### last time

#### counting semaphores

down: decrement — wait first if would be negative up: increment — wake up if another thread waiting intuition: number that should be zero when waiting

reader/writer locks

multiple readers share lock single writer at a time priority question: prefer readers or writers or other?

#### deadlocks

circular dependencies resulting in indefinite waiting common with locks, but can happen with many resources classic example T1: Lock(A) Lock(B); T2: Lock(B) Lock(A)

### deadlock

...

deadlock — circular waiting for resources

resource = something needed by a thread to do work locks CPU time disk space memory

often non-deterministic in practice

most common example: when acquiring multiple locks

### deadlock

...

deadlock — circular waiting for resources

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often non-deterministic in practice

most common example: when acquiring multiple locks

### deadlock versus starvation

starvation: one+ unlucky (no progress), one+ lucky (yes progress) example: low priority threads versus high-priority threads

deadlock: no one involved in deadlock makes progress

### deadlock versus starvation

starvation: one+ unlucky (no progress), one+ lucky (yes progress) example: low priority threads versus high-priority threads

deadlock: no one involved in deadlock makes progress

starvation: once starvation happens, taking turns will resolve low priority thread just needed a chance...

deadlock: once it happens, taking turns won't fix

## deadlock requirements

#### mutual exclusion

one thread at a time can use a resource

#### hold and wait

thread holding a resources waits to acquire another resource

#### no preemption of resources

resources are only released voluntarily thread trying to acquire resources can't 'steal'

#### circular wait

```
there exists a set \{T_1, \ldots, T_n\} of waiting threads such that T_1 is waiting for a resource held by T_2
T_2 is waiting for a resource held by T_3
\vdots
T_n is waiting for a resource held by T_1
```

## how is deadlock possible?

```
Given list: A, B, C, D, E
```

```
RemoveNode(LinkedListNode *node) {
    pthread mutex lock(&node->lock);
    pthread_mutex_lock(&node->prev->lock);
    pthread mutex lock(&node->next->lock);
    node->next->prev = node->prev;
    node->prev->next = node->next;
    pthread mutex unlock(&node->next->lock);
    pthread mutex unlock(&node->prev->lock);
    pthread mutex unlock(&node->lock);
```

Which of these (all run in parallel) can deadlock?

- A. RemoveNode(B) and RemoveNode(C)
- B. RemoveNode(B) and RemoveNode(D)
- C. RemoveNode(B) and RemoveNode(C) and RemoveNode(D)
- D. A and C. E. B and C
- F. all of the above G. none of the above

### how is deadlock — solution

Remove B	Remove C
lock B	lock C
lock A (prev)	wait to lock B (prev)
wait to lock C (next)	

With B and D — only overlap in in node C — no circular wait possible

#### infinite resources

or at least enough that never run out

no shared resources

no mutual exclusion

no mutual exclusion

#### no waiting

"busy signal" — abort and (maybe) retry revoke/preempt resources no hold and wait/ preemption

acquire resources in consistent order

no *circular wait* 

request all resources at once

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no mutual exclusion

memory allocation: malloc() fails rather than waiting (no deadlock)
locks: pthread\_mutex\_trylock fails rather than waiting
...
no waiting
 "busy signal" — abort and (maybe) retry
 revoke/preempt resources
 no hold and wait/
 preemption

acquire resources in consistent order

no *circular wait* 

request all resources at once

#### infinite resources

or at least enough that never run out

no mutual exclusion

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no mutual exclusion

#### **no waiting** "busy signal" — abort and (maybe) retry revoke/preempt resources no hold and wait/ preemption

acquire resources in consistent order

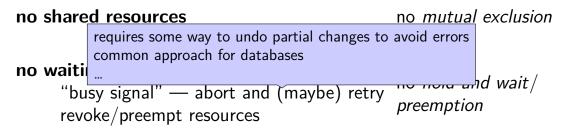
no circular wait

request all resources at once

#### infinite resources

or at least enough that never run out

no mutual exclusion



acquire resources in consistent order

no *circular wait* 

request all resources at once

## acquiring locks in consistent order (1)

```
MoveFile(Dir* from_dir, Dir* to_dir, string filename) {
  if (from dir->path < to dir->path) {
    lock(&from dir->lock);
    lock(&to dir->lock);
  } else {
    lock(&to dir->lock);
    lock(&from dir->lock);
  }
```

## acquiring locks in consistent order (1)

```
MoveFile(Dir* from_dir, Dir* to_dir, string filename) {
  if (from dir->path < to dir->path) {
    lock(&from dir->lock);
    lock(&to dir->lock);
  } else {
    lock(&to dir->lock);
    lock(&from_dir->lock);
  }
                       any ordering will do
                      e.g. compare pointers
```

## acquiring locks in consistent order (2)

often by convention, e.g. Linux kernel comments:

```
/*
   lock order:
*
        contex.ldt usr sem
*
          mmap_sem
*
            context.lock
*/
/*
  lock order:
*
   1. slab mutex (Global Mutex)
*
  2. node->list lock
    3. slab_lock(page) (Only on some arches and for debugging)
*
   . . .
 *
```

#### infinite resources

or at least enough that never run out

no mutual exclusion

no shared resources

no mutual exclusion

#### no waiting

"busy signal" — abort and (maybe) retry revoke/preempt resources no hold and wait/ preemption

acquire resources in consistent order

no *circular wait* 

request all resources at once

### beyond threads: event based programming

writing server that servers multiple clients?

e.g. multiple web browsers at a time

maybe don't really need multiple processors/cores one network, not that fast

idea: one thread handles multiple connections

### beyond threads: event based programming

writing server that servers multiple clients?

- e.g. multiple web browsers at a time
- maybe don't really need multiple processors/cores one network, not that fast
- idea: one thread handles multiple connections
- issue: read from/write to multiple streams at once?

### event loops

```
while (true) {
    event = WaitForNextEvent();
    switch (event.type) {
    case NEW CONNECTION:
        handleNewConnection(event); break;
    case CAN_READ_DATA_WITHOUT WAITING:
        connection = LookupConnection(event.fd);
        handleRead(connection);
        break:
    case CAN WRITE DATA WITHOUT WAITING:
        connection = LookupConnection(event.fd);
        handleWrite(connection):
        break;
        . . .
    }
```

## **POSIX** support for event loops

select and poll functions

take list(s) of file descriptors to read and to write wait for them to be read/writeable without waiting (or for new connections associated with them, etc.)

many OS-specific extensions/improvements/alternatives: examples: Linux epoll, Windows IO completion ports better ways of managing list of file descriptors enqueue read/write instead of learning when read/write okay

### message passing

instead of having variables, locks between threads...

send messages between threads/processes

what you need anyways between machines big 'supercomputers' = really many machines together arguably an easier model to program can't have locking issues

#### a prereq note

in CS 3330 or CoA 2, we cover virtual memory for several days CS3330 = Computer Architecture CoA2 = Computer Organization and Architecture 2 in the CS 2020 curriculum pilot

for CpEs: the prereq for this class is ECE's *embedded* class (and *not the CpE architecture class*)

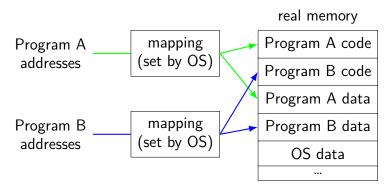
I think little virtual memory coverage in CpE embedded *or* architecture?

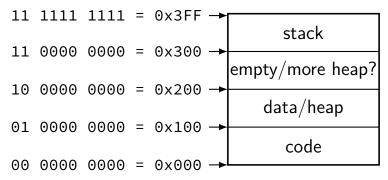
don't have precise information about that

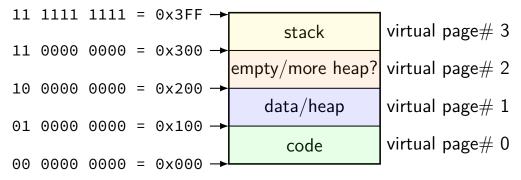
## scheduling note on paging/protection

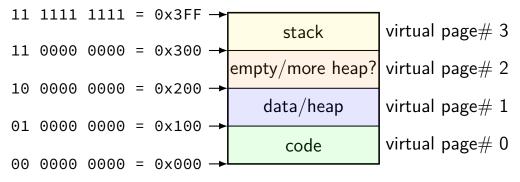
not sure if we'll get to enough for next assignment by Thursday may adjust deadlines for that (and future assignments)

### address translation

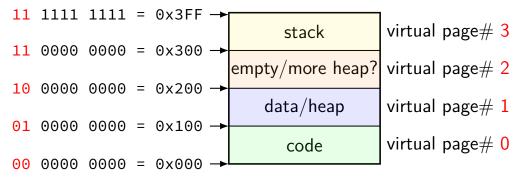




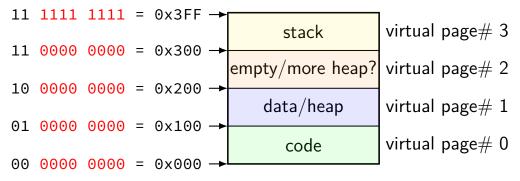




divide memory into pages ( $2^8$  bytes in this case) "virtual" = addresses the program sees



page number is upper bits of address (because page size is power of two)



rest of address is called page offset

#### real memory

#### physical addresses

111	0000	0000	to
111	1111	1111	
001	0000	0000	to
001	1111	1111	
000	0000	0000	to
000	1111	1111	

# program memory virtual addresses

11	0000	0000	to
11	1111	1111	
10	0000	0000	to
10	1111	1111	
01	0000	0000	to
01	1111	1111	
00	0000	0000	to
00	1111	1111	

program memory			
virtual addresses			
11	0000	0000	to
11	1111	1111	
10	0000	0000	to
10	1111	1111	
01	0000	0000	to
01	1111	1111	

00 0000 0000 to

1111 1111

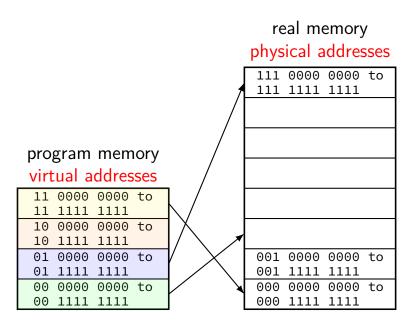
00

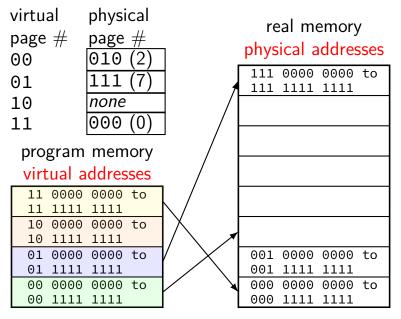
.........

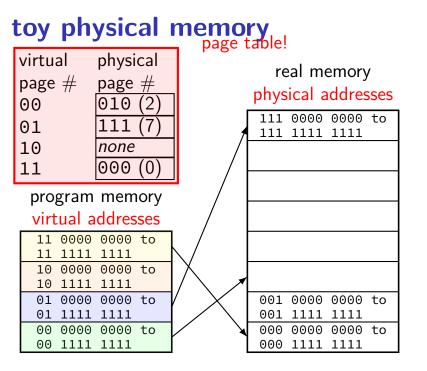
----

rear memory	
physical addresses	
111 0000 0000 to 111 1111 1111	physical page 7
001 0000 0000 to 001 1111 1111	physical page 1
000 0000 0000 to 000 1111 1111	physical page 0

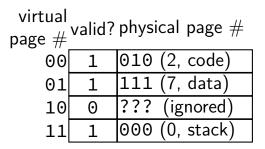
real memory

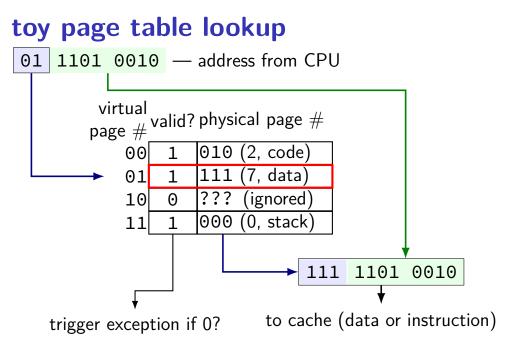


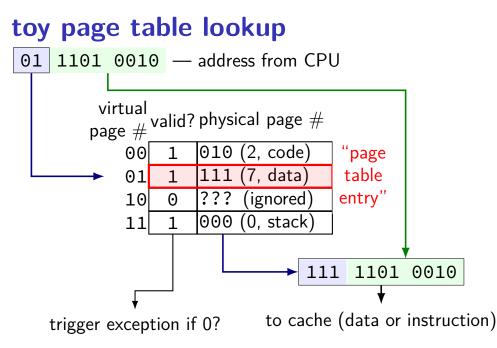


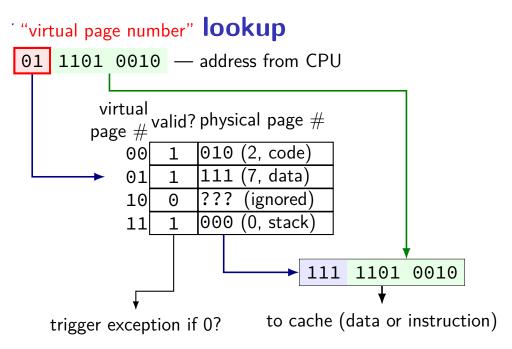


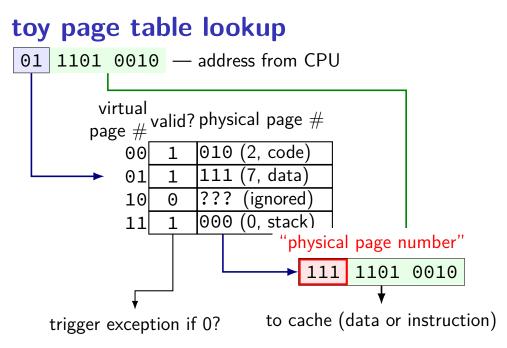
### toy page table lookup

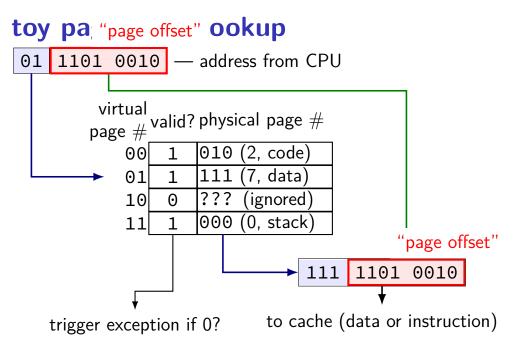












## x86-32: VPN and PO

32-bit x86: 4096 byte ( $2^{12}$  byte) pages

given virtual address 0xABCD0123

virtual page number = \_\_\_\_\_

page offset = \_\_\_\_\_

if that virtual page maps to physical page 0x998

physical address = \_\_\_\_\_

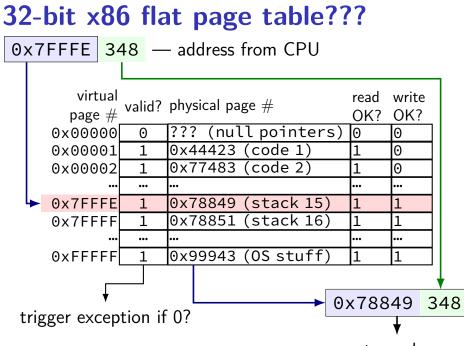
## x86-32: VPN and PO (solution)

- 32-bit x86: 4096 byte ( $2^{12}$  byte) pages
- given virtual address 0xABCD0123
- virtual page number = 0xABCD0

```
page offset = 0x123
```

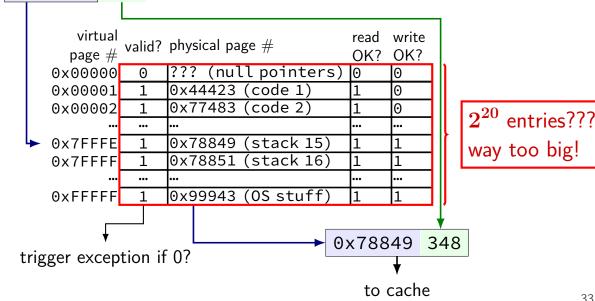
if that virtual page maps to physical page 0x998

```
physical address = 0x998123
```



## 32-bit x86 flat page table???

0x7FFFE 348 — address from CPU

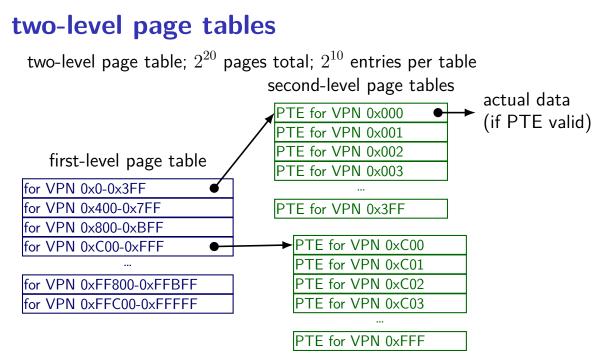


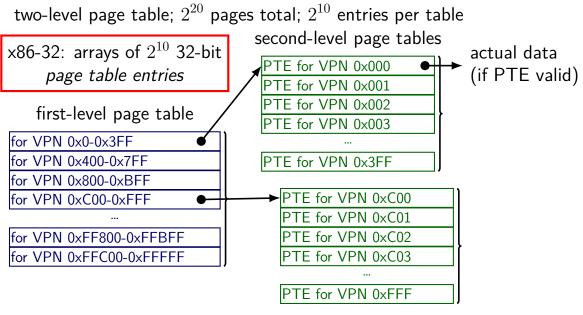
## storing huge page table?

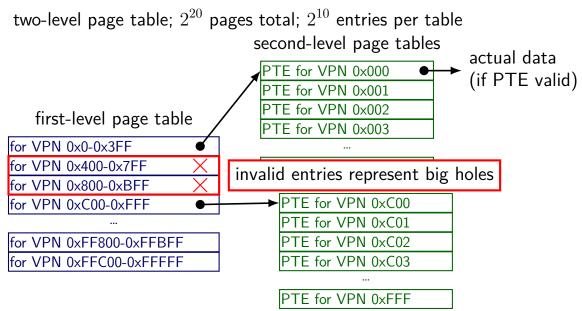
keep it in memory

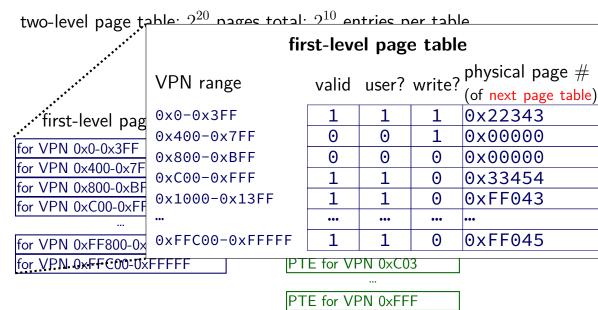
add special cache for page table entries to handle memory being slow special cached called translation lookaside buffer (TLB)

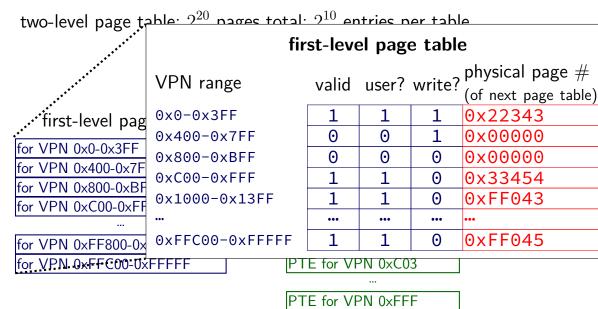
use a tree and don't store most invalid page table entries take advantage of large contiguous invalid regions (between stack and heap, most high memory addresses, etc.)

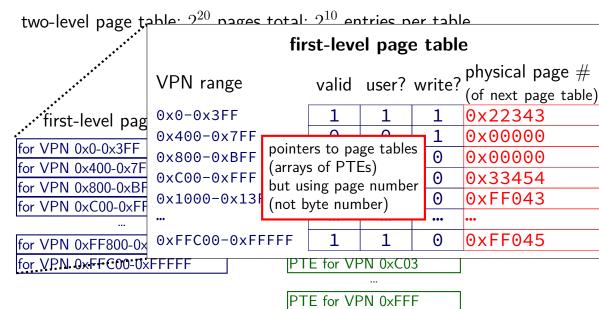


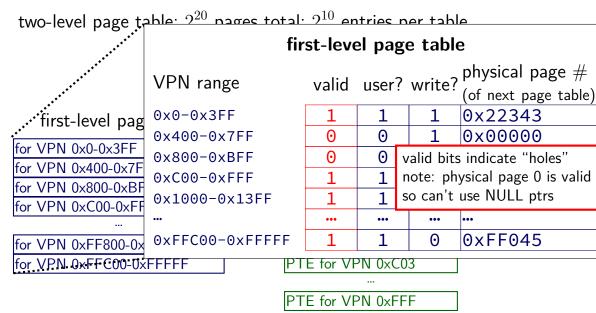


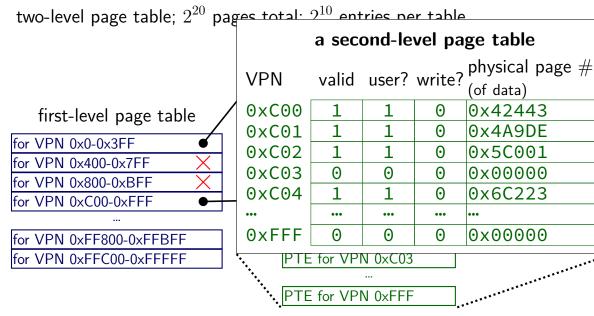


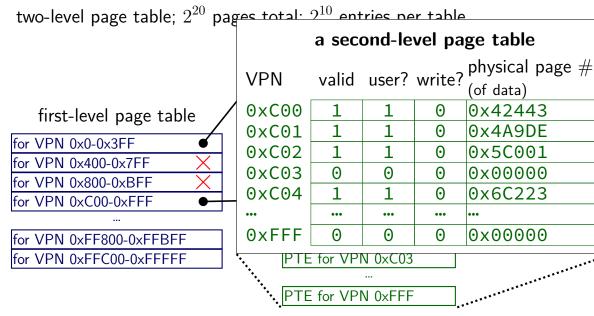












### two-level page table naming

- what the page table base register points to:
- first-level page table
- top-level page table
- page directory (Intel's term, used in xv6 code)

- what first-level page table entries point to
- second-level page table
- page table (Intel's term, used in xv6 code) I'll avoid using this term unqualified... but Intel manuals/xv6 do not

## 32-bit x86 paging

- 4096 (=  $2^{12}$ ) byte pages
- 4-byte page table entries stored in memory
- two-level table:
  - first 10 bits lookup in first level ("page directory") second 10 bits lookup in second level
- remaining 12 bits: which byte of 4096 in page?

## 32-bit x86 paging (in xv6)

xv6 header: mmu.h

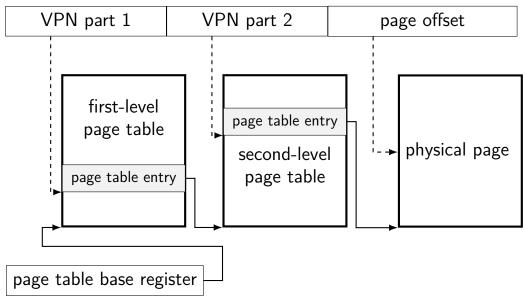
// A virtual address 'va' has a three-part structure as follows:
//
// +----10-----12-----+
// | Page Directory | Page Table | Offset within Page |
// | Index | Index |
// +-----+
// \--- PDX(va) --/ \--- PTX(va) --/

// page directory index
#define PDX(va) (((uint)(va) >> PDXSHIFT) & 0x3FF)

// page table index
#define PTX(va) (((uint)(va) >> PTXSHIFT) & 0x3FF)

// construct virtual address from indexes and offset
#define PGADDR(d, t, o) ((uint)((d) << PDXSHIFT | (t) << PTXSHIFT |</pre>

#### another view



# exercise (1)

- 4096 (=  $2^{12}$ ) byte pages
- 4-byte page table entries stored in memory

two-level table:

first 10 bits lookup in first level ("page directory") second 10 bits lookup in second level

exercise:

virtual address 0x12345678 base pointer 0x1000 (byte address) first-level PTE *contents*: PPN 0x14; second-level PTE: PPN 0x15

address of 1st-level PTE? of second-level PTE?

# exercise (2)

- 4096 (=  $2^{12}$ ) byte pages
- 4-byte page table entries stored in memory

two-level table:

first 10 bits lookup in first level ("page directory") second 10 bits lookup in second level

exercise: how big is...

a process's x86-32 page tables with 1 valid 4K page? a process's x86-32 page tables with all 4K pages populated?

# exercise (2)

- 4096 (=  $2^{12}$ ) byte pages
- 4-byte page table entries stored in memory

two-level table:

first 10 bits lookup in first level ("page directory") second 10 bits lookup in second level

exercise: how big is...

a process's x86-32 page tables with 1 valid 4K page? 2 pages (1 first-level, 1 second) a process's x86-32 page tables with all 4K pages populated?

# exercise (2)

- 4096 (=  $2^{12}$ ) byte pages
- 4-byte page table entries stored in memory

two-level table:

first 10 bits lookup in first level ("page directory") second 10 bits lookup in second level

exercise: how big is...

a process's x86-32 page tables with 1 valid 4K page? 2 pages (1 first-level, 1 second) a process's x86-32 page tables with all 4K pages populated? 1025 pages (1 first-level, 1024 second)

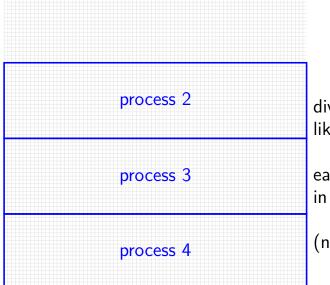
### backup slides

### message passing API

core functions: Send(told, data)/Recv(fromId, data)

simplest(?) version: functions wait for other processes/threads

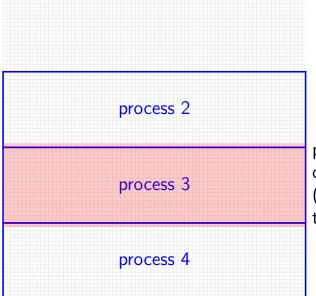
```
if (thread_id == 0) {
    for (int i = 1; i < MAX_THREAD; ++i) {</pre>
        Send(i, getWorkForThread(i));
    }
    for (int i = 1; i < MAX_THREAD; ++i) {</pre>
        WorkResult result;
        Recv(i, &result);
        handleResultForThread(i, result);
    }
} else {
    WorkInfo work;
    Recv(0, &work);
    Send(0, ComputeResultFor(work));
```



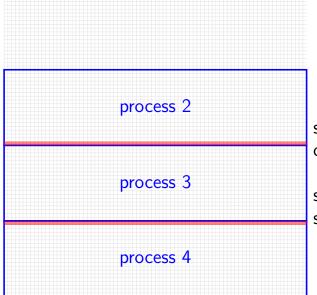
divide grid like you would for normal threads

each process stores cells in that part of grid

(no shared memory!)

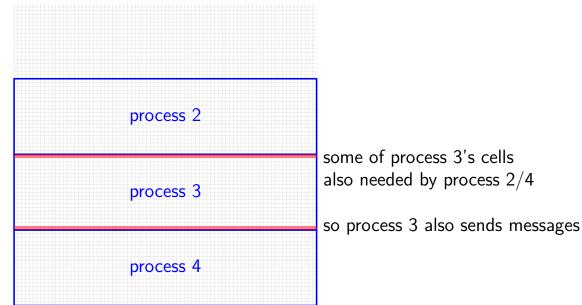


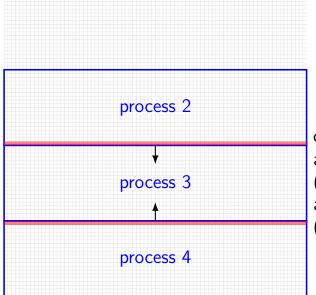
process 3 only needs values of cells around its area (values of cells adjacent to the ones it computes)



small slivers of other process's cells needed

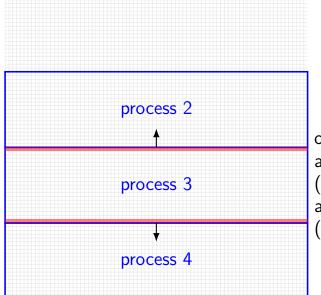
solution: process 2, 4 send messages with cells every iterat





one possible pseudocode: all even processes send messages (while odd receives), then all odd processes send messages (while even receives)

# message passing game of life



one possible pseudocode: all even processes send messages (while odd receives), then all odd processes send messages (while even receives)

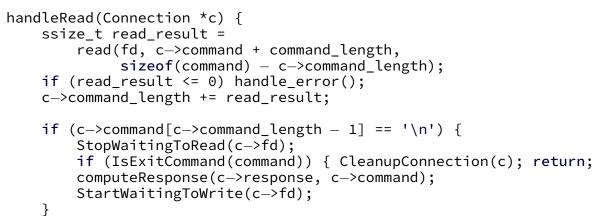
# some single-threaded processing code

```
void ProcessRequest(int fd) {
  while (true) {
    char command [1024] = \{\};
    size_t command_length = 0;
    do {
      ssize_t read_result =
          read(fd, command + command_length,
               sizeof(command) - command_length);
      if (read_result <= 0) handle_error();</pre>
      command length += read result:
    } while (command command length -1] != '\n');
    if (IsExitCommand(command)) { return; }
    char response[1024];
    computeResponse(response, commmand);
    size t total written = 0;
    while (total written < sizeof(response)) {</pre>
    }
```

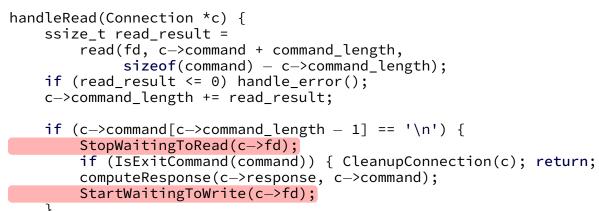
```
some single-threaded processing code
        original code: loop to handle one request
void Pro
        reads/writes multiple times; each read/write can block
  while
    char commana[1024] = {};
    size t command length = 0;
    do {
      ssize_t read_result =
          read(fd, command + command_length,
               sizeof(command) - command_length);
      if (read_result <= 0) handle_error();</pre>
      command length += read result:
    } while (command[command_length - 1] != '\n');
    if (IsExitCommand(command)) { return; }
    char response[1024];
    computeResponse(response, command);
    size_t total_written = 0;
    while (total written < sizeof(response)) {</pre>
```

# some single-threaded processing code

```
struct Connection {
void ProcessRequest(int fd) {
                                          int fd;
  while (true) {
                                          char command[1024];
    char command [1024] = \{\};
                                          size_t command_length;
    size_t command_length = 0;
    do {
                                          char response[1024];
      ssize_t read_result =
                                          size_t total_written;
          read(fd, command + command_
               sizeof(command) - comma };
      if (read_result <= 0) handle err</pre>
      command_length += read_result;
    } while (command [command length -1] != '\n');
    if (IsExitCommand(command)) { return; }
    char response[1024];
    computeResponse(response, commmand);
    size t total written = 0;
    while (total_written < sizeof(response)) {</pre>
```



new code: one read step per handleRead call Connection struct: info between write calls



```
handleRead(Connection *c) {
    ssize_t read_result =
        read(fd, c->command + command_length,
            sizeof(command) - c->command_length);
    if (read_result <= 0) handle_error();
    c->command_length += read_result;
```

```
if (c->command[c->command_length - 1] == '\n') {
   StopWaitingToRead(c->fd);
   if (IsExitCommand(command)) { CleanupConnection(c); return;
   computeResponse(c->response, c->command);
   StartWaitingToWrite(c->fd);
}
```

```
handleRead(Connection *c) {
    ssize_t read_result =
        read(fd, c->command + command_length,
            sizeof(command) - c->command_length);
    if (read_result <= 0) handle_error();
    c->command_length += read_result;
```

```
if (c->command[c->command_length - 1] == '\n') {
   StopWaitingToRead(c->fd);
   if (IsExitCommand(command)) { CleanupConnection(c); return;
   computeResponse(c->response, c->command);
   StartWaitingToWrite(c->fd);
}
```

```
handleRead(Connection *c) {
  ssize_t read_result =
     read(fd, c->command + command_length,
         sizeof(command) - c->command_length);
  if (read_result <= 0) handle_error();
  c->command_length += read_result;
  if (c->command[c->command_length - 1] == '\n') {
    StopWaitingToRead(c->fd);
    if (IsExitCommand(command)) { CleanupConnection(c); return; }
    computeResponse(c->response, c->command);
    StartWaitingToWrite(c->fd);
  }
```

```
handleRead(Connection *c) {
  ssize_t read_result =
      read(fd, c->command + command_length,
           sizeof(command) - c->command_length);
  if (read_result <= 0) handle_error();</pre>
 c->command_length += read_result;
  if (c->command[c->command_length - 1] == '\n') {
    StopWaitingToRead(c->fd);
    if (IsExitCommand(command)) { CleanupConnection(c); return; }
    computeResponse(c->response, c->command):
    StartWaitingToWrite(c->fd);
                                     . . .
                                    do {
                                       ssize_t read_result =
                                            read(fd, command + command_length,
                                                 sizeof(command) - command length);
                                        if (read_result <= 0) handle_error();</pre>
                                       command_length += read_result;
                                    } while (command[command_length - 1] != '\n');
                                    if (IsExitCommand(command)) { return; }
                                    computeResponse(response, command);
                                     ... // write response
```

```
handleRead(Connection *c) {
  ssize_t read_result =
      read(fd, c->command + command_length,
           sizeof(command) - c->command_length);
 if (read_result <= 0) handle_error();</pre>
 c->command_length += read_result;
  if (c->command[c->command_length - 1] == '\n') {
    StopWaitingToRead(c->fd);
    if (IsExitCommand(command)) { CleanupConnection(c); return; }
    computeResponse(c->response, c->command):
    StartWaitingToWrite(c->fd);
                                     . . .
                                    do {
                                       ssize_t read_result =
                                            read(fd, command + command_length,
                                                 sizeof(command) - command length);
                                       if (read result <= 0) handle_error();</pre>
                                       command_length += read_result;
                                    } while (command[command_length - 1] != '\n');
                                    if (IsExitCommand(command)) { return; }
                                    computeResponse(response, command);
                                    ... // write response
```

```
handleRead(Connection *c) {
  ssize_t read_result =
      read(fd, c->command + command_length,
           sizeof(command) - c->command_length);
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 c->command_length += read_result;
 if (c->command[c->command_length - 1] == '\n') {
    StopWaitingToRead(c->fd);
    if (IsExitCommand(command)) { CleanupConnection(c); return; }
    computeResponse(c->response, c->command):
    StartWaitingToWrite(c->fd);
                                     . . .
                                    do {
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                                    } while (command[command_length - 1] != '\n');
                                     if (IsExitCommand(command)) { return; }
                                    computeResponse(response, commmand);
                                     ... // write response
```

# deadlock with free space

#### Thread 1

AllocateOrWaitFor(1 MB) AllocateOrWaitFor(1 MB)

(do calculation)

Free(1 MB)

Free(1 MB)

#### Thread 2

AllocateOrWaitFor(1 MB) AllocateOrWaitFor(1 MB) (do calculation) Free(1 MB) Free(1 MB)

2 MB of space — deadlock possible with unlucky order

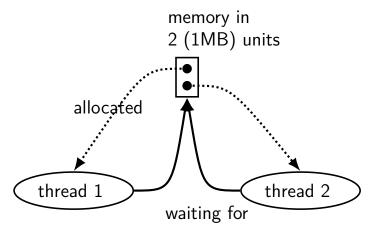
#### deadlock with free space (unlucky case) Thread 1 Thread 2 AllocateOrWaitFor(1 MB)

AllocateOrWaitFor(1 MB)

AllocateOrWaitFor(1 MB... stalled

AllocateOrWaitFor(1 MB... stalled

# free space: dependency graph



# deadlock with free space (lucky case) Thread 1 AllocateOrWaitFor(1 MB) AllocateOrWaitFor(1 MB)

(do calculation)

Free(1 MB);
Free(1 MB);

AllocateOrWaitFor(1 MB)
AllocateOrWaitFor(1 MB)
(do calculation)
Free(1 MB);
Free(1 MB);

# **AllocateOrFail**

**Thread 1** AllocateOrFail(1 MB)

AllocateOrFail(1 MB) fails!

Free(1 MB) (cleanup after failure)

#### Thread 2

AllocateOrFail(1 MB)

AllocateOrFail(1 MB) fails!

Free(1 MB) (cleanup after failure)

okay, now what? give up? both try again? — maybe this will keep happening? (called livelock) try one-at-a-time? — gaurenteed to work, but tricky to implement

# **AllocateOrSteal**

**Thread 1** AllocateOrSteal(1 MB)

#### Thread 2

AllocateOrSteal(1 MB) Thread killed to free 1MB

AllocateOrSteal(1 MB) (do work)

problem: can one actually implement this?

problem: can one kill thread and keep system in consistent state?

# fail/steal with locks

pthreads provides pthread\_mutex\_trylock — "lock or fail"

some databases implement *revocable locks* 

do equivalent of throwing exception in thread to 'steal' lock need to carefully arrange for operation to be cleaned up

# stealing locks???

how do we make stealing locks possible

unclean: just kill the thread problem: inconsistent state?

clean: have code to undo partial oepration some databases do this

won't go into detail in this class

# revokable locks?

```
try {
    AcquireLock();
    use shared data
} catch (LockRevokedException le) {
    undo operation hopefully?
} finally {
    ReleaseLock();
```

# }

# deadlock prevention techniques

#### infinite resources

or at least enough that never run out

no mutual exclusion

no shared resources

no mutual exclusion

#### **no waiting** "busy signal" — abort and (maybe) retry revoke/preempt resources no hold and wait/ preemption

acquire resources in consistent order

no circular wait

request all resources at once

no hold and wait

# abort and retry limits?

abort-and-retry

how many times will you retry?

# moving two files: abort-and-retry

```
struct Dir {
  mutex t lock; map<string, DirEntry> entries;
};
void MoveFile(Dir *from_dir, Dir *to_dir, string filename) {
 while (true) {
    mutex lock(&from dir->lock);
    if (mutex_trylock(&to_dir->lock) == LOCKED) break;
    mutex unlock(&from dir->lock);
  }
  to dir->entries[filename] = from dir->entries[filename];
  from dir->entries.erase(filename);
  mutex unlock(&to dir->lock);
  mutex unlock(&from dir->lock);
}
Thread 1: MoveFile(A, B, "foo")
Thread 2: MoveFile(B, A, "bar")
```

moving two files: lots of bad luck?	
Thread 1	Thread 2
<pre>MoveFile(A, B, "foo")</pre>	MoveFile(B, A, "bar")
$lock(\&A->lock) \rightarrow LOCKED$	
	lock(&B->lock) $ ightarrow$ LOCKED
$\texttt{trylock(\&B->lock)} \rightarrow \texttt{FAILED}$	
	<code>trylock(&amp;A-&gt;lock) <math> ightarrow</math> FAILED</code>
unlock(&A->lock)	
	unlock(&B->lock)
lock(&A->lock) $ ightarrow$ LOCKED	
	$lock(\&B->lock) \to LOCKED$
${\tt trylock(\&B->lock)}  ightarrow {\tt FAILED}$	
	<code>trylock(&amp;A-&gt;lock) <math> ightarrow</math> FAILED</code>
unlock(&A->lock)	
	unlock(&B->lock)

# livelock

livelock: keep aborting and retrying without end

like deadlock — no one's making progress potentially forever

unlike deadlock — threads are not waiting

# preventing livelock

make schedule random — e.g. random waiting after abort

make threads run one-at-a-time if lots of aborting

other ideas?

# deadlock detection

idea: search for cyclic dependencies

# detecting deadlocks on locks

let's say I want to detect deadlocks that only involve mutexes goal: help programmers debug deadlocks

```
...by modifying my threading library:
```

```
struct Thread {
    ... /* stuff for implementing thread */
    /* what extra fields go here? */
```

```
};
```

```
struct Mutex {
    ... /* stuff for implementing mutex */
    /* what extra fields go here? */
```

# deadlock detection

idea: search for cyclic dependencies

need:

list of all contended resources what thread is waiting for what? what thread 'owns' what?

## aside: divisible resources

deadlock is possible with divisibe resources like memory,...

example: suppose 6MB of RAM for threads total: thread 1 has 2MB allocated, waiting for 2MB thread 2 has 2MB allocated, waiting for 2MB thread 3 has 1MB allocated, waiting for keypress

cycle: thread 1 waiting on memory owned by thread 2?

not a deadlock — thread 3 can still finish and after it does, thread 1 or 2 can finish

# aside: divisible resources

deadlock is possible with divislbe resources like memory,...

example: suppose 6MB of RAM for threads total: thread 1 has 2MB allocated, waiting for 2MB thread 2 has 2MB allocated, waiting for 2MB thread 3 has 1MB allocated, waiting for keypress

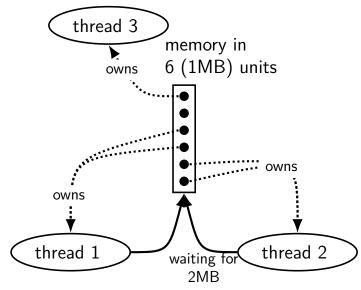
cycle: thread 1 waiting on memory owned by thread 2?

not a deadlock — thread 3 can still finish and after it does, thread 1 or 2 can finish

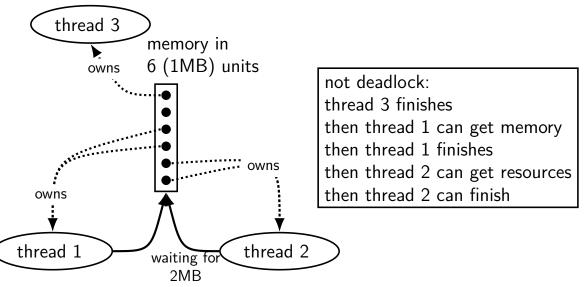
...but would be deadlock

...if thread 3 waiting lock held by thread 1 ...with 5MB of RAM

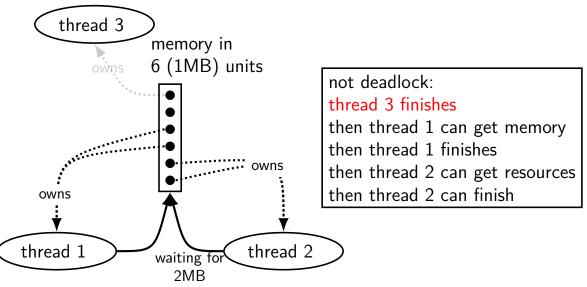
#### divisible resources: not deadlock

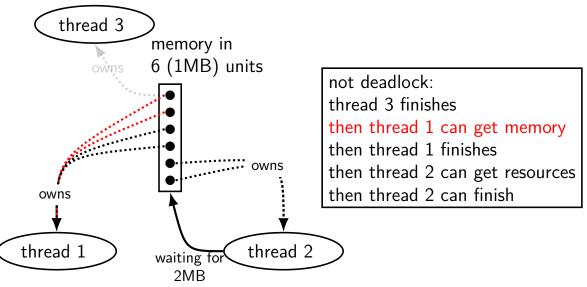


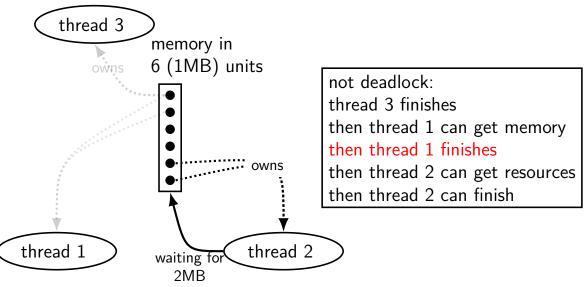
# divisible resources: not deadlock

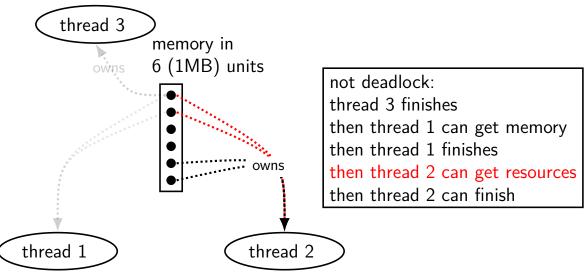


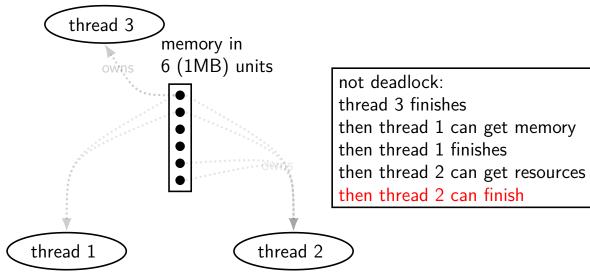
# divisible resources: not deadlock

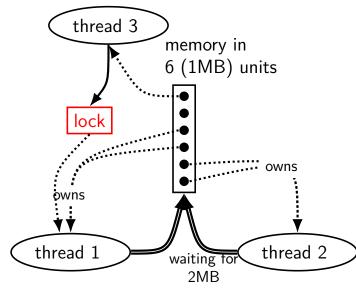


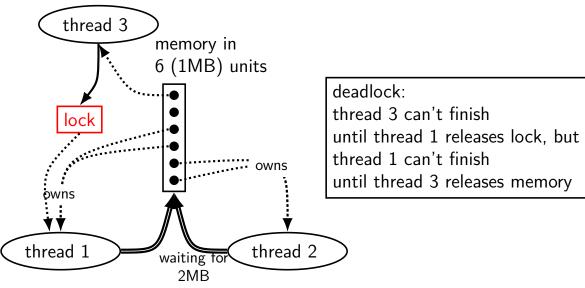


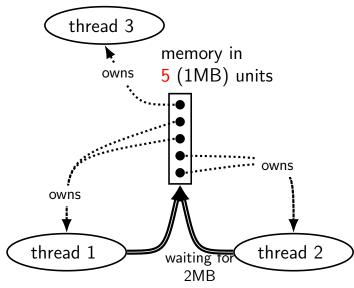


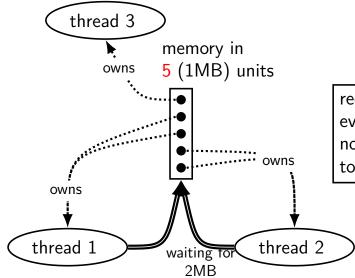


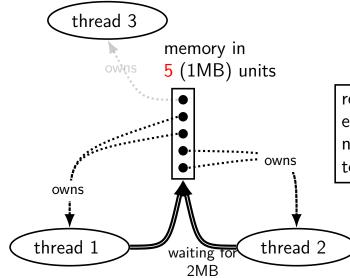


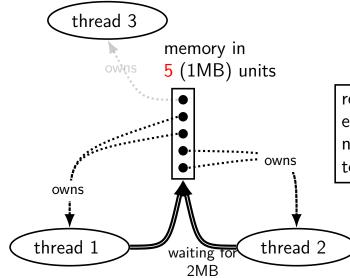


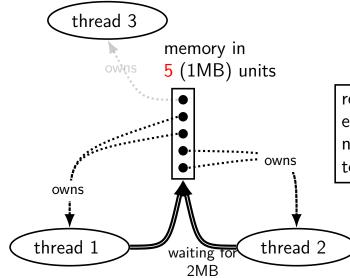


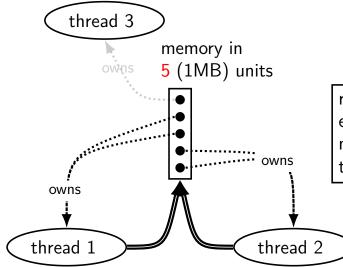












### deadlock detection with divisibe resources

can't rely on cycles in graphs in this case

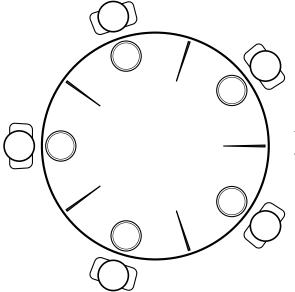
alternate algorithm exists

similar technique to how we showed no deadlock

high-level intuition: simulate what could happen find threads that could finish based on resources available now

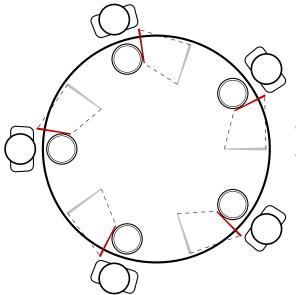
full details: look up Baker's algorithm

# dining philosophers



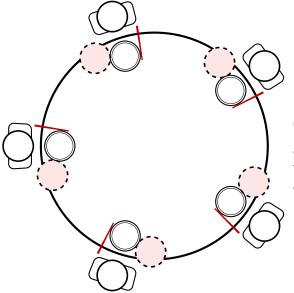
five philosophers either think or eat to eat, grab chopsticks on either side

# dining philosophers



everyone eats at the same time? grab left chopstick, then...

dining philosophers



everyone eats at the same time? grab left chopstick, then try to grab right chopstick, ... we're at an impasse

# skipping the guard page

```
void example() {
    int array[2000];
    array[0] = 1000;
}
example:
    subl $8024, %esp // allocate 8024 bytes on stack
            $1000, 12(%esp) // write near bottom of allocation
    movl
        // goes beyond guard page
        // since not all of array init'd
```

```
pde t*
setupkvm(void)
{
  pde_t *pgdir;
  struct kmap *k;
  if((pgdir = (pde_t*)kalloc()) == 0)
    return 0;
  memset(pgdir, 0, PGSIZE);
  if (P2V(PHYSTOP) > (void*)DEVSPACE)
    panic("PHYSTOP too high");
  for(k = kmap; k < &kmap[NELEM(kmap)]; k++)</pre>
    if (mappages(pgdir, k->virt, k->phys end - k->phys start,
                  (uint)k \rightarrow phys start, k \rightarrow perm) < 0) {
      freevm(pgdir);
      return 0;
  return pgdir;
```

```
allocate first-level page table
("page directory")
```

```
pde t*
setupkvm(void)
  pde_t *pgdir;
  struct kmap *k;
  if((pgdir = (pde_t*)kalloc()) == 0)
    return 0;
  memset(pgdir, 0, PGSIZE);
  if (P2V(PHYSTOP) > (void*)DEVSPACE)
    panic("PHYSTOP too high");
  for(k = kmap; k < &kmap[NELEM(kmap)]; k++)</pre>
    if (mappages(pgdir, k->virt, k->phys end - k->phys start,
                  (uint)k \rightarrow phys start, k \rightarrow perm) < 0) {
      freevm(pgdir);
      return 0;
  return pgdir;
```

```
initialize to 0 — every page invalid
```

```
pde t*
setupkvm(void)
  pde_t *pgdir;
  struct kmap *k;
  if((pgdir = (pde_t*)kalloc()) == 0)
    return 0;
  memset(pgdir, 0, PGSIZE);
  if (P2V(PHYSTOP) > (void*)DEVSPACE)
    panic("PHYSTOP too high");
  for(k = kmap; k < &kmap[NELEM(kmap)]; k++)</pre>
    if (mappages(pgdir, k->virt, k->phys end - k->phys start,
                  (uint)k \rightarrow phys start, k \rightarrow perm) < 0) {
      freevm(pgdir);
      return 0;
  return pgdir;
```

```
iterate through list of kernel-space mappings
pde t*
                        for everything above address 0x8000 0000
setupkvm(void)
                        (hard-coded table including flag bits, etc.
  pde_t *pgdir;
                        because some addresses need different flags
  struct kmap *k;
                        and not all physical addresses are usable)
  if((pgdir = (pde_t*
    return 0;
  memset(pgdir, 0, PGSIZE);
  if (P2V(PHYSTOP) > (void*)DEVSPACE)
    panic("PHYSTOP too high");
  for(k = kmap; k < &kmap[NELEM(kmap)]; k++)</pre>
    if (mappages(pgdir, k->virt, k->phys end - k->phys start,
                  (uint)k \rightarrow phys start, k \rightarrow perm) < 0) {
      freevm(pgdir);
      return 0;
  return pgdir;
```

```
create new page table (kernel mappings)
                 on failure (no space for new second-level page tales)
pde t*
setupkvm(void) | free everything
  pde_t *pgdir;
  struct kmap *k;
  if((pgdir = (pde_t*)kalloc()) == 0)
    return 0;
  memset(pgdir, 0, PGSIZE);
  if (P2V(PHYSTOP) > (void*)DEVSPACE)
    panic("PHYSTOP too high");
  for(k = kmap; k < &kmap[NELEM(kmap)]; k++)</pre>
    if (mappages(pgdir, k->virt, k->phys end - k->phys start,
                 (uint)k \rightarrow phys start, k \rightarrow perm) < 0) {
      freevm(pgdir);
      return 0;
  return pgdir;
```

# reading executables (headers)

xv6 executables contain list of sections to load, represented by:

struct proghdr { uint type; uint flags; uint align; };

/\* <-- debugging-only or not? \*/ uint off; /\* <-- location in file \*/</pre> uint filesz; /\* <-- amount to load \*/</pre> /\* <-- readable/writeable (ignored) \*/

# reading executables (headers)

. . .

xv6 executables contain list of sections to load, represented by:

if((sz = allocuvm(pgdir, sz, ph.vaddr + ph.memsz)) == 0)
goto bad;

if(loaduvm(pgdir, (char\*)ph.vaddr, ip, ph.off, ph.filesz) < 0)
goto bad;</pre>

# reading executables (headers)

xv6 executables contain list of sections to load, represented by:

struct proghdr { sz — top of heap of new program uint type; name of the field in struct proc uint off; uint vaddr: /\* <-- location in memory \*/ uint paddr; /\* <-- confusing ignored field \*/
uint filesz; /\* <-- amount to load \*/</pre> /\* <-- readable/writeable (ignored) \*/ uint flags; uint align; }; if((sz = allocuvm(pgdir, sz, ph.vaddr + ph.memsz)) == 0) goto bad; . . . if(loaduvm(pgdir, (char\*)ph.vaddr, ip, ph.off, ph.filesz) < 0) goto bad;

```
loaduvm(pde_t *pgdir, char *addr, struct inode *ip, uint offset, uin
ł
  . . .
  for(i = 0; i < sz; i += PGSIZE){</pre>
    if((pte = walkpgdir(pgdir, addr+i, 0)) == 0)
      panic("loaduvm: address should exist");
    pa = PTE ADDR(*pte);
    if(sz - i < PGSIZE)</pre>
      n = sz - i:
    else
      n = PGSIZE:
    if(readi(ip, P2V(pa), offset+i, n) != n)
      return -1;
  }
  return 0;
```

```
get page table entry being loaded
loaduvm(pde_t *pgdir, char *addr
                                                                        uir
                                    already allocated earlier
                                    look up address to load into
  . . .
  for(i = 0; i < sz; i += PGSIZE____</pre>
    if((pte = walkpgdir(pgdir, addr+i, 0)) == 0)
      panic("loaduvm: address should exist");
    pa = PTE ADDR(*pte);
    if(sz - i < PGSIZE)</pre>
      n = sz - i:
    else
      n = PGSIZE:
    if(readi(ip, P2V(pa), offset+i, n) != n)
      return -1;
  return 0;
```

```
loaduvm(pde_t *pgdir, ch
{
    get physical address from page table entry
    convert back to (kernel) virtual address
                                                                                  uiı
                              for read from disk
   . . .
  for(i = 0; i < sz; i + - PUSIZE)</pre>
     if((pte = walkpgdir(pgdir, addr+i, 0)) == 0)
       panic("loaduvm: address should exist");
     pa = PTE ADDR(*pte);
     if(sz - i < PGSIZE)</pre>
       n = sz - i;
     else
       n = PGSIZE:
     if(readi(ip, P2V(pa), offset+i, n) != n)
       return -1;
  return 0;
```

# 

return 0;

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```
\begin{array}{c} \begin{array}{c} \text{copy from file (represented by struct inode) into memory} \\ 1 \end{array} \\ \begin{array}{c} \text{P2V(pa)} & - \text{mapping of physical addresss in kernel memory} \end{array} \end{array}
```

```
. .
for(i = 0; i < sz; i += PGSIZE){</pre>
  if((pte = walkpgdir(pgdir, addr+i, 0)) == 0)
    panic("loaduvm: address should exist");
 pa = PTE ADDR(*pte);
  if(sz - i < PGSIZE)</pre>
    n = sz - i:
 else
    n = PGSIZE;
  if(readi(ip, P2V(pa), offset+i, n) != n)
    return -1;
return 0;
```

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