

CS 6354: Static Scheduling / Branch Prediction

12 September 2016

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On out-of-order RDTSC

Because of pipelines, etc.:

RDTSC can actually take its time measurement after it starts

Earlier instructions can still be completing by the time RDTSC starts

Solutions:

Time longer things so the overlap isn't significant

Use synchronizing instructions like CPUID

2

General notes about accurate timing

take **multiple measurements** — detect/avoid outliers

make sure instruction caches, etc. are filled — **discard first** few measurements

prefer longer benchmarks — it's easier to accurately measure microseconds than nanoseconds

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Some pitfalls

initialize arrays

OS may map multiple virtual pages to one physical page of zeroes

if you want something in cache, access it to do that
allocating it doesn't count

4

Note about optimizations

```
int test(void) {
    int array[1024 * 1024];
    memset(array, sizeof array, 42);
    return 0;
}
```

generated assembly from gcc -O:

```
test:
    movl    $0, %eax
    ret
```

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Note about throughput/latency

try to **exclude** benchmark overhead

throughput should take prefetching, concurrent memory requests, etc. into account

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Other homework 1 questions?

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Recall: The MIPS pipeline

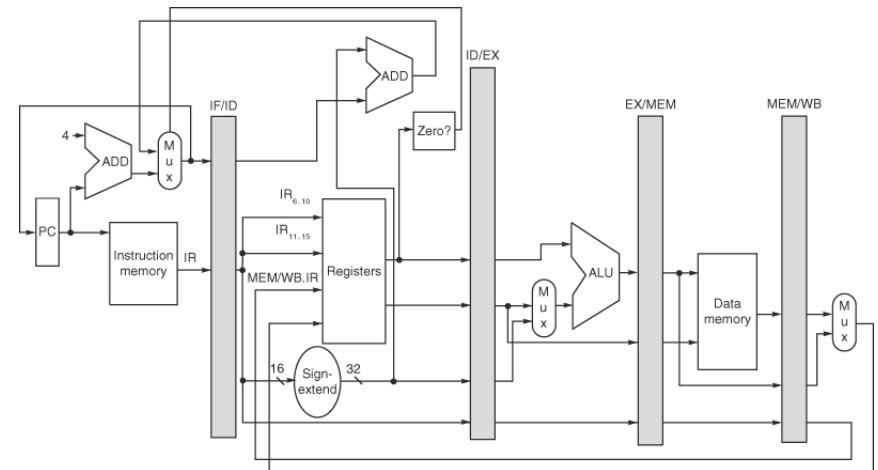


Figure C.28 The stall from branch hazards can be reduced by moving the zero test and branch-target calculation into the ID phase of the pipeline. Notice that we have made two important changes, each of which removes 1 cycle from the 3-cycle stall for branches. The first change is to move both the branch-target address calculation and the branch condition calculation into the ID phase. The second change is to write the PC of the instruction in the IF phase, using either the branch target address computed during ID or

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Forwarding/Stalls Example

```

mempcy: ; $a0 = destination, $a1 = source
        ; $a2 = length
        lb $t0, ($a1) ; $t0 <- MEM[$a1]
        sb $t0, ($a0) ; MEM[$a0] <- $t0
        addiu $a0, $a0, 1
        addiu $a1, $a1, 1
        addiu $a2, $a2, -1
        beqz $a2, memcpy
        nop ; DELAY SLOT
    
```

Quick reference:

- IF fetch instruction
- ID decode (read regs, compute branches)
- EX execute (ALU)
- MEM data memory
- WB write back

Which of these require forwarding or stalls?
Between what pipeline stages?

1. for \$t0 between lb and sb
2. for \$a0 between sb and addiu
3. for \$a1 between lb and addiu
4. for \$a2 between addiu and beqz
5. for \$a1 between addiu and the following iteration's lb

Forwarding/Stalls Example

```

mempcy: ; $a0 = destination, $a1 = source
        ; $a2 = length
        lb $t0, ($a1) ; $t0 <- MEM[$a1]
        sb $t0, ($a0) ; MEM[$a0] <- $t0
        addiu $a0, $a0, 1
        addiu $a1, $a1, 1
        addiu $a2, $a2, -1
        beqz $a2, memcpy
        nop ; DELAY SLOT
    
```

Quick reference:

- IF fetch instruction
- ID decode (read regs, compute branches)
- EX execute (ALU)
- MEM data memory
- WB write back

	T=1	T=2	T=3	T=4	T=5	T=6	T=7
IF	sb	addiu	addiu	addiu	beqz	nop	lb
ID	lb	sb	addiu	addiu	addiu	sb	beqz
EX		lb	sb	addiu	addiu	addiu	beqz
MEM			lb	sb	addiu	addiu	addiu
WB				lb	sb	addiu	addiu

MIPS R2000 pipeline

4 cycles without prediction

2 cycles with taken/not-taken prediction

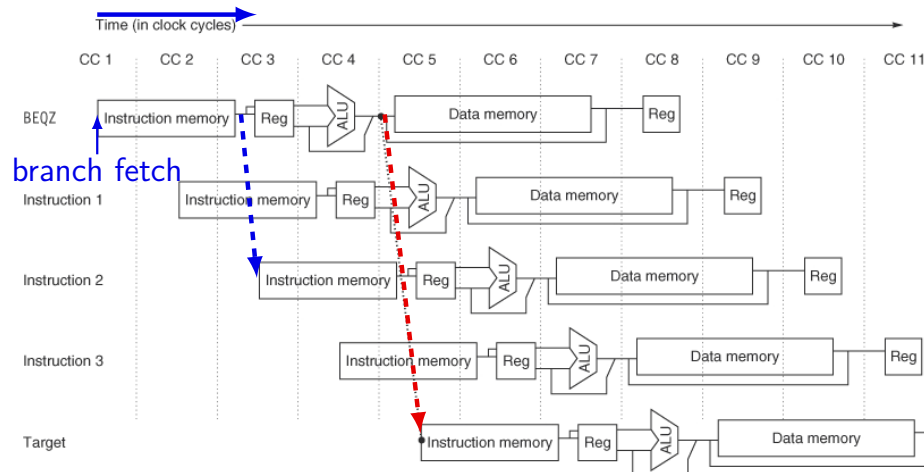
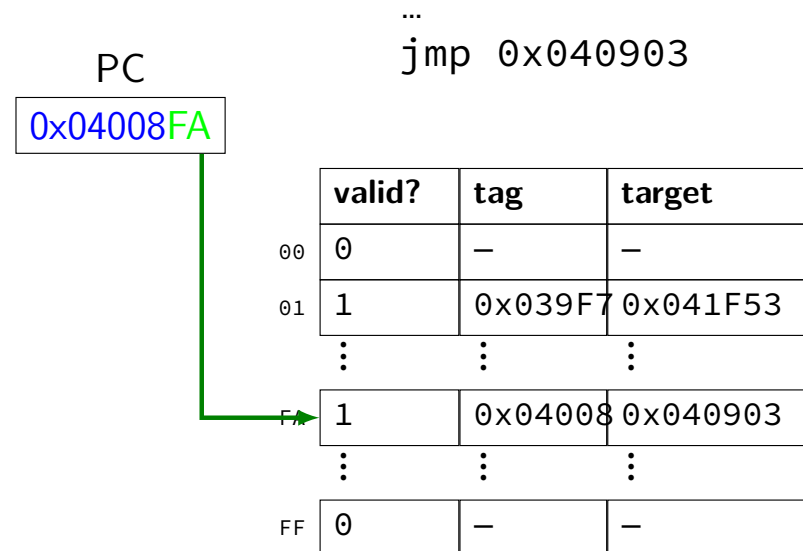


Figure C.44 The basic branch delay is 3 cycles, since the condition evaluation is performed during EX.

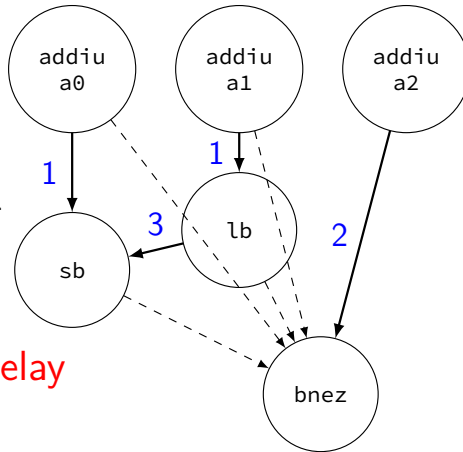
Branch Target Buffers



Scheduling dependencies

(badly ordered loop:)

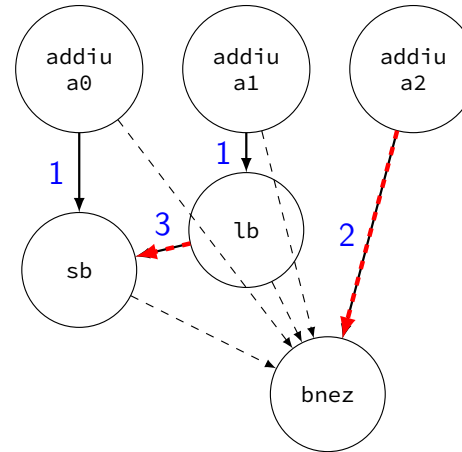
```
addiu $a0, $a0, 1
addiu $a1, $a1, 1
lb $t0, ($a1)
sb $t0, ($a0)
addiu $a2, $a2, -1
bnez $a2, loop
```



label edges with necessary delay
made up delays above

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Scheduling dependencies



Good schedule:

```
addiu $a1, $a1, 1
lb $t0, ($a1)
addiu $a2, $a2, -1
addiu $a0, $a0, 1
sb $t0, ($a0)
bnez $a2, loop
```

correctness: parents before children

performance: distance \geq edge weight

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Loop Unrolling

```
for (int i = 0; i < size; i += 1) {
    dest[i] = source[i];
}
```

converts into

```
assert(i % 4 == 0);
for (int i = 0; i < size; i += 4) {
    dest[i] = source[i];
    dest[i+1] = source[i+1];
    dest[i+2] = source[i+2];
    dest[i+3] = source[i+3];
}
```

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Loop Unrolling — Instructions

One iteration:

normal (4 instrs.)	unroll x 4 (10 instrs.)
load	load
store	store
add	load
branch	store
	load
	store
	load
	store
	add
	branch

$4N$ versus $2.5N = \frac{10}{4}N$

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Loop Unrolling — Assembly

```
; $a0 = dest, $a1 = source, $a2 = i
lb $t0, 0($a1) ; load
sb $t0, 0($a0) ; store
lb $t0, 1($a1) ; load
sb $t0, 1($a0) ; store
lb $t0, 2($a1) ; load
sb $t0, 2($a0) ; store
lb $t0, 3($a1) ; load
sb $t0, 3($a0) ; store
addiu $a2, $a2, -1
bnez $a2, $a2, loop
```

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Loop Unrolling — Fringe

```
for (int i = 0; i + 3 < size; i += 4) {
    dest[i] = source[i];
    dest[i+1] = source[i+1];
    dest[i+2] = source[i+2];
    dest[i+3] = source[i+3];
}
for (i = 0; i < size; i += 1) {
    dest[i] = source[i];
}
```

size = N items: $10 \lfloor N/4 \rfloor + 1 + 4(N \bmod 4)$

still less than normal if $N > 4$

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Loop Unrolling — Cache Pressure

4x unrolled — $10 + 4 + 1 = 25$ instrs. in cache

normal — 4 instrs. in cache

6.25x space in l-cache for 4x unrolled

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Loop Unrolling — Assembly

```
; $a0 = dest, $a1 = source, $a2 = i
lb $t0, 0($a1) ; load
sb $t0, 0($a0) ; store
lb $t0, 1($a1) ; load
sb $t0, 1($a0) ; store
lb $t0, 2($a1) ; load
sb $t0, 2($a0) ; store
lb $t0, 3($a1) ; load
sb $t0, 3($a0) ; store
addiu $a2, $a2, -1
bnez $a2, $a2, loop
```

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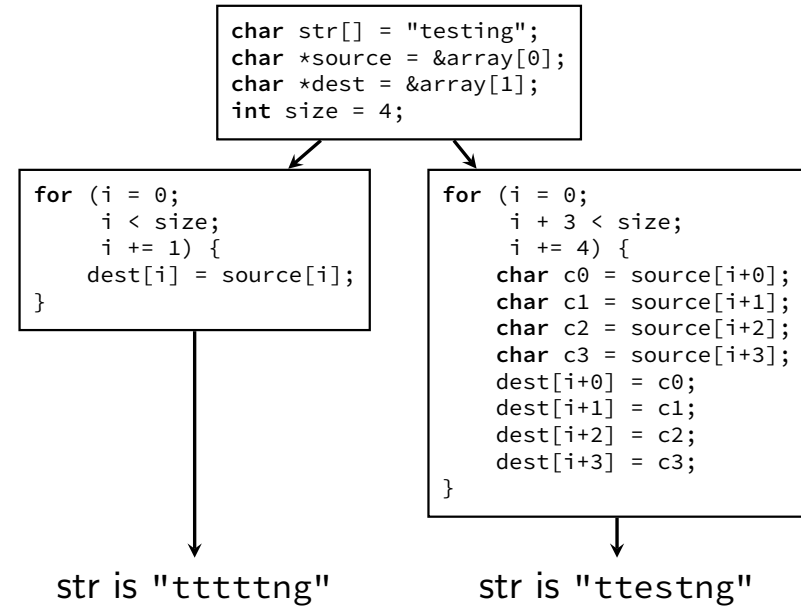
Loop Unrolling — Scheduling?

```
; $a0 = dest, $a1 = source, $a2 = i
lb $t0, 0($a1) ; load 0
lb $t1, 1($a1) ; load 1
lb $t2, 2($a1) ; load 2
lb $t3, 3($a1) ; load 3
sb $t0, 0($a0) ; store 0
sb $t1, 1($a0) ; store 1
sb $t2, 2($a0) ; store 2
sb $t3, 3($a0) ; store 3
addiu $a2, $a2, -1
bnez $a2, $a2, loop
```

Maybe faster — but not always the same!

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Aliasing



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Aliasing testing

```
if (source - dest > 0 && source - dest < 4) {
    for (i = 0; i + 3 < size; i += 4) {
        dest[i+0] = source[i+0]; dest[i+1] = source[i+1];
        dest[i+2] = source[i+2]; dest[i+3] = source[i+3];
    }
} else {
    for (i = 0; i + 3 < size; i += 4) {
        char c0 = source[i+0], c1 = source[i+1], c2 = source[i+2], c3 = sou
        dest[i+0] = c0; dest[i+1] = c1; dest[i+2] = c2; dest[i+3] = c3;
    }
}
for (; i < size; i += 1) {
    dest[i] = source[i];
}
```

even **bigger code size**

tricky for compilers

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Loop Unrolling: Register Pressure

better scheduling — **extra registers**

our example: 7 vs. 4 in original

generally — extra places to put results to hide

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Software Pipelining

Hide **memory latency** in loops

Load **earlier**

More time for arithmetic to catch up

Store **later**

Be sure arithmetic already finished

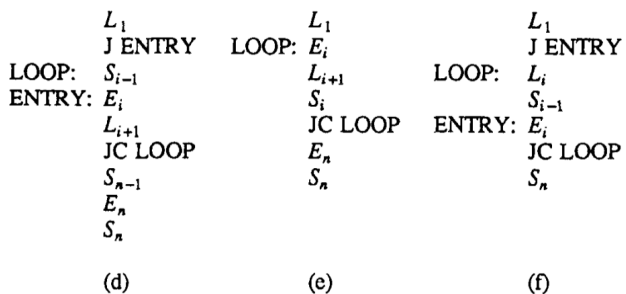
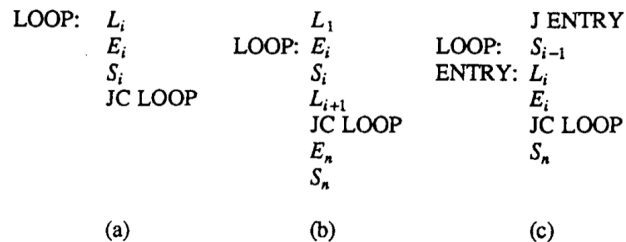
Instruction scheduling — across iterations

Splitting Loops

```

for (i = 0; i < size; i += 1) {
    a[i] += b[i] * c[i];
}
/* transforms into: */
for (i = 0; i < size; i += 1) {
    /* LOADS: */
    curA = a[i]
    curB = b[i];
    curC = c[i];
    /* EXECUTE: */
    curA += curB * curC;
    /* STORES: */
    a[i] = curA;
}
    
```

Rearranging



Order (e)

```

/* Load 1 */
curA = a[0]; curB = b[0]; curC = c[0];
for (i = 0; i < size - 1; i += 1) {
    /* Execute i */
    prevA = curA + curB * curC;
    /* Load i + 1 */
    curA = a[i + 1];
    /* Store i */
    a[i] = prevA;
}
prevA = curA + curB * curC;
a[i] = prevA;
    
```

Software Pipelining: Register Pressure

load $i + 1$ before storing i — **twice the registers!**

Decoupled Architecture

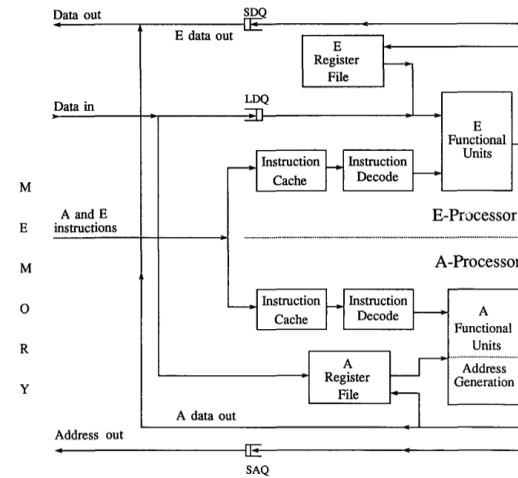


Fig. 5. A streamlined decoupled architecture.

idea: execute memory instructions independently
synchronize with **queues**

Decoupled Architecture Decomposition

```

/* Access Program */
for (i = 0; i < size - 1; i += 1) {
    EnqueueLoad(&a[i]);
    EnqueueLoad(&b[i]);
    EnqueueLoad(&c[i]);
    EnqueueStore(&a[i]);
}
/* Execute Program */
for (i = 0; i < size - 1; i += 1) {
    curA = DequeueLoad();
    curB = DequeueLoad();
    curC = DequeueLoad();
    EnqueueStore(curA + curB * curC);
}
    
```

Why bimodal: loops

```

for (int i = 0; i < 10000; i += 1) {
    ...
}

li $t0, 0 ; i ← 0
loop:
    ...
    addiu $t0, $t0, 1
    blt $t0, 10000, loop
    
```


Why bimodal: non-loops

```
char *data = malloc(...);  
if (!data) handleOutOfMemory();
```

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Why more than 1-bit?

```
for (int j = 0; j < 10000; ++j) {  
    for (int i = 0; i < 4; ++i) {  
        ...  
    }  
}
```

iteration	last taken	prediction	correct?
0	—	—	—
1	yes	taken	yes
2	yes	taken	yes
3	yes	taken	yes
4	yes	taken	no
5	no	not taken	no
6	yes	taken	yes

... ..

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Saturating counters (1)

```
for (int j = 0; j < 10000; ++j) {  
    for (int i = 0; i < 4; ++i) {  
        ...  
    }  
}
```

iteration	counter before	prediction	correct?
0	0?	—	—
1	1	taken	yes
2	2 (MAX)	taken	yes
3	2 (MAX)	taken	yes
4	2 (MAX)	taken	no
5	1	taken	yes
6	2 (MAX)	taken	yes

... ..

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Saturating counters (2)

```
for (int j = 0; j < 10000; ++j) {  
    for (int i = 0; ++i) {  
        ...  
        if (i == 3) break;  
    }  
}
```

iteration	counter before	prediction	correct?
0	0?	—	—
1	-1 (MIN)	not taken	yes
2	-1 (MIN)	not taken	yes
3	-1 (MIN)	not taken	yes
4	0	not taken	no
5	-1 (MIN)	not taken	yes
6	-1 (MIN)	not taken	yes

... ..

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Local history: loops

```
for (int j = 0; j < 10000; ++j) {
  for (int i = 0; i < 4; ++i) {
  }
}
```

observation: taken/not-taken pattern is
NNNTNNNTNNNT...

construct table:

prior five results	prediction
TNNNT	N
NTNNN	T
NNTNN	N
NNNTN	N

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Local history predictor

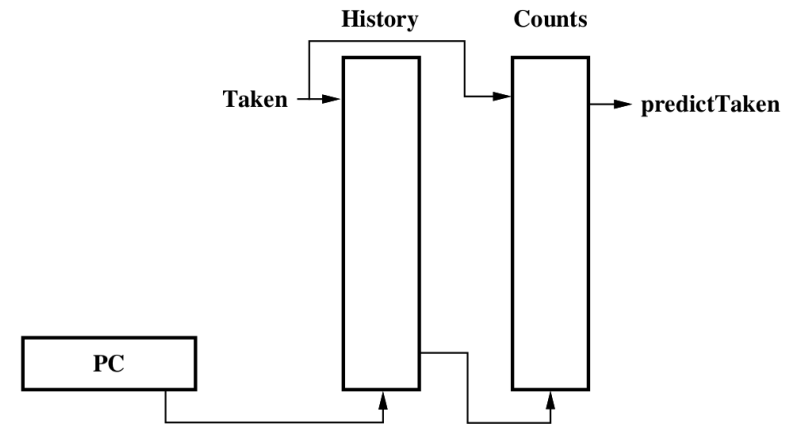


Figure 4: Local History Predictor Structure

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Global history

```
if (x >= 0) ...
if (x <= 0) ...
```

result for prior branches	prediction
...N	T
...T	N

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Global history identifies branches

```
for (i=0; i<100; i++)
  for (j=0; j<3; j++)
```

After the initial startup time, the conditional branches have the following behavior, assuming GR is shifted to the left:

test	value	GR	result
j<3	j=1	1101	taken
j<3	j=2	1011	taken
j<3	j=3	0111	not taken
i<100		1110	usually taken

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Global history predictor

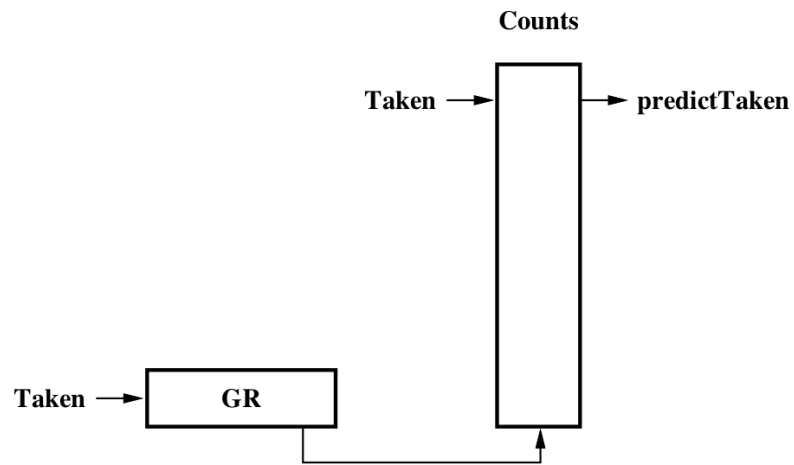


Figure 6: Global History Predictor Structure

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Combining local and global

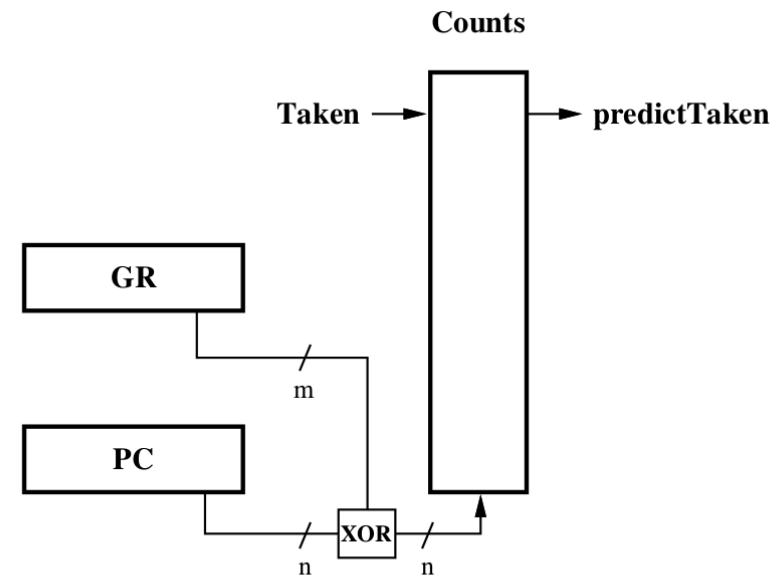


Figure 10: Global History Predictor with Index Sharing

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Combining generally

branch predictor predictor

counter per branch:

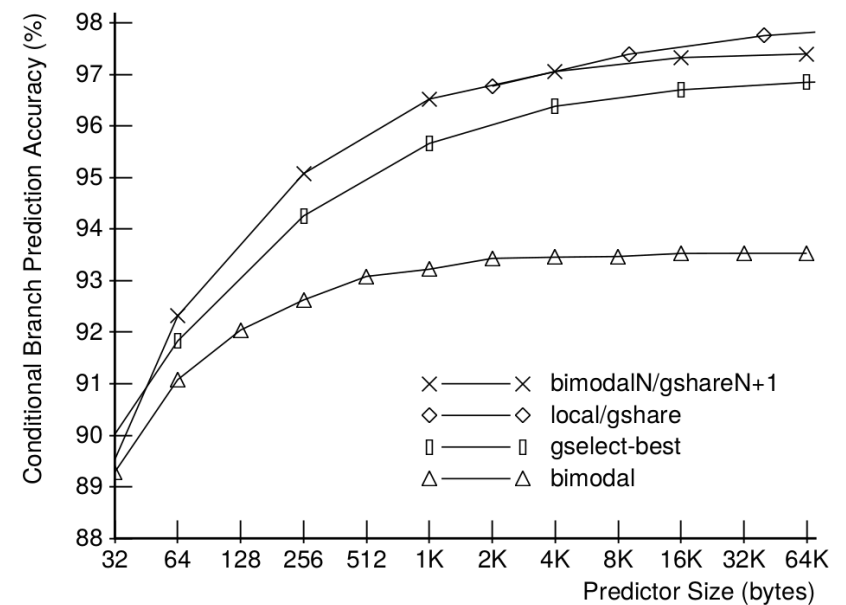
increment when first predictor is better
decrement when first predictor is worse

use first predictor if non-negative

2-bit saturating — predictor gets 'second chance'

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The experiments



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Return address stack

Predicting function call return addresses

Solution: **stack in processor registers**

baz saved registers
baz return address
bar saved registers
bar return address
foo local variables
foo saved registers
foo return address
foo saved registers

baz return address
bar return address
foo return address

shadow stack
in CPU registers

stack in memory

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Speculation: Loop termination prediction

Predicting loops with fixed iteration counts

Solution: **record last iteration count**

(times since change of branch result)

address	last # iters	current #
0x040102	128	98
...

```
for (int i = 0;
     i < 128;
     ++i) {
    ...
}
```

loop count table

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Speculation: More

register value prediction

will two loads/stores alias each other?

...

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Preview: Vectorization

single-instruction multiple-data

convert byte-oriented iteration:

```
lb $t0, 0($a1) ; load 0
lb $t1, 1($a1) ; load 1
lb $t2, 2($a1) ; load 2
lb $t3, 3($a1) ; load 3
sb $t0, 0($a0) ; store 0
sb $t1, 1($a0) ; store 1
sb $t2, 2($a0) ; store 2
sb $t3, 3($a0) ; store 3
```

into word (4-byte)-oriented

```
lw $t0, 0($a1) ; load 0-3
sw $t0, 0($a1) ; store 0-3
```

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Preview: Vectorization

single instruction multiple-data

```
x[i] *= y[i]; x[i+1] *= y[i+1];
```

can become (x86):

```
movupd (%rsi,%rcx,8), %xmm0 # xmm0 = {y[i],y[i+1]}
movupd (%rdi,%rcx,8), %xmm1 # xmm1 = {x[i],x[i+1]}
mulpd %xmm0, %xmm1 # xmm1 = {xmm0[0]*xmm1[0], xmm0[1]*xmm1[1]}
movupd %xmm1, (%rdi,%rcx,8) # {x[i],x[i+1]} = xmm1
```

instead of:

```
movsd (%rsi,%rcx,8), %xmm0 # xmm0 = y[i]
movsd (%rdi,%rcx,8), %xmm1 # xmm1 = x[i]
mulsd %xmm0, %xmm1 # xmm1 = xmm0*xmm1
movsd %xmm1, (%rdi,%rcx,8) # x[i] = xmm1
movsd 8(%rsi,%rcx,8), %xmm0 # xmm0 = y[i+1]
movsd 8(%rdi,%rcx,8), %xmm1 # xmm1 = x[i+1]
mulsd %xmm0, %xmm1 # xmm1 = xmm0*xmm1
movsd %xmm1, 8(%rdi,%rcx,8) # x[i+1] = xmm1
```

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Modern vectorization

many more functional units (e.g. multipliers)

only accessible using vectorized interfaces

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Next time

starting multiple instructions at the same time

intuition: multiple copies of pipeline

to start: **scheduled by compiler**

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