students to course

...even if one machine fails

no confusion about student is in course

# the centralized solution

one solution: a new machine D decides what to do  
for machines A-C which store records

machine D maintains a redo log for all machines

treats them as just data storage

# the centralized solution

one solution: a new machine D decides what to do  
for machines A-C which store records

machine D maintains a redo log for all machines

treats them as just data storage

problem: we'd like machines to work independently  
not really taking advantage of distributed  
why did we split student records across two machines anyways?

# decentralized solution sketch

want each machine to be responsible just for their own data

only coordinate when transaction crosses machine

e.g. changing course + student records

only coordinate with involved machines

hopefully, scales to tens or hundreds of machines

typical transaction would involve 1 to 3 machines?

# distributed transactions and failures

extra tool: persistent log

idea: machine remembers what happen on failure

same idea as redo log: record what to do in log

    preview: whether trying to do/not do action

...but need to handle if machine stopped while writing log

## two-phase commit: setup

every machine *votes* on transaction

commit — do the operation (add student A to class)

abort — don't do it (something went wrong)

require unanimity to commit

otherwise, default=abort

# two-phase commit: phases

phase 1: *preparing*

each machine states their intention: commit/abort

phase 2: *finishing*

gather intentions, figure out whether to do/not do it

# preparing

agree to commit

promise: “I will accept this transaction”

promise recorded in the machine log in case it crashes

agree to abort

promise: “I will **not** accept this transaction”

promise recorded in the machine log in case it crashes

never ever take back agreement!

# preparing

agree to commit

promise: “I will accept this transaction”

promise recorded in the machine log in case it crashes

agree to abort

promise: “I will **not** accept this transaction”

promise recorded in the machine log in case it crashes

never e

to keep promise: can't allow interfering operations  
e.g. agree to add student to class → reserve seat in class  
(even though student might not be added)

# finishing

learn all machines agree to commit: commit transaction

actually apply transaction (e.g. record student is in class)  
record decision in local log

learn any machine agreed to abort: abort transaction

don't ever try to apply transaction  
record decision in local log

# finishing

learn all machines agree to commit: commit transaction  
actually apply transaction (e.g. record student is in class)  
record decision in local log

learn any machine agreed to abort: abort transaction  
don't ever try to apply transaction  
record decision in local log

unsure which? just ask everyone what they agreed to do  
they **can't change their mind** once they tell you

## two-phase commit: blocking

agree to commit “add student to class”?

can't allow conflicting actions...

...until know transaction *globally* committed/aborted

# two-phase commit: blocking

agree to commit “add student to class”?

can't allow conflicting actions...

- adding student to conflicting class?

- removing student from the class?

- not leaving seat in class?

...until know transaction *globally* committed/aborted

# waiting forever?

machine goes away, two-phase commit state is uncertain

*never* resolve what happens

solution in practice: manual intervention

# two-phase commit: roles

typical two-phase commit implementation

several *workers*

one *coordinator*

might be same machine as a worker

# two-phase-commit messages

coordinator → worker: PREPARE

“will you agree to do this action?”

on failure: can ask multiple times!

worker → coordinator: VOTE-COMMIT or VOTE-ABORT

I agree to commit/abort transaction

worker records decision in log, returns same result each time

coordinator → worker: GLOBAL-COMMIT or GLOBAL-ABORT

I counted the votes and the result is commit/abort

only commit if all votes were commit

# reasoning about protocols: state machines

very hard to reason about dist. protocol correctness

typical tool: **state machine**

each machine is in some state

know what every message does in this state

# reasoning about protocols: state machines

very hard to reason about dist. protocol correctness

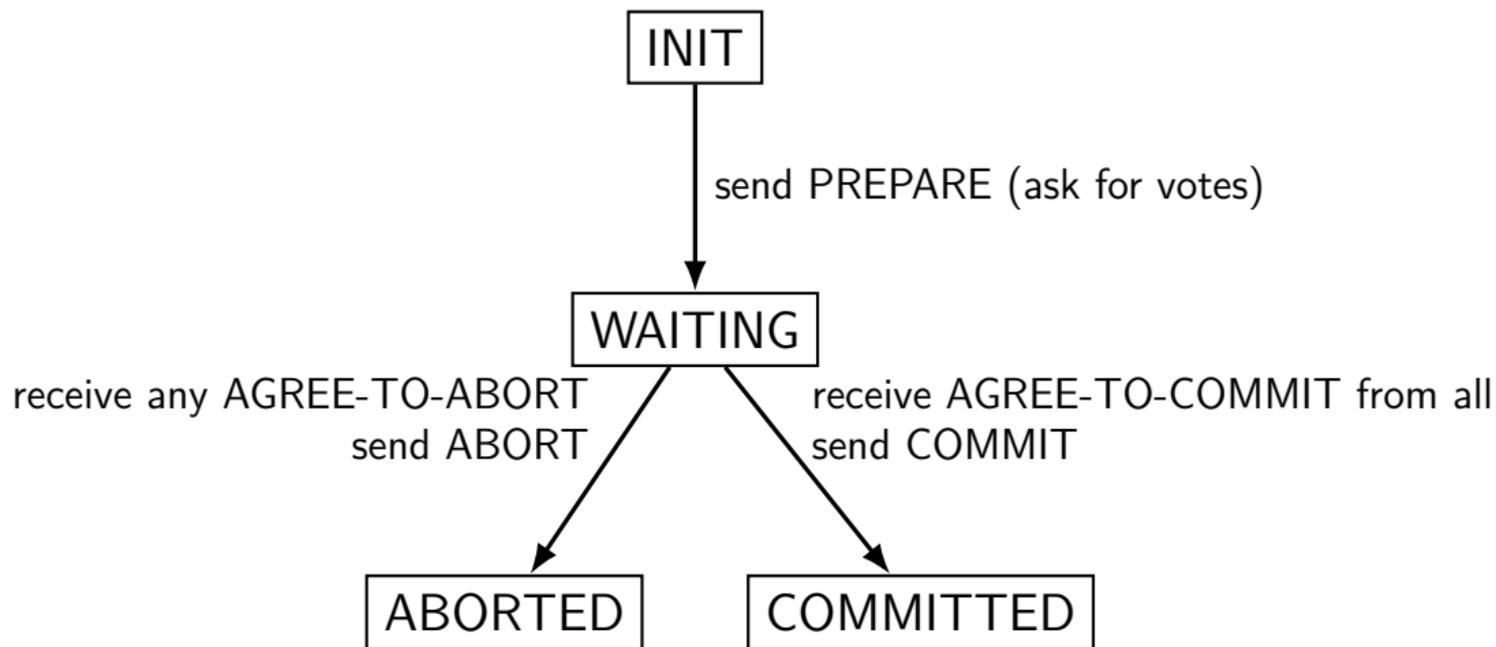
typical tool: **state machine**

each machine is in some state

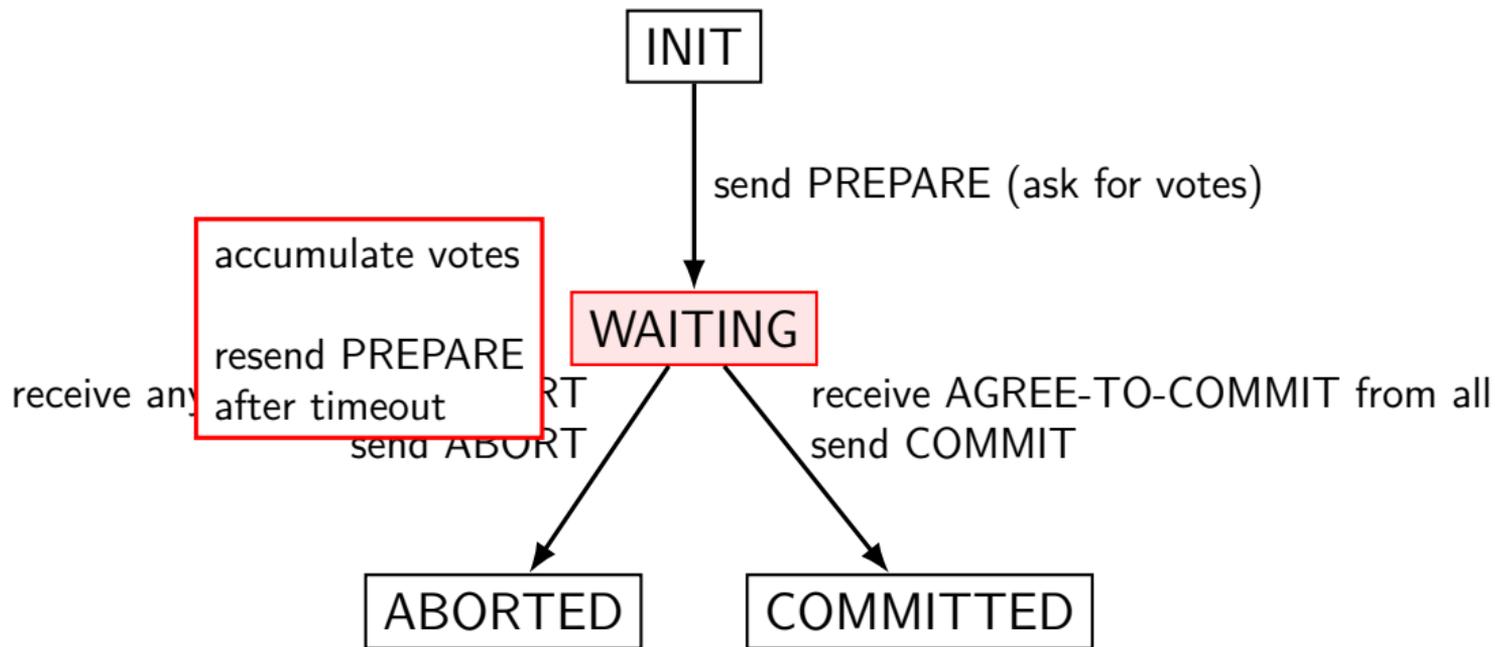
know what every message does in this state

avoids common problem: don't know what message does

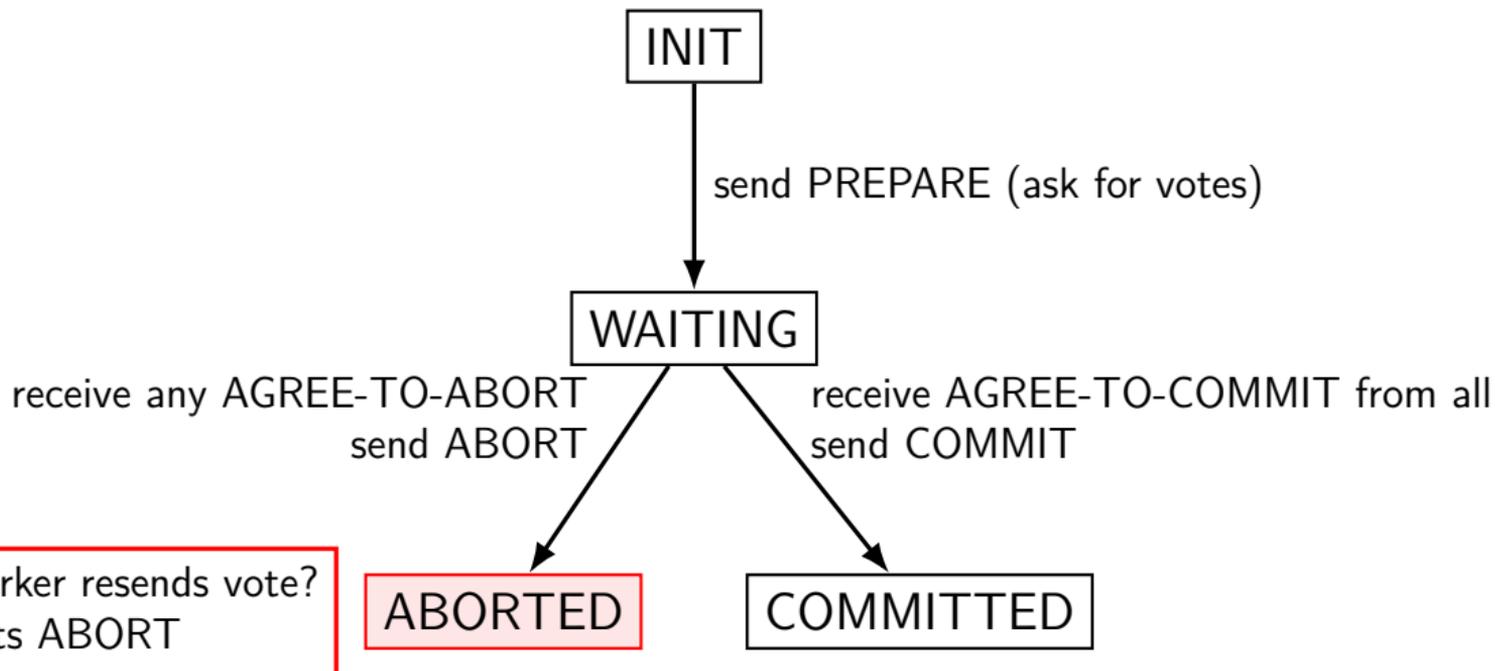
# coordinator state machine (simplified)



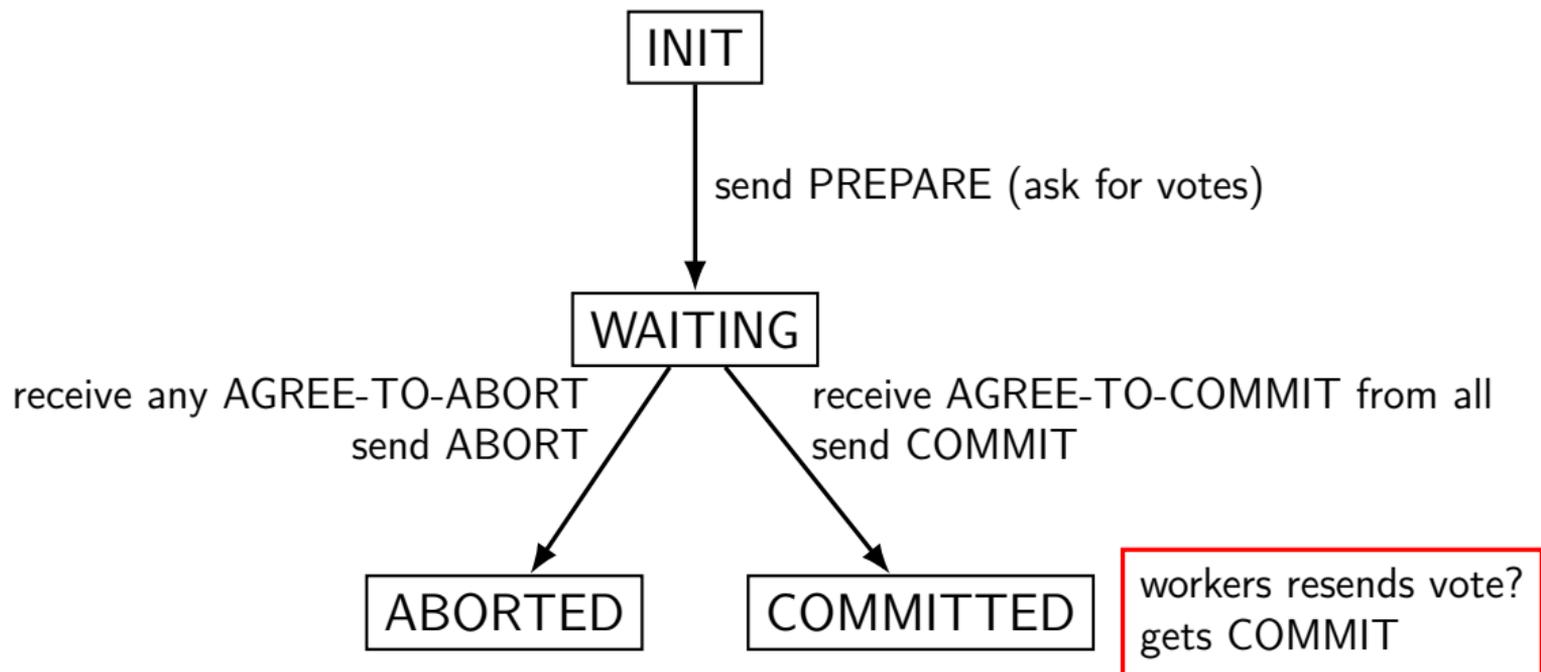
# coordinator state machine (simplified)



# coordinator state machine (simplified)



# coordinator state machine (simplified)



# coordinator failure recovery

duplicate messages okay — unique transaction ID!

coordinator crashes? *log* indicating last state

- log written *before* sending any messages

- if INIT: resend PREPARE,

- if WAIT/ABORTED: send ABORT to all (dups okay!)

- if COMMITTED: resend COMMIT to all (dups okay!)

message doesn't make it to worker?

- coordinator can resend PREPARE after timeout (or just ABORT)

- worker can resend vote to coordinator to get extra reply

# coordinator failure recovery

duplicate messages okay — unique transaction ID!

coordinator crashes? *log indicating last state*

- log written *before* sending any messages

- if INIT: resend PREPARE,

- if WAIT/ABORTED: send ABORT to all (dups okay!)

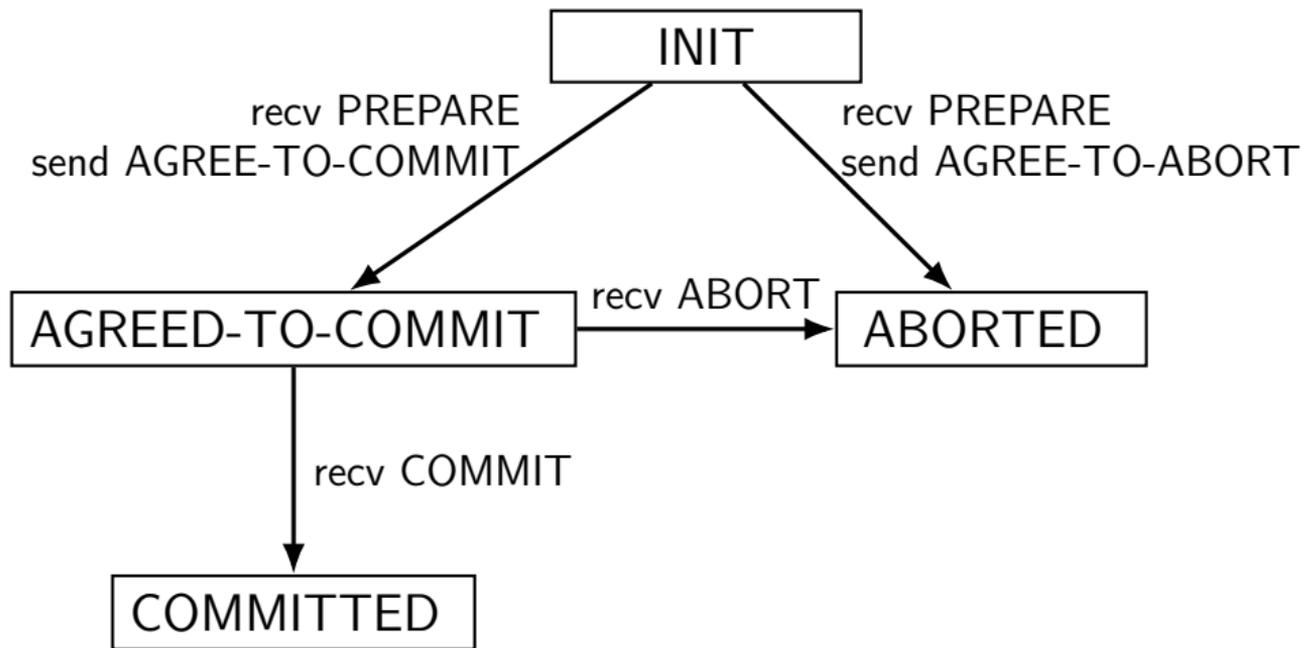
- if COMMITTED: resend COMMIT to all (dups okay!)

message doesn't make it to worker?

- coordinator can resend PREPARE after timeout (or just ABORT)

- worker can resend vote to coordinator to get extra reply

# worker state machine (simplified)



# worker failure recovery

duplicate messages okay — unique transaction ID!

worker crashes? *log* indicating last state

- if INIT: wait for PREPARE (resent)?

- if AGREE-TO-COMMIT or ABORTED: resend

- AGREE-TO-COMMIT/ABORT

- if COMMITTED: redo operation

message doesn't make it to coordinator

- resend after timeout or during reboot on recovery

# state machine missing details

really want to specify *result of/action for every message!*

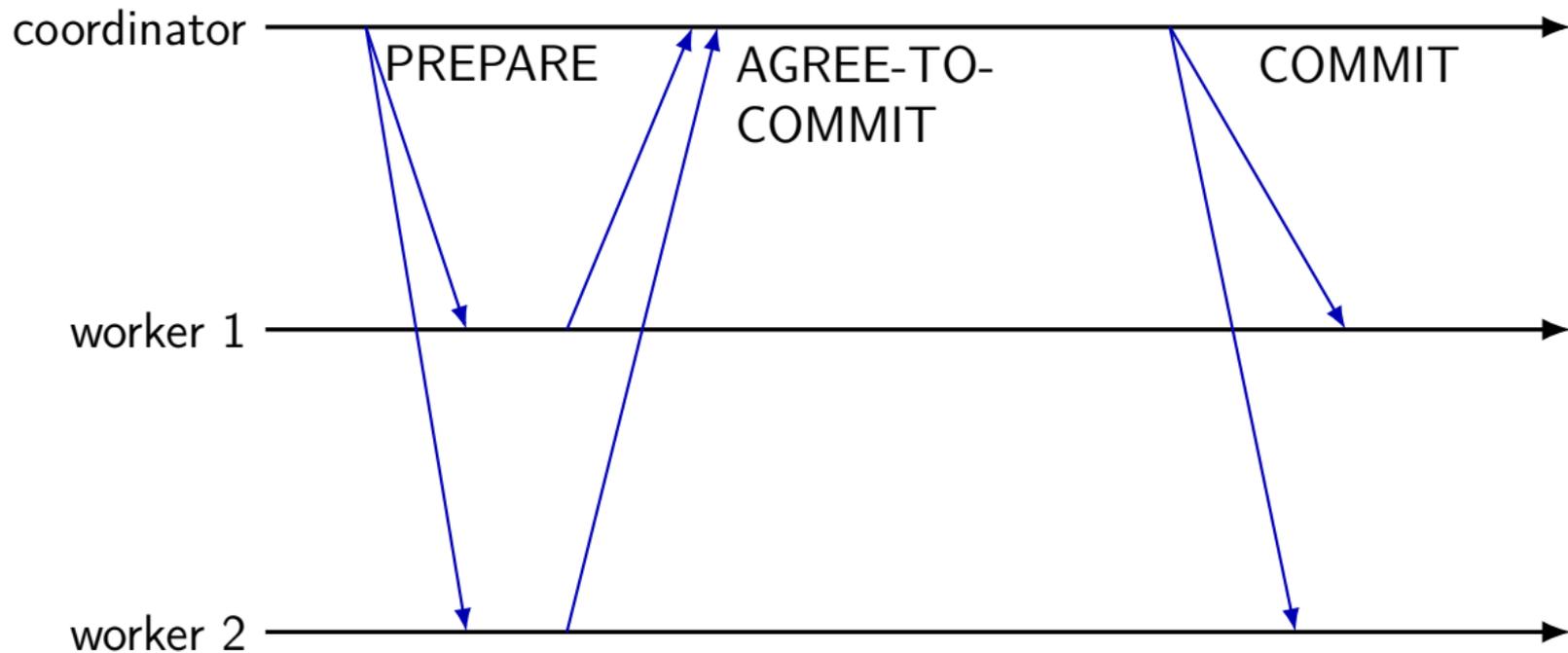
allows verifying properties of state machine

- what happens if machine fails at each possible time?

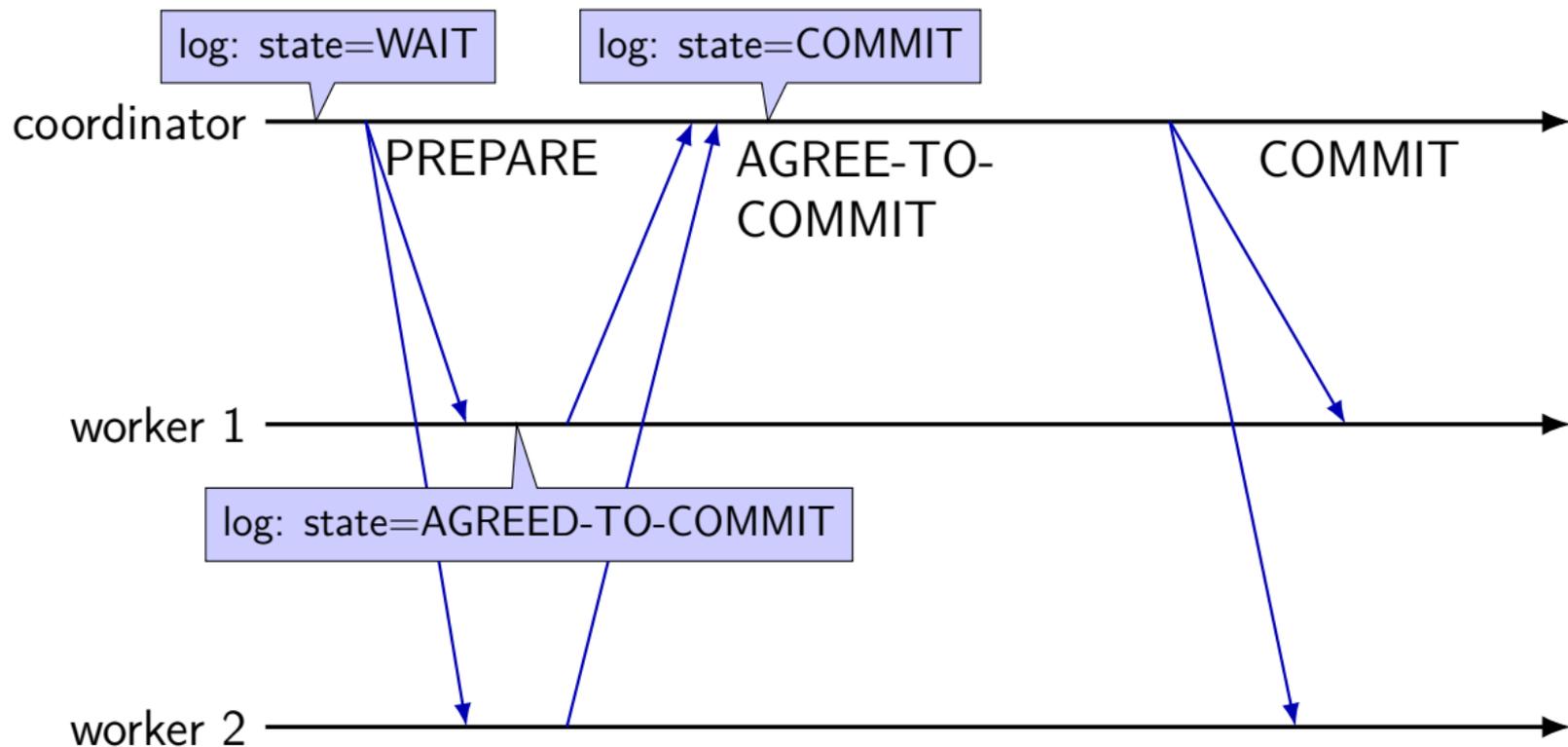
- what happens if possible message is lost?

- ...

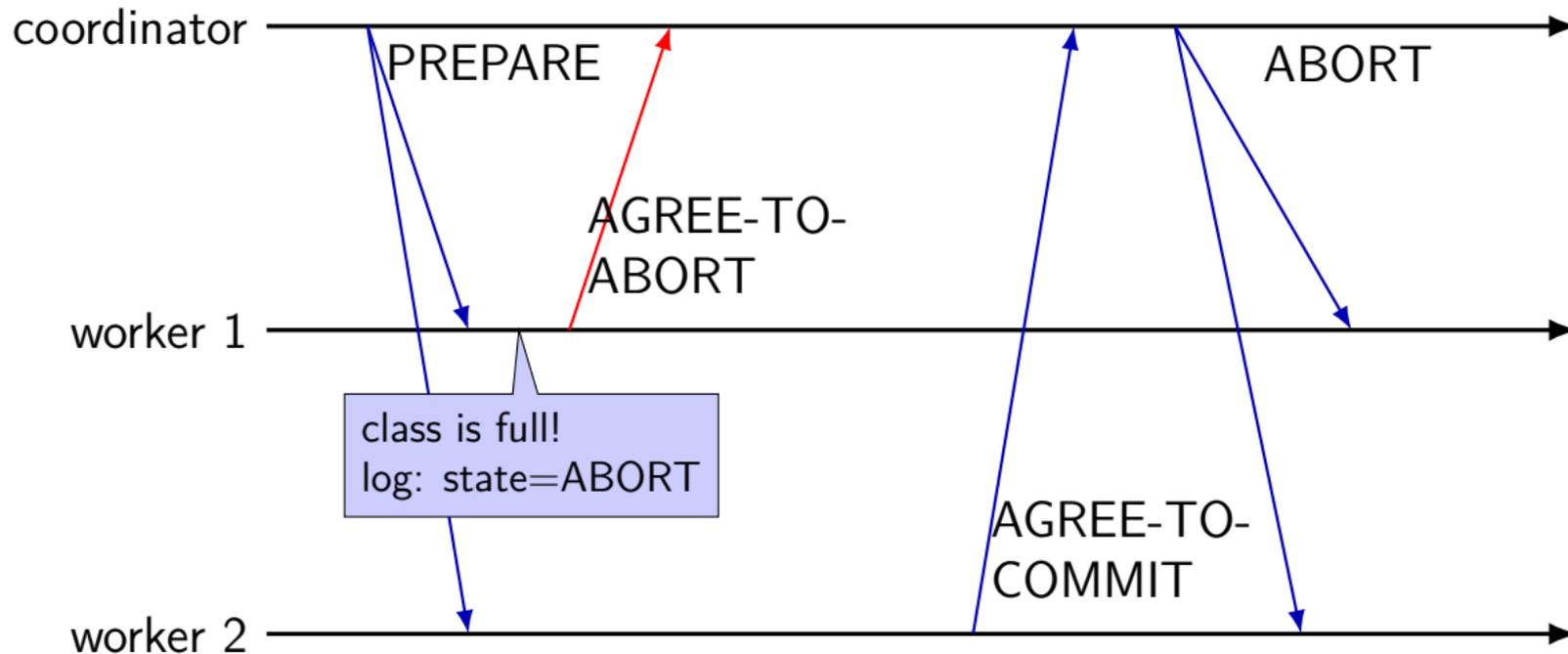
# TPC: normal operation



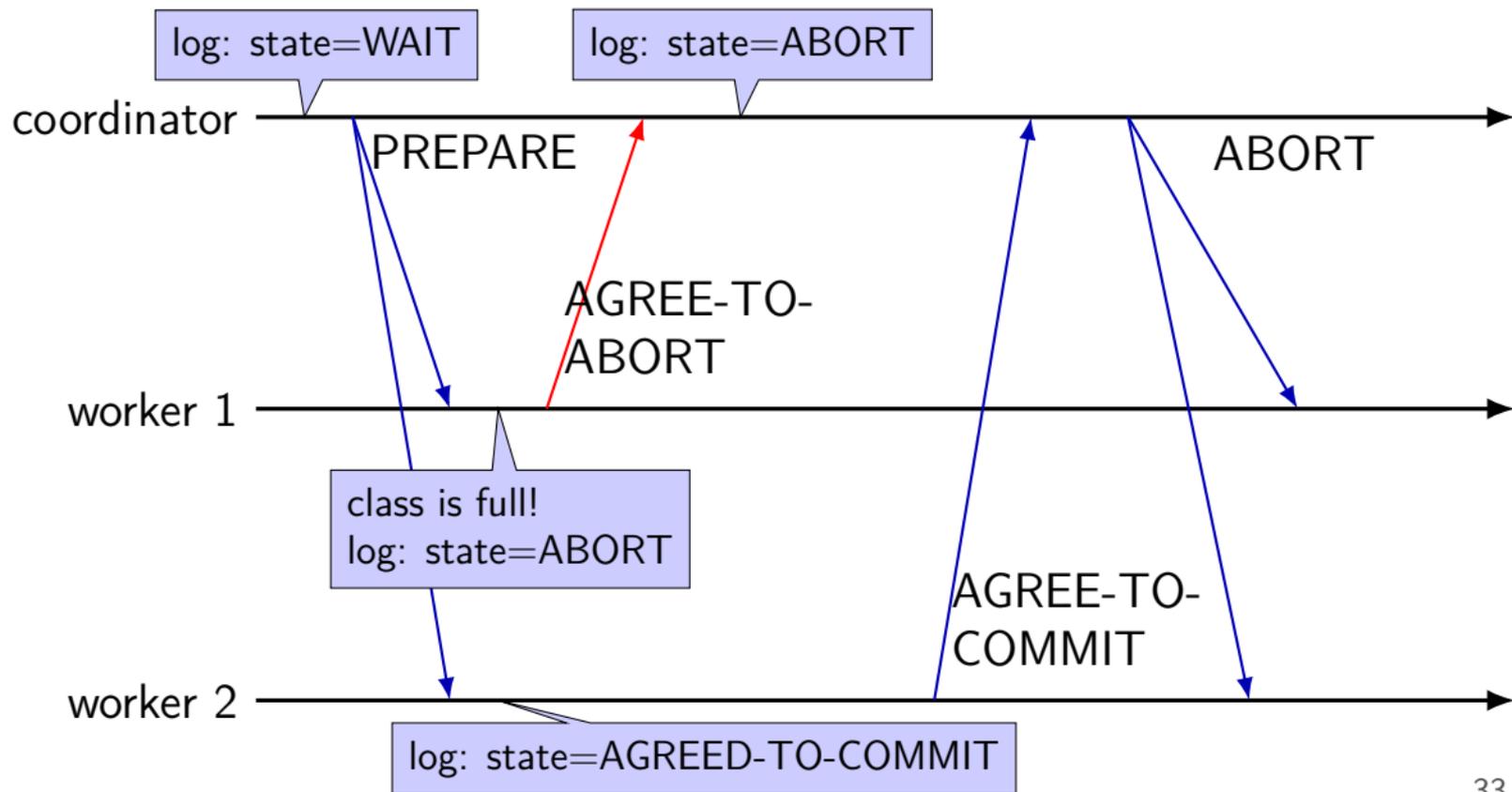
# TPC: normal operation



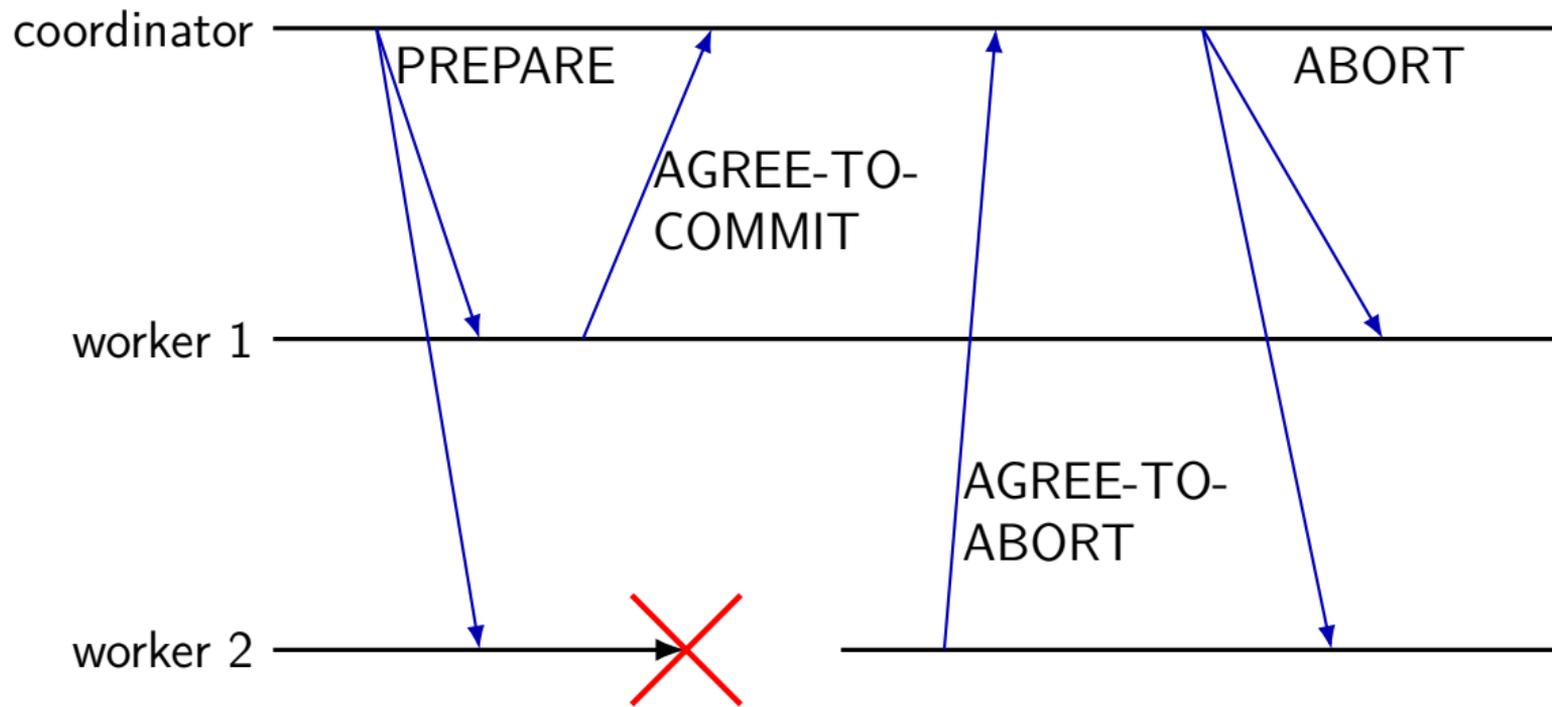
# TPC: normal operation — conflict



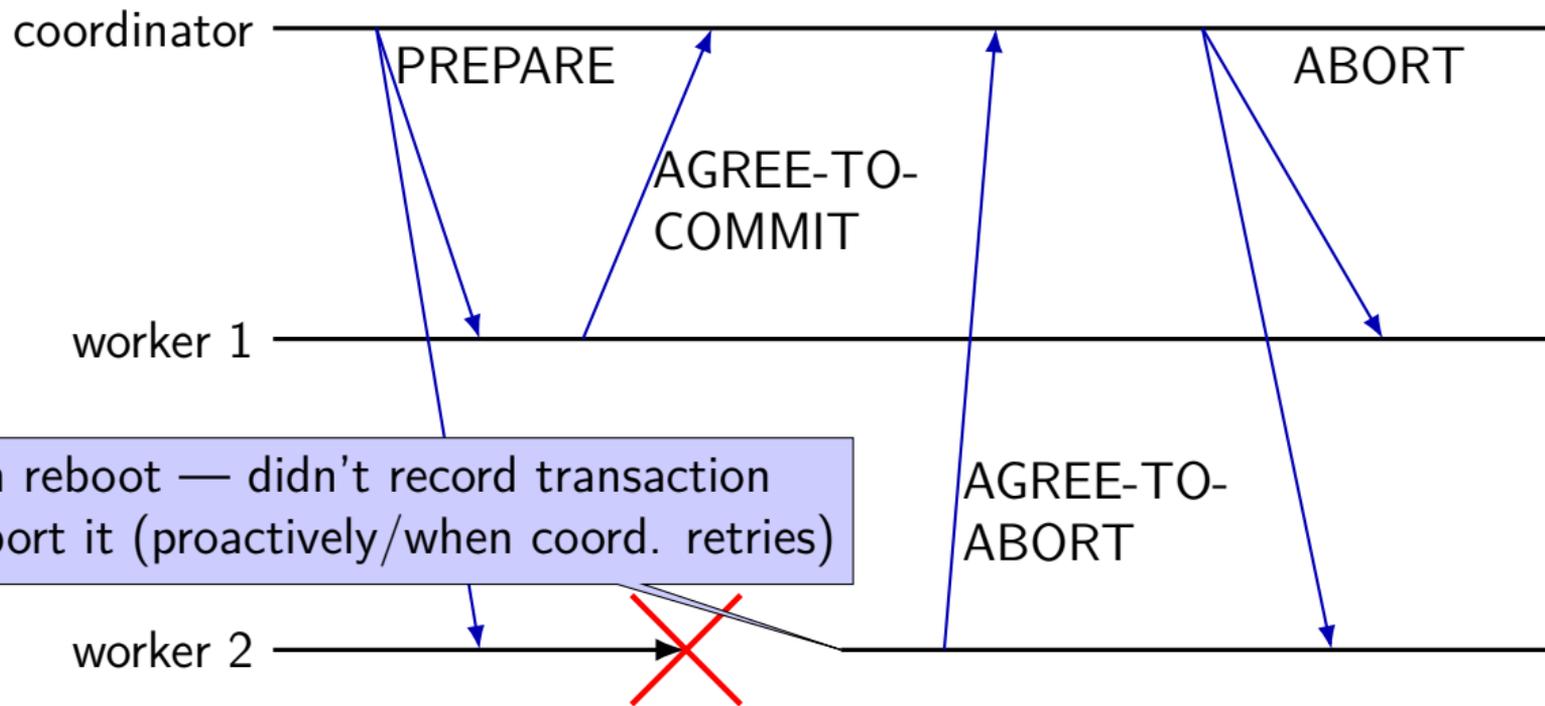
# TPC: normal operation — conflict



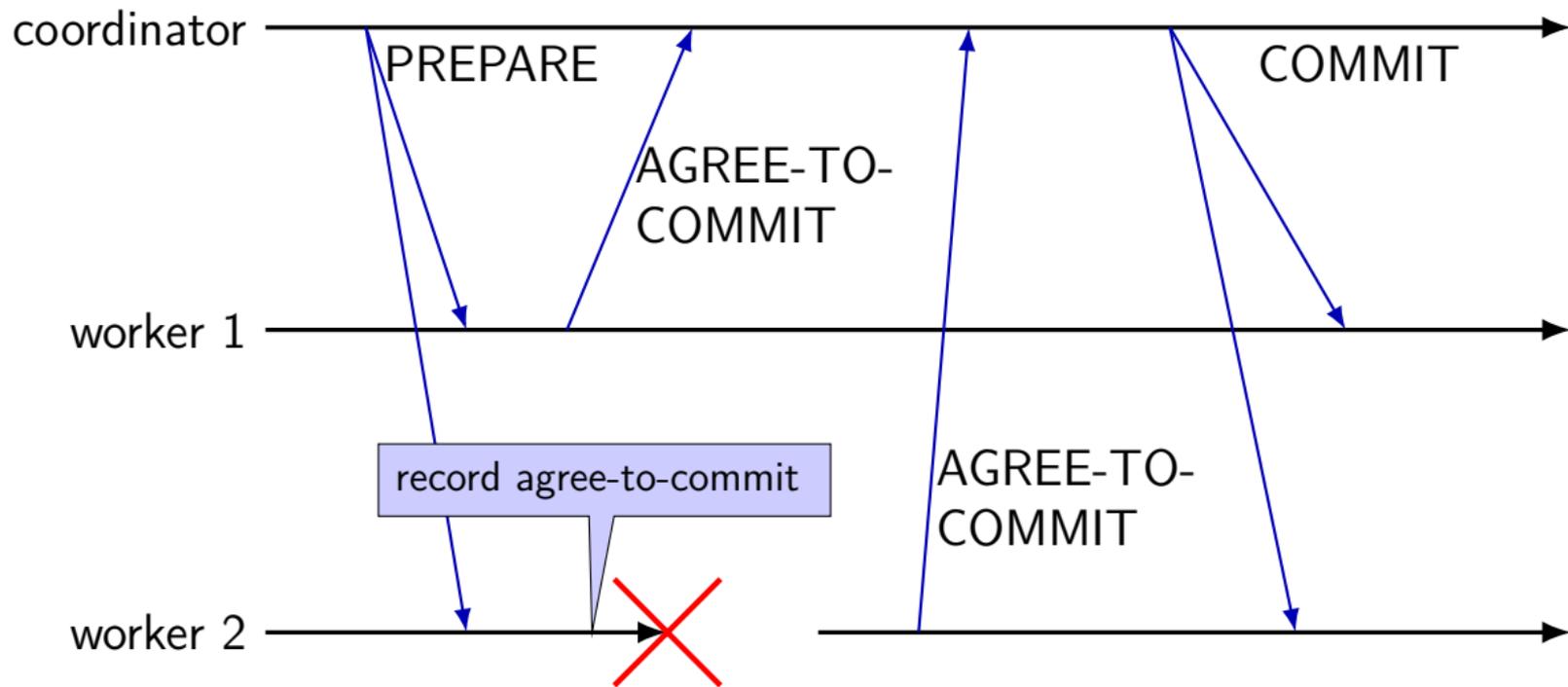
# TPC: worker failure (1)



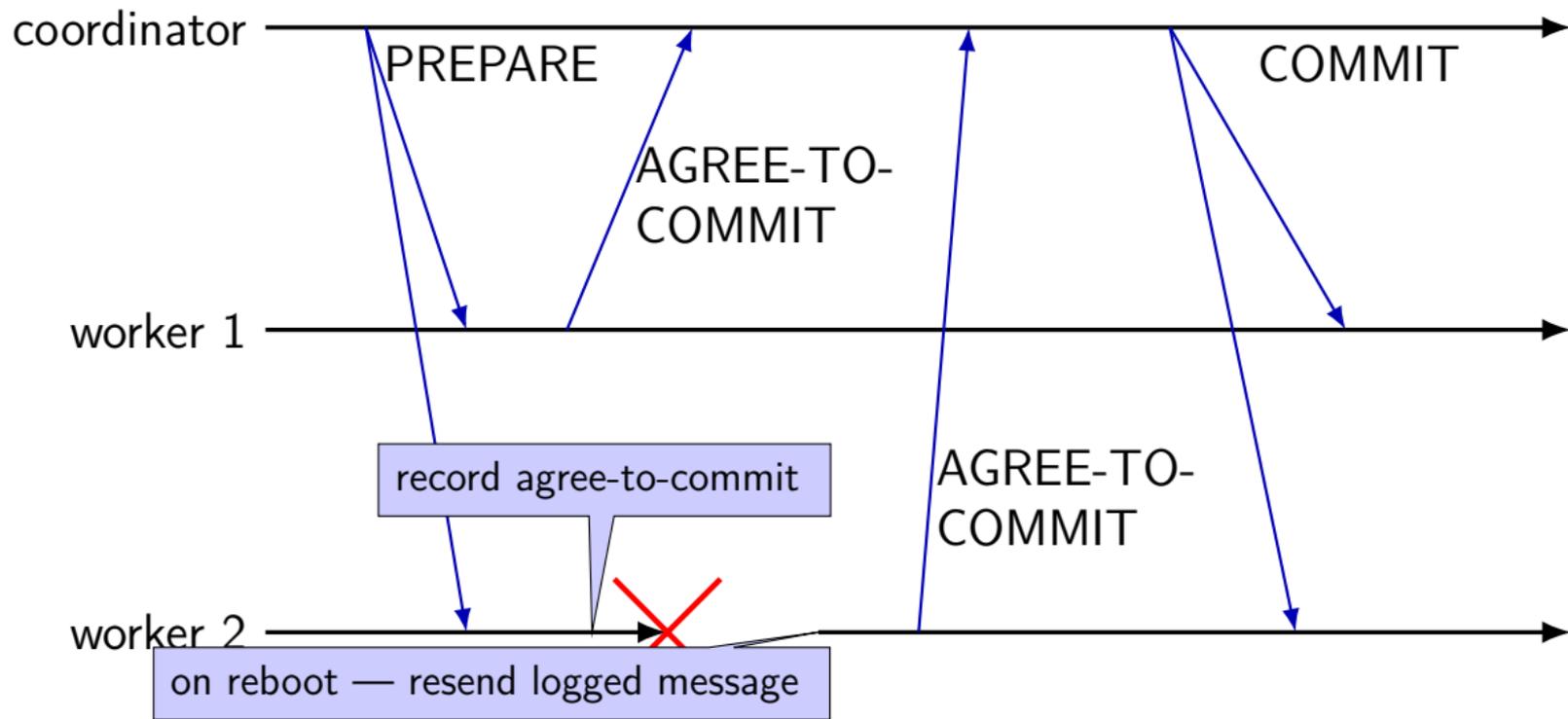
# TPC: worker failure (1)



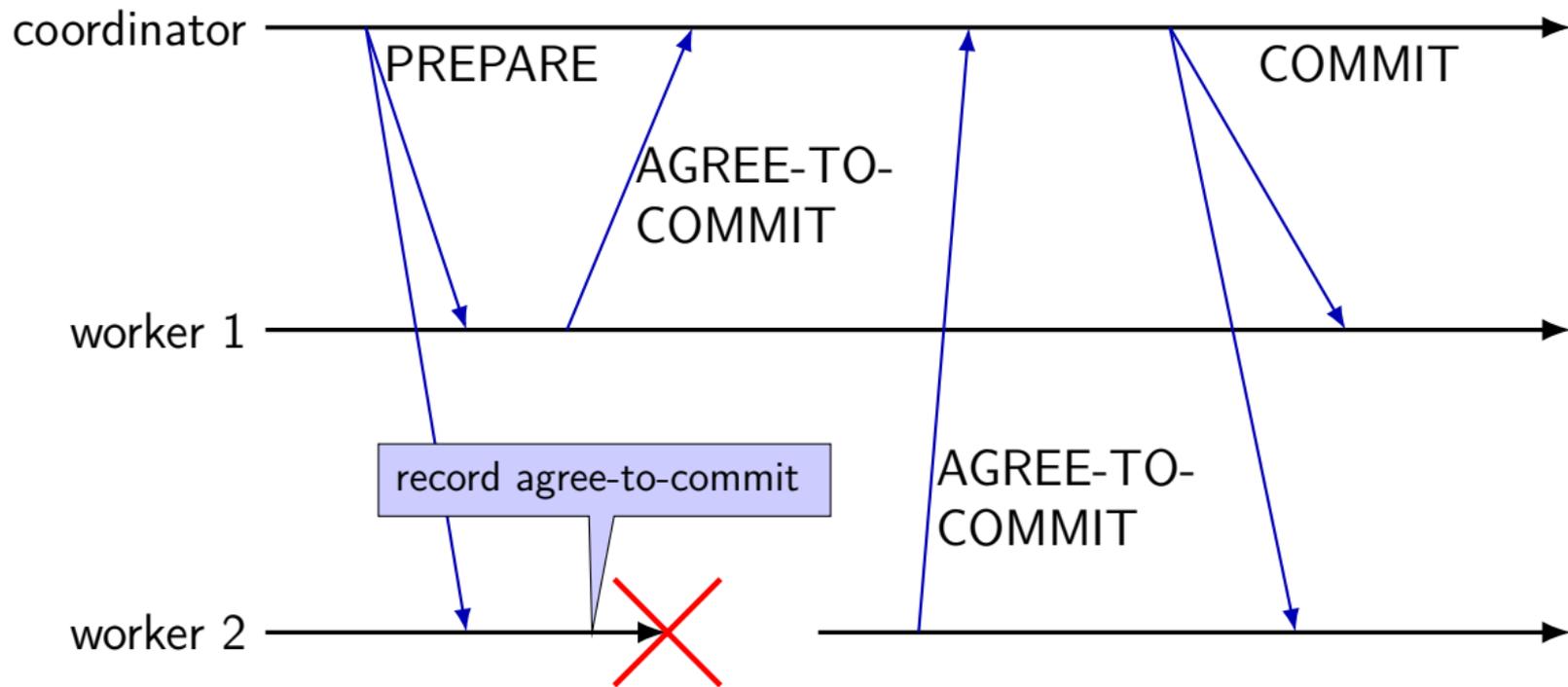
# TPC: worker failure (2)



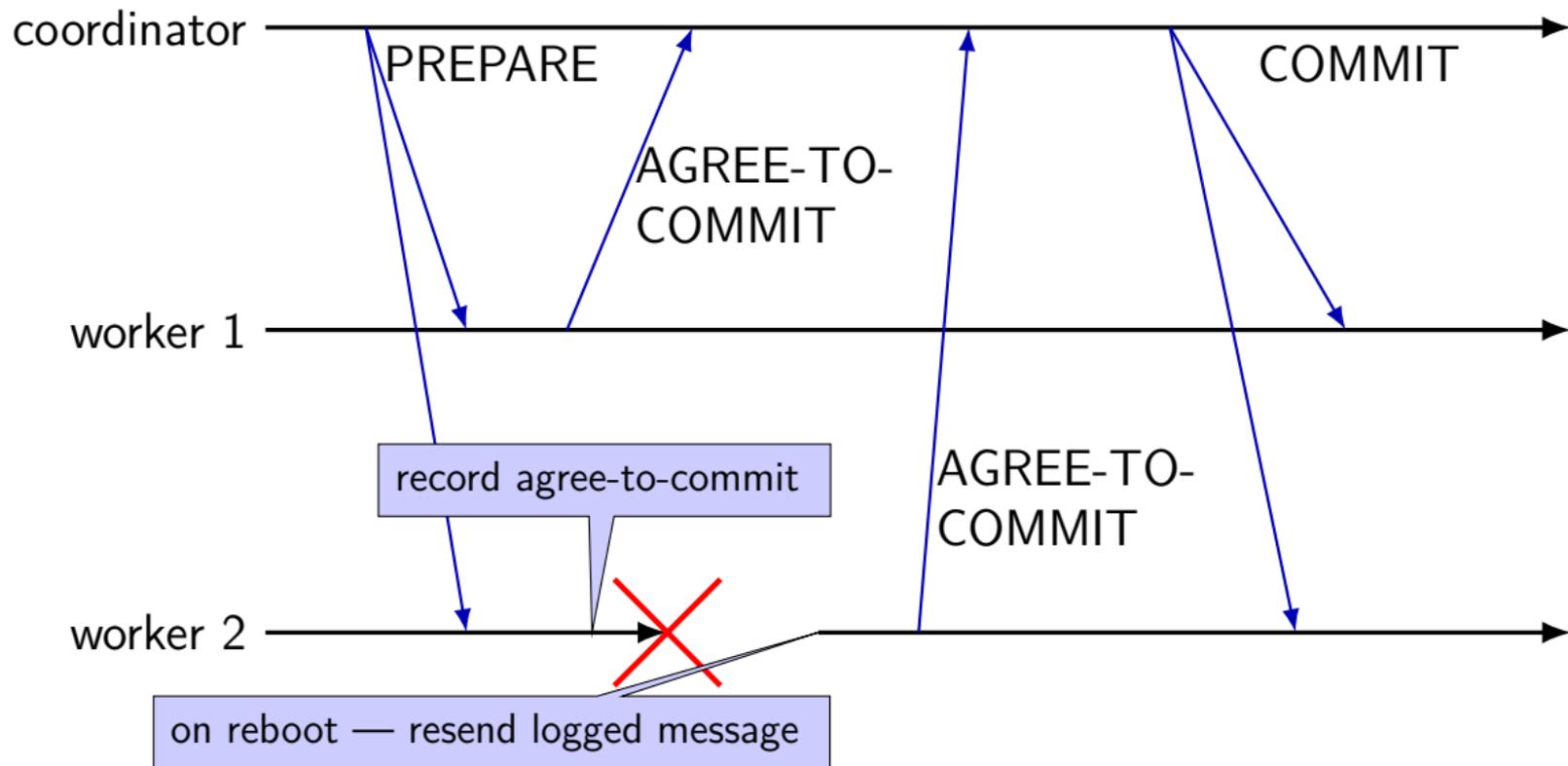
# TPC: worker failure (2)



# TPC: worker failure (3)



# TPC: worker failure (3)



# extending voting

two-phase commit: unanimous vote to commit

assumption: data split across nodes, every must cooperate

# extending voting

two-phase commit: unanimous vote to commit

assumption: data split across nodes, every must cooperate

other model: every node has a copy of data

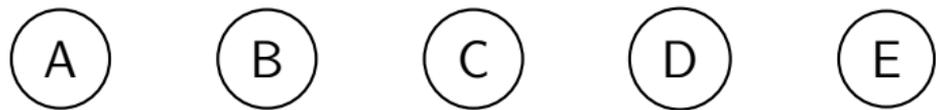
goal: work despite a few failing nodes

just require “enough” nodes to be working

for now — assume fail-stop

nodes don't respond or tell you if broken

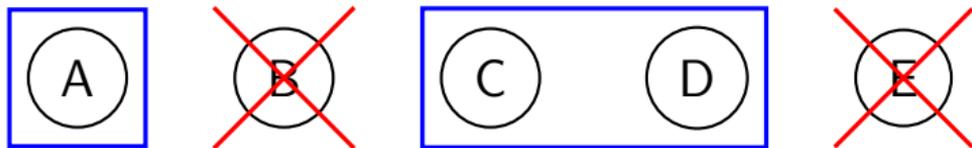
# quorums (1)



perform read/write with vote of any *quorum* of nodes

any quorum enough — okay if some nodes fail

## quorums (1)



perform read/write with vote of any *quorum* of nodes

any quorum enough — okay if some nodes fail

if A, C, D agree: that's enough

B, E will figure out what happened when they come back up

## quorums (2)



requirement: quorums overlap

overlap = *someone in quorum* knows about every update

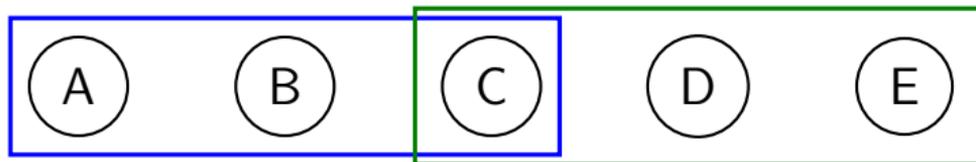
e.g. every operation requires majority of nodes

part of voting — provide other voting nodes with ‘missing’ updates

make sure updates survive later on

cannot get a quorum to agree on anything conflicting with past updates

## quorums (2)



requirement: **quorums overlap**

overlap = *someone in quorum* knows about every update

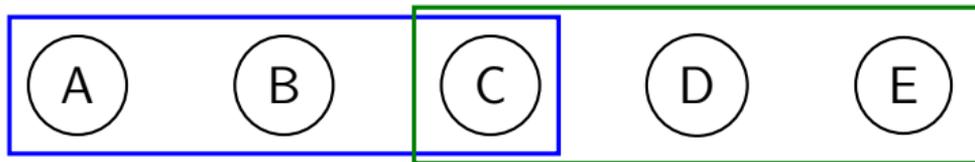
e.g. every operation requires majority of nodes

part of voting — provide other voting nodes with ‘missing’ updates

make sure updates survive later on

cannot get a quorum to agree on anything conflicting with past updates

## quorums (2)



requirement: quorums overlap

overlap = *someone in quorum* knows about every update

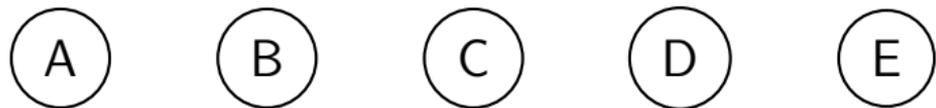
e.g. every operation requires majority of nodes

part of voting — provide other voting nodes **with 'missing' updates**

make sure updates survive later on

cannot get a quorum to agree on anything conflicting with past updates

## quorums (3)



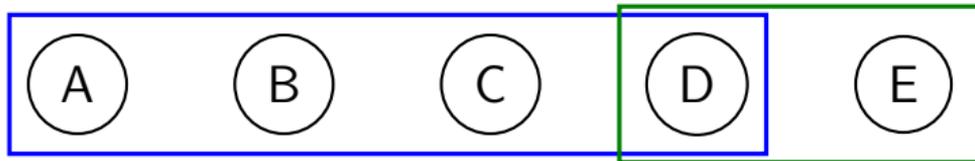
sometimes vary quorum based on operation type

example: update quorum = 4 of 5; read quorum = 2 of 5

requirement: read *overlaps* with last update

compromise: better performance sometimes, but tolerate less failures

## quorums (3)



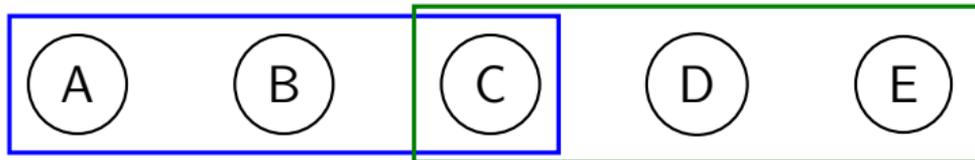
sometimes vary quorum based on operation type

example: **update** quorum = 4 of 5; **read** quorum = 2 of 5

requirement: read *overlaps* with last update

compromise: better performance sometimes, but tolerate less failures

# quorums



details very tricky

- what about coordinator failures?

- how does recovery happen?

- what information needs to be logged?

- “catching up” nodes that aren’t part of several updates

full details: lookup Raft or Paxos

# quorums for Byzantine failures

just overlap not enough

problem: node can give inconsistent votes

tell A “I agree to commit”, tell B “I do not”

need to confirm consistency of votes with other nodes

need *supermajority*-type quorums

$f$  failures —  $3f + 1$  nodes

full details: lookup PBFT

# protection/security

protection: mechanisms for controlling access to resources

page tables, preemptive scheduling, encryption, ...

security: *using protection* to prevent misuse

misuse represented by **policy**

e.g. “don’t expose sensitive info to bad people”

this class: about mechanisms more than policies

goal: provide enough flexibility for many policies

# adversaries

security is about **adversaries**

do the worst possible thing

challenge: adversary can be clever...

# authorization v authentication

*authentication* — who is who

# authorization v authentication

*authentication* — who is who

*authorization* — who can do what  
probably need authentication first...

# authentication

password

hardware token

...

# authentication

password

hardware token

...

this class: mostly won't deal with how

just tracking afterwards

# access control matrix: who does what?

	file 1	file 2	process 1
domain 1	read/write		
domain 2	read	write	wakeup
domain 3	read	write	kill

# access control matrix: who does what?

	file 1	file 2	process 1
domain 1	read/write		
domain 2	read	write	wakeup
domain 3	read	write	kill

each process belongs  
to 1+ *protection domains*:

“user cr4bd”

“group csfaculty”

...

# access control matrix: who does what?

objects (whatever type) with restrictions

	file 1	file 2	process 1
domain 1	read/write		
domain 2	read	write	wakeup
domain 3	read	write	kill

each process belongs  
to 1+ *protection domains*:

“user cr4bd”

“group csfaculty”

...

# representing access

with objects (files, etc.): *access control list*

list of protection domains (users, groups, processes, etc.) allowed to use each item

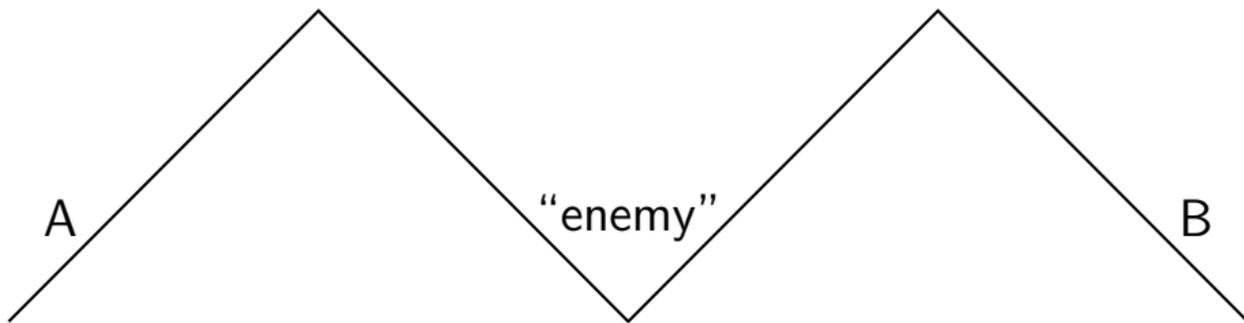
list of (domain, object, permissions) stored “on the side”

example: AppArmor on Linux

configuration file with list of program + what it is allowed to access  
prevent, e.g., print server from writing files it shouldn't



## two general's problem (setup)



general A and B want to agree on time to attack enemy (center)

only attack if they know the other will

attack together: victory

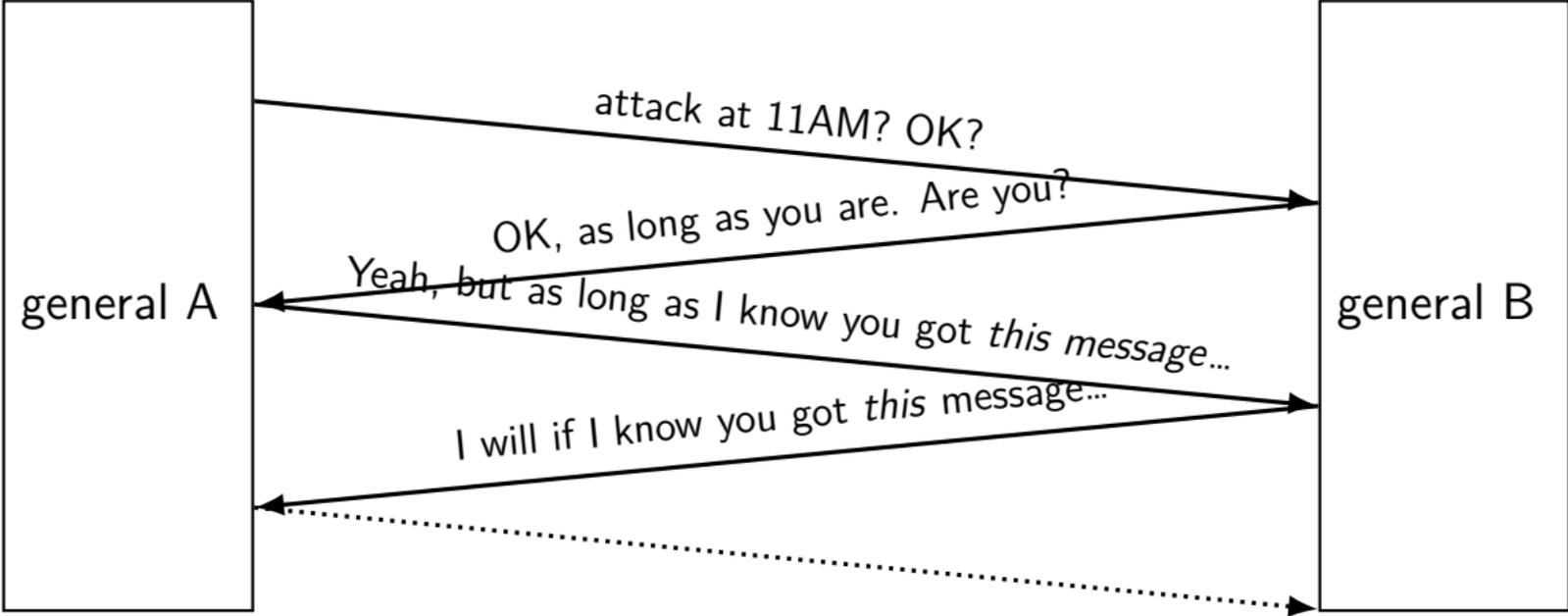
attack separately: defeat

communication mechanism: unreliable messengers

could be captured by enemy — message lost

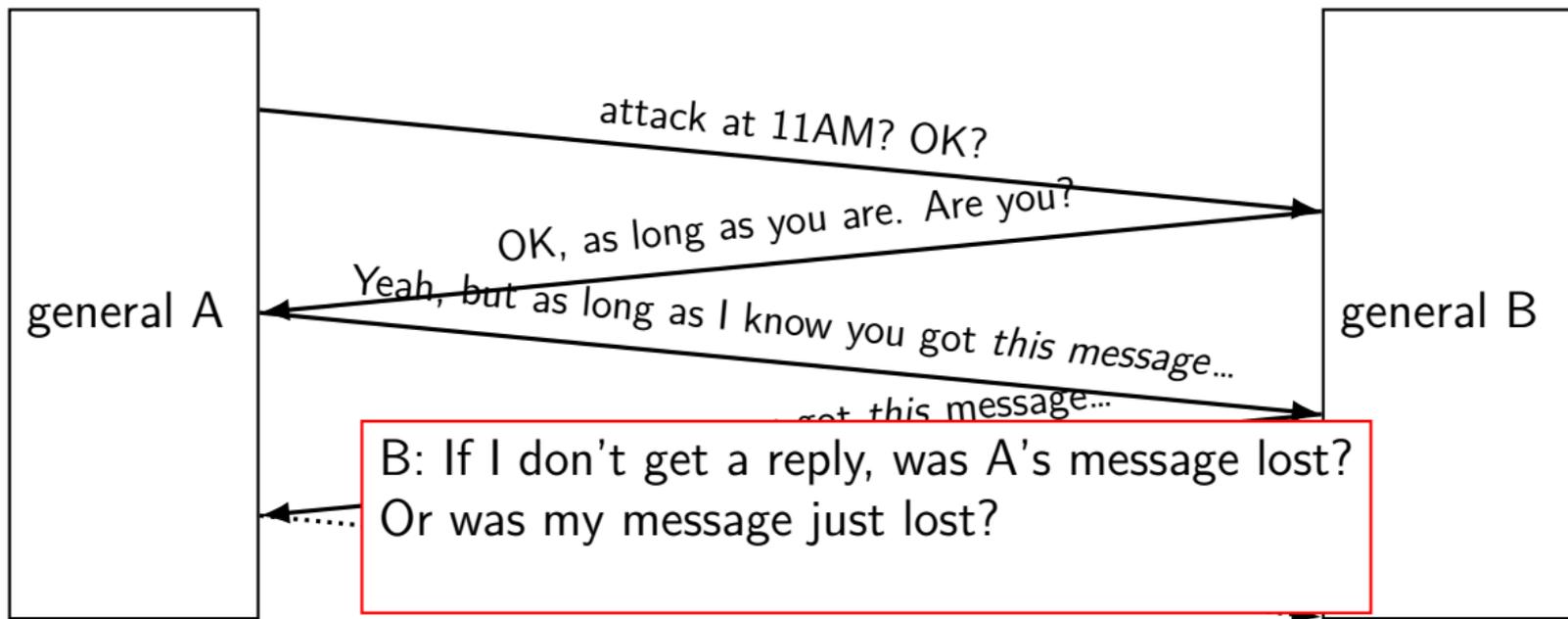
# two general's problem

recall: *both* agree to attack at same time  
(otherwise don't attack — sure defeat)



# two general's problem

recall: *both* agree to attack at same time  
(otherwise don't attack — sure defeat)



# impossibility

can't guarantee that both parties will attack

...even if no messages are lost

proof sketch:

some message flips A's state from "attacking" to "not attacking"

...but what if that message is lost — contradiction

# relaxing assumptions

can't get guarantee of receiving message

in practice: best approximation

wait for acknowledgement

retry on timeout

lots of timeouts — look like machine failure