Changelog

25 Feb 2021 (after lecture): add some explanation slides to CFS exercises

last time

first-come, first-served run whatever became ready first until done

round-robin

choose *time quantum* run for time quantum amount of time switch to next in list

time quantum tradeoffs

shorter time quantum = lower throughput + better fairness

priority scheduling

proportional share/lottery scheduling weighted random choice

shortest first — minimize mean turnaround time avoid convoy effect — short jobs waiting behind long

minimizing turnaround time

recall: first-come, first-served best order: had shortest CPU bursts first

- \rightarrow scheduling algorithm: 'shortest job first' (SJF)
- = same as priority where CPU burst length determines priority

...but without preemption for now priority = job length doesn't quite work with preemption (preview: need priority = remaining time)

a practical problem

so we want to run the shortest CPU burst first

how do I tell which thread that is?

we'll deal with this problem later

...kinda







preemption: definition

stopping a running program while it's still runnable

example: FCFS did not do preemption. RR did.

what we need to solve the problem: 'accidentally' ran long task, now need room for short one

adding preemption (1)

what if a long job is running, then a short job interrupts it? short job will wait for too long

solution is preemption — reschedule when new job arrives new job is shorter — run now!

adding preemption (2)

what if a long job is *almost done* running, then a medium job interrupts it?

recall: priority = job length long job waits for medium job ...for longer than it would take to finish worse than letting long job finish

adding preemption (2)

what if a long job is *almost done* running, then a medium job interrupts it?

recall: priority = job length long job waits for medium job ...for longer than it would take to finish worse than letting long job finish

solution: priority = remaining time

called shortest *remaining time* first (SRTF) prioritize by what's left, not the total









SRTF, SJF are optimal (for turnaround time)

SJF minimizes turnaround time/waiting time ...if you disallow preemption/leaving CPU deliberately idle

SRTF minimizes turnaround time/waiting time ... if you ignore context switch costs

aside on names

we'll use:

- SRTF for preemptive algorithm with remaining time
- SJF for non-preemptive with total time=remaining time
- might see different naming elsewhere/in books, sorry...

knowing job (CPU burst) lengths

seems hard

sometimes you can ask common in batch job scheduling systems

and maybe you'll get accurate answers, even

the SRTF problem

want to know CPU burst length

well, how does one figure that out?

the SRTF problem

want to know CPU burst length

well, how does one figure that out?

```
e.g. not any of these fields
```

```
uint sz;
pde t* pgdir;
char *kstack:
enum procstate state;
int pid;
struct proc *parent;
struct trapframe *tf;
struct context *context;
void *chan;
int killed;
struct file *ofile[NOFILE]; // Open files
struct inode *cwd;
char name[16];
```

```
// Size of process memory (bytes)
   // Page table
   // Bottom of kernel stack for this pi
 // Process state
  // Process ID
 // Parent process
  // Trap frame for current syscall
  // swtch() here to run process
   // If non-zero, sleeping on chan
   // If non-zero, have been killed
// Current directory
   // Process name (debugging)
```

predicting the future

worst case: need to run the program to figure it out

but heuristics can figure it out (read: often works, but no gaurentee)

key observation: CPU bursts now are like CPU bursts later intuition: interactive program with lots of I/O tends to stay interactive intuition: CPU-heavy program is going to keep using CPU

multi-level feedback queues

classic strategy based on priority scheduling

combines update time estimates and running shorter times first

key idea: current priority \approx current time estimate

small(ish) number of time estimate "buckets"

multi-level feedback queues: setup



goal: place processes at priority level based on CPU burst time just a few priority levels — can't guess CPU burst precisely anyways

dynamically adjust priorities based on observed CPU burst times priority level \rightarrow allowed/expected time quantum use more than 1ms at priority 3? — you shouldn't be there use less than 1ms at priority 0? — you shouldn't be there

idea: priority = CPU burst length













used whole timeslice? add to lower priority queue now

finished early? put on higher priority next time

multi-level feedback queue idea

higher priority = shorter time quantum (before interrupted)

adjust priority and timeslice based on last timeslice

intuition: thread always uses same CPU burst length? ends up at "right" priority

rises up to queue with quantum just shorter than it's burst then goes down to next queue, then back up, then down, then up, etc.











cheating multi-level feedback queuing

algorithm: don't use entire time quantum? priority increases

```
getting all the CPU:
```

```
while (true) {
    useCpuForALittleLessThanMinimumTimeQuantum();
    yieldCpu();
```

multi-level feedback queuing and fairness

suppose we are running several programs:

A. one very long computation that doesn't need any I/O B1 through B1000. 1000 programs processing data on disk C. one interactive program

how much time will A get?
multi-level feedback queuing and fairness

suppose we are running several programs:

A. one very long computation that doesn't need any I/O B1 through B1000. 1000 programs processing data on disk C. one interactive program

how much time will A get?

almost none — starvation

intuition: the B programs have higher priority than A because it has smaller CPU bursts

conflicting goals for interactivity heuristics

efficiency

avoid scanning all threads every few milliseconds

figure out new programs quickly

adapt to changes/spikes in program behavior

avoid pathological behavior

starvation, hanging when new compute-intensive program starts, etc.

exercise: how to handle each of these well? what does MLFQ do well?

Linux's Completely Fair Scheduler (CFS)

Linux's default scheduler is a proportional share scheduler...

...without randomization (consistent)

...with $O(\log N)$ scheduling decision (handles many threads/processes)

...which favors interactive programs

...which adjusts timeslices dynamically shorter timeslices if many things to run

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CFS: tracking runtime

each thread has a *virtual runtime* (\sim how long it's run)

incremented when run based how long it runs

scheduling decision: run thread with lowest virtual runtime data structure: balanced tree

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incremented when run based how long it runs

more/less important thread? multiply adjustments by factor

adjustments for threads that are new or were sleeping too big an advantage to start at runtime 0

scheduling decision: run thread with lowest virtual runtime data structure: balanced tree

virtual time, always ready, 1 ms quantum



virtual time, always ready, 1 ms quantum



at each time:

update current thread's time run thread with lowest total time

virtual time, always ready, 1 ms quantum



at each time:

update current thread's time run thread with lowest total time

same effect as round robin if everyone uses whole quantum

what about threads waiting for I/O, ...?

should be advantage for processes not using the CPU as much haven't used CPU for a while — deserve priority now ...but don't want to let them hog the CPU

Linux solution: newly ready task time = max of its prior virtual time a little less than minimum virtual time (of already ready tasks)

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Linux solution: newly ready task time = max of its prior virtual time a little less than minimum virtual time (of already ready tasks)

not runnable briefly? still get your share of CPU (catch up from prior virtual time)

not runnable for a while? get bounded advantage

0 ms 1 ms 2 ms 3 ms





3 ms



A's long sleep... 0 ms 1 ms 2 ms 3 ms









handling proportional sharing

solution: multiply used time by weight

e.g. 1 ms of CPU time costs process 2 ms of virtual time higher weight \implies process less favored to run

CFS exercise (0)



suppose programs A, B with alternating CPU + I/O as above

with CFS (and equal weights) and **no adjustments to virtual time for programs waking up from sleep**, **about** what portion of CPU does program A get?

exercise solution

if A, B, were running alone, could get at most 1/2 the CPU B can't use that much time

so B will run 2/5ths of the time (the most it can)

so B will almost always have lower virtual time than A

A will get the remaining about 3/5ths

exception: time both A and B are both doing I/O

CFS exercise (1)



suppose programs A, B, C with alternating CPU + $\rm I/O$ as above

with CFS (and equal weights) and **no adjustments to virtual time for programs waking up from sleep**, about what portion of CPU does program A get?

CFS exercise: maximum time for A



A running alone: A runs 2/5ths of the time

A, B, C sharing fairly: each runs 1/3rd of the time if A used more than 1/3rd of the time... then it would have a higher virtual time... and B and C would catch up (and same for B or C)

result: A runs at most 1/3rd of the time...

unless B can't use its full share because of I/O (because of being interrupted by A too much?)

CFS exercise (2)



suppose we add adjustments to virtual time for waking up from sleep

expected direction of change in how much compute time A gets?

CFS exercise: A disadvantage from sleep



CFS exercise: A interrupted by B?



A interrupted by B a bunch sometimes...?

might not start I/O as often

might not be able to run 1/3rd of the time

e.g. sometimes $2/(2+2+3) \approx 28\%$ of CPU

which scheduler should I choose?

I care about...

- CPU throughput: first-come first-serve
- average response time: SRTF approximation
- ${\sf I}/{\sf O}$ throughput: SRTF approximation
- fairness medium-term CPU usage: something like Linux CFS
- fairness wait time: something like RR
- real-world deadlines: earliest deadline first or similar
- favoring certain users: strict priority

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a note on multiprocessors

what about multicore?

extra considerations:

want two processors to schedule without waiting for each other want to keep process on same processor (better for cache) what process to preempt when three+ choices?

4.4BSD scheduler

 $4.4BSD\ /\ FreeBSD\ pre-2003$ scheduler was a variation on MLFQ

64 priority levels, 100 ms quantum

same quantum at every priority

priorities adjusted periodically

in retrospect not good for performance — iterate through all threads part of why FreeBSD stopped using this scheduler

priority of threads that spent a lot of time waiting for ${\rm I}/{\rm O}$ increased

priority of threads that used a lot of CPU time decreased

real-time

so far: "best effort" scheduling best possible (by some metrics) given some work

alternate model: need gaurnetees

deadlines imposed by real-world

process audio with 1ms delay computer-controlled cutting machines (stop motor at right time) car brake+engine control computer

•••

real time example: CPU + deadlines



example with RR



earliest deadline first


impossible deadlines



no way to meet all deadlines!

admission control

given *worst-case* runtimes, start times, deadlines, scheduling algorithm,...

figure out whether it's possible to gaurentee meeting deadlines details on how — not this course (probably)

if not, then

change something so they can? don't ship that device? tell someone at least?

earliest deadline first and...

earliest deadline first does *not* (even when deadlines met) minimize response time maximize throughput maximize fairness

exercise: give an example

other real-time schedulers

typical real time systems: *periodic tasks with deadlines* "*rate monotonic*"

commonly approximate EDF with lower period = higher priority easier to implement than true EDF

well-known method to determine if schedule is admissible = won't exceed deadline (under some assumptions)

MLFQ variations

version of MLFQ I described is in Anderson-Dahlin

problems:

starvation

worse than with real SRTF — based on guess, not real remaining time

oscillation not great for predictability

variation to prevent starvation

Apraci-Dusseau presents version of MLFQ w/o starvation two changes:

don't increase priority when whole quantum not used instead keep the same — more stable

periodically increase priority of *all threads*

allow compute-heavy threads to run a little still deals with thread's behavior changing over time replaces finer-grained upward adjustments

FreeBSD scheduler

current default FreeBSD scheduler based on MLFQ idea

...but: time quantums don't depend on priority

computes interactivity score $\sim \frac{I/O \text{ wait}}{I/O \text{ wait} + \text{runtime}}$ note: deliberately not estimating remaining time

(using "recent" history of thread)

thread priorities set based on interactivity score

aside: measuring fairness (1)

first question: what needs to be divided fairly?

problem: what about programs waiting for I/O?

answer 1: don't consider what happens when program waiting for ${\rm I/O}$

answer 2:

give program credit for time not running while waiting for $\ensuremath{I/O}$

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aside: measuring fairness (2)

one way: max-min fairness

choose schedule that maximizes the minimum resource given to anyone

aside: measuring fairness (2)

one way: max-min fairness

choose schedule that maximizes the minimum resource given to anyone

| most fair | | least fair |
|-----------|--|------------|

CFS quantum lengths goals

first priority: constrain minimum quantum length (default: 0.75ms) avoid too-frequent context switching

second priority: run every process "soon" (default: 6ms) avoid starvation

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quantum \approx max(fixed window / num processes, minimum quantum)

CFS: avoiding excessive context switching

conflicting goals:

schedule newly ready tasks immediately (assuming less virtual time than current task)

avoid excessive context switches

CFS rule: if virtual time of new task < current virtual time by threshold default threshold: 1 ms

(otherwise, wait until quantum is done)