POSIX process API

last time

kernel part of context switch

- save all registers; restore all registers
- trick: function calls save some registers automatically

user registers: save/restore on mode switch

- part of exception handling (even if no context switch)

thread + process control blocks

[3:30pm] myproc() as processor-local "variable"

process control block

some data structure needed to represent a process

called Process Control Block

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called Process Control Block

xv6: `struct proc`

xv6: struct proc

```
struct proc {
  uint sz;                     // Size of process memory (bytes)
  pde_t* pgdir;                // Page table
  char *kstack;                // Bottom of kernel stack for this process
  enum procstate state;        // Process state
  int pid;                     // Process ID
  struct proc *parent;         // Parent process
  struct trapframe *tf;        // Trap frame for current syscall
  struct context *context;     // swtch() here to run process
  void *chan;                  // If non-zero, sleeping on chan
  int killed;                  // If non-zero, have been killed
  struct file *ofile[NOFILE];  // Open files
  struct inode *cwd;           // Current directory
  char name[16];               // Process name (debugging)
};
```

xv6: struct proc

pointers to current registers/PC of process (user and kernel) stored on its kernel stack
(if not currently running)

≈ thread's state

```
struct proc
  uint sz;
  pde_t* pg
  char *kst                                                    ss
  enum proc
  int pid;                      // Process ID
  struct proc *parent;          // Parent process
  struct trapframe *tf;         // Trap frame for current syscall
  struct context *context;      // swtch() here to run process
  void *chan;                   // If non-zero, sleeping on chan
  int killed;                   // If non-zero, have been killed
  struct file *ofile[NOFILE];   // Open files
  struct inode *cwd;            // Current directory
  char name[16];                // Process name (debugging)
};
```

xv6: struct proc

the kernel stack for this process
every process has one kernel stack

```
struct proc {
  uint sz;                     // Size of process memory (bytes)
  pde_t* pgdir;                // Page table
  char *kstack;                // Bottom of kernel stack for this process
  enum procstate state;        // Process state
  int pid;                     // Process ID
  struct proc *parent;         // Parent process
  struct trapframe *tf;        // Trap frame for current syscall
  struct context *context;     // swtch() here to run process
  void *chan;                  // If non-zero, sleeping on chan
  int killed;                  // If non-zero, have been killed
  struct file *ofile[NOFILE];  // Open files
  struct inode *cwd;           // Current directory
  char name[16];               // Process name (debugging)
};
```

xv6: struct proc

```
enum procstate {
    UNUSED, EMBRYO, SLEEPING,
    RUNNABLE, RUNNING, ZOMBIE };
```

```
struct proc
  uint sz;
  pde_t* pg
  char *kst
  enum procstate state;          // Process st
  int pid;                       // Process ID
  struct proc *parent;           // Parent process
  struct trapframe *tf;          // Trap frame for current syscall
  struct context *context;       // swtch() here to run process
  void *chan;                    // If non-zero, sleeping on chan
  int killed;                    // If non-zero, have been killed
  struct file *ofile[NOFILE];    // Open files
  struct inode *cwd;             // Current directory
  char name[16];                 // Process name (debugging)
};
```

is process running?
or waiting?
or finished?
if waiting,
waiting for what (chan)?

xv6: struct proc

process ID
to identify process in system calls

```
struct proc {
  uint sz;                     // Size of process memory (bytes)
  pde_t* pgdir;                // Page table
  char *kstack;                // Bottom of kernel stack for this process
  enum procstate state;        // Process state
  int pid;                     // Process ID
  struct proc *parent;         // Parent process
  struct trapframe *tf;        // Trap frame for current syscall
  struct context *context;     // swtch() here to run process
  void *chan;                  // If non-zero, sleeping on chan
  int killed;                  // If non-zero, have been killed
  struct file *ofile[NOFILE];  // Open files
  struct inode *cwd;           // Current directory
  char name[16];               // Process name (debugging)
};
```

xv6: struct proc

```
struct proc {
  uint sz;                     // Size of process memory (bytes)
  pde_t* pgdir;                // Page table
  char *kstack;                // Bottom of kernel stack for this process
  enum procstate state;        // Process state
  int pid;                     // Proc
  struct proc *parent;         // Pare
  struct trapframe *tf;        // Trap
  struct context *context;     // swtc
  void *chan;                  // If n
  int killed;                  // If non-zero, have been killed
  struct file *ofile[NOFILE];  // Open files
  struct inode *cwd;           // Current directory
  char name[16];               // Process name (debugging)
};
```

information about address space

pgdir — used by processor

sz — used by OS only

xv6: struct proc

information about open files, etc.

```
struct proc {
  uint sz;                     // Size of process memory (bytes)
  pde_t* pgdir;                // Page table
  char *kstack;                // Bottom of kernel stack for this process
  enum procstate state;        // Process state
  int pid;                     // Process ID
  struct proc *parent;         // Parent process
  struct trapframe *tf;        // Trap frame for current syscall
  struct context *context;     // swtch() here to run process
  void *chan;                  // If non-zero, sleeping on chan
  int killed;                  // If non-zero, have been killed
  struct file *ofile[NOFILE];  // Open files
  struct inode *cwd;           // Current directory
  char name[16];               // Process name (debugging)
};
```

process control blocks generally

contains process's context(s) (registers, PC, ...)

- if context is not on a CPU
- (in xv6: pointers to these, actual location: process's kernel stack)

process's status — running, waiting, etc.

information for system calls, etc.

- open files
- memory allocations
- process IDs
- related processes

xv6 myproc

xv6 function: `myproc()`

retrieves pointer to currently running `struct proc`

myproc: using a global variable

```
struct cpu cpus[NCPU];
```

```
struct proc*
myproc(void) {
  struct cpu *c;
  ...
  c = mycpu();    /* finds entry of cpus array
                     using special "ID" register
                     as array index */
  p = c->proc;
  ...
  return p;
}
```

this class: focus on Unix

Unix-like OSes will be our focus

we have source code

used to from 2150, etc.?

have been around for a while

xv6 imitates Unix

Unix history

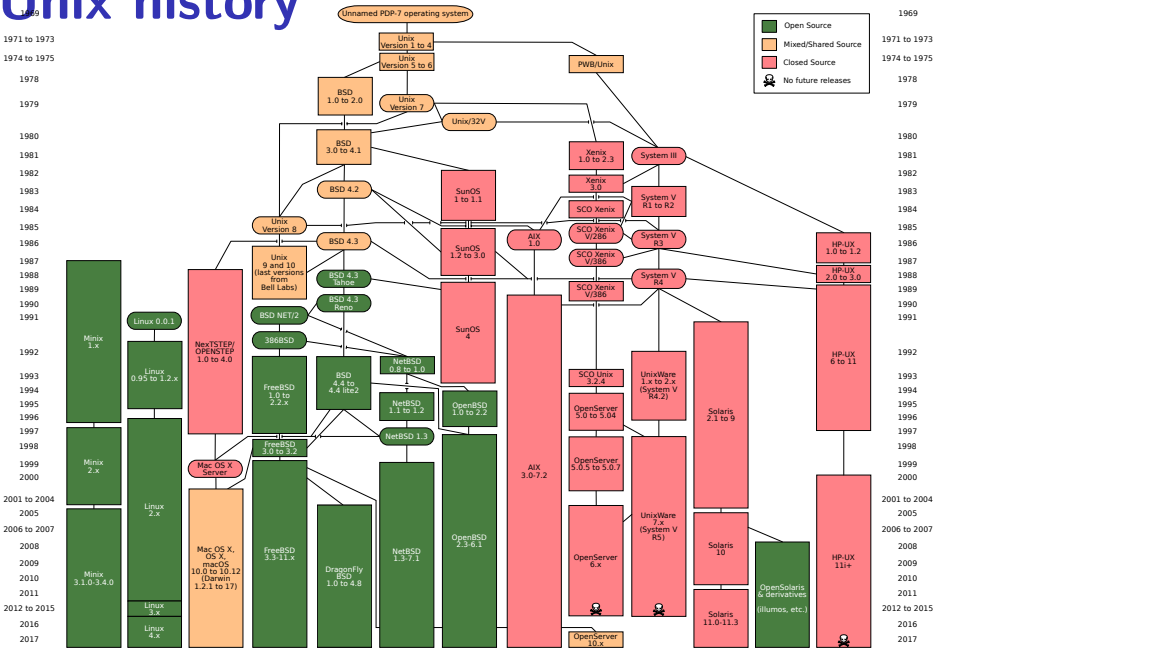

image: Wikpedia/Eraserhead1+Infinity0+Sav_vas

POSIX: standardized Unix

Portable Operating System Interface (POSIX)

> "standard for Unix"

current version online:
https://pubs.opengroup.org/onlinepubs/9699919799/

(almost) followed by most current Unix-like OSes

...but OSes add extra features

...and POSIX doesn't specify everything

what POSIX defines

POSIX specifies the library and shell interface

- source code compatibility

doesn't care what is/is not a system call...

doesn't specify binary formats...

idea: write applications for POSIX, recompile and run on all implementations

- this was a very important goal in the 80s/90s
- at the time, no dominant Unix-like OS (Linux was very immature)

POSIX process management

essential operations

process information: `getpid`

process creation: `fork`

running programs: `exec*`

also `posix_spawn` (not widely supported), ...

waiting for processes to finish: `waitpid` (or `wait`)

process destruction, 'signaling': `exit`, `kill`

POSIX process management

essential operations

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waiting for processes to finish: `waitpid` (or `wait`)

process destruction, 'signaling': `exit`, `kill`

getpid

```
pid_t my_pid = getpid();
printf("my pid is %ld\n", (long) my_pid);
```

process ids in ps

```
cr4bd@machine:~$ ps
  PID TTY          TIME CMD
14777 pts/3    00:00:00 bash
14798 pts/3    00:00:00 ps
```

POSIX process management

essential operations

process information: `getpid`

process creation: `fork`

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also `posix_spawn` (not widely supported), ...

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process destruction, 'signaling': `exit`, `kill`

fork

`pid_t fork()` — copy the current process

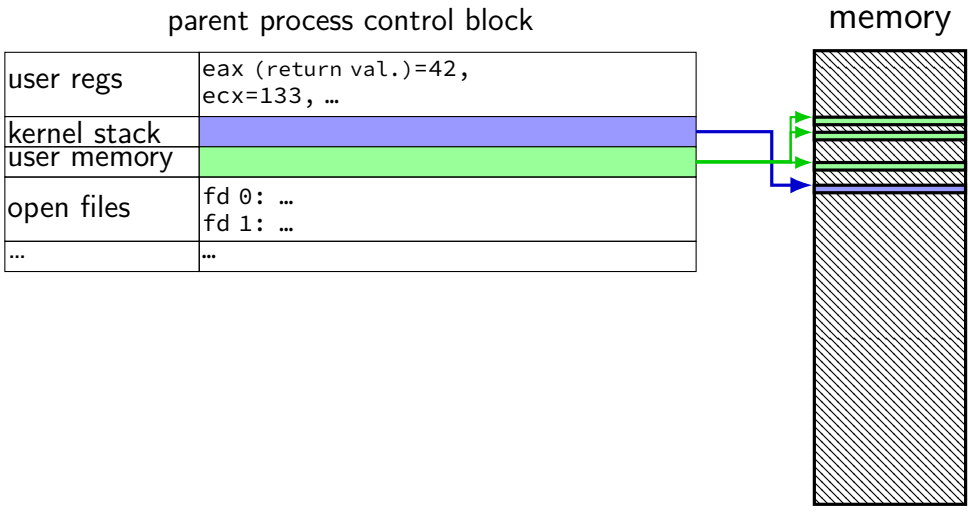
returns twice:

- in *parent* (original process): pid of new *child* process
- in *child* (new process): `0`

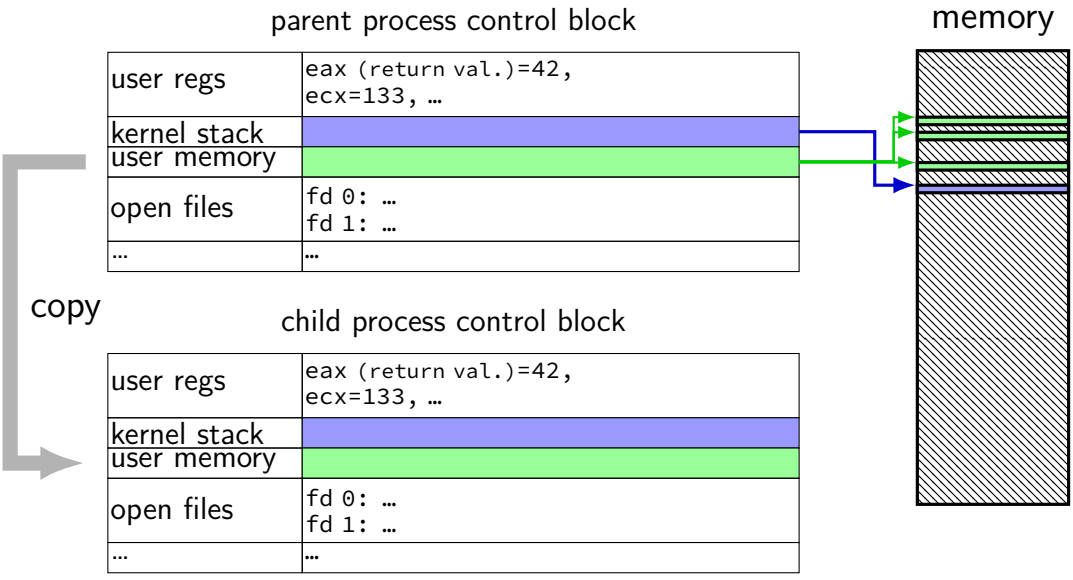
everything (but pid) duplicated in parent, child:

- memory
- file descriptors (later)
- registers

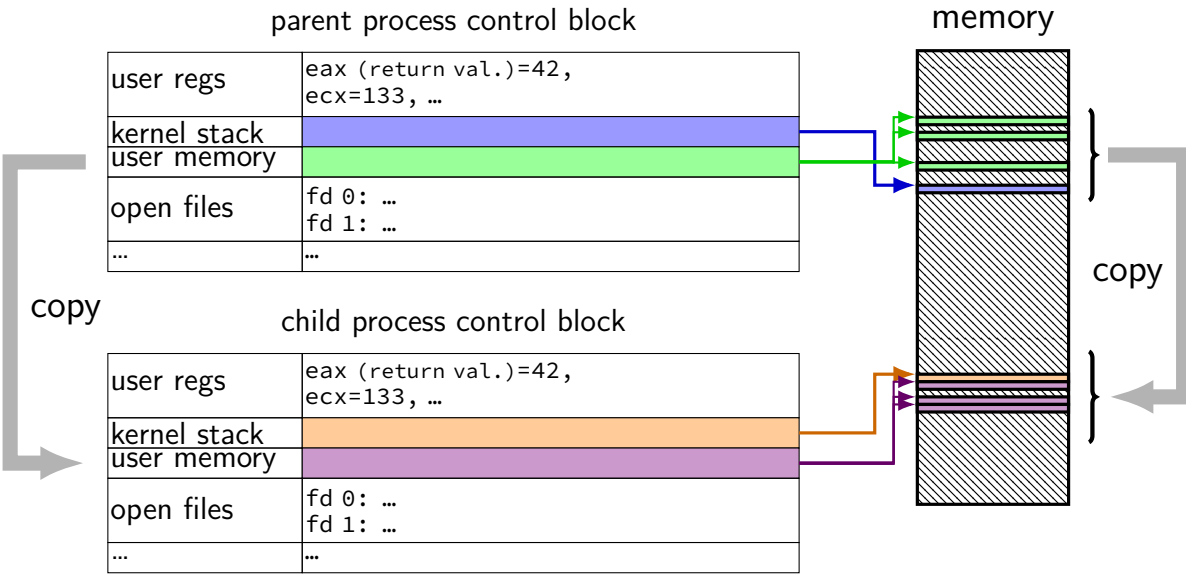
fork and PCBs



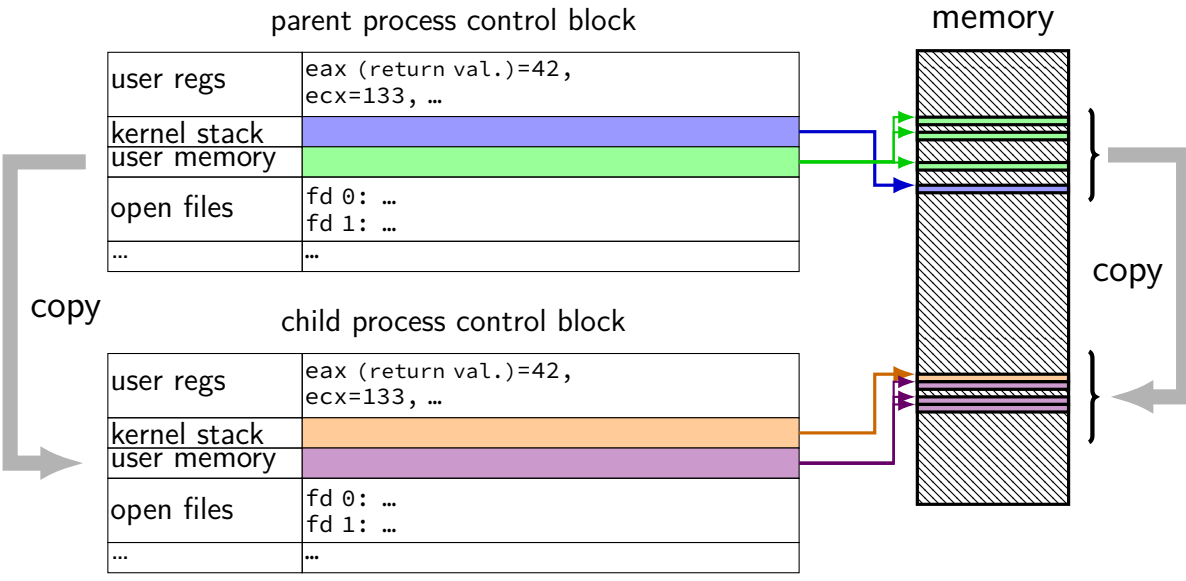
fork and PCBs



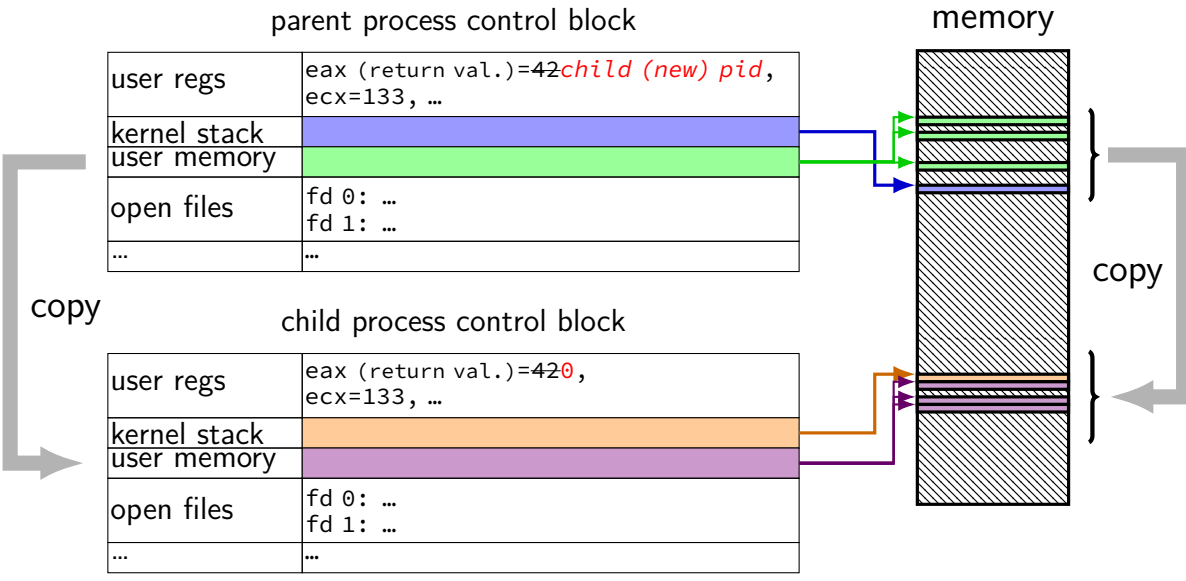
fork and PCBs



fork and PCBs



fork and PCBs



fork example

```c
#include <stdlib.h>
#include <stdio.h>
#include <unistd.h>
#include <sys/types.h>
int main(int argc, char *argv[]) {
    pid_t pid = getpid();
    printf("Parent pid: %d\n", (int) pid);
    pid_t child_pid = fork();
    if (child_pid > 0) {
        /* Parent Process */
        pid_t my_pid = getpid();
        printf("[%d] parent of [%d]\n", (int) my_pid, (int) child_pid);
    } else if (child_pid == 0) {
        /* Child Process */
        pid_t my_pid = getpid();
        printf("[%d] child\n", (int) my_pid);
    } else {
        perror("Fork failed");
    }
    return 0;
}
```

fork example

```c
#include <stdlib.h>
#include <stdio.h>
#include <unistd.h>
#include <sys/types.h>
int main(int argc, char *argv[]) {
    pid_t pid = getpid();
    printf("Parent pid: %d\n", (int) pid);
    pid_t child_pid = fork();
    if (child_pid > 0) {
        /* Parent Process */
        pid_t my_pid = getpid();
        printf("[%d] parent of [%d]\n", (int) my_pid, (int) child_pid);
    } else if (child_pid == 0) {
        /* Child Process */
        pid_t my_pid = getpid();
        printf("[%d] child\n", (int) my_pid);
    } else {
        perror("Fork failed");
    }
    return 0;
}
```

`getpid` — returns current process pid

fork example

```
#include <stdlib.h>
#include <stdio.h>
#include <unist
#include <sys/t
int main(int ar
    pid_t pid =
    printf("Par
    pid_t child_pid = fork();
    if (child_pid > 0) {
        /* Parent Process */
        pid_t my_pid = getpid();
        printf("[%d] parent of [%d]\n", (int) my_pid, (int) child_pid);
    } else if (child_pid == 0) {
        /* Child Process */
        pid_t my_pid = getpid();
        printf("[%d] child\n", (int) my_pid);
    } else {
        perror("Fork failed");
    }
    return 0;
}
```

cast in case `pid_t` isn't int

POSIX doesn't specify (some systems it is, some not...)

(not necessary if you were using C++'s cout, etc.)

fork example

```
#include <stdlib.h>
#include <stdio.h>
#include
#include
int main(
    pid_t
    print
    pid_t child_pid = fork();
    if (child_pid > 0) {
        /* Parent Process */
        pid_t my_pid = getpid();
        printf("[%d] parent of [%d]\n", (int) my_pid, (int) child_pid);
    } else if (child_pid == 0) {
        /* Child Process */
        pid_t my_pid = getpid();
        printf("[%d] child\n", (int) my_pid);
    } else {
        perror("Fork failed");
    }
    return 0;
}
```

prints out `Fork failed: error message`
(example *error message*: "Resource temporarily unavailable")
from error number stored in special global variable `errno`

fork example

```c
#include <stdlib.h>
#include <stdio.h>
#include <unistd.h>
#include <sys/types.h>
int main(int argc, char *argv[]) {
    pid_t pid = getpid();
    printf("Parent pid: %d\n", (int) pid);
    pid_t child_pid = fork();
    if (child_pid > 0) {
        /* Parent Process */
        pid_t my_pid = getpid();
        printf("[%d] parent of [%d]\n", (int) my_pid, (int) child_pid);
    } else if (child_pid == 0) {
        /* Child Process */
        pid_t my_pid = getpid();
        printf("[%d] child\n", (int) my_pid);
    } else {
        perror("Fork failed");
    }
    return 0;
}
```

Example output:

```
Parent pid: 100
[100] parent of [432]
[432] child
```

a fork question

```
int main() {
    pid_t pid = fork();
    if (pid == 0) {
        printf("In child\n");
    } else {
        printf("Child %d\n", pid);
    }
    printf("Done!\n");
}
```

Exercise: Suppose the pid of the parent process is 99 and child is 100. Give **two** possible outputs. (Assume no crashes, etc.)

a fork question

```
int main() {
    pid_t pid = fork();
    if (pid == 0) {
        printf("In child\n");
    } else {
        printf("Child %d\n", pid);
    }
    printf("Done!\n");
}
```

Exercise: Suppose the pid of the parent process is 99 and child is 100. Give **two** possible outputs. (Assume no crashes, etc.)


```
Child 100
In child
Done!
Done!
```


```
In child
Done!
Child 100
Done!
```

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running programs: `exec*`

also `posix_spawn` (not widely supported), ...

waiting for processes to finish: `waitpid` (or `wait`)

process destruction, 'signaling': `exit`, `kill`

exec*

exec* — replace current program with new program

* — multiple variants

same pid, new process image

```
int execv(const char *path, const char **argv)
```

path: new program to run

argv: array of arguments, termianted by null pointer

execv example

```
...
child_pid = fork();
if (child_pid == 0) {
  /* child process */
  char *args[] = {"ls", "-l", NULL};
  execv("/bin/ls", args);
  /* execv doesn't return when it works.
     So, if we got here, it failed. */
  perror("execv");
  exit(1);
} else if (child_pid > 0) {
  /* parent process */
  ...
}
```

execv example

```
...
child_pid = fork();
if (child_pid == 0) {
  /* child process */
  char *args[] = {"ls", "-l", NULL};
  execv("/bin/ls", args);
  /* execv doesn't return when it works.
     So, if we got
  perror("execv");
  exit(1);
} else if (child_p
  /* parent process
  ...
}
```

used to compute argv, argc
when program's `main` is run

convention: first argument is program name

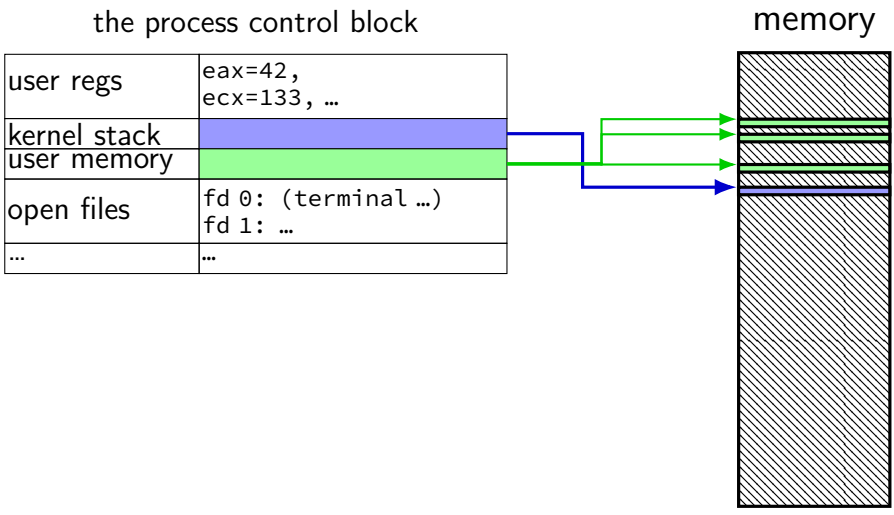
execv example

```
...
child_pid = fork();
if (child_pid == 0) {
  /* child process */
  char *args[] = {"ls", "-l", NULL};
  execv("/bin/ls", args);
  /* execv doesn't return when it works.
     So, if we got here,
  perror("execv");
  exit(1);
} else if (child_pid > 0)
  /* parent process */
  ...
}
```

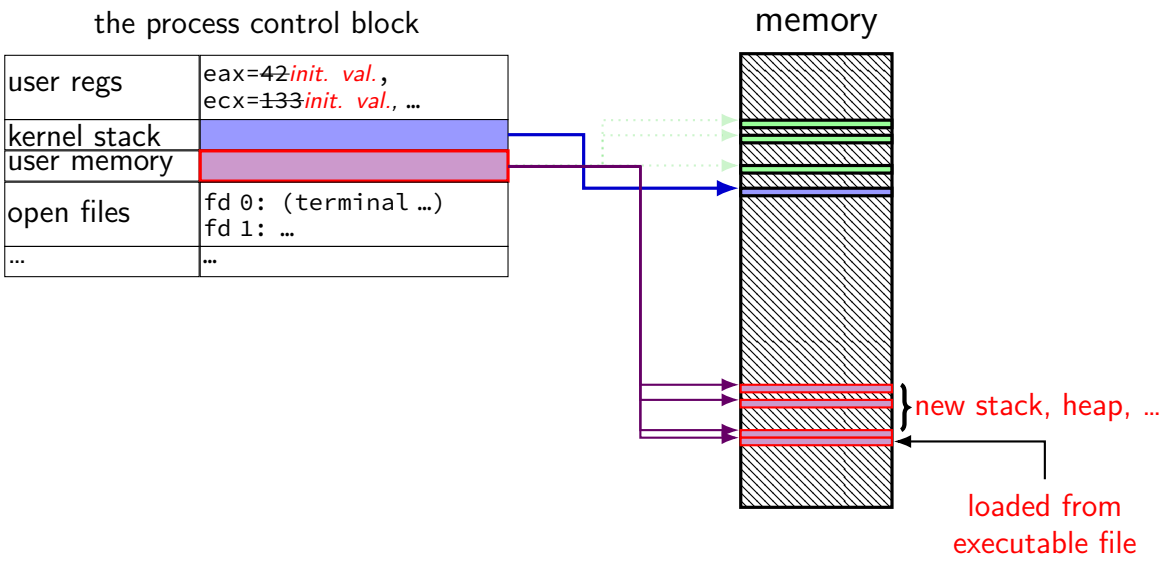
path of executable to run
need not match first argument
(but probably should match it)

on Unix /bin is a directory
containing many common programs,
including `ls` ('list directory')

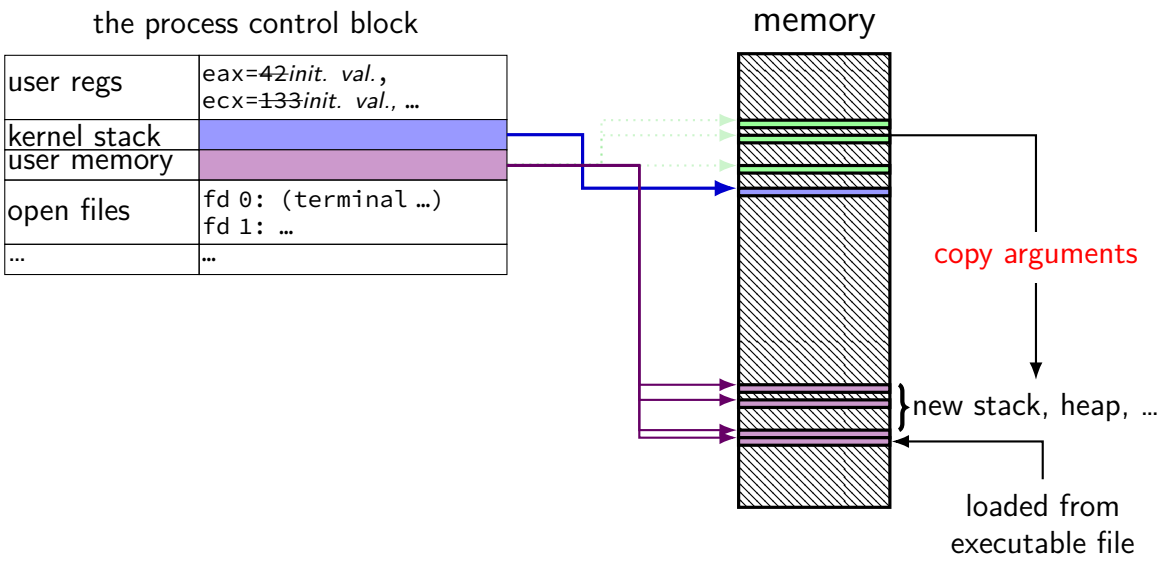
exec and PCBs



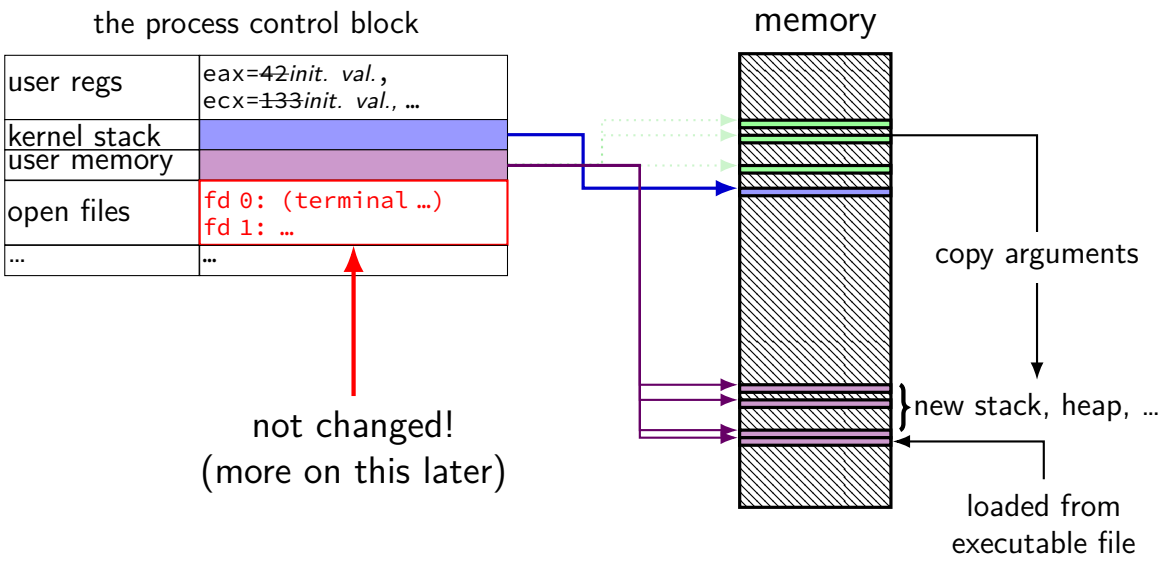
exec and PCBs



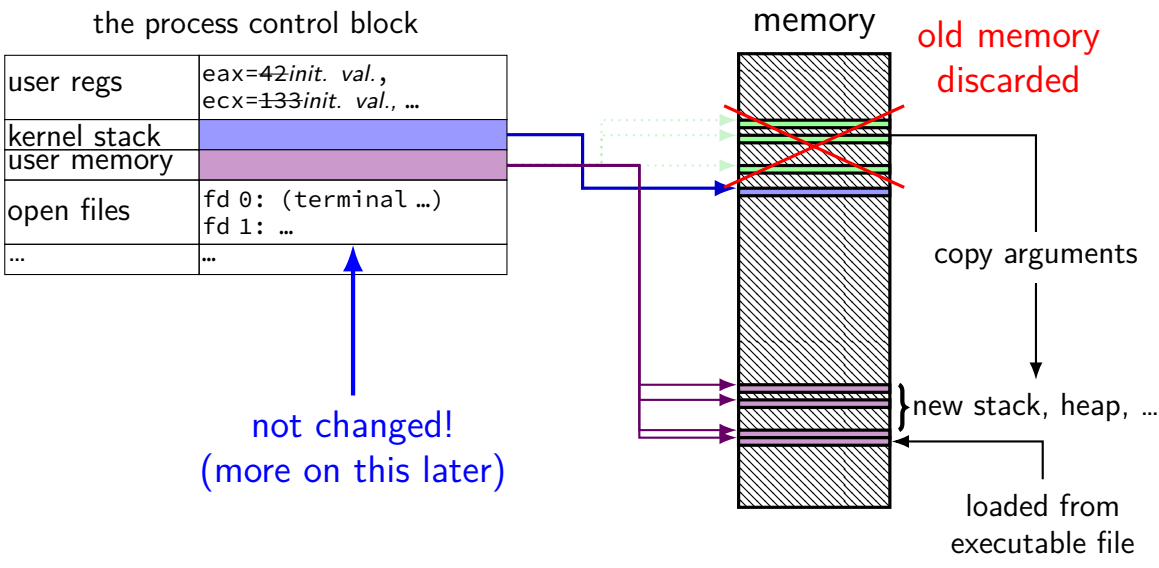
exec and PCBs



exec and PCBs



exec and PCBs



why fork/exec?

could just have a function to spawn a new program

- Windows `CreateProcess()`; POSIX's (rarely used) `posix_spawn`

some other OSs do this (e.g. Windows)

needs to include API to set new program's state

- e.g. without fork: need function to set new program's current directory
- e.g. with fork: just change your current directory before exec

but allows OS to avoid 'copy everything' code

- probably makes OS implementation easier

posix_spawn

```
pid_t new_pid;
const char argv[] = { "ls", "-l", NULL };
int error_code = posix_spawn(
    &new_pid,
    "/bin/ls",
    NULL /* null = copy current process's open files;
            if not null, do something else */,
    NULL /* null = no special settings for new process */,
    argv,
    NULL /* null = copy current process's "environment variabl
            if not null, do something else */
);
if (error_code == 0) {
    /* handle error */
}
```

some opinions (via HotOS '19)

A fork() in the road

Andrew Baumann, Microsoft Research
Jonathan Appavoo, Boston University
Orran Krieger, Boston University
Timothy Roscoe, ETH Zurich

ABSTRACT

The received wisdom suggests that Unix's unusual combination of `fork()` and `exec()` for process creation was an inspired design. In this paper, we argue that fork was a clever hack for machines and programs of the 1970s that has long outlived its usefulness and is now a liability. We catalog the ways in which fork is a terrible abstraction for the modern programmer to use, describe how it compromises OS implementations, and propose alternatives.

POSIX process management

essential operations

process information: `getpid`

process creation: `fork`

running programs: `exec*`

also `posix_spawn` (not widely supported), ...

waiting for processes to finish: `waitpid` (or `wait`)

process destruction, 'signaling': `exit`, `kill`

wait/waitpid

```
pid_t waitpid(pid_t pid, int *status,
                  int options)
```

wait for a child process (with pid=`pid`) to finish

sets `*status` to its "status information"

`pid=-1` → wait for any child process instead

options? see manual page (command `man waitpid`)

- `0` — no options

exit statuses

```
int main() {
    return 0;  /* or exit(0);  */
}
```

waitpid example

```
#include <sys/wait.h>
...
  child_pid = fork();
  if (child_pid > 0) {
      /* Parent process */
      int status;
      waitpid(child_pid, &status, 0);
  } else if (child_pid == 0) {
      /* Child process */
      ...
```

the status

```
#include <sys/wait.h>
...
  waitpid(child_pid, &status, 0);
  if (WIFEXITED(status)) {
    printf("main returned or exit called with %d\n",
           WEXITSTATUS(status));
  } else if (WIFSIGNALED(status)) {
    printf("killed by signal %d\n", WTERMSIG(status));
  } else {
      ...
  }
```

"status code" encodes both return value and if exit was abnormal

W* macros to decode it

the status

```
#include <sys/wait.h>
...
  waitpid(child_pid, &status, 0);
  if (WIFEXITED(status)) {
    printf("main returned or exit called with %d\n",
           WEXITSTATUS(status));
  } else if (WIFSIGNALED(status)) {
    printf("killed by signal %d\n", WTERMSIG(status));
  } else {
      ...
  }
```

"status code" encodes both return value and if exit was abnormal

W* macros to decode it

aside: signals

signals are a way of communicating between processes

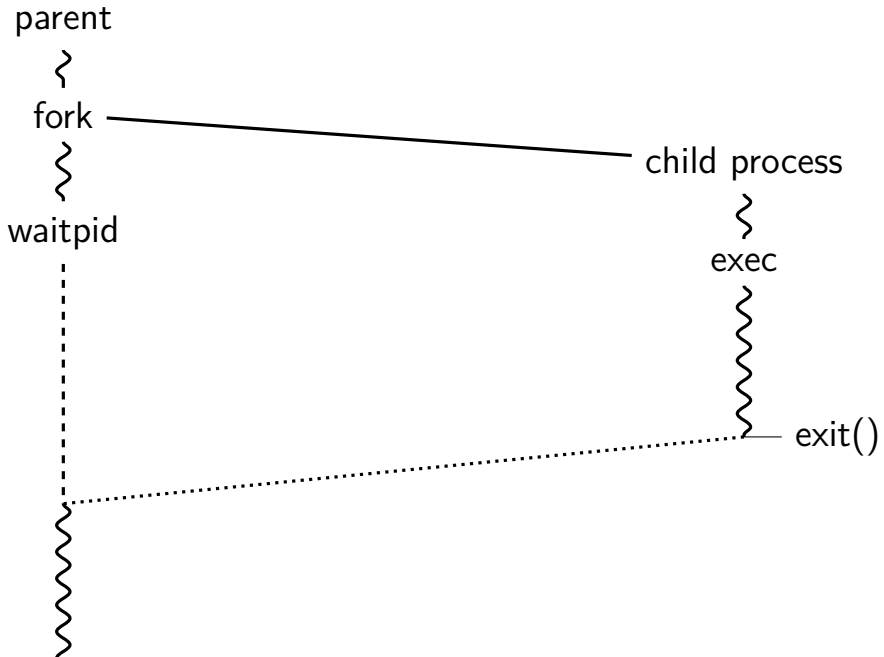
they are also how abnormal termination happens

- kernel communicating "something bad happened" → kills program by default

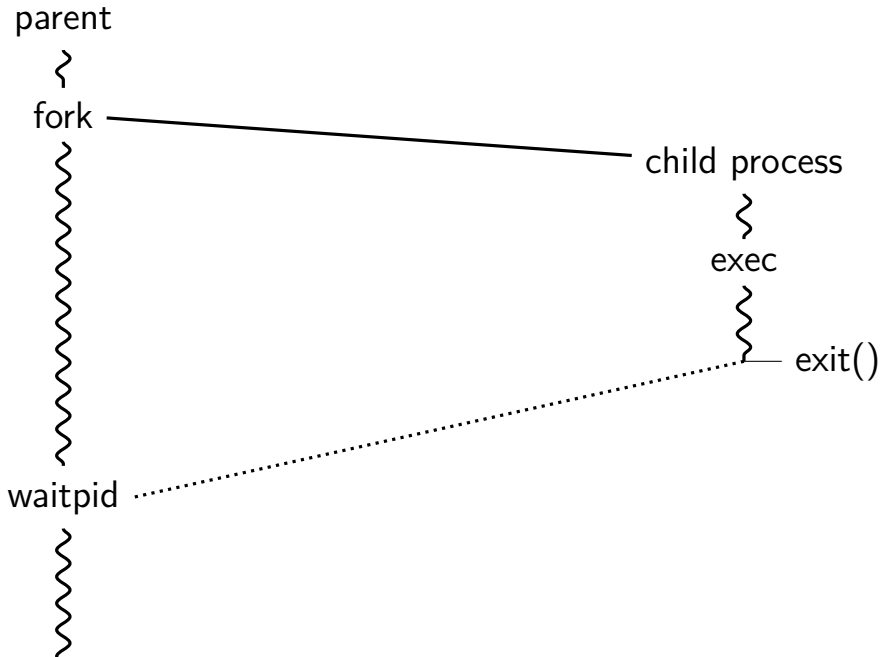
wait's status will tell you when and what signal killed a program

- constants in signal.h
- SIGINT — control-C
- SIGTERM — `kill` command (by default)
- SIGSEGV — segmentation fault
- SIGBUS — bus error
- SIGABRT — `abort()` library function
- ...

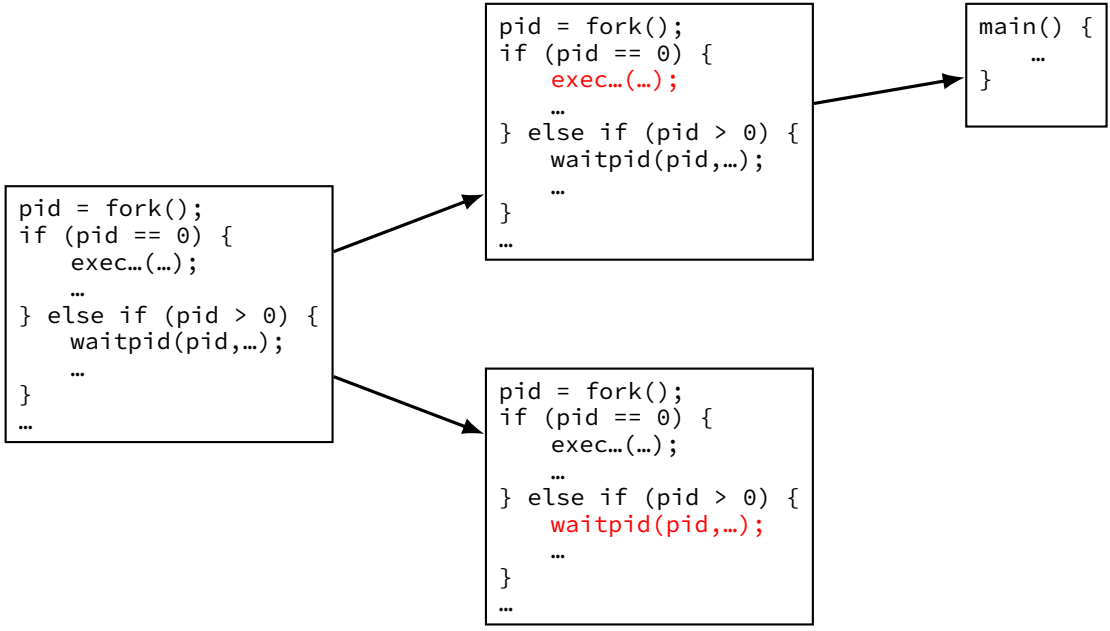
typical pattern



typical pattern (alt)



typical pattern (detail)



multiple processes?

```
while (...) {
    pid = fork();
    if (pid == 0) {
        exec ...
    } else if (pid > 0) {
        pids.push_back(pid);
    }
}

/* retrieve exit statuses in order */
for (pid_t pid : pids) {
    waitpid(pid, ...);
    ...
}
```

multiple processes?

```
while (...) {
    pid = fork();
    if (pid == 0) {
        exec ...
    } else if (pid > 0) {
        pids.push_back(pid);
    }
}

/* retrieve exit statuses as processes finish */
while ((pid = waitpid(-1, ...)) != -1) {
    handleProcessFinishing(pid);
}
```

POSIX process management

essential operations

process information: `getpid`

process creation: `fork`

running programs: `exec*`

also `posix_spawn` (not widely supported), ...

waiting for processes to finish: `waitpid` (or `wait`)

process destruction, 'signaling': `exit`, `kill`

backup slides

aside: environment variables (1)

key=value pairs associated with every process:

```
$ printenv
MODULE_VERSION_STACK=3.2.10
MANPATH=:/opt/puppetlabs/puppet/share/man
XDG_SESSION_ID=754
HOSTNAME=labsrv01
SELINUX_ROLE_REQUESTED=
TERM=screen
SHELL=/bin/bash
HISTSIZE=1000
SSH_CLIENT=128.143.67.91 58432 22
SELINUX_USE_CURRENT_RANGE=
QTDIR=/usr/lib64/qt-3.3
OLDPWD=/zf14/cr4bd
QTINC=/usr/lib64/qt-3.3/include
SSH_TTY=/dev/pts/0
QT_GRAPHICSSYSTEM_CHECKED=1
USER=cr4bd
LS_COLORS=rs=0:di=01;34:ln=01;36:mh=00:pi=40;33:so=01;35:do=01;35:bd=40;33;01:cd=40;33;01:or=
MODULE_VERSION=3.2.10
MAIL=/var/spool/mail/cr4bd
PATH=/zf14/cr4bd/.cargo/bin:/zf14/cr4bd/bin:/usr/lib64/qt-3.3/bin:/usr/local/bin:/usr/bin:/us
PWD=/zf14/cr4bd
LANG=en_US.UTF-8
MODULEPATH=/sw/centos/Modules/modulefiles:/sw/linux-any/Modules/modulefiles
LOADEDMODULES=
KDEDIRS=/usr
```

aside: environment variables (2)

environment variable library functions:

`getenv("KEY")` → *value*

`putenv("KEY=value")` (sets KEY to *value*)

`setenv("KEY", "value")` (sets KEY to *value*)

```
int execve(char *path, char **argv, char **envp)
```

```
char *envp[] = { "KEY1=value1", "KEY2=value2", NULL };
char *argv[] = { "somecommand", "some arg", NULL };
execve("/path/to/somecommand", argv, envp);
```

normal exec versions — keep same environment variables

aside: environment variables (3)

interpretation up to programs, but common ones...

`PATH=/bin:/usr/bin`

to run a program 'foo', look for an executable in `/bin/foo`, then `/usr/bin/foo`

`HOME=/zf14/cr4bd`

current user's home directory is '/zf14/cr4bd'

`TERM=screen-256color`

your output goes to a 'screen-256color'-style terminal

...

waiting for all children

```
#include <sys/wait.h>
...
  while (true) {
    pid_t child_pid = waitpid(-1, &status, 0);
    if (child_pid == (pid_t) -1) {
      if (errno == ECHILD) {
        /* no child process to wait for */
        break;
      } else {
        /* some other error */
      }
    }
    /* handle child_pid exiting */
  }
```

‘waiting’ without waiting

```
#include <sys/wait.h>
...
  pid_t return_value = waitpid(child_pid, &status, WNOHANG);
  if (return_value == (pid_t) 0) {
    /* child process not done yet */
  } else if (child_pid == (pid_t) -1) {
    /* error */
  } else {
    /* handle child_pid exiting */
  }
```

running in background

```
$ ./long_computation >tmp.txt &
[1] 4049
$ ...
[1]+    Done          ./long_computation > tmp.txt
$ cat tmp.txt
the result is ...
```

& — run a program in "background"

initially output PID (above: 4049)

print out after terminated

- one way: use `waitpid` with option saying "don't wait"

execv and const

```
int execv(const char *path, char *const *argv);
```

argv is a pointer to constant pointer to char

probably should be a pointer to constant pointer to *constant* char

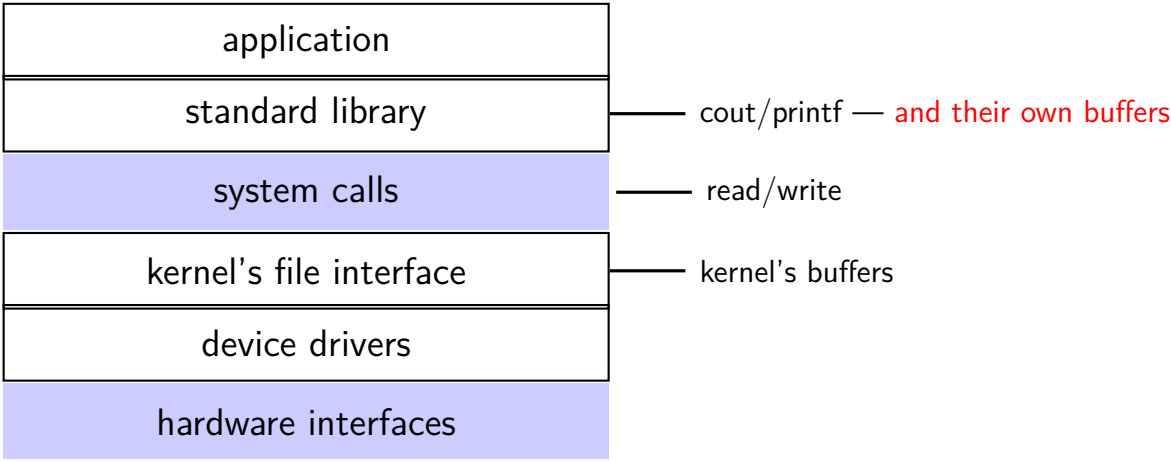
...this causes some awkwardness:

```
const char *array[] = { /* ... */ };
execv(path, array); // ERROR
```

solution: cast

```
const char *array[] = { /* ... */ };
execv(path, (char **) array); // or (char * const *)
```

layering


application
standard library
system calls
kernel's file interface
device drivers
hardware interfaces
cout/printf — and their own buffers
read/write
kernel's buffers

why the extra layer

better (but more complex to implement) interface:

- read line
- formatted input (scanf, cin into integer, etc.)
- formatted output

less system calls (bigger reads/writes) sometimes faster

- buffering can combine multiple in/out library calls into one system call

more portable interface

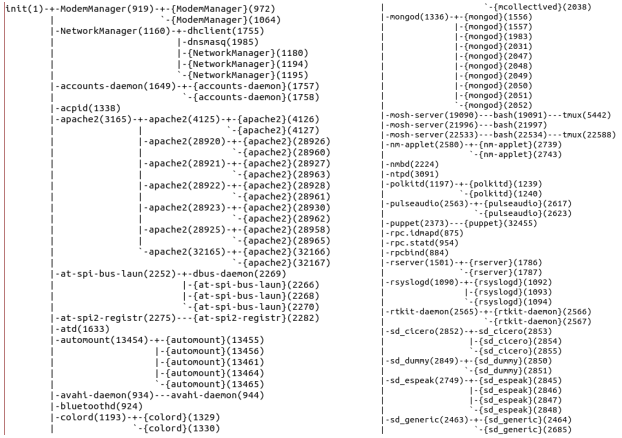
- cin, printf, etc. defined by C and C++ standards

parent and child processes

every process (but process id 1) has a *parent process* (`getppid()`)

this is the process that can wait for it

creates tree of processes (Linux `pstree` command):



parent and child questions...

what if parent process exits before child?

- child's parent process becomes process id 1 (typically called *init*)

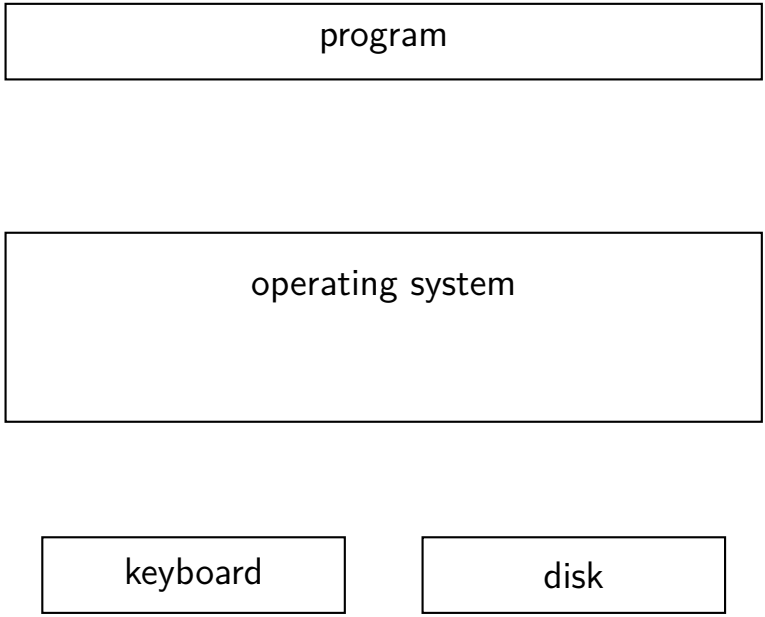
what if parent process never `waitpid()`s (or equivalent) for child?

- child process stays around as a "zombie"
- can't reuse pid in case parent wants to use `waitpid()`

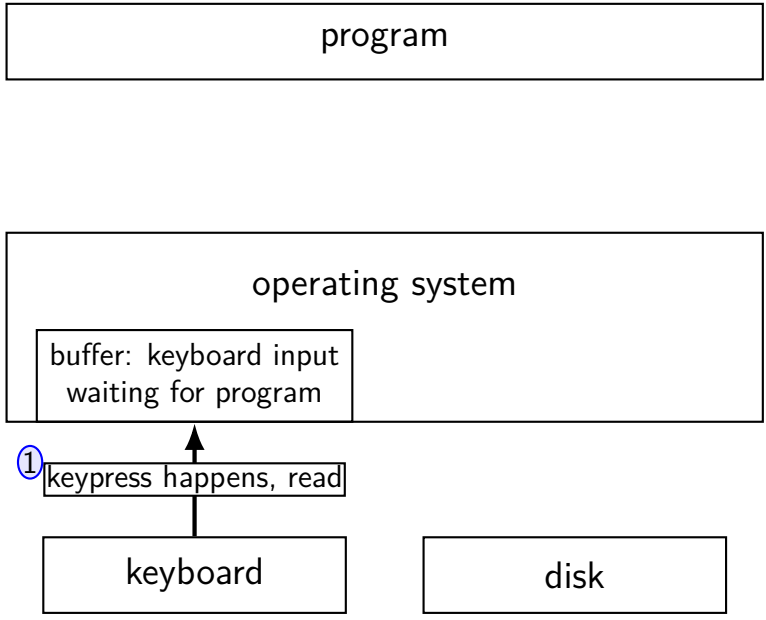
what if non-parent tries to `waitpid()` for child?

- waitpid fails

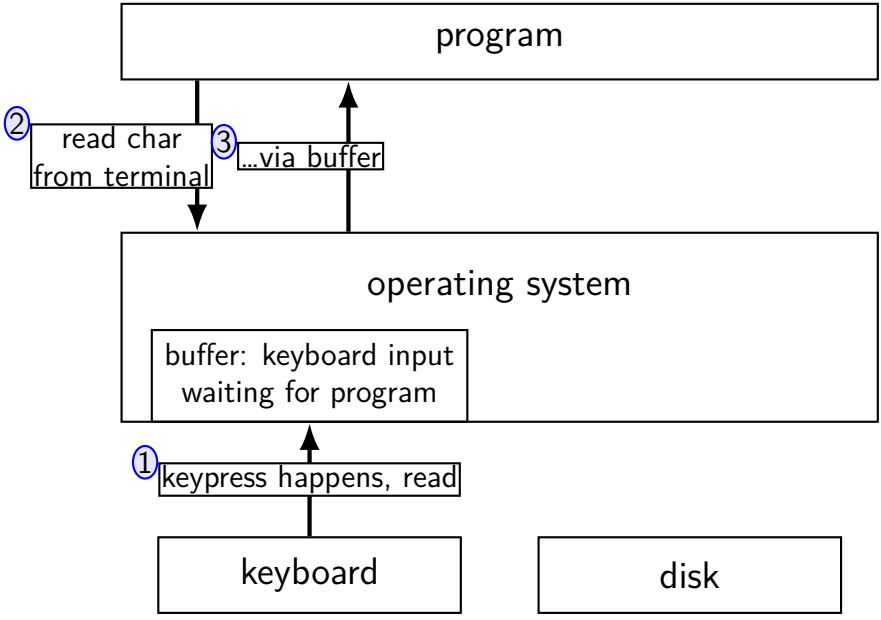
kernel buffering (reads)



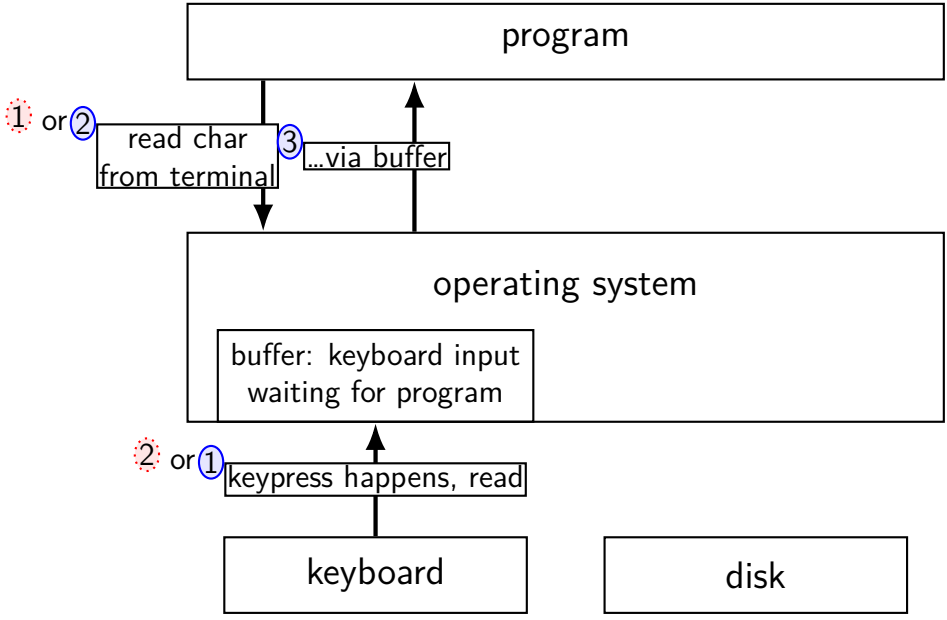
kernel buffering (reads)



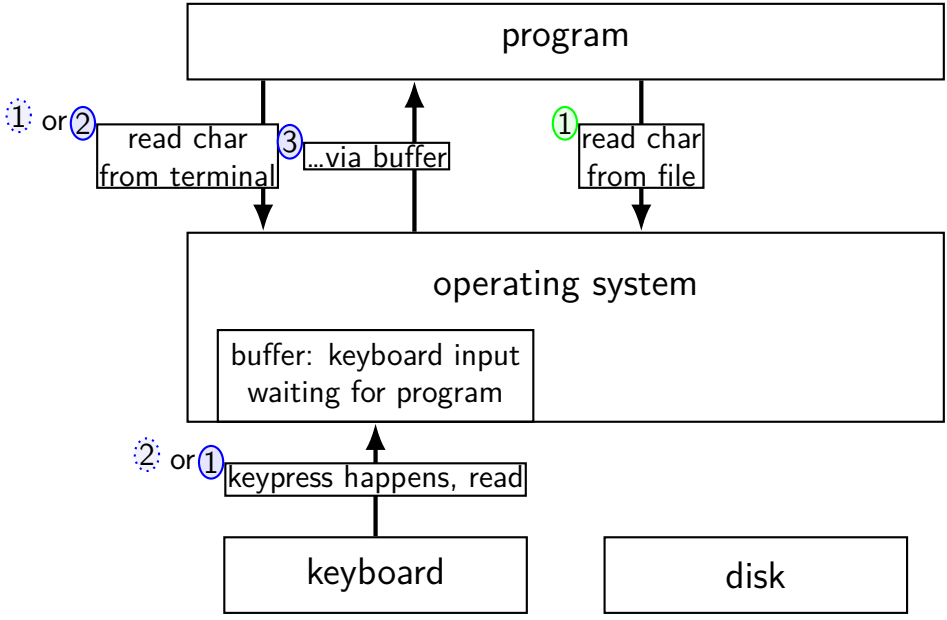
kernel buffering (reads)



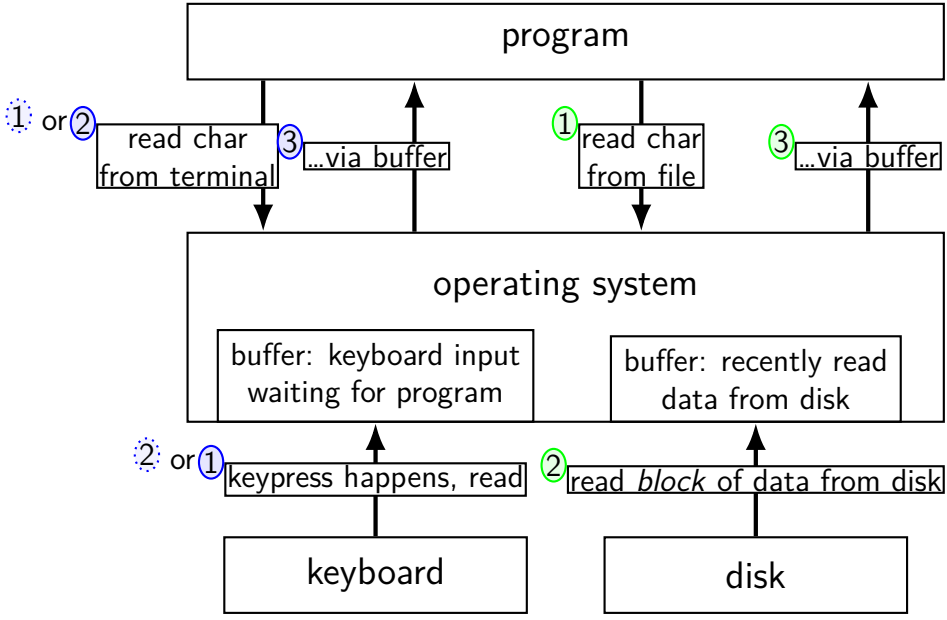
kernel buffering (reads)



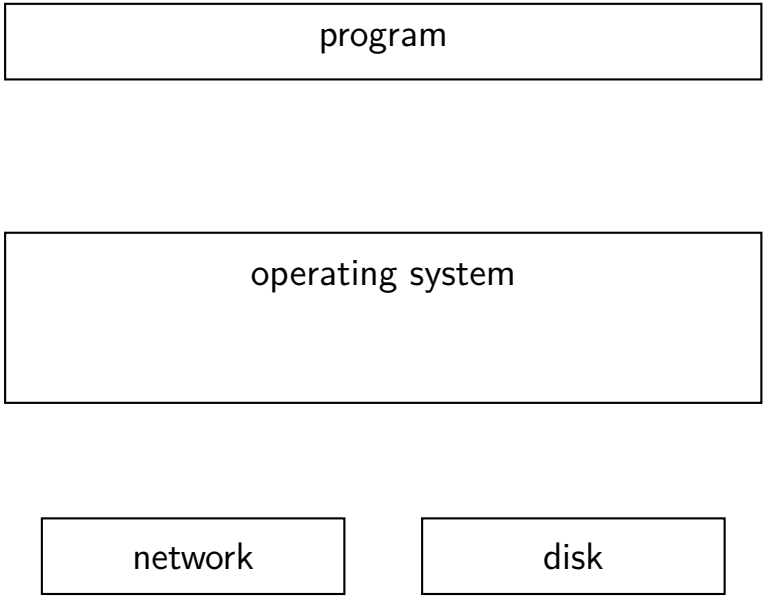
kernel buffering (reads)



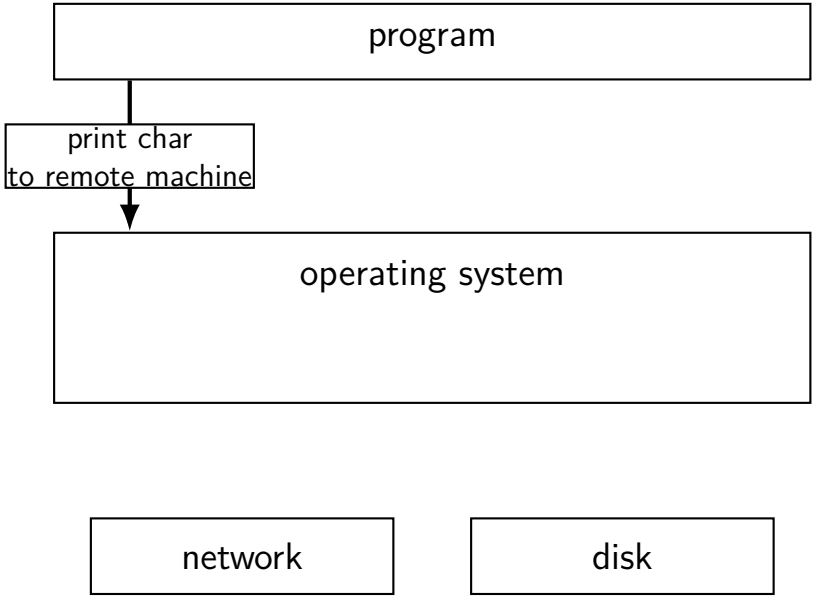
kernel buffering (reads)



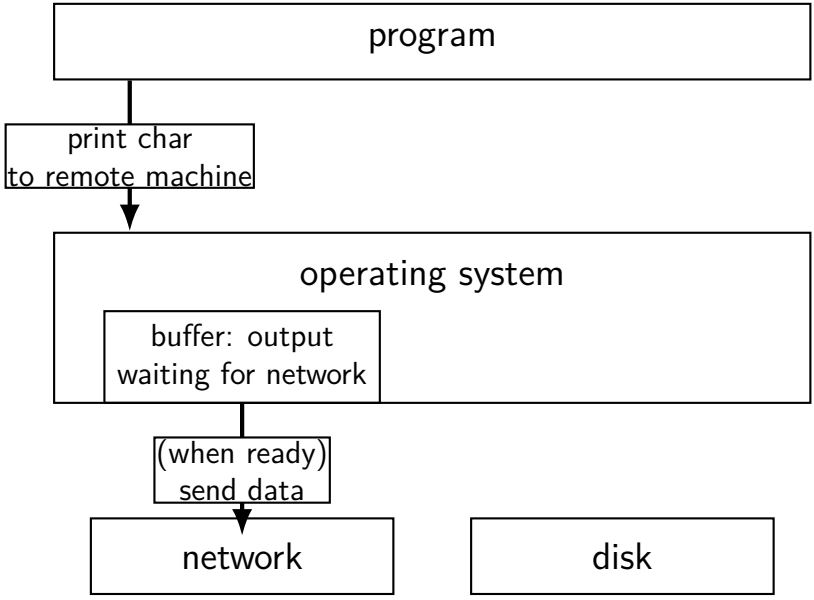
kernel buffering (writes)



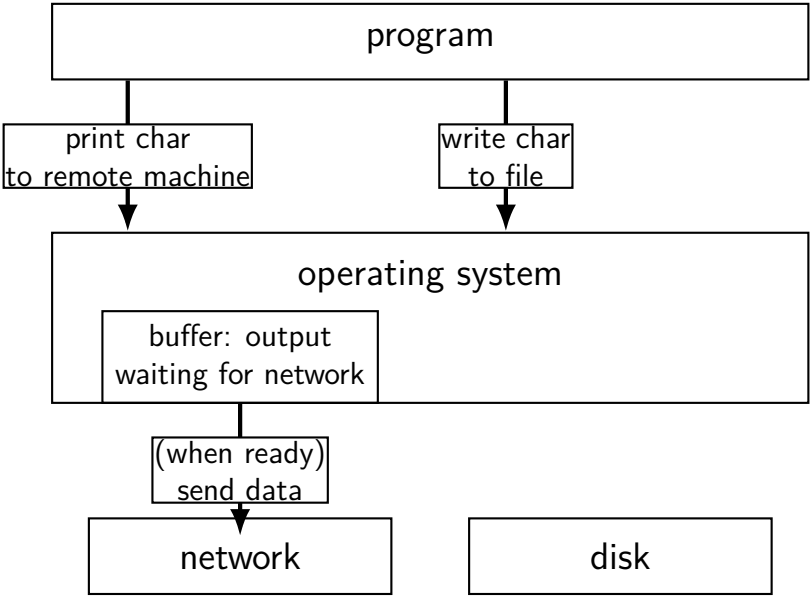
kernel buffering (writes)



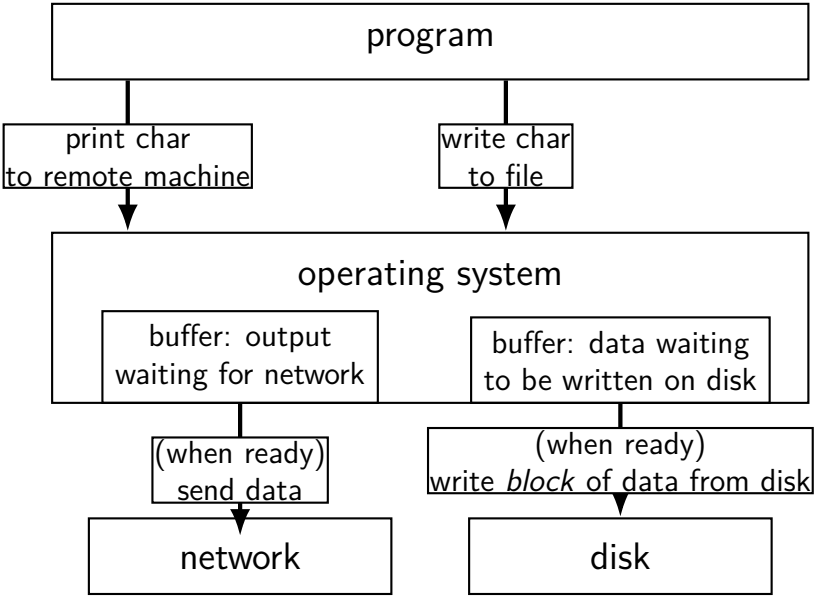
kernel buffering (writes)



kernel buffering (writes)



kernel buffering (writes)



read/write operations

read()/write(): move data into/out of buffer

possibly wait if buffer is empty (read)/full (write)

actual I/O operations — wait for device to be ready

- trigger process to stop waiting if needed