

CS 4102: Algorithms

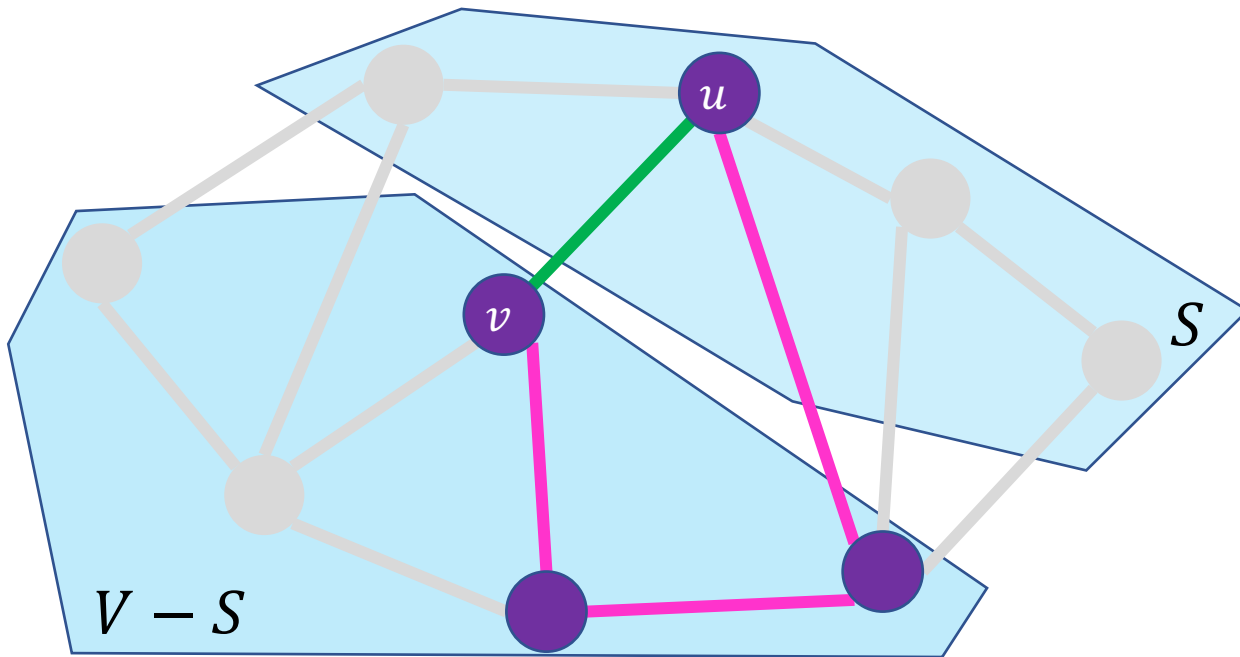
Lecture 20: Shortest Path Algorithms

David Wu

Fall 2019

Warm-Up

Show that no cycle crosses a cut exactly once



- Consider an edge $e = (u, v)$ that crosses the cut
- After removing the edge e from the graph, there is still a **path** from $u \in S$ to $v \notin S$
- At least one edge along the **path** from cross the cut

Today's Keywords

Graphs

Shortest paths algorithms

Dijkstra's algorithm

Breadth-first search (BFS)

CLRS Readings: Chapter 22, 23

Homework

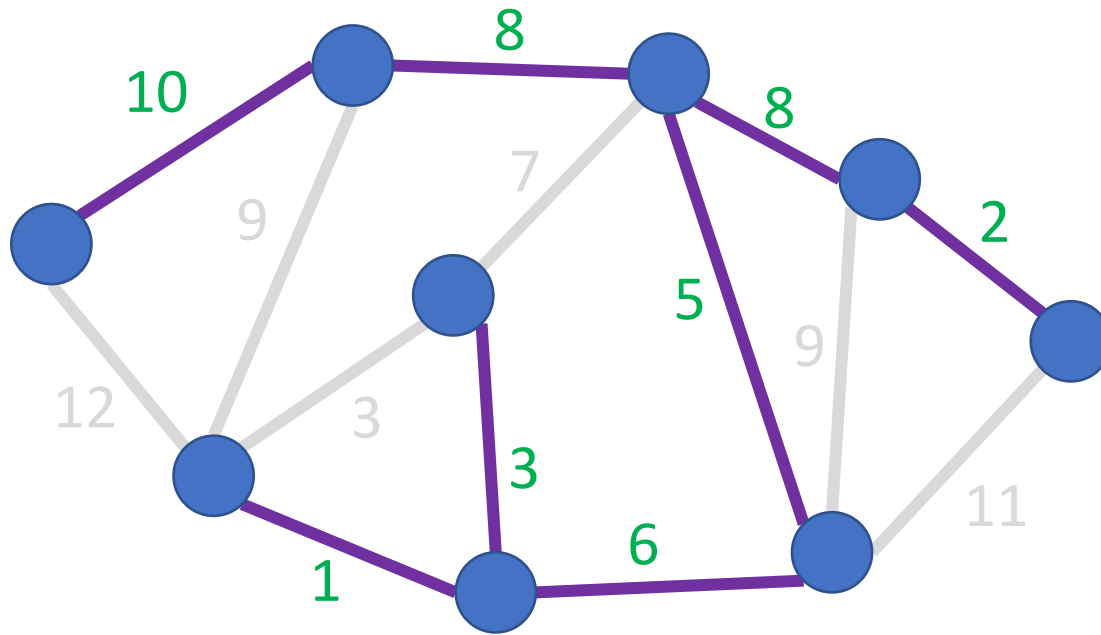
HW7 due Thursday, November 14, 11pm

- Graph algorithms
- Written (use LaTeX!) – Submit both zip and **pdf** (two separate attachments)!

HW10B also out today, due Thursday, November 14, 11pm

- No late submissions allowed (no exceptions)

Minimum Spanning Tree

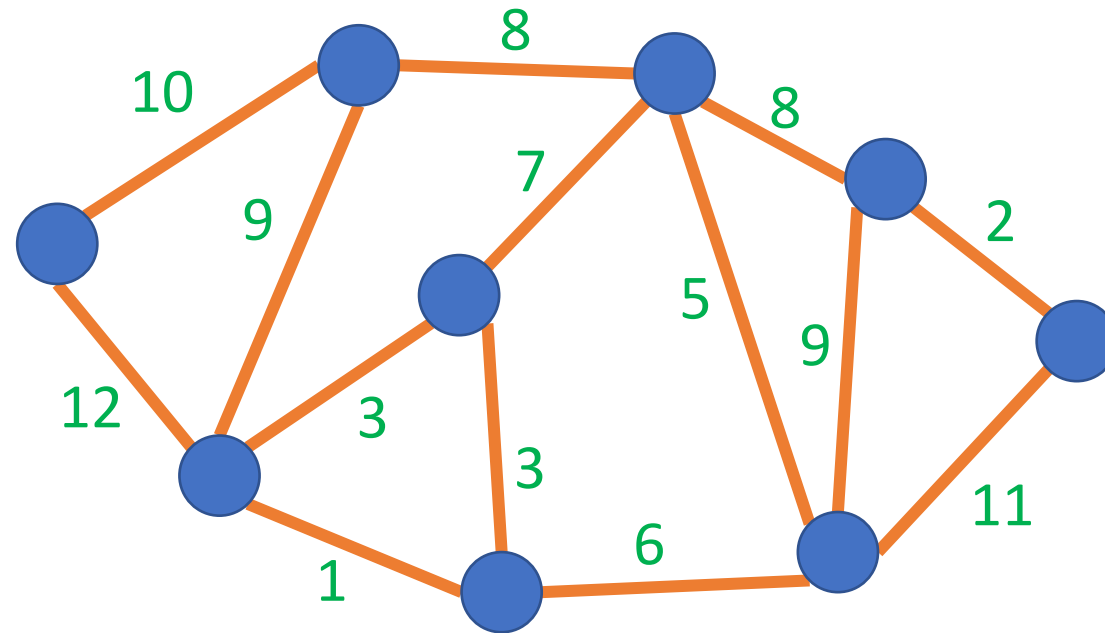


$$\text{Cost}(T) = \sum_{e \in E_T} w(e)$$

A tree $T = (V_T, E_T)$ is a **minimum spanning tree** for an undirected graph $G = (V, E)$ if T is a spanning tree of minimal cost

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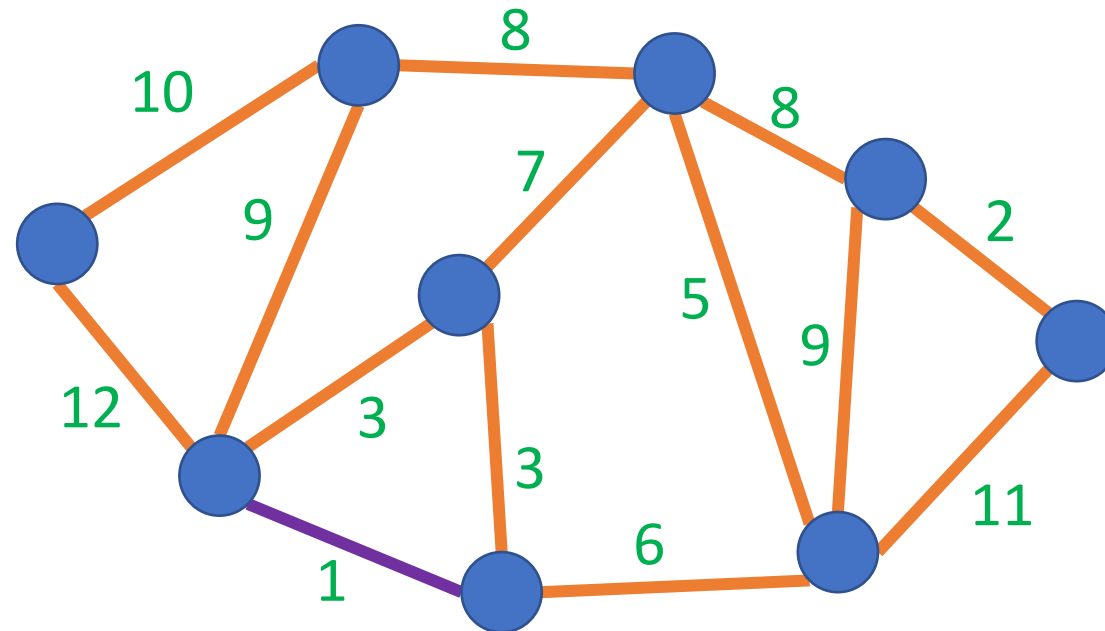
Two greedy algorithms:



Kruskal: add minimum-weight edge that does not introduce a cycle

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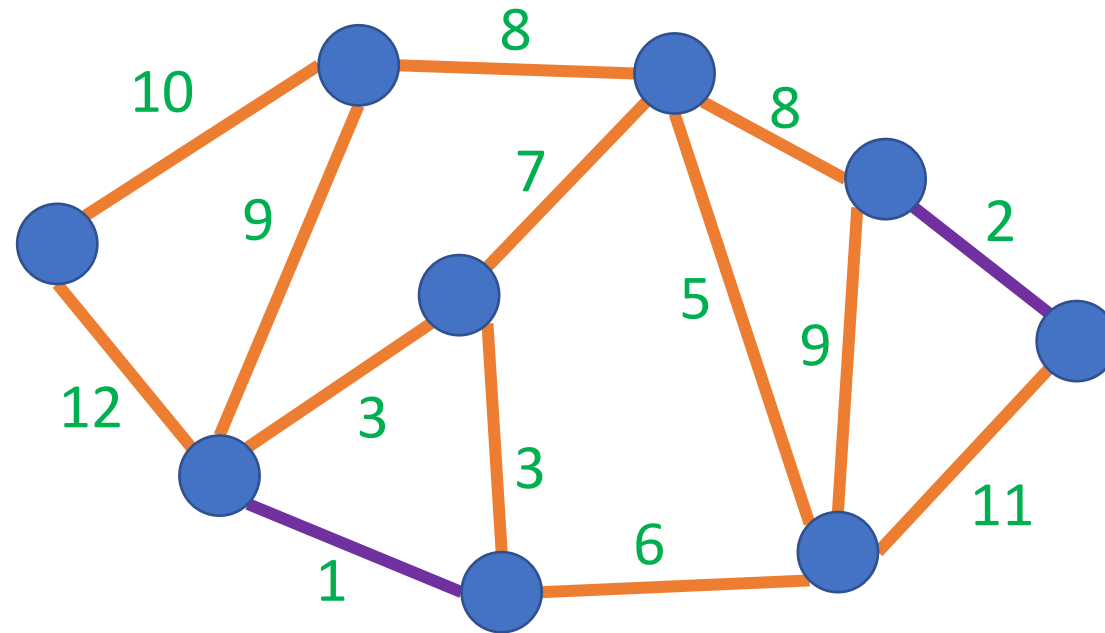
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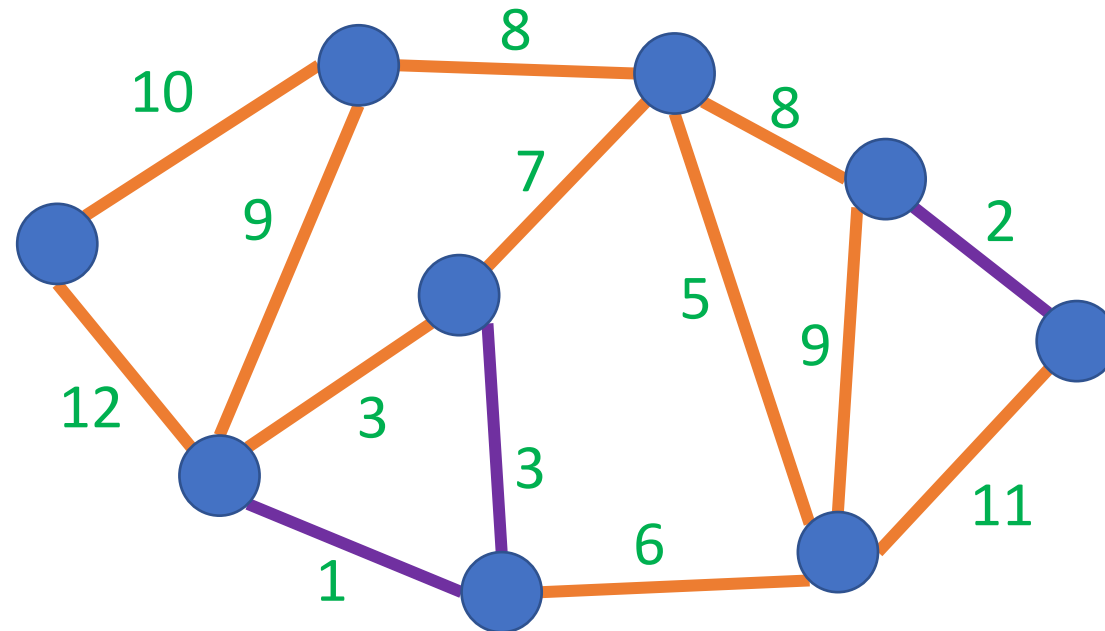
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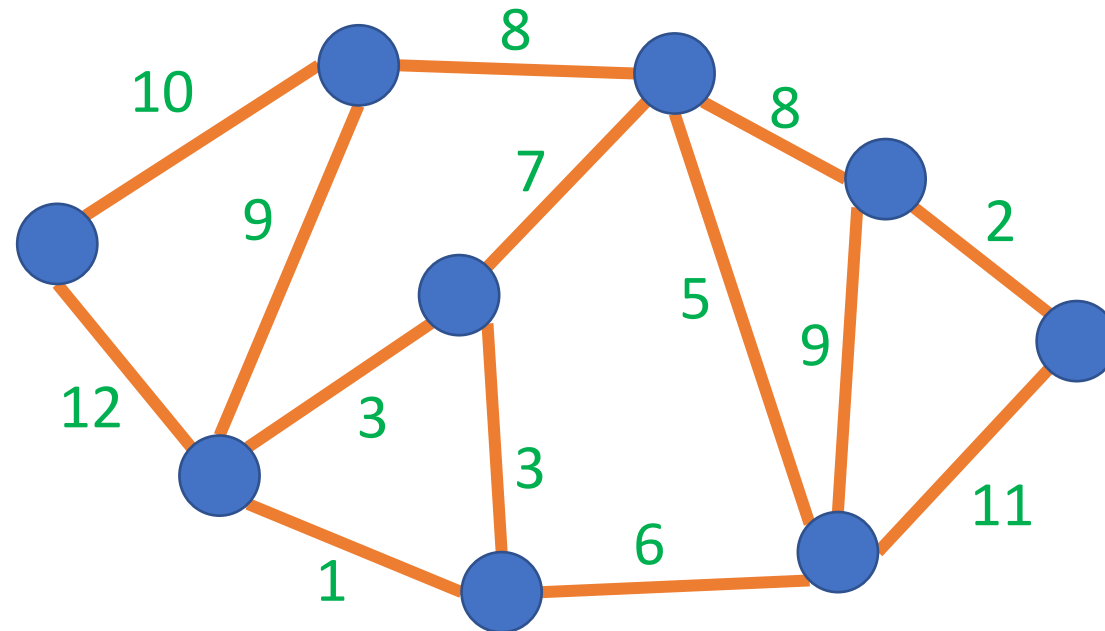
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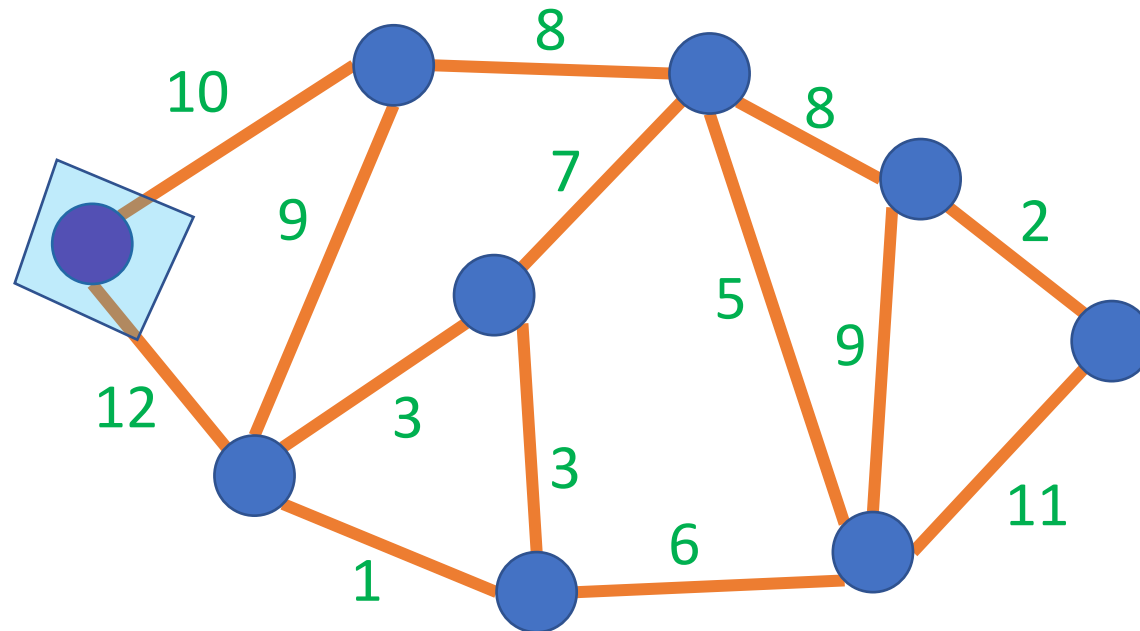
Two greedy algorithms:



Prim: “grow” a tree by adding minimum-weight edge from the tree to an external node

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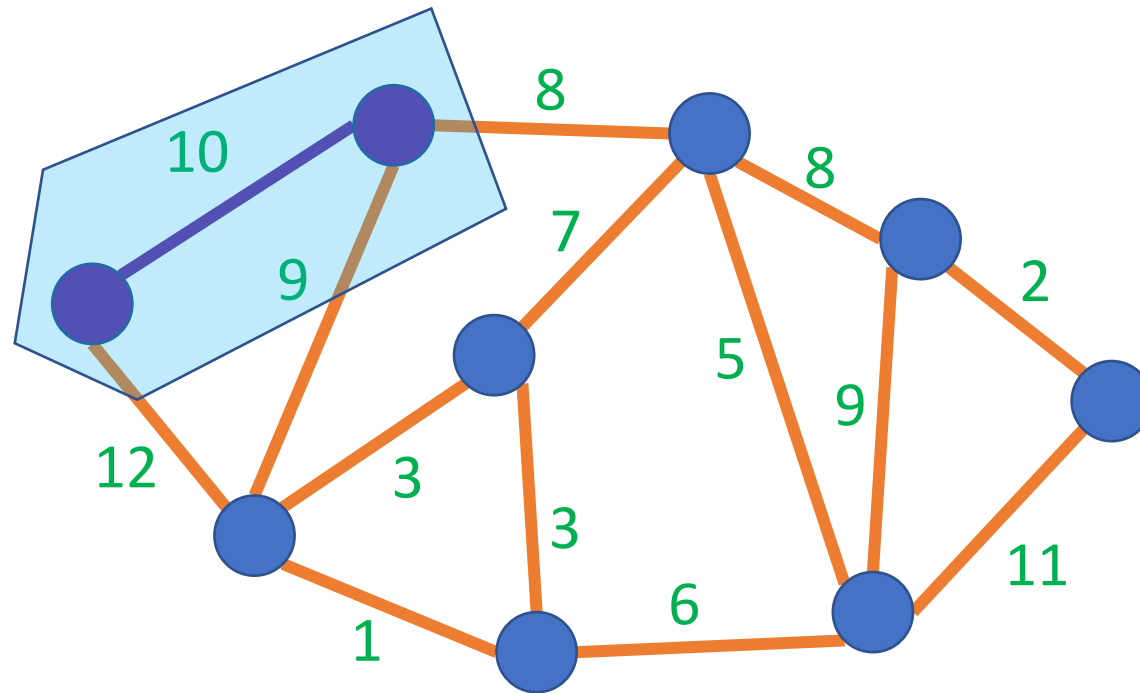
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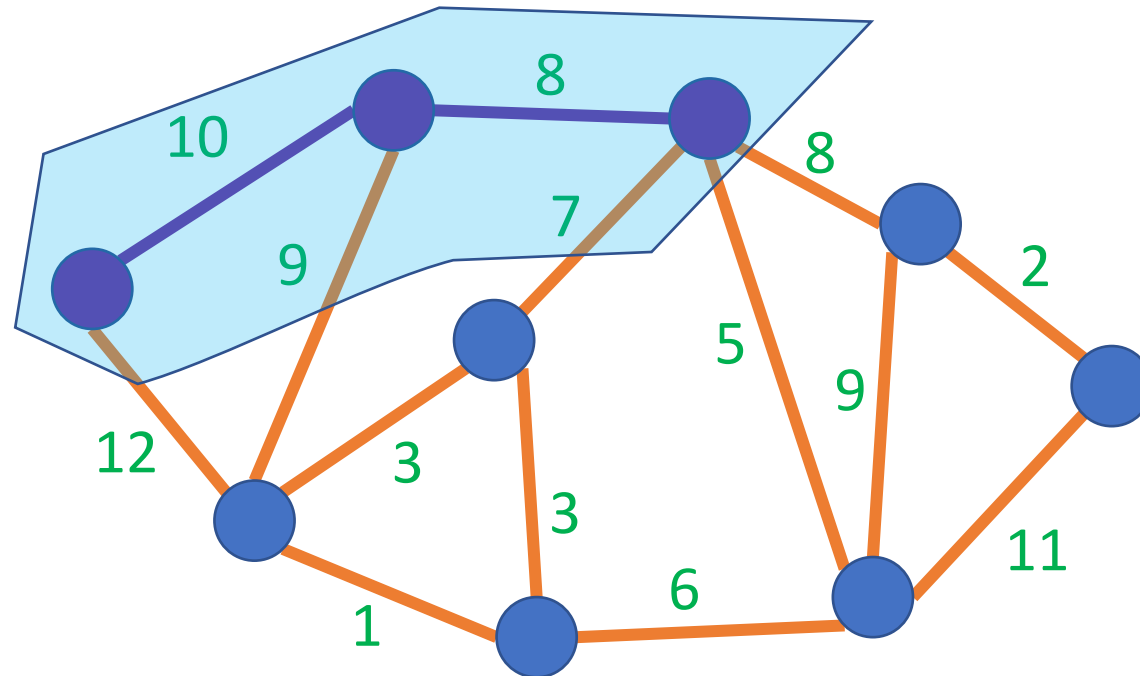
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Prim's Algorithm Implementation

1. Start with an empty tree T and pick a start node and add it to T
2. Repeat $|V| - 1$ times:
 - Add the min-weight edge which connects a node in T with a node not in T

Implementation (with nodes in the priority queue):

initialize $d_v = \infty$ for each node v

add all nodes $v \in V$ to the priority queue PQ, using d_v as the key

pick a starting node s and set $d_s = 0$

while PQ is not empty:

$v = \text{PQ.extractMin}()$

for each $u \in V$ such that $(v, u) \in E$:

if $u \in \text{PQ}$ and $w(v, u) < d_u$:

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$u.\text{parent} = v$

each node also maintains a parent, initially NULL

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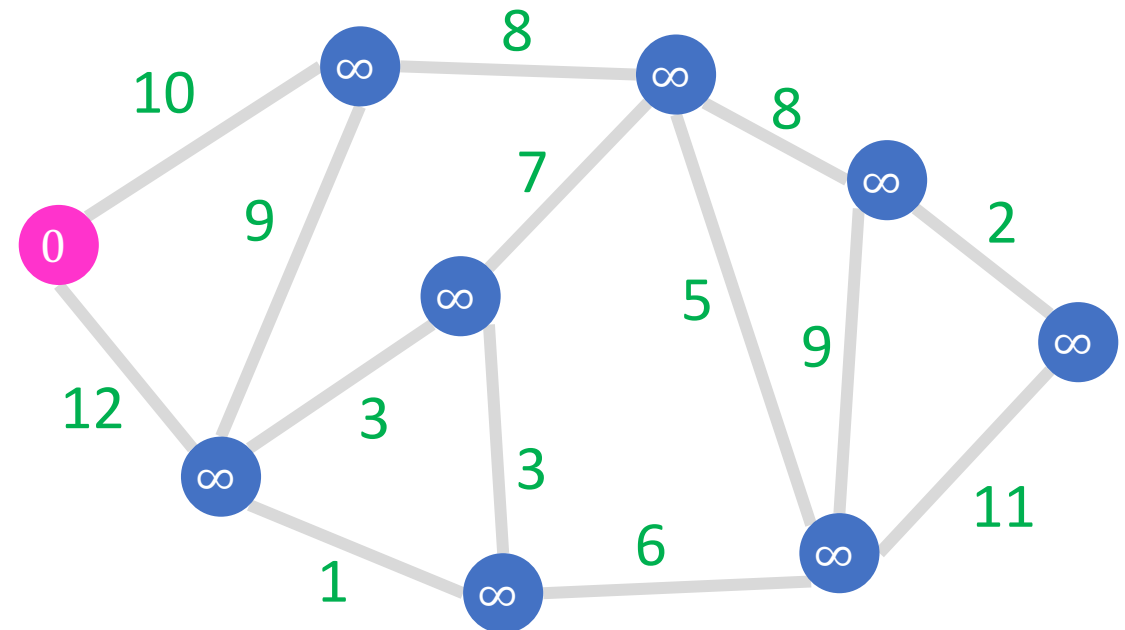
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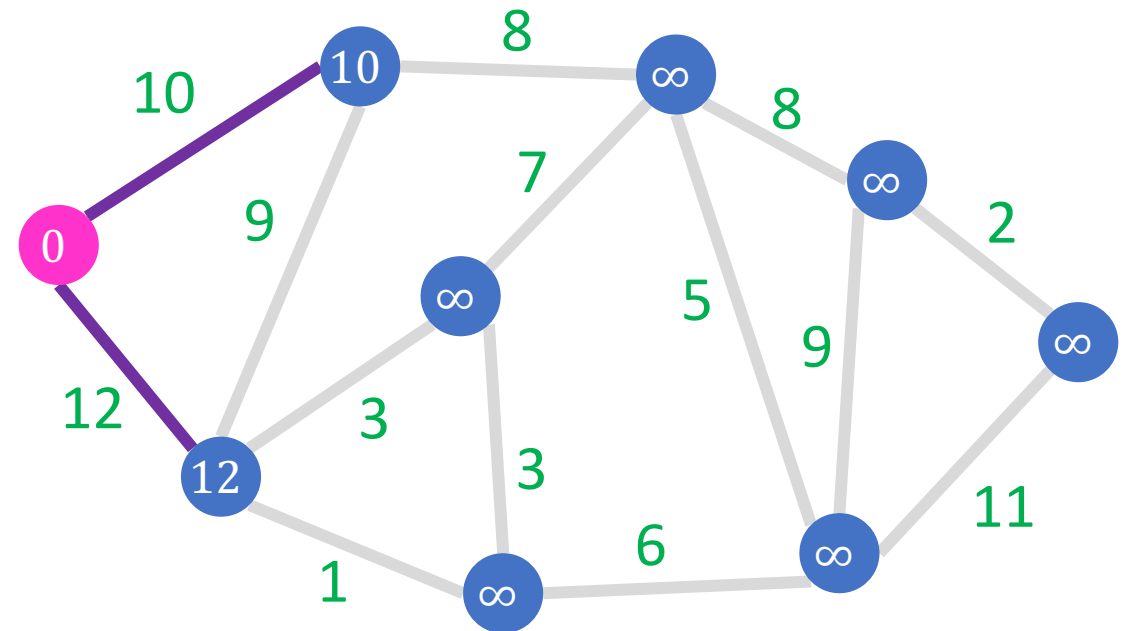
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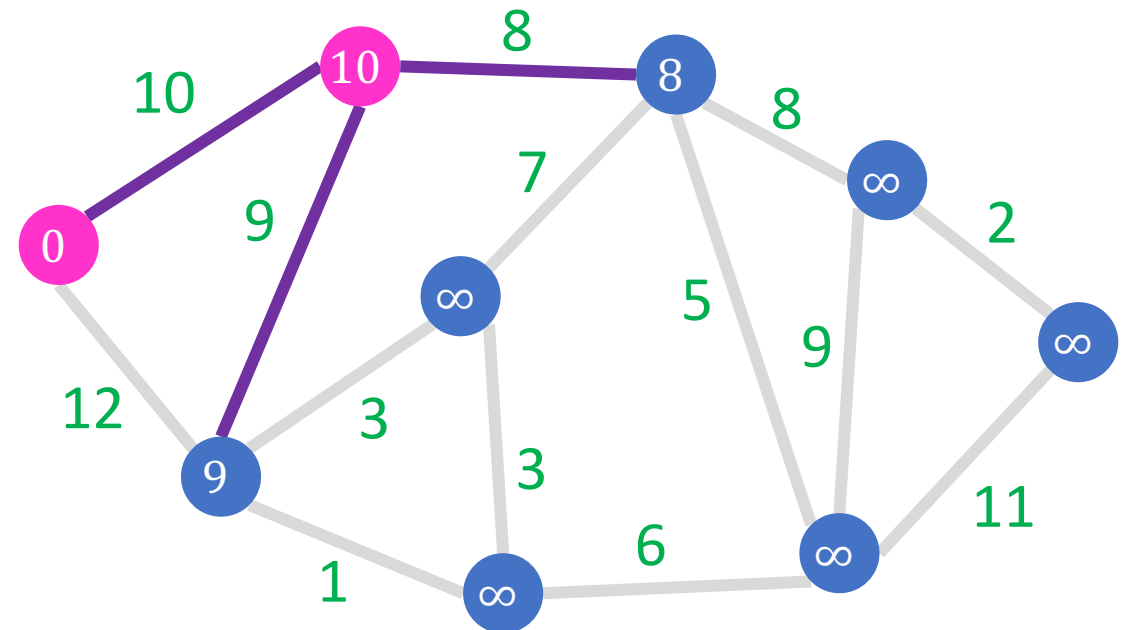
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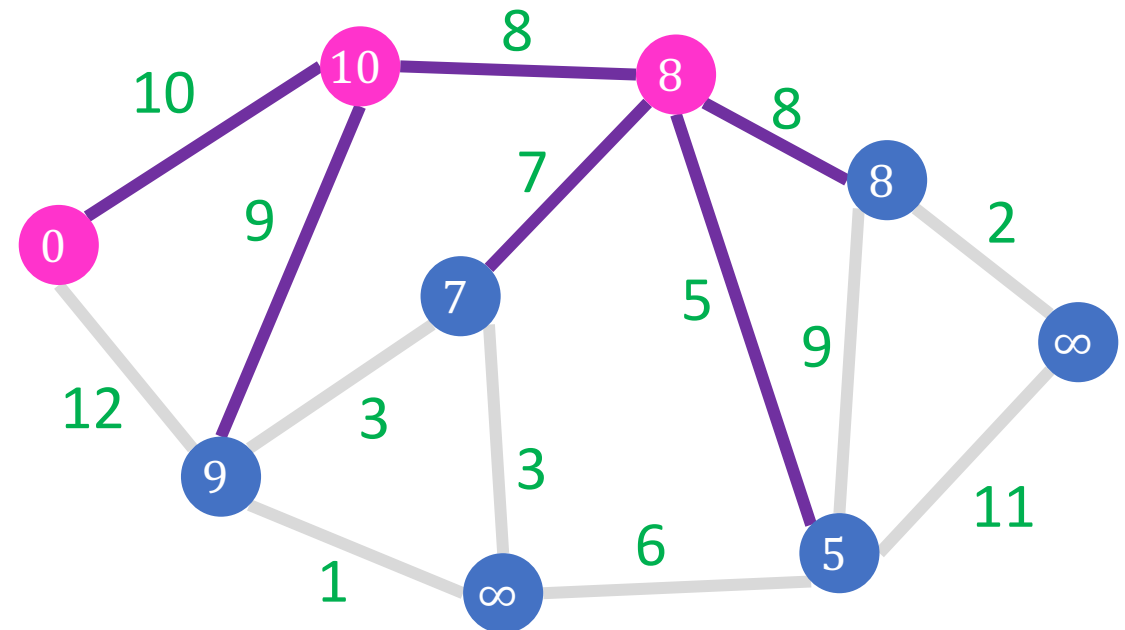
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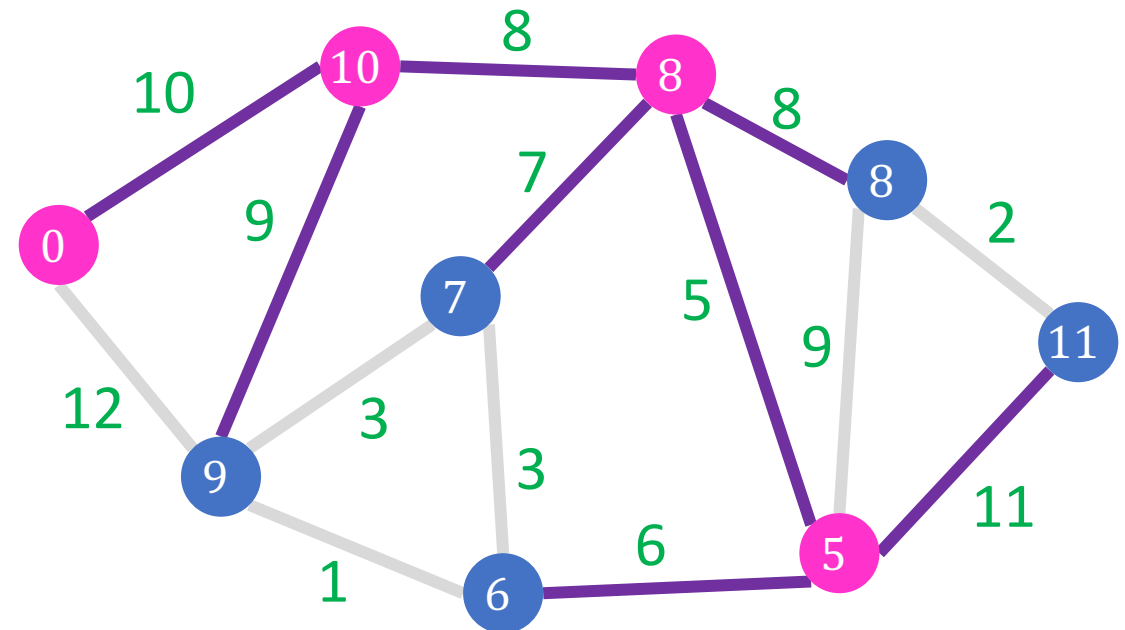
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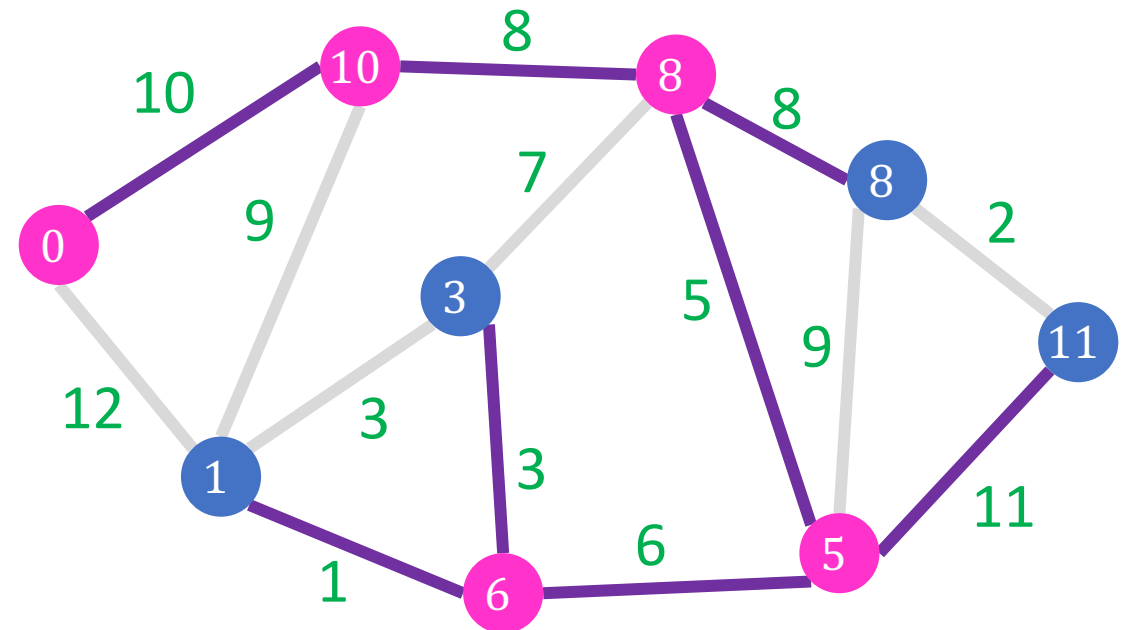
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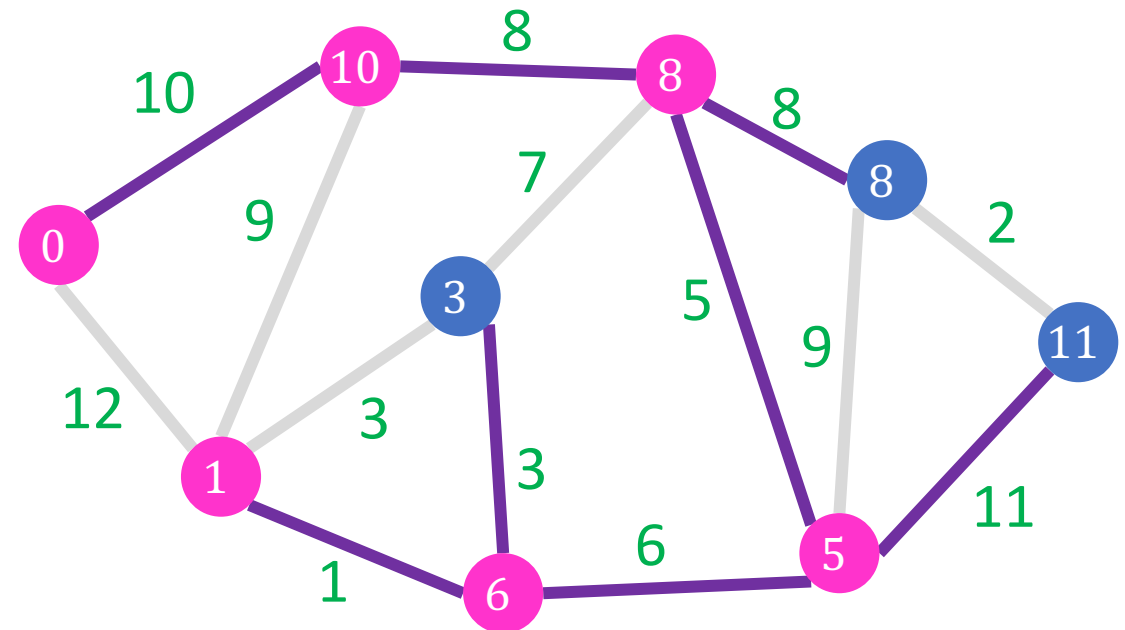
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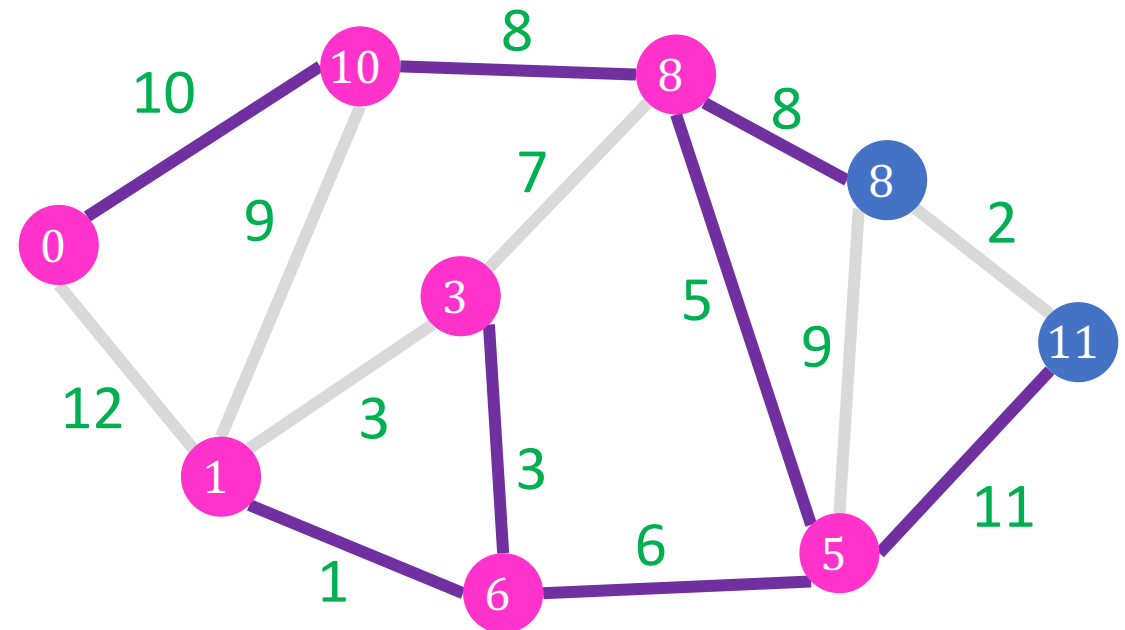
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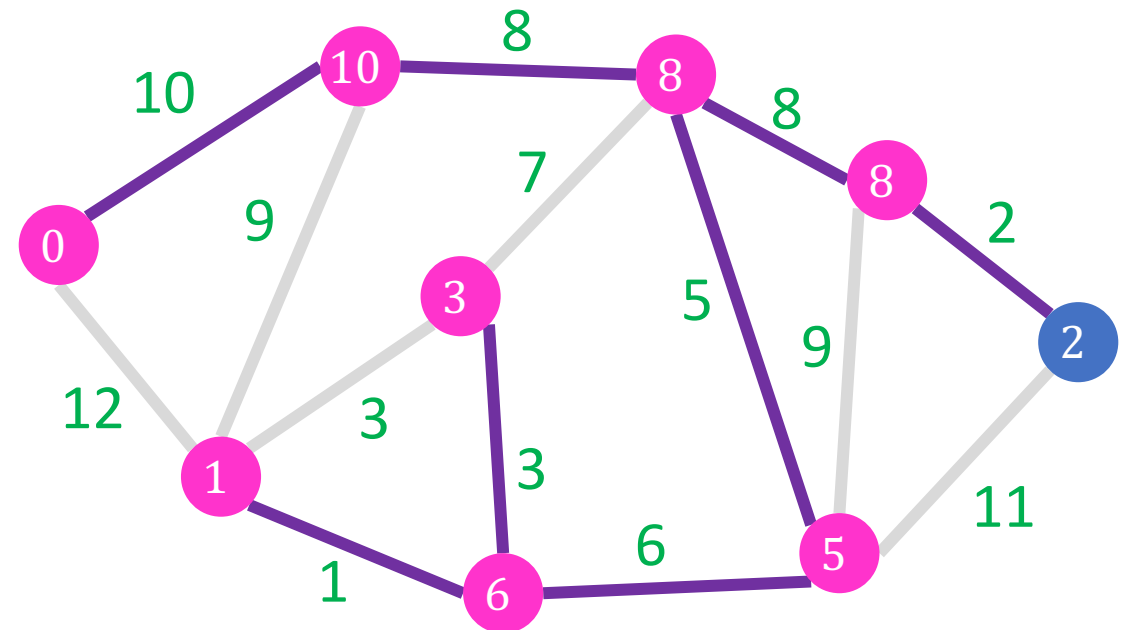
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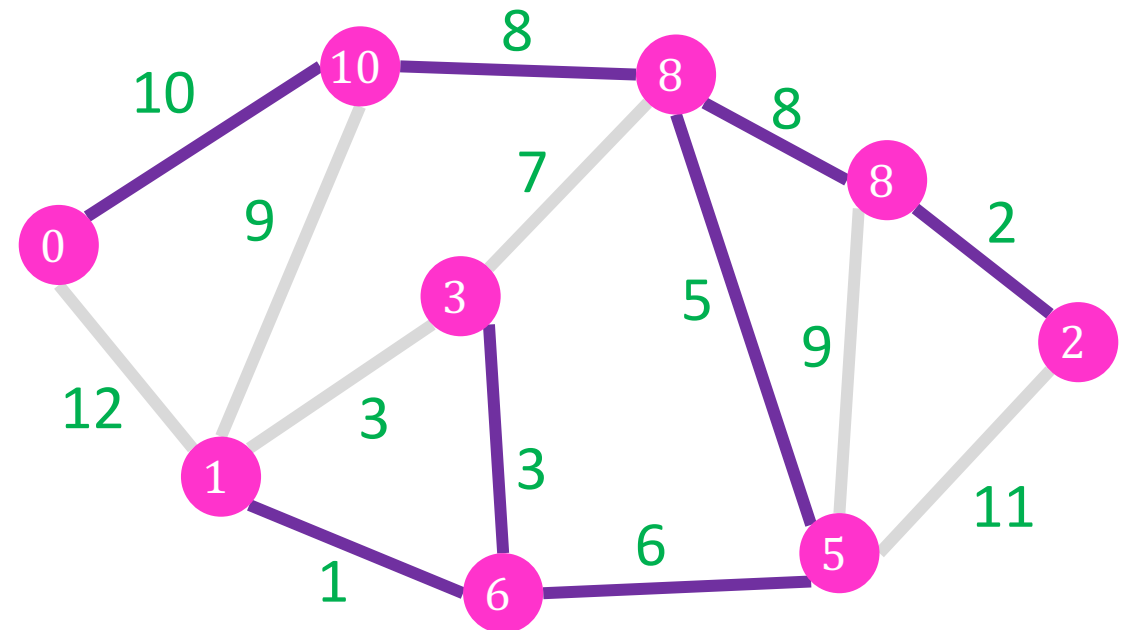
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Initialization:

$O(|V|)$

$|V|$ iterations

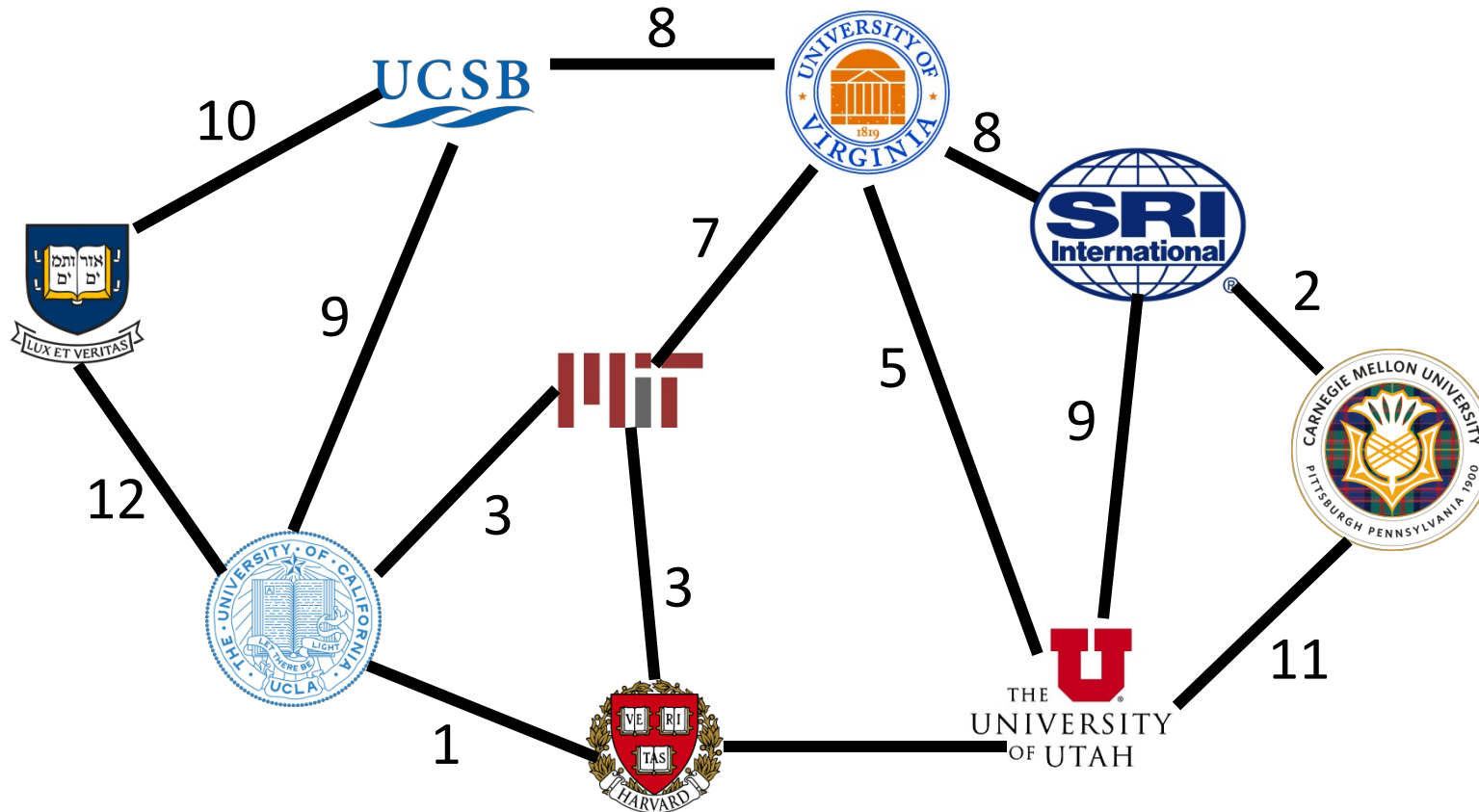
$O(\log|V|)$

$|E|$ iterations total

$O(\log|V|)$

Overall running time: $O(|V| \log|V| + |E| \log|V|) = O(|E| \log|V|)$

Single-Source Shortest Path



Find the shortest path from UVA to each of these other places

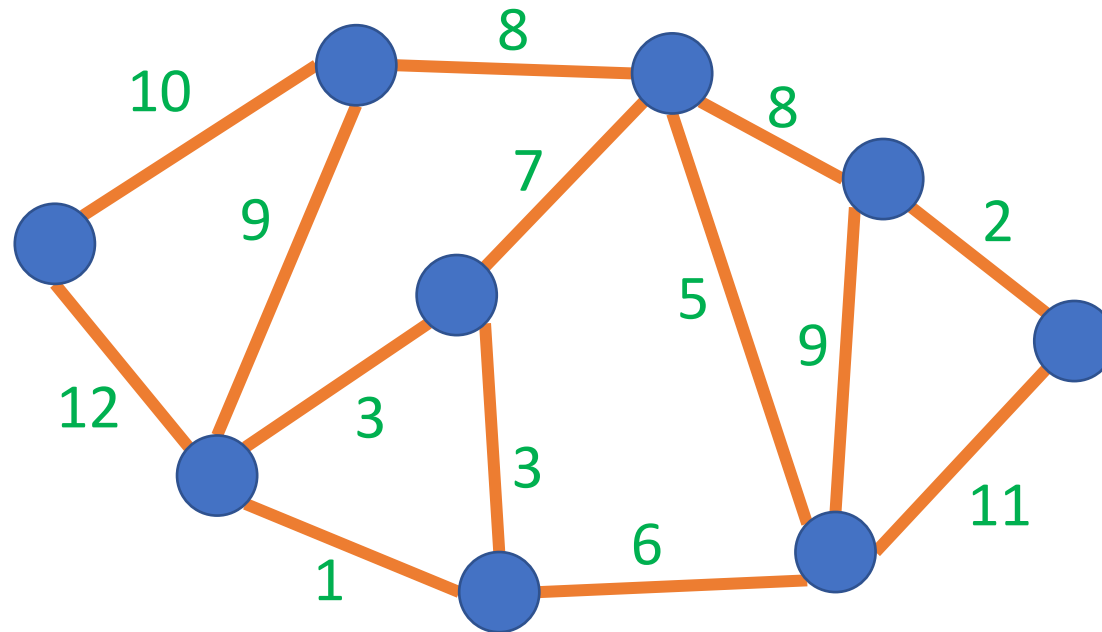
Given a graph $G = (V, E)$ and a start node (i.e., source) $s \in V$,

for each $v \in V$ find the minimum-weight path from $s \rightarrow v$ (call this weight $\delta(s, v)$)

Assumption (for now): all edge weights are positive

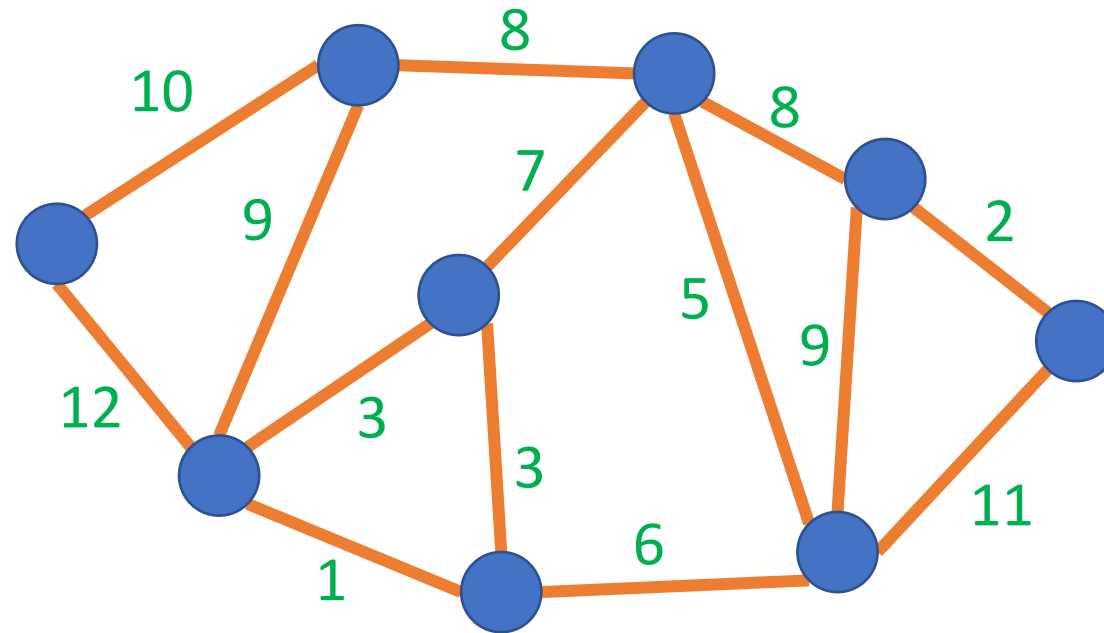
Dijkstra's Algorithm

1. Start with an empty tree T and add the source to T
2. Repeat $|V| - 1$ times:
 - Add the “nearest” node not yet in T to T



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key: length of shortest path $s \rightarrow u$ using nodes in PQ

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key: minimum cost to connect u to nodes in PQ

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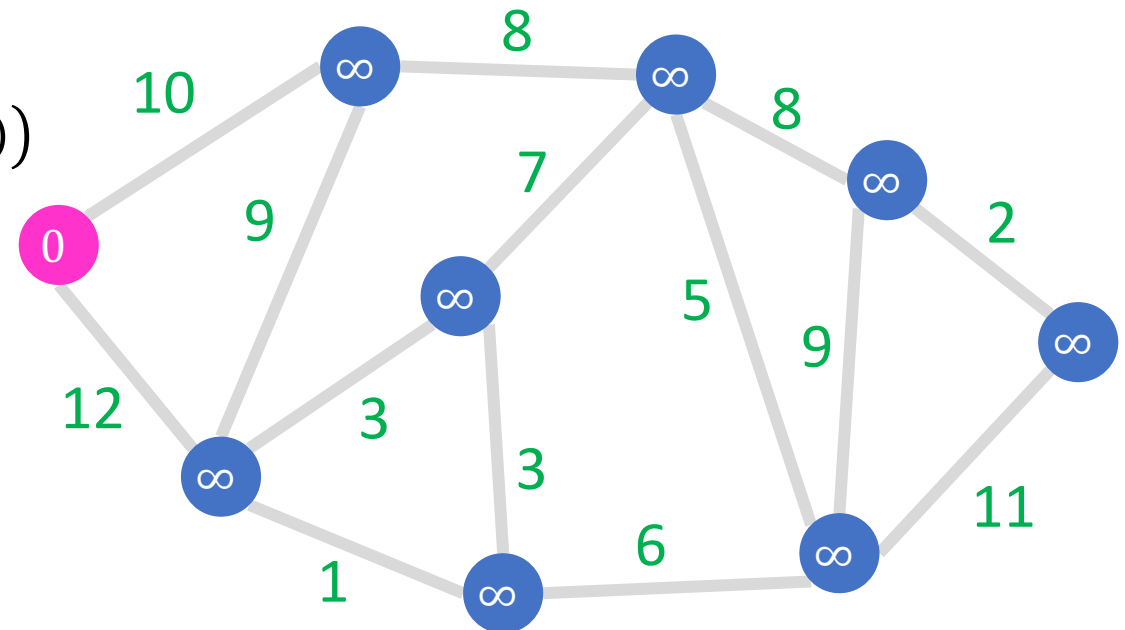
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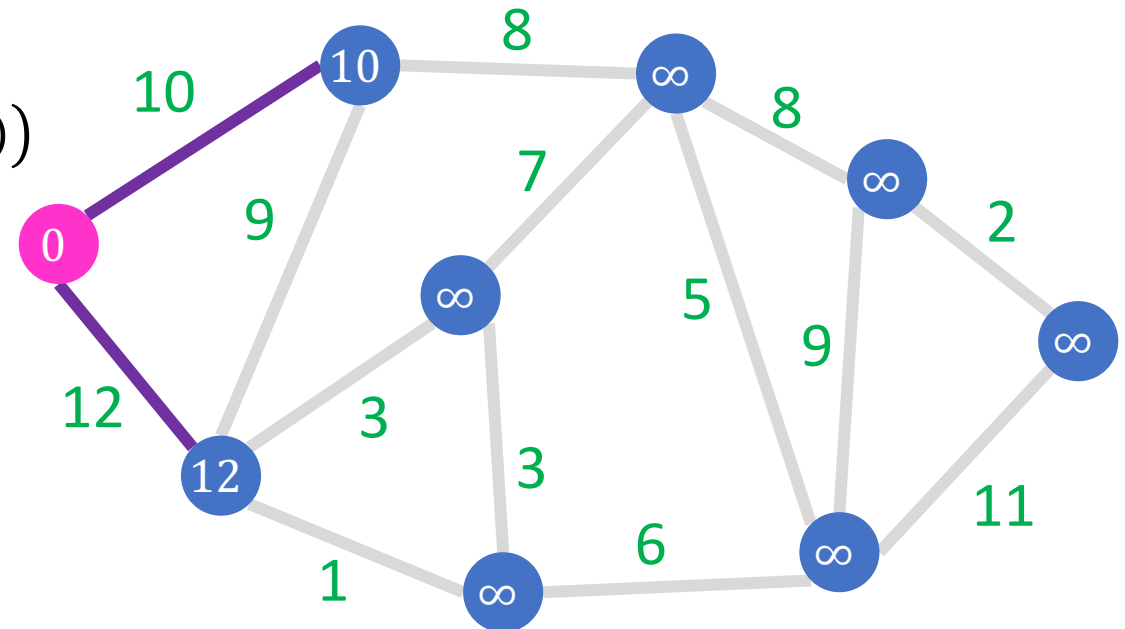
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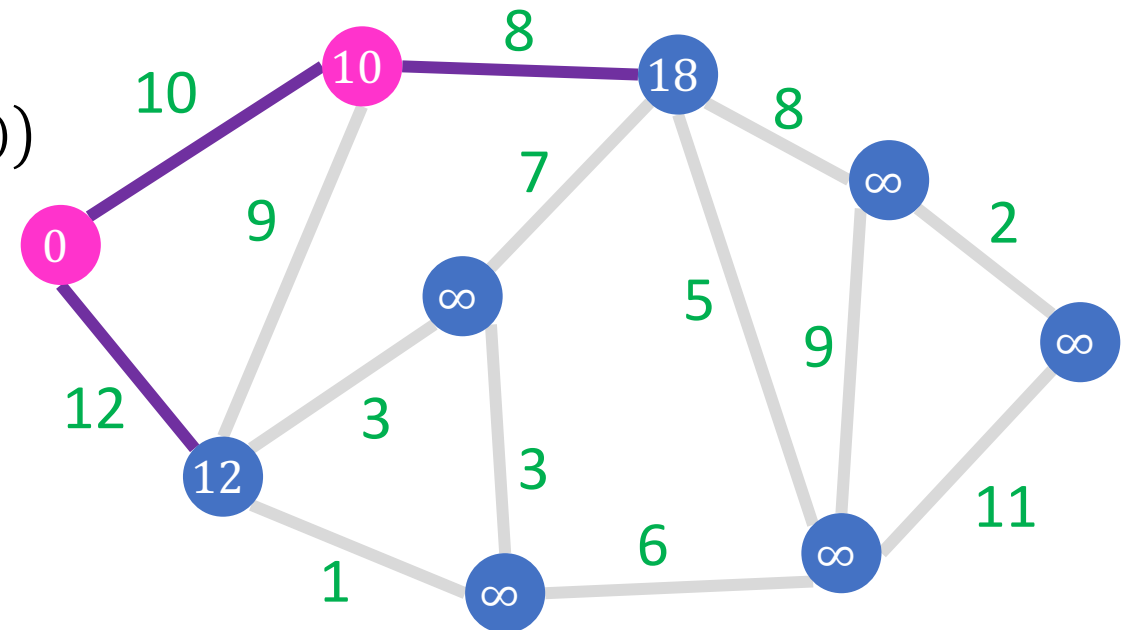
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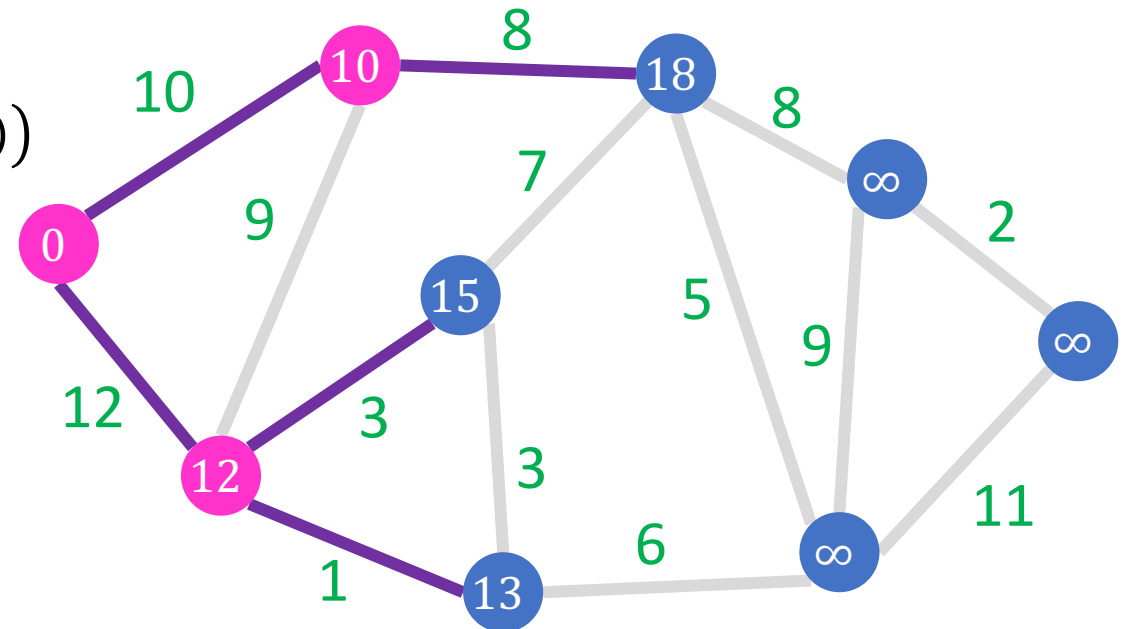
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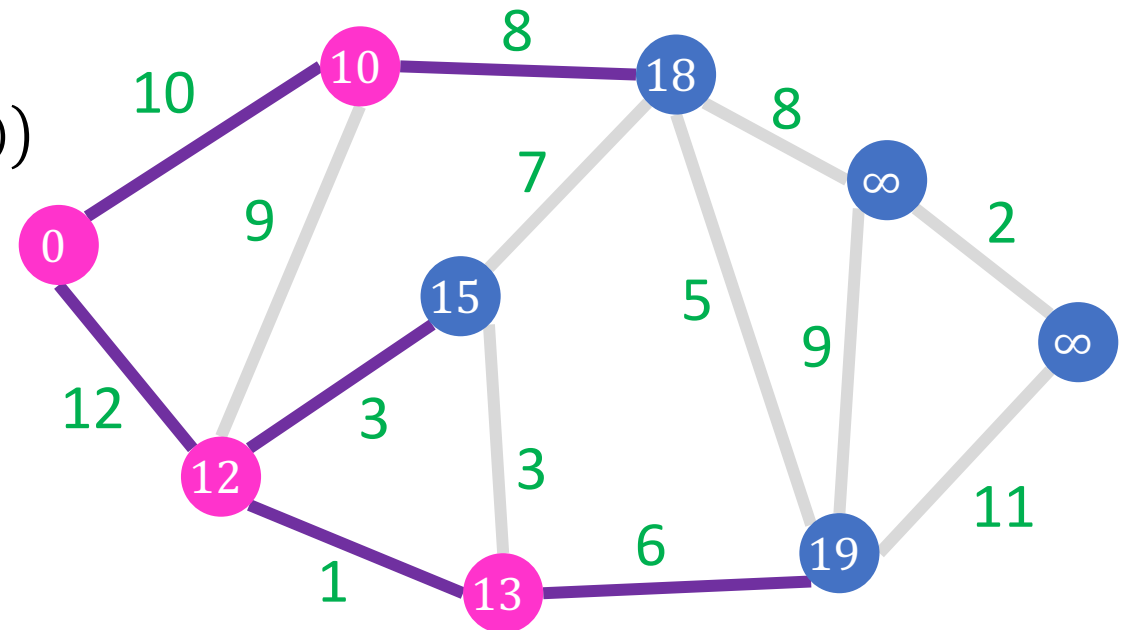
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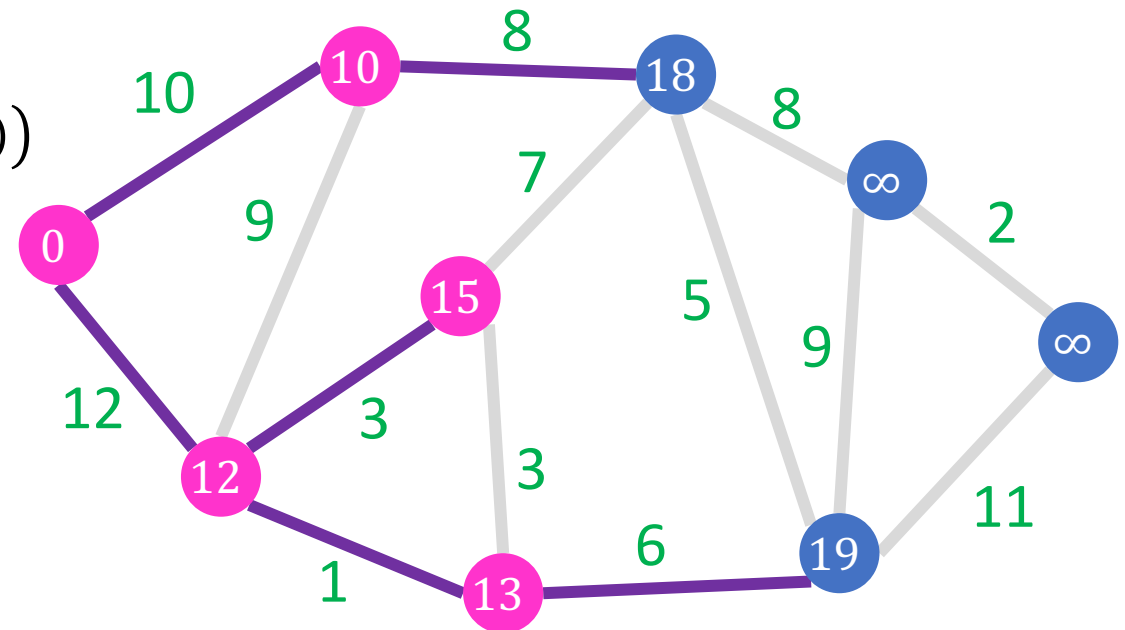
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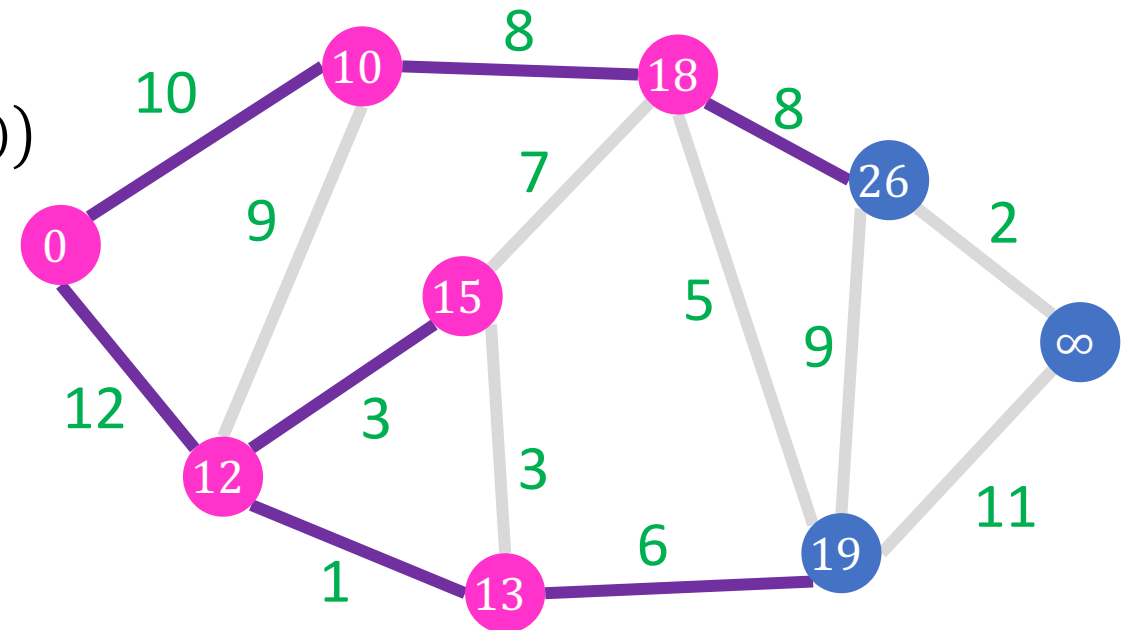
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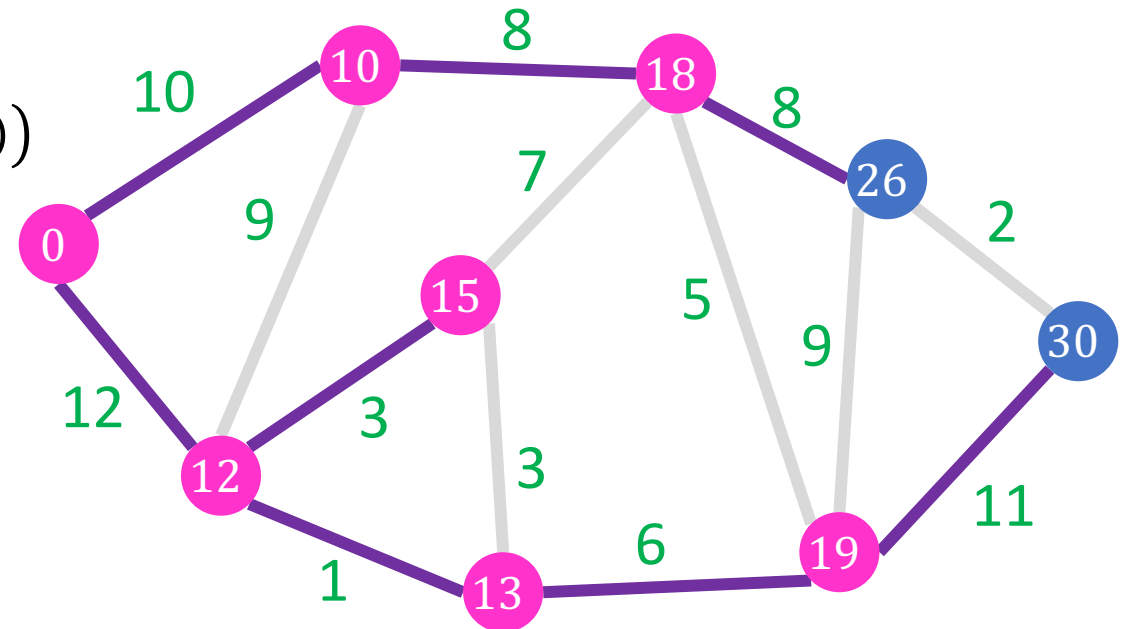
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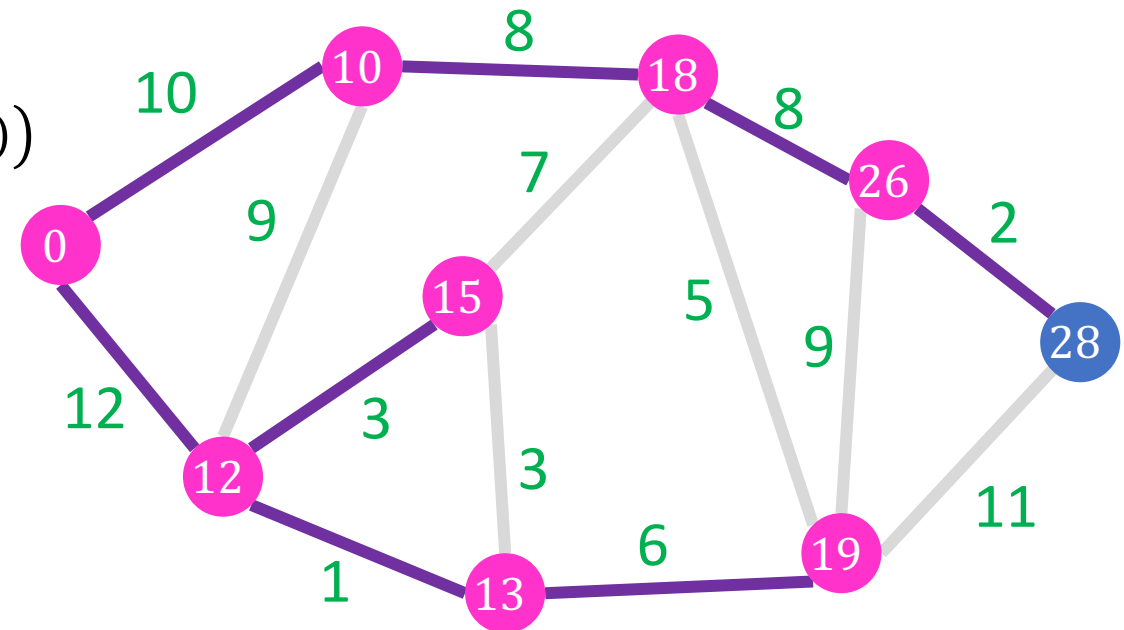
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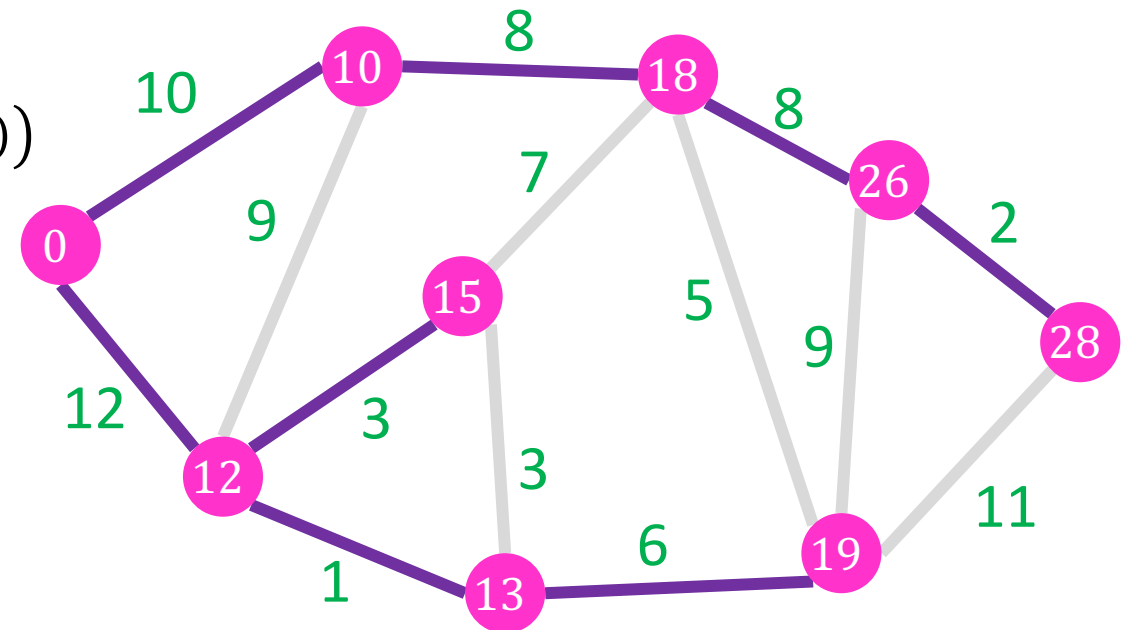
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PQ.decreaseKey($u, d_v + w(v, u)$)

$u.\text{parent} = v$

Every subpath of a shortest path is itself a shortest path (optimal substructure)

Observe: shortest paths from a source forms a tree, but **not** a minimum spanning tree



Dijkstra's Algorithm Running Time

Implementation:

initialize $d_v = \infty$ for each node v

add all nodes $v \in V$ to the priority queue PQ, using d_v as the key

set $d_s = 0$

while PQ is not empty:

$v = \text{PQ.extractMin}()$

 for each $u \in V$ such that $(v, u) \in E$:

 if $u \in \text{PQ}$ and $d_v + w(v, u) < d_u$:

$\text{PQ.decreaseKey}(u, d_v + w(v, u))$

$u.\text{parent} = v$

Initialization:

$O(|V|)$

$|V|$ iterations

$O(\log|V|)$

$|E|$ iterations total

$O(\log|V|)$

Overall running time: $O(|V| \log|V| + |E| \log|V|) = O(|E| \log|V|)$

Dijkstra's Algorithm Proof Strategy

Proof by induction

Proof Idea: we will show that when node u is removed from the priority queue, $d_u = \delta(s, u)$

- **Claim 1:** There is a path of length d_u (as long as $d_u < \infty$) from s to u in G
- **Claim 2:** For every path (s, \dots, u) , $w(s, \dots, u) \geq d_u$

Correctness of Dijkstra's Algorithm

Inductive hypothesis: Suppose that nodes $v_1 = s, \dots, v_i$ have been removed from PQ, and for each of them $d_{v_i} = \delta(s, v_i)$, and there is a path from s to v_i with distance d_{v_i} (whenever $d_{v_i} < \infty$)

Base case:

- $i = 0: v_1 = s$
- Claim holds trivially

Correctness of Dijkstra's Algorithm: Claim 1

Let u be the $(i + 1)^{\text{st}}$ node extracted

Claim 1: There is a path of length d_u (as long as $d_u < \infty$) from s to u in G

Proof:

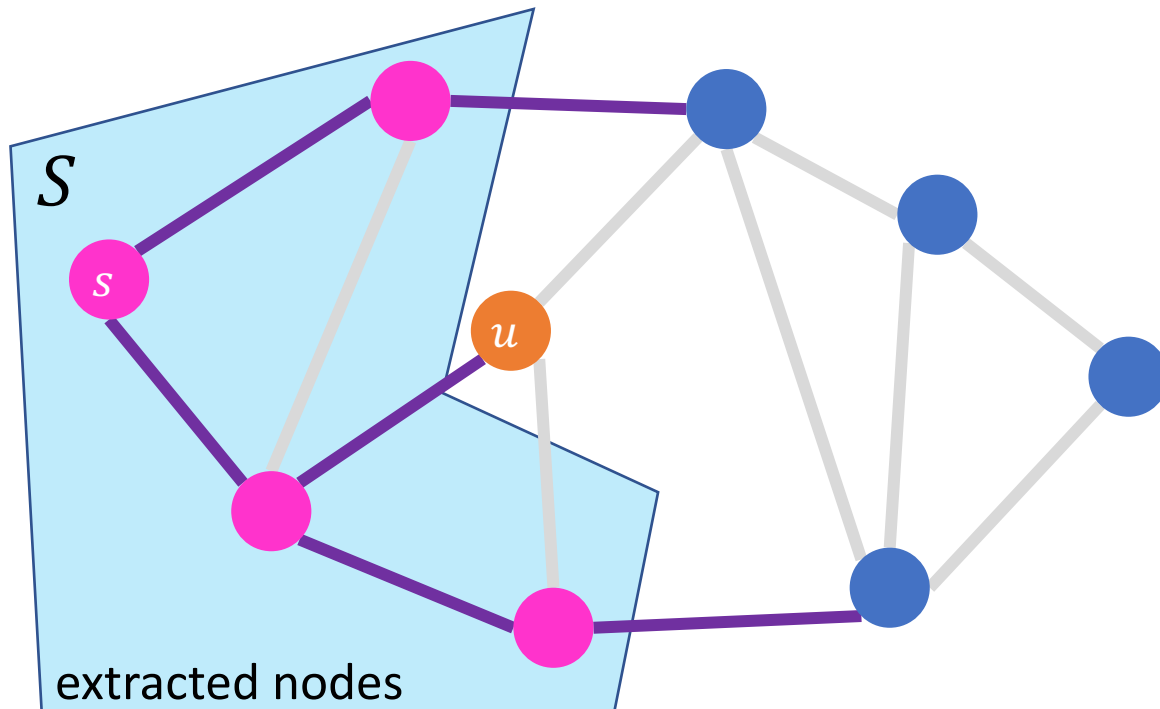
- Suppose $d_u < \infty$
- This means that PQ. decreaseKey was invoked on node u on an earlier iteration
- Consider the last time PQ. decreaseKey is invoked on node u
- PQ. decreaseKey is only invoked when there exists an edge $(v, u) \in E$ and node v was extracted from PQ in a previous iteration
- In this case, $d_u = d_v + w(v, u)$
- By the inductive hypothesis, there is a path $s \rightarrow v$ of length d_v in G and since there is an edge $(v, u) \in E$, there is a path $s \rightarrow u$ of length d_u in G

Correctness of Dijkstra's Algorithm: Claim 2

Let u be the $(i + 1)^{\text{st}}$ node extracted

Claim 2: For every path (s, \dots, u) , $w(s, \dots, u) \geq d_u$

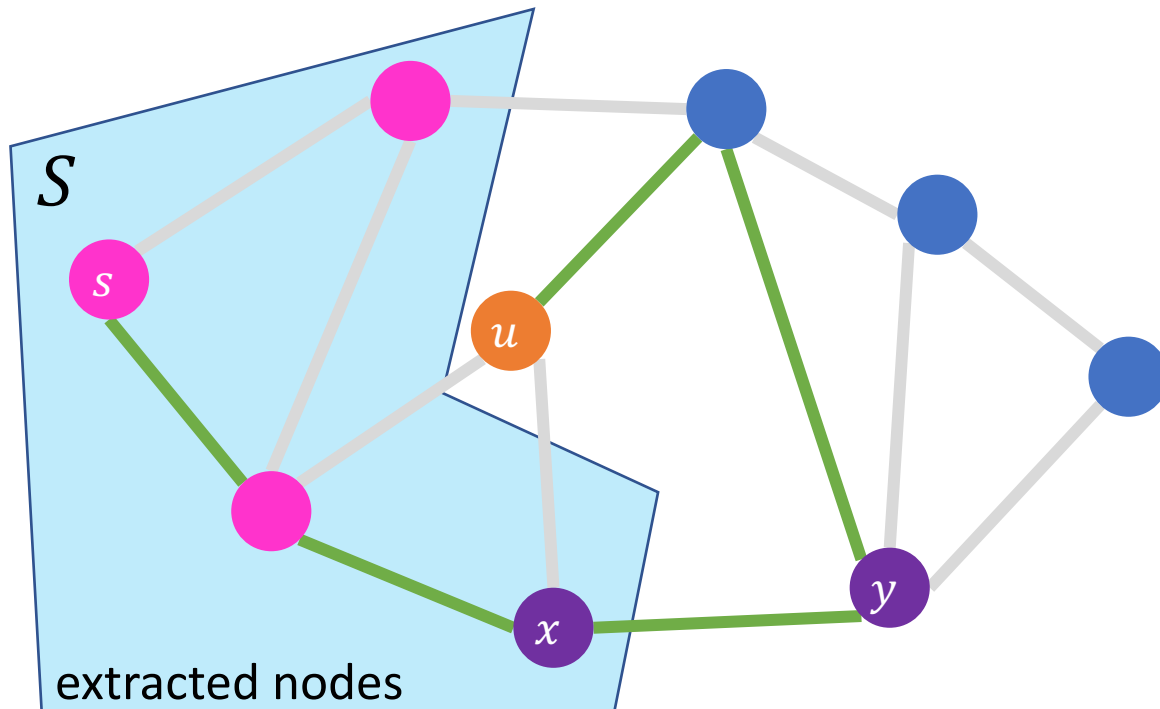
Extracted nodes define a cut $(S, V - S)$ of G



Correctness of Dijkstra's Algorithm: Claim 2

Let u be the $(i + 1)^{\text{st}}$ node extracted

Claim 2: For every path (s, \dots, u) , $w(s, \dots, u) \geq d_u$



Extracted nodes define a cut $(S, V - S)$ of G

Take any path (s, \dots, u)

Since $u \notin S$, (s, \dots, u) crosses the cut somewhere

- Let (x, y) be last edge in the path that crosses the cut

$$w(s, \dots, u) \geq \delta(s, x) + w(x, y) + w(y, \dots, u)$$

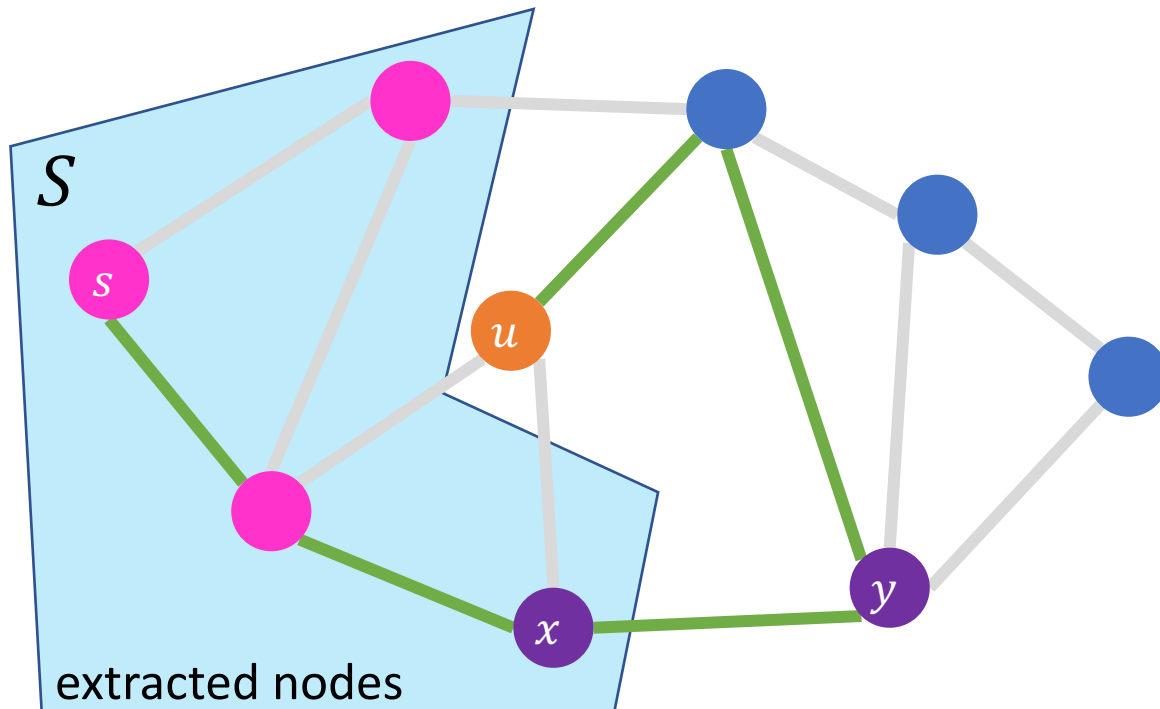
$$w(s, \dots, u) = w(s, \dots, x) + w(x, y) + w(y, \dots, u)$$

$w(s, \dots, x) \geq \delta(s, x)$ since $\delta(s, x)$ is weight of shortest path from s to x

Correctness of Dijkstra's Algorithm: Claim 2

Let u be the $(i + 1)^{\text{st}}$ node extracted

Claim 2: For every path (s, \dots, u) , $w(s, \dots, u) \geq d_u$



Extracted nodes define a cut $(S, V - S)$ of G

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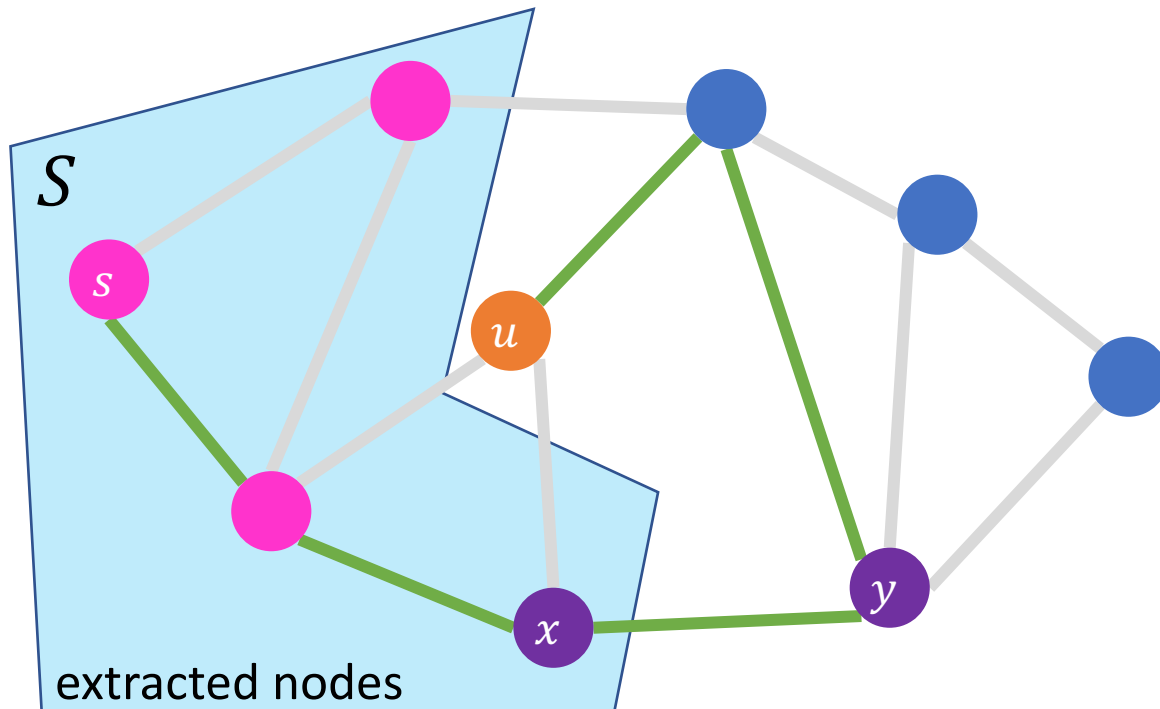
$$\begin{aligned} w(s, \dots, u) &\geq \delta(s, x) + w(x, y) + w(y, \dots, u) \\ &= d_x + w(x, y) + w(y, \dots, u) \end{aligned}$$

Inductive hypothesis: since x was extracted before, $d_x = \delta(s, x)$

Correctness of Dijkstra's Algorithm: Claim 2

Let u be the $(i + 1)^{\text{st}}$ node extracted

Claim 2: For every path (s, \dots, u) , $w(s, \dots, u) \geq d_u$



Extracted nodes define a cut $(S, V - S)$ of G

Take any path (s, \dots, u)

Since $u \notin S$, (s, \dots, u) crosses the cut somewhere

- Let (x, y) be last edge in the path that crosses the cut

$$\begin{aligned} w(s, \dots, u) &\geq \delta(s, x) + w(x, y) + w(y, \dots, u) \\ &= d_x + w(x, y) + w(y, \dots, u) \\ &\geq d_y + w(y, \dots, u) \end{aligned}$$

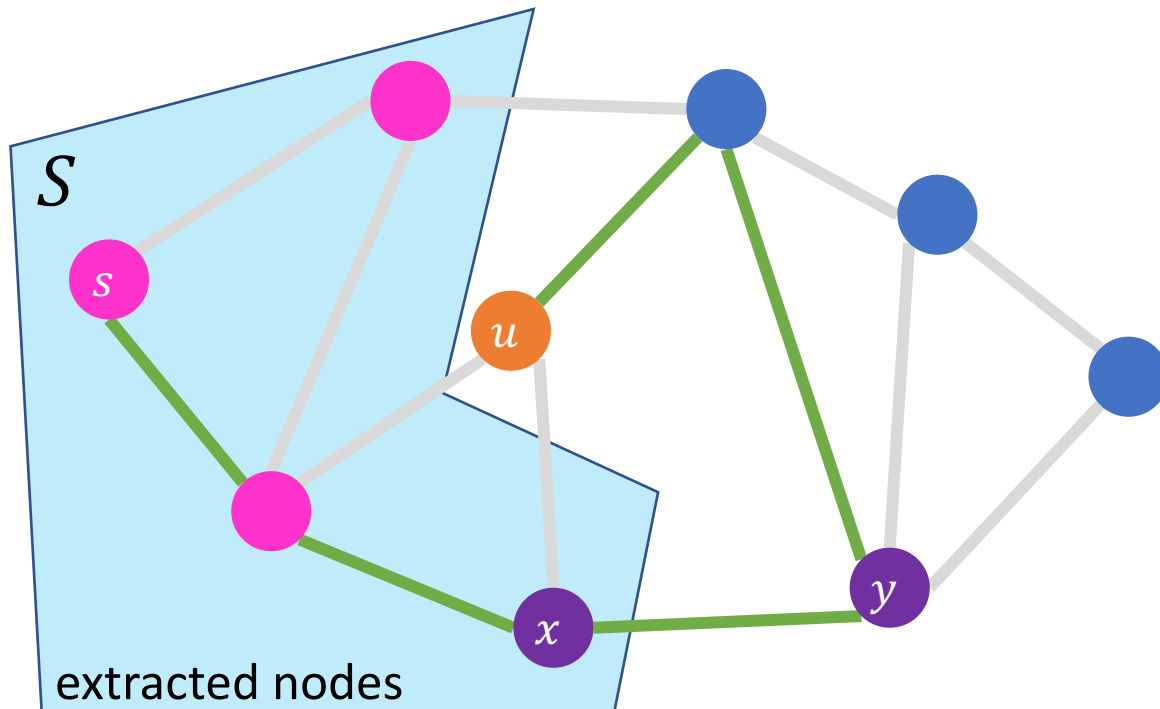
By construction of Dijkstra's algorithm, when x is extracted, d_y is updated to satisfy

$$d_y \leq d_x + w(x, y)$$

Correctness of Dijkstra's Algorithm: Claim 2

Let u be the $(i + 1)^{\text{st}}$ node extracted

Claim 2: For every path (s, \dots, u) , $w(s, \dots, u) \geq d_u$



Extracted nodes define a cut $(S, V - S)$ of G

Take any path (s, \dots, u)

Since $u \notin S$, (s, \dots, u) crosses the cut somewhere

- Let (x, y) be last edge in the path that crosses the cut

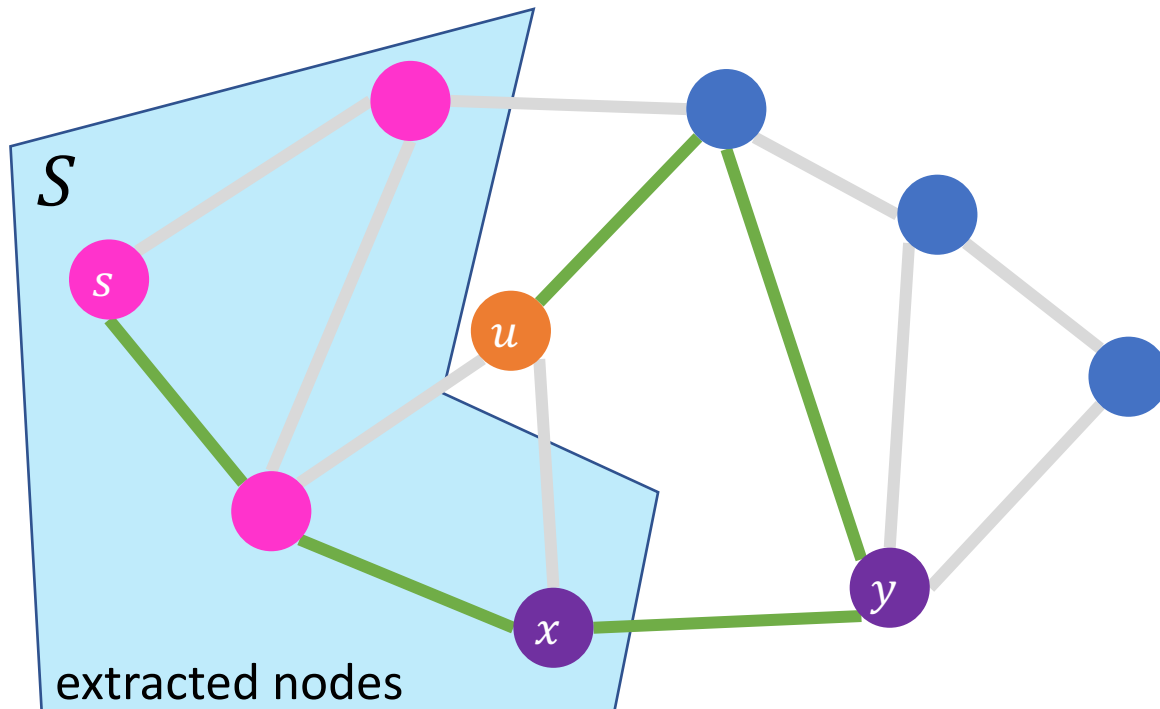
$$\begin{aligned}w(s, \dots, u) &\geq \delta(s, x) + w(x, y) + w(y, \dots, u) \\ &= d_x + w(x, y) + w(y, \dots, u) \\ &\geq d_y + w(y, \dots, u) \\ &\geq d_u + w(y, \dots, u)\end{aligned}$$

Greedy choice property: we always extract the node of minimal distance so $d_u \leq d_y$

Correctness of Dijkstra's Algorithm: Claim 2

Let u be the $(i + 1)^{\text{st}}$ node extracted

Claim 2: For every path (s, \dots, u) , $w(s, \dots, u) \geq d_u$



Extracted nodes define a cut $(S, V - S)$ of G

Take any path (s, \dots, u)

Since $u \notin S$, (s, \dots, u) crosses the cut somewhere

- Let (x, y) be last edge in the path that crosses the cut

$$\begin{aligned}w(s, \dots, u) &\geq \delta(s, x) + w(x, y) + w(y, \dots, u) \\ &= d_x + w(x, y) + w(y, \dots, u) \\ &\geq d_y + w(y, \dots, u) \\ &\geq d_u + w(y, \dots, u) \\ &\geq d_u\end{aligned}$$

All edge weights assumed to be positive

Correctness of Dijkstra's Algorithm

Proof by induction

Proof Idea: we will show that when node u is removed from the priority queue, $d_u = \delta(s, u)$

- **Claim 1:** There is a path of length d_u (as long as $d_u < \infty$) from s to u in G
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Breadth-First Search

Input: a node s

Behavior: Start with node s , visit all neighbors of s , then all neighbors of neighbors of s , until all nodes have been visited

Output: lots of choices!

- Is the graph connected?
- Is there a path from s to u ?
- Smallest number of “hops” from s to u

Sounds like a “shortest path” property!

Dijkstra's Algorithm

initialize $d_v = \infty$ for each node v

add all nodes $v \in V$ to the priority queue **PQ**, using d_v as the key

set $d_s = 0$

while **PQ** is not empty:

$v = \text{PQ.extractMin}()$

 for each $u \in V$ such that $(v, u) \in E$:

 if $u \in \text{PQ}$ and $d_v + w(v, u) < d_u$:

PQ.decreaseKey($u, d_v + w(v, u)$)

$u.\text{parent} = v$

Breadth-First Search

initialize a flag $d_v = 0$ for each node v

pick a start node s

Q .push(s)

while Q is not empty:

$v = Q$.pop() and set $d_v = 1$

 for each $u \in V$ such that $(v, u) \in E$:

 if $d_u = 0$:

Q .push(u)

flag to denote whether a node
has been visited or not

Key observation: replace the priority queue with a queue

BFS to Count Number of Hops

initialize a counter $d_v = \infty$ for each node v

pick a start node s and set $d_s = 0$

Q. push(s)

while Q is not empty:

$v = \text{Q.pop}()$

for each $u \in V$ such that $(v, u) \in E$:

if $d_u = \infty$:

Q. push(u)

$d_u = d_v + 1$

counter to denote number of hops from the source