

CS 4102: Algorithms

Lecture 25: P vs. NP

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Fall 2019

Today's Keywords

Reductions

NP-Completeness

P vs. NP

CLRS Readings: Chapter 34

Homework

HW9, HW10C due Thursday, December 5, 11pm

- Graphs, Reductions
- Written (LaTeX)

Final Exam

Monday, December 9, 7pm in Olsson 120

- Practice exam coming soon
- Review session likely the weekend before
- SDAC: Please sign-up for a time on December 9

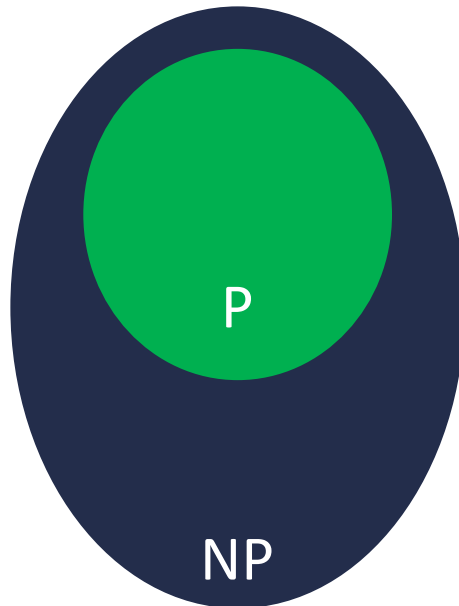
P vs. NP

A language $\mathcal{L} \in \text{NP}$ if there exists a deterministic polynomial-time “verifier” \mathcal{R} such that

$$x \in \mathcal{L} \Leftrightarrow \exists w \in \{0,1\}^{\text{poly}(|x|)}: \mathcal{R}(x, w) = 1$$

A language $\mathcal{L} \in \text{P}$ if there exists a deterministic polynomial-time “solver” \mathcal{R} such that

$$x \in \mathcal{L} \Leftrightarrow \mathcal{R}(x) = 1$$



If we can decide a problem in polynomial time, we can verify a solution to the problem in polynomial time:

$$\text{P} \subseteq \text{NP}$$

Biggest open problem in computer science: is this containment strict?

$$\text{P} = \text{NP} \text{ or } \text{P} \neq \text{NP}$$

Understanding the Landscape of NP

Question: What are the hard problems in NP?

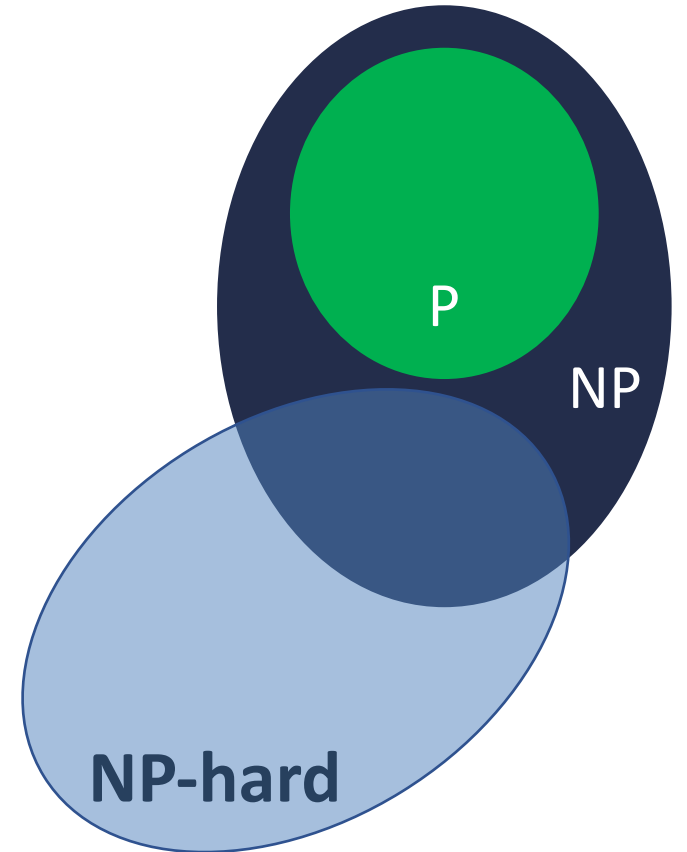
- Can we systematically characterize these?
- Can we use insights from one problem to help solve another problem?

Strategy: Identify problems at least as “hard” as NP

- If any of these “hard” problems can be solved in polynomial time, then all NP problems can be solved in polynomial time

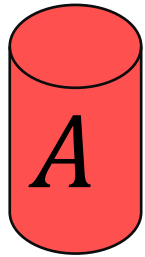
A problem (or language) B is **NP-hard**

- $\forall A \in \text{NP}, A \leq_p B$
- $A \leq_p B$ means A reduces to B in polynomial time

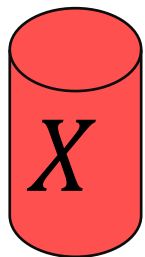


NP-Hardness

any NP problem



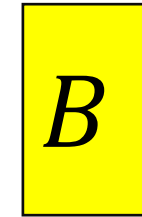
Solution for A



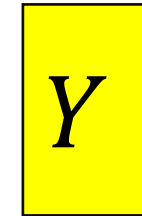
Map instances of problem A to instances of B
polynomial time

Map solutions of problem B to solutions of A
polynomial time

NP-hard problem



Solution for B

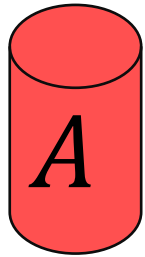


NP-hardness reduction

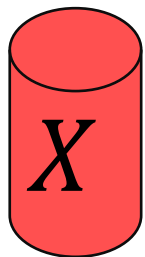
$A \leq_p B$: there is a polynomial-time reduction from A to B

NP-Hardness

any NP problem



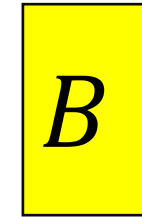
Solution for A



Map instances of problem A to instances of B
polynomial time

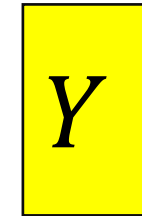
Map solutions of problem B to solutions of A
polynomial time

NP-hard problem



Algorithm for B

Solution for B



Very powerful: if we can solve even one NP-hard problem in polynomial time, we can solve all of them!

Understanding the Landscape of NP

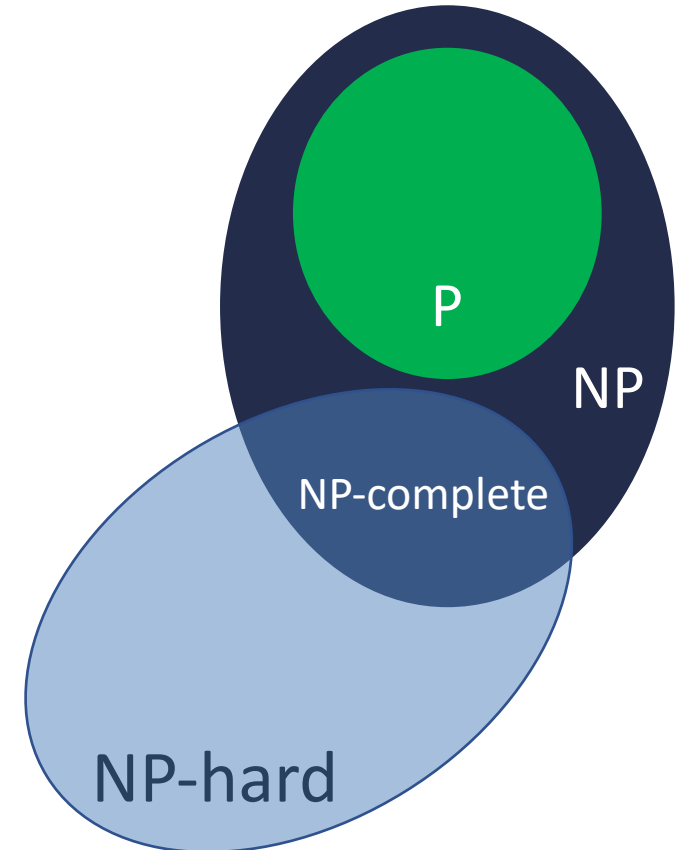
Question: What are the hardest problems in NP?

- By definition, an efficient algorithm for an NP-hard problem implies an efficient algorithm for every NP problem
- **Answer:** the ones that are NP-hard (if there are any)

NP-complete = $NP \cap NP\text{-hard}$

“Complete” for NP in the sense that a solution to one implies a solution to all

- To show $P = NP$, just need a single polynomial-time algorithm for a single NP-complete (or NP-hard) problem
- To show $P \neq NP$, just need a single lower-bound that some NP problem cannot be solved in polynomial time



Understanding the Landscape of NP

Question: What are the hardest problems in NP?

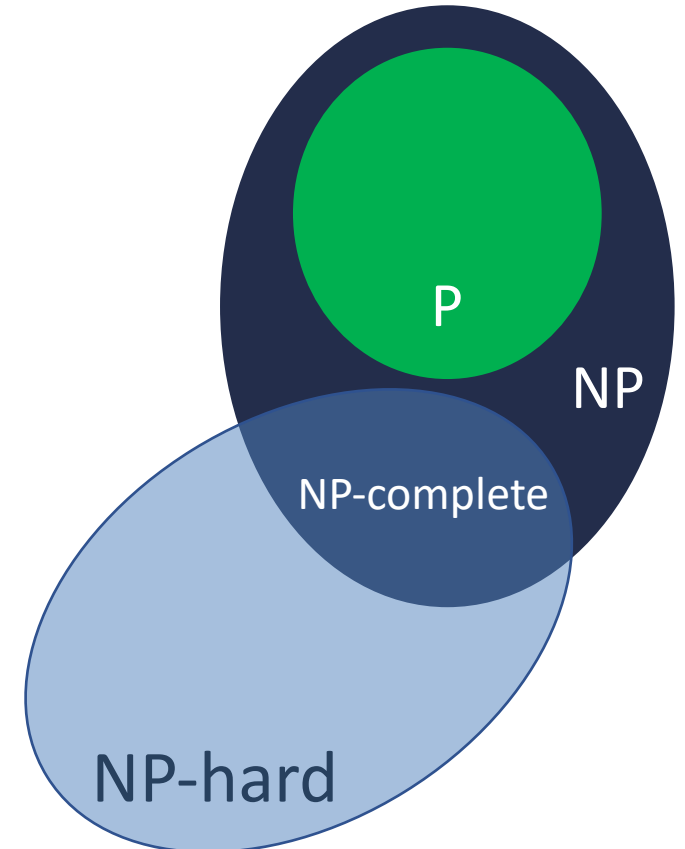
- By definition, an efficient algorithm for an NP-hard problem implies an efficient algorithm for every NP problem
- **Answer:** the ones that are NP-hard (if there are any)

NP-complete = $NP \cap NP\text{-hard}$

“Complete” for NP means that we can find a polynomial time solution to all

- To show $P = NP$, we need to find a single NP-complete problem
- To show $P \neq NP$, just need a single lower-bound that some NP problem cannot be solved in polynomial time

Not only do our existing techniques for proving lower bounds not work here, we are able to prove that most of our techniques will always fail...



NP-Completeness

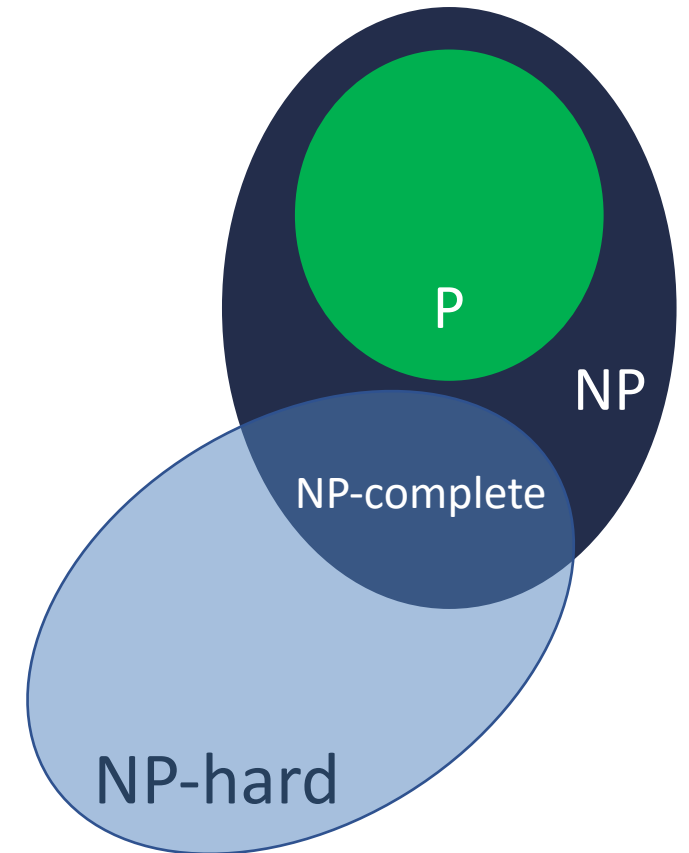
NP-complete = NP \cap NP-hard

To prove that a problem (or language) is NP-complete:

- Show it is in NP (i.e., construct a polynomial-time verifier)
- Show it is NP-hard (i.e., show every problem in NP reduces to it)



But there are a lot of problems in NP...

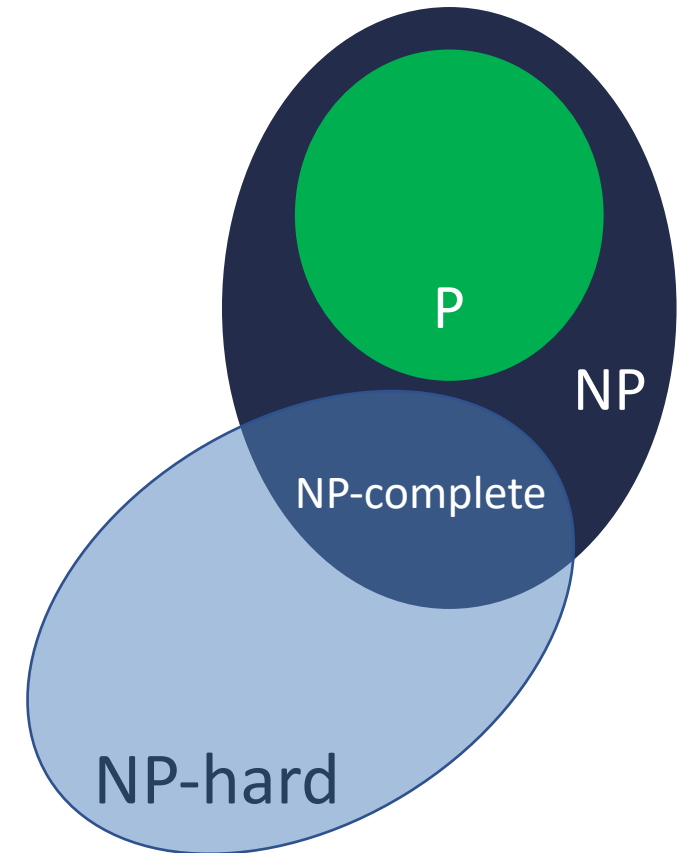


NP-Completeness

NP-complete = NP \cap NP-hard

To prove that a problem (or language) is NP-complete:

- Show it is in NP (i.e., construct a polynomial-time verifier)
- Show it is NP-hard (i.e., show every problem in NP reduces to it)
 - Sufficient to show that another NP-hard problem reduces to it
 - Suppose C is NP-hard and $C \leq_p B$; then for all $A \in \text{NP}$
$$A \leq_p C \leq_p B \Rightarrow A \leq_p B$$
 - **Challenge:** coming up with a first NP-hard problem



3-SAT (Satisfiability)

Shown to be NP-hard by Cook and Levin (independently)

Given a 3-CNF formula (logical AND of **clauses**, each an OR of 3 **variables**), is there an **assignment** of true/false to each variable to make the formula true (i.e., satisfy the formula)?

$$\underbrace{(x \vee y \vee z)}_{\text{Clause}} \wedge (x \vee \bar{y} \vee y) \wedge (u \vee y \vee \bar{z}) \wedge (z \vee \bar{x} \vee u) \wedge (\bar{x} \vee \bar{y} \vee \bar{z})$$

Variables

$x = \text{true}$
 $y = \text{false}$
 $z = \text{false}$
 $u = \text{true}$

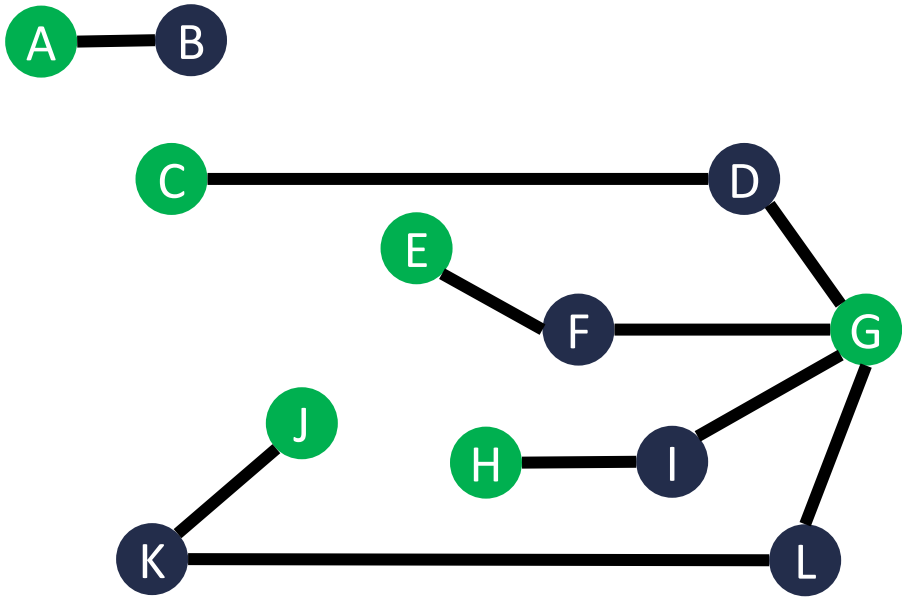
k -Independent Set is NP-Complete

1. Show that it belongs to NP
2. Show it is NP-Hard
 - Show $3\text{-SAT} \leq_p k\text{-Independent Set}$

k -Independent Set is in NP

Show: For any graph G :

- There is a short witness (i.e., proof) that G has a k -independent set
- The proof can be checked efficiently (in polynomial time)



Graph G

Witness for G : $S = \{A, C, E, G, H, J\}$
(nodes in the k -independent set)

Checking the witness:

- Check that $|S| = k$
- Check that every edge is incident on at most one node in S

$$O(k) = O(|V|)$$

$$O(|V| + |E|)$$

Total time: $O(|E| + |V|) = \text{poly}(|V| + |E|)$

k -Independent Set is NP-Complete

1. Show that it belongs to NP
2. Show it is NP-Hard
 - Show $3\text{-SAT} \leq_p k\text{-Independent Set}$



3-SAT \leq_p k -Independent Set

3-SAT

$$(x \vee y \vee z) \wedge (x \vee \bar{y} \vee y) \wedge (u \vee y \vee \bar{z})$$

$x = \text{true}$
 $y = \text{false}$
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 $u = \text{true}$

Map instances of problem A to instances of B

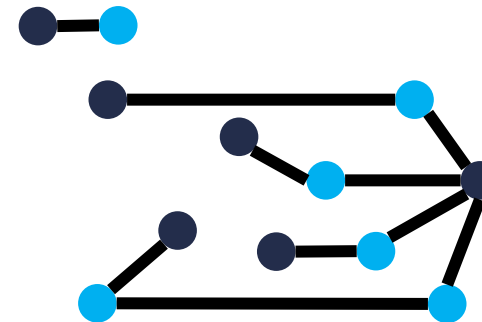
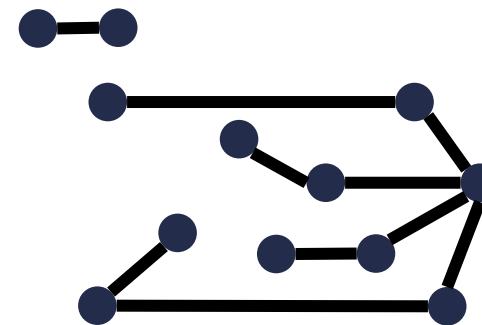
polynomial time

Map solutions of problem B to solutions of A

polynomial time

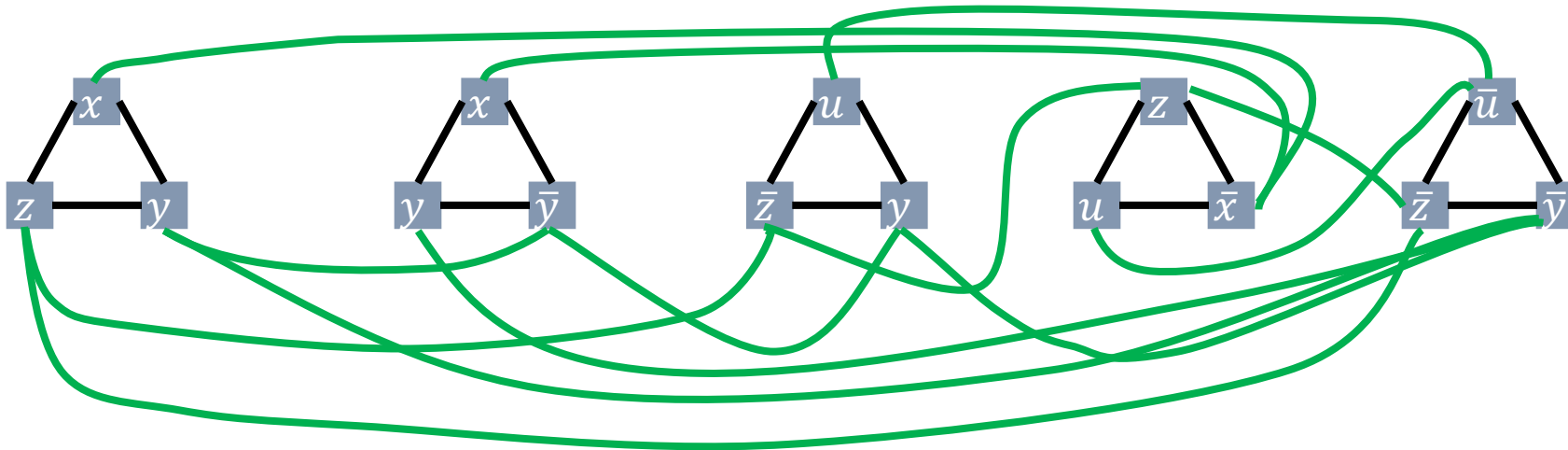
polynomial-time reduction

k -independent set



3-SAT \leq_p k -Independent Set

$$(x \vee y \vee z) \wedge (x \vee \bar{y} \vee y) \wedge (u \vee y \vee \bar{z}) \wedge (z \vee \bar{x} \vee u) \wedge (\bar{x} \vee \bar{y} \vee \bar{z})$$



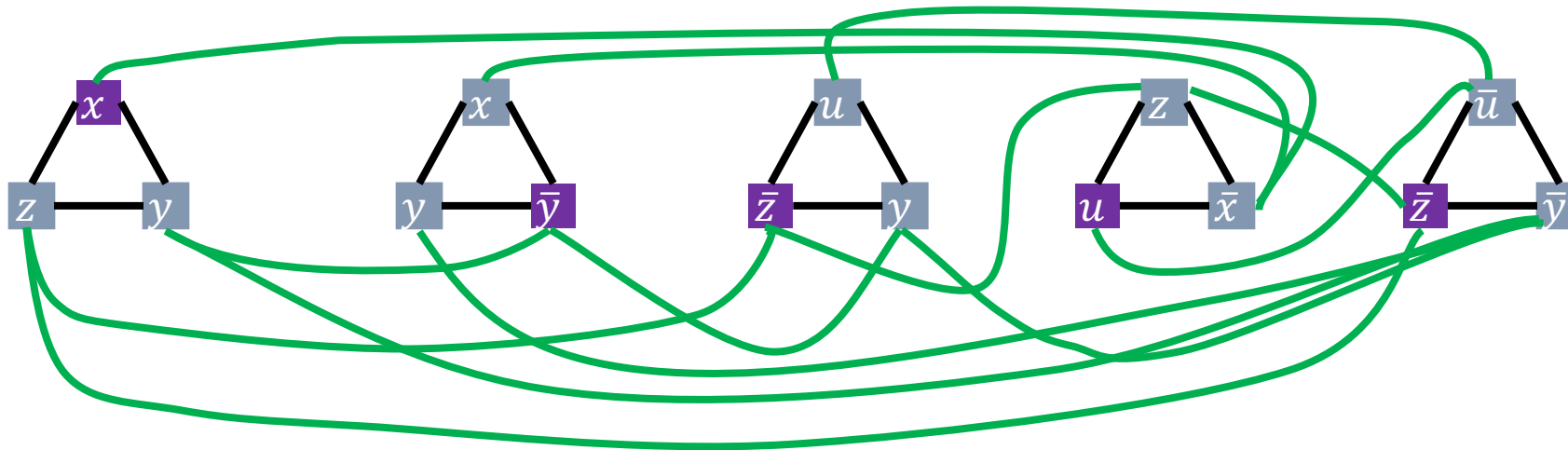
For each clause, construct a triangle graph with its three variables as nodes
Add an edge between each node and its negation

Let k = number of clauses

Claim. There is a k -independent set in this graph if and only if there is a satisfying assignment

3-SAT \leq_p k -Independent Set

$$(x \vee y \vee z) \wedge (x \vee \bar{y} \vee y) \wedge (u \vee y \vee \bar{z}) \wedge (z \vee \bar{x} \vee u) \wedge (\bar{x} \vee \bar{y} \vee \bar{z})$$



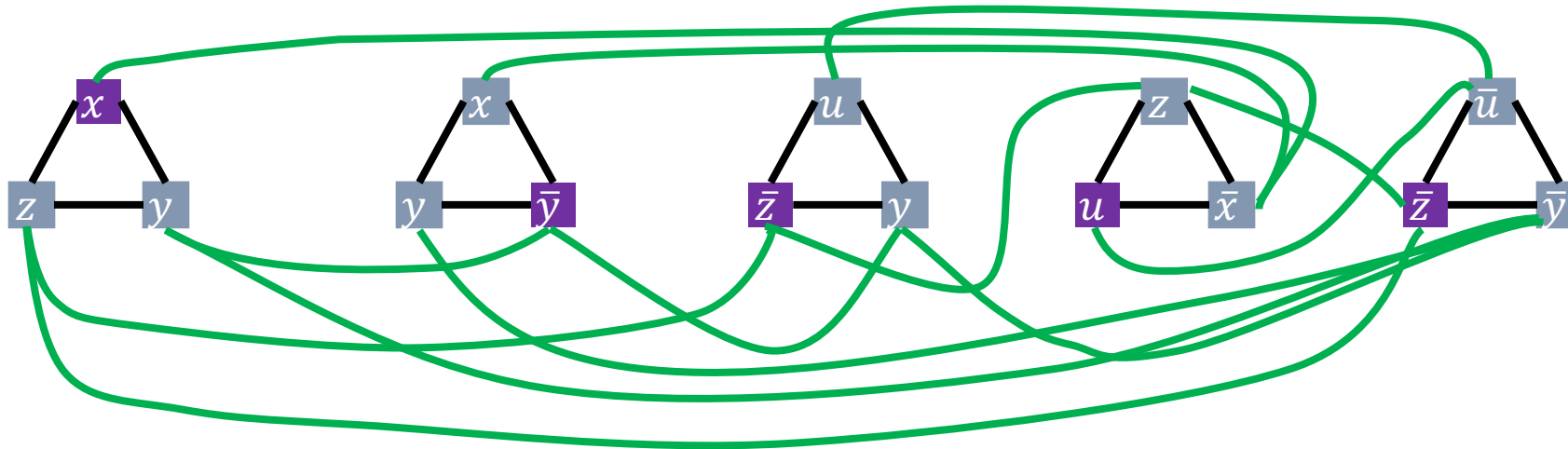
$x = \text{true}$
 $y = \text{false}$
 $z = \text{false}$
 $u = \text{true}$

Suppose there is a k -independent set S in this graph G

- By construction of G , at most one node from each triangle is in S
- Since $|S| = k$ and there are k triangles, each triangle contributes one node
- If a variable x is selected in one triangle, then \bar{x} is never selected in another triangle (since each variable is connected to its negation)
- There are no contradicting assignments, so can set variable chosen in each triangle to “true”; satisfying assignment by construction

3-SAT \leq_p k -Independent Set

$$(x \vee y \vee z) \wedge (x \vee \bar{y} \vee y) \wedge (u \vee y \vee \bar{z}) \wedge (z \vee \bar{x} \vee u) \wedge (\bar{x} \vee \bar{y} \vee \bar{z})$$



$x = \text{true}$
 $y = \text{false}$
 $z = \text{false}$
 $u = \text{true}$

Suppose there is a **satisfying assignment** to the formula

- At least one variable in each clause must be true
- Add the node to that variable to the set S
- There are k clauses, so set S has exactly k nodes
- If we use x in any clause, we will never use \bar{x} , so there are no edges among the nodes in S

3-SAT \leq_p k -Independent Set

3-SAT

$$(x \vee y \vee z) \wedge (x \vee \bar{y} \vee y) \wedge (u \vee y \vee \bar{z})$$

$x = \text{true}$
 $y = \text{false}$
 $z = \text{false}$
 $u = \text{true}$

Map instances of problem **A** to instances of **B**

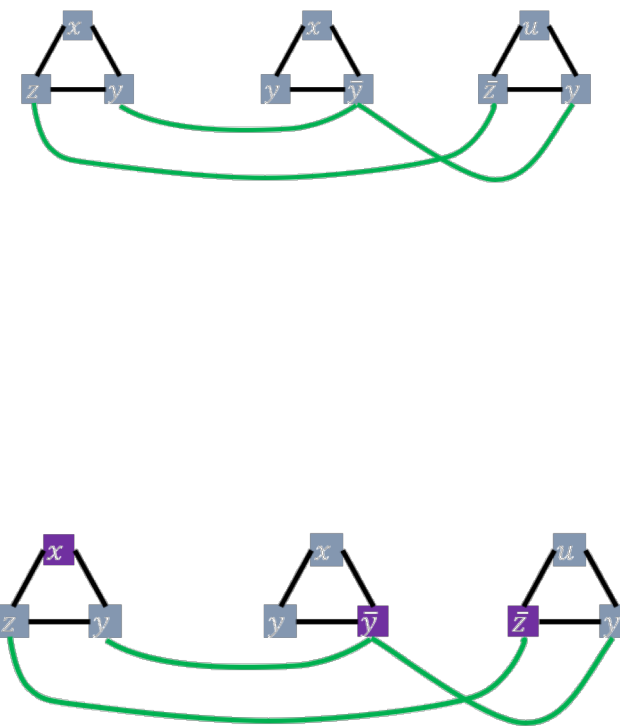
polynomial time

Map solutions of problem **B** to solutions of **A**

polynomial time

polynomial-time reduction

k -independent set



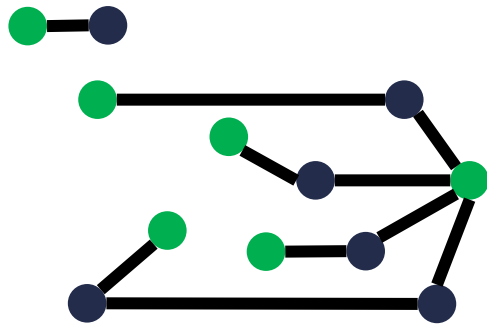
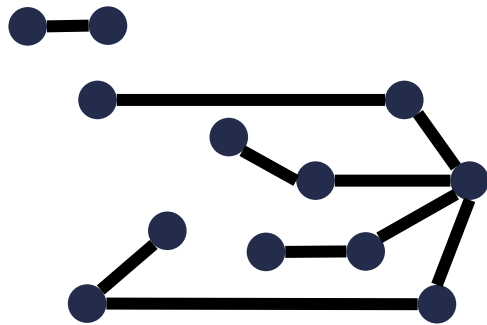
k -Independent Set is NP-Complete

1. Show that it belongs to NP
2. Show it is NP-Hard
 - Show $3\text{-SAT} \leq_p k\text{-independent set}$



Max Independent Set \leq_p Min Vertex Cover

k -independent set



Map instances of problem A to instances of B

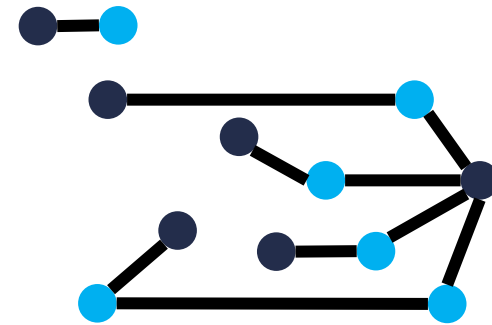
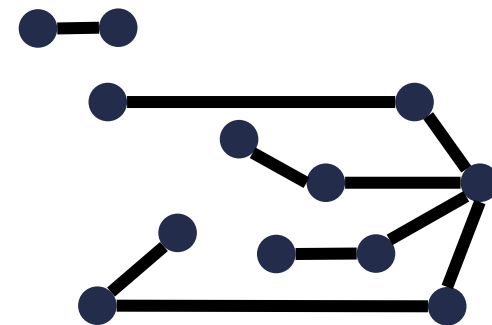
$O(1)$ time

Map solutions of problem B to solutions of A



$O(|V|)$ time

Reduction

k -vertex cover



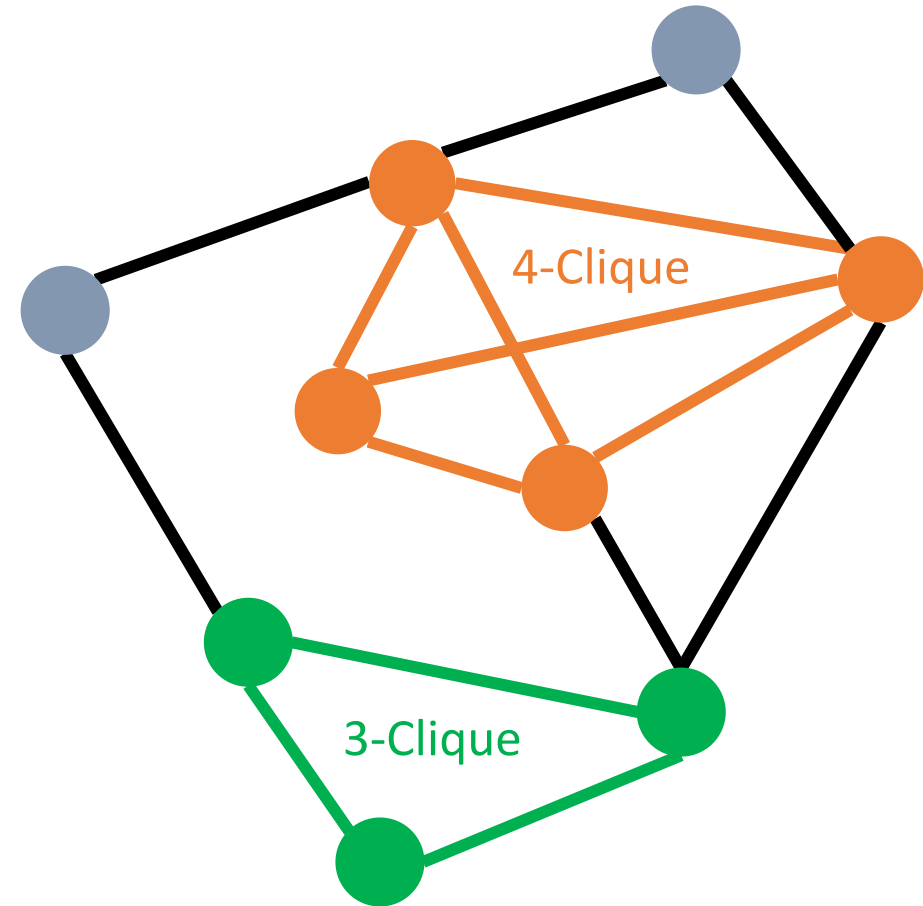
k -Vertex Cover is NP-Complete

1. Show that it belongs to NP 
 - Given a candidate cover, check that every edge is covered
2. Show it is NP-Hard 
 - Show k -independent set $\leq_p k$ -vertex cover

k -Clique Problem

Clique: A complete subgraph

k -Clique problem: given a graph G and a number k , is there a clique of size k ?



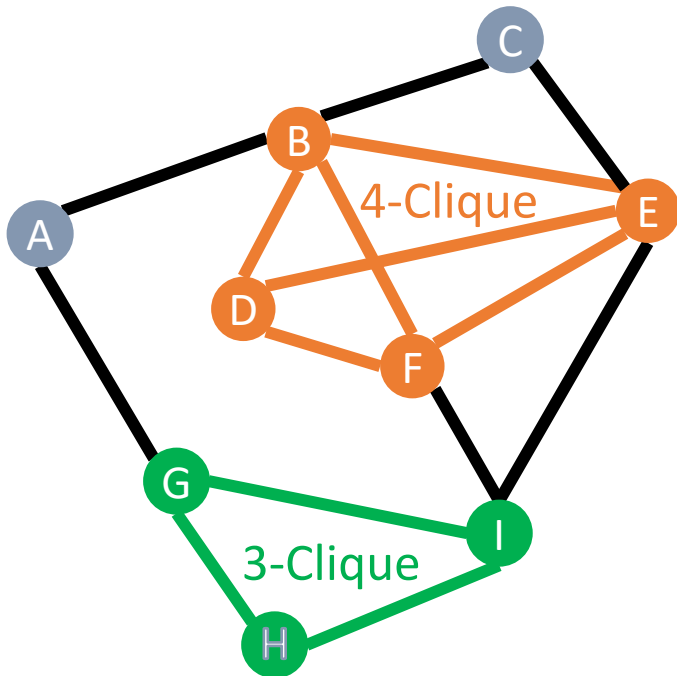
k -Clique is NP-Complete

1. Show that it belongs to NP
 - Give a polynomial time verifier
2. Show it is NP-Hard
 - Give a reduction from a known NP-Hard problem
 - We will show $3\text{-SAT} \leq_p k\text{-clique}$

k -Clique is in NP

Show: For any graph G :

- There is a short witness (i.e., proof) that G has a k -clique
- The proof can be checked efficiently (in polynomial time)



Graph G

Suppose $k = 4$

Witness for G : $S = \{B, D, E, F\}$
(nodes in the k -clique)

Checking the witness:


- Check that $|S| = k$
- Check that every pair of nodes in S share an edge

$$O(k) = O(|V|)$$

$$O(k^2) = O(|V|^2)$$

Total time: $O(|V|^2) = \text{poly}(|V| + |E|)$

k -Clique is NP-Complete

1. Show that it belongs to NP 
 - Give a polynomial time verifier
2. Show it is NP-Hard
 - Give a reduction from a known NP-Hard problem
 - We will show $3\text{-SAT} \leq_p k\text{-clique}$

3-SAT \leq_p k -Clique

3-SAT

$$(x \vee y \vee z) \wedge (x \vee \bar{y} \vee y) \wedge (u \vee y \vee \bar{z})$$

$x = \text{true}$
 $y = \text{false}$
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Map instances of problem **A** to instances of **B**

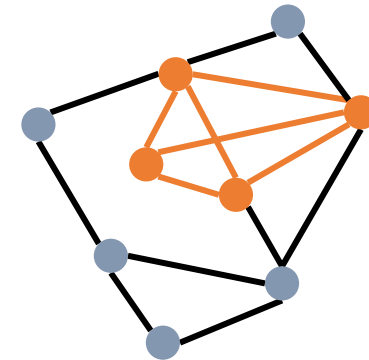
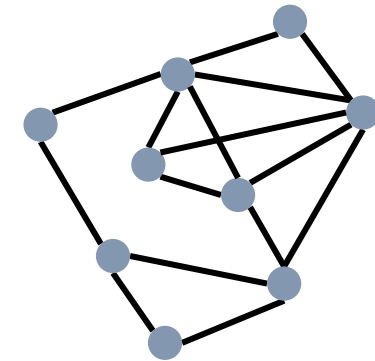
polynomial time

Map solutions of problem **B** to solutions of **A**

polynomial time

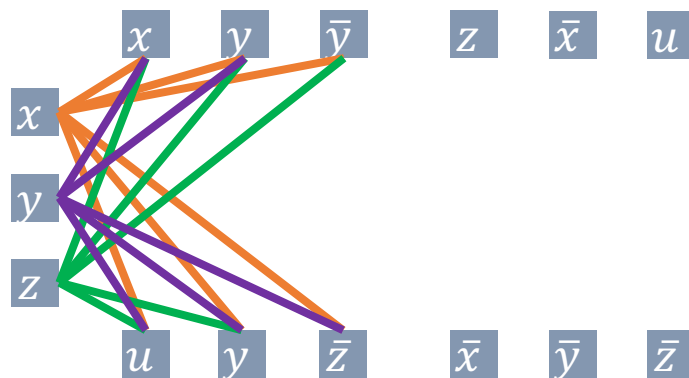
polynomial-time reduction

k -clique



3-SAT \leq_p k -Clique

$$(x \vee y \vee z) \wedge (x \vee \bar{y} \vee y) \wedge (u \vee y \vee \bar{z}) \wedge (z \vee \bar{x} \vee u) \wedge (\bar{x} \vee \bar{y} \vee \bar{z})$$



(also do this for the other clauses,
omitted due to clutter)

For each clause, introduce a node for each of its three variables

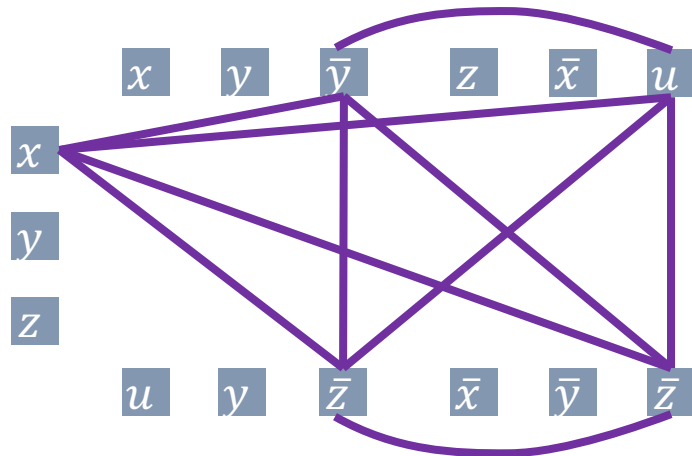
Add an edge from each node to all non-contradictory nodes in the other clauses (i.e., to all nodes that is not the negation of its own variable)

Let k = number of clauses

Claim. There is a k -clique in this graph if and only if there is a satisfying assignment

3-SAT \leq_p k -Clique

$$(x \vee y \vee z) \wedge (x \vee \bar{y} \vee y) \wedge (u \vee y \vee \bar{z}) \wedge (z \vee \bar{x} \vee u) \wedge (\bar{x} \vee \bar{y} \vee \bar{z})$$

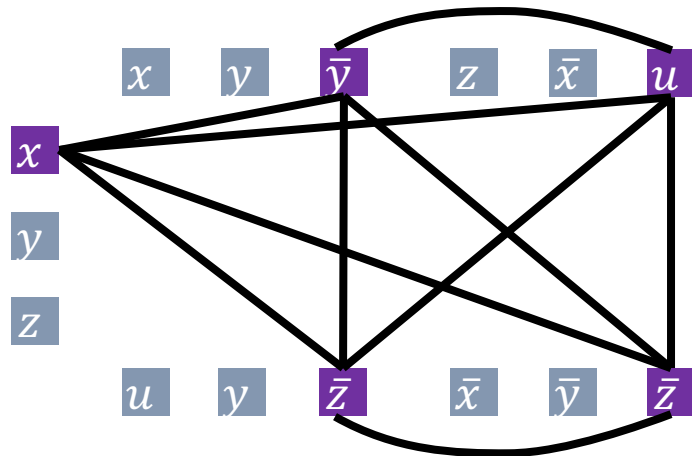


Suppose there is a k -clique in this graph

- There are no edges between nodes for variables in the same clause, so k -clique must contain one node from each clause
- Nodes in clique cannot contain variable and its negation
- Nodes in clique must then correspond to a satisfying assignment

3-SAT \leq_p k -Clique

$$(x \vee y \vee z) \wedge (x \vee \bar{y} \vee y) \wedge (u \vee y \vee \bar{z}) \wedge (z \vee \bar{x} \vee u) \wedge (\bar{x} \vee \bar{y} \vee \bar{z})$$



Suppose there is a **satisfying assignment** to the formula

- For each clause, choose one node whose value is true
- There are k clauses, so this yields a collection of k nodes
- Since the assignment is consistent, there is an edge between every pair of nodes, so this constitutes a k -clique

3-SAT \leq_p k -Clique

3-SAT

$$(x \vee y \vee z) \wedge (x \vee \bar{y} \vee y) \wedge (u \vee y \vee \bar{z})$$

$x = \text{true}$
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Map instances of problem **A** to instances of **B**

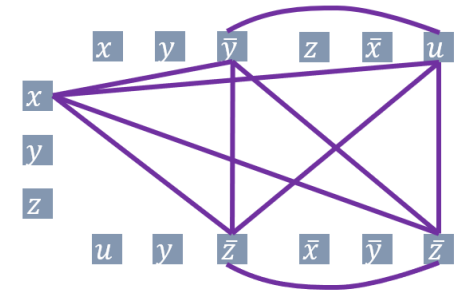
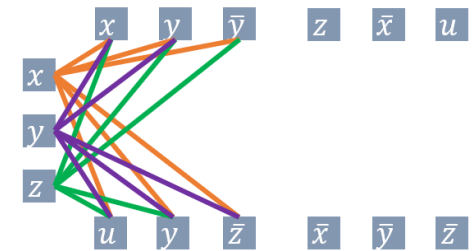
polynomial time

Map solutions of problem **B** to solutions of **A**



polynomial time

polynomial-time reduction

k -clique



k -Clique is NP-Complete

1. Show that it belongs to NP 
 - Give a polynomial time verifier
2. Show it is NP-Hard 
 - Give a reduction from a known NP-Hard problem
 - We will show $3\text{-SAT} \leq_p k\text{-clique}$

Bonus Material: Coping with NP-Hardness

Material from subsequent slides will not be on the exam

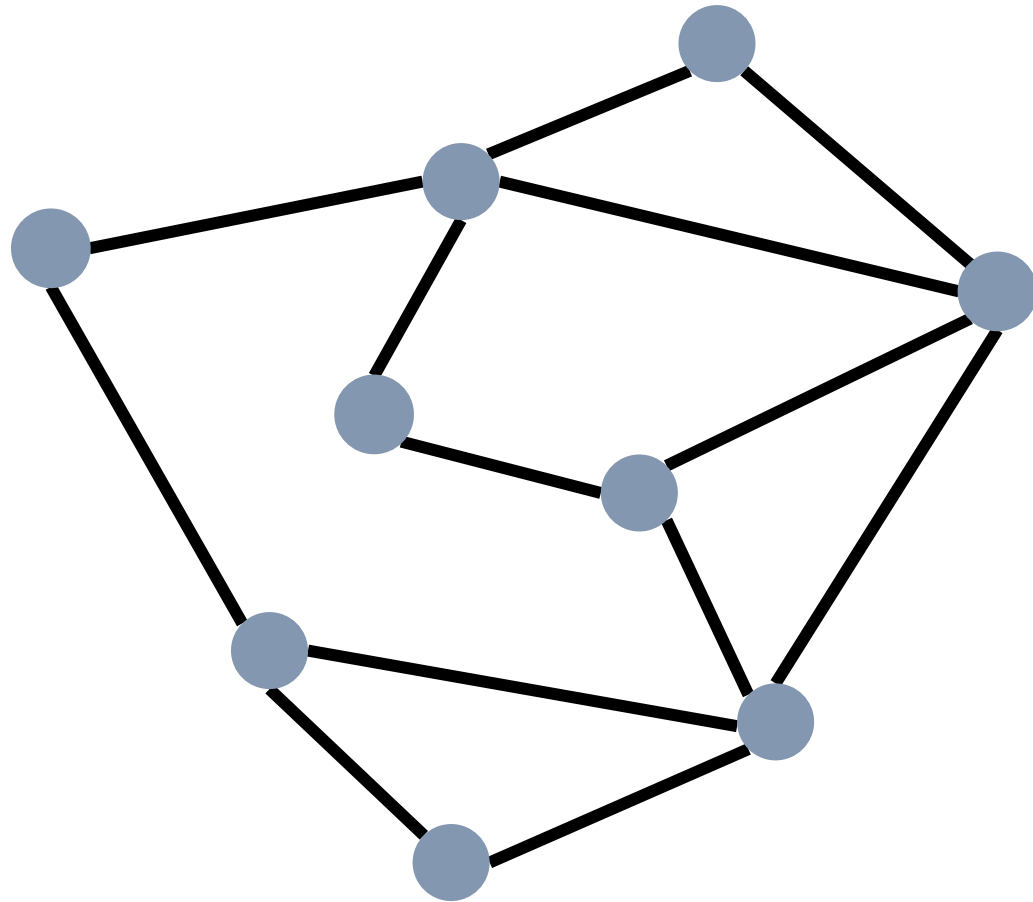
Coping with NP-Hardness

Many optimization problems that come up in practice are NP-complete

What do we do?

Approach 1: Find an algorithm that gives nearly-optimal solutions

Greedy Vertex Cover

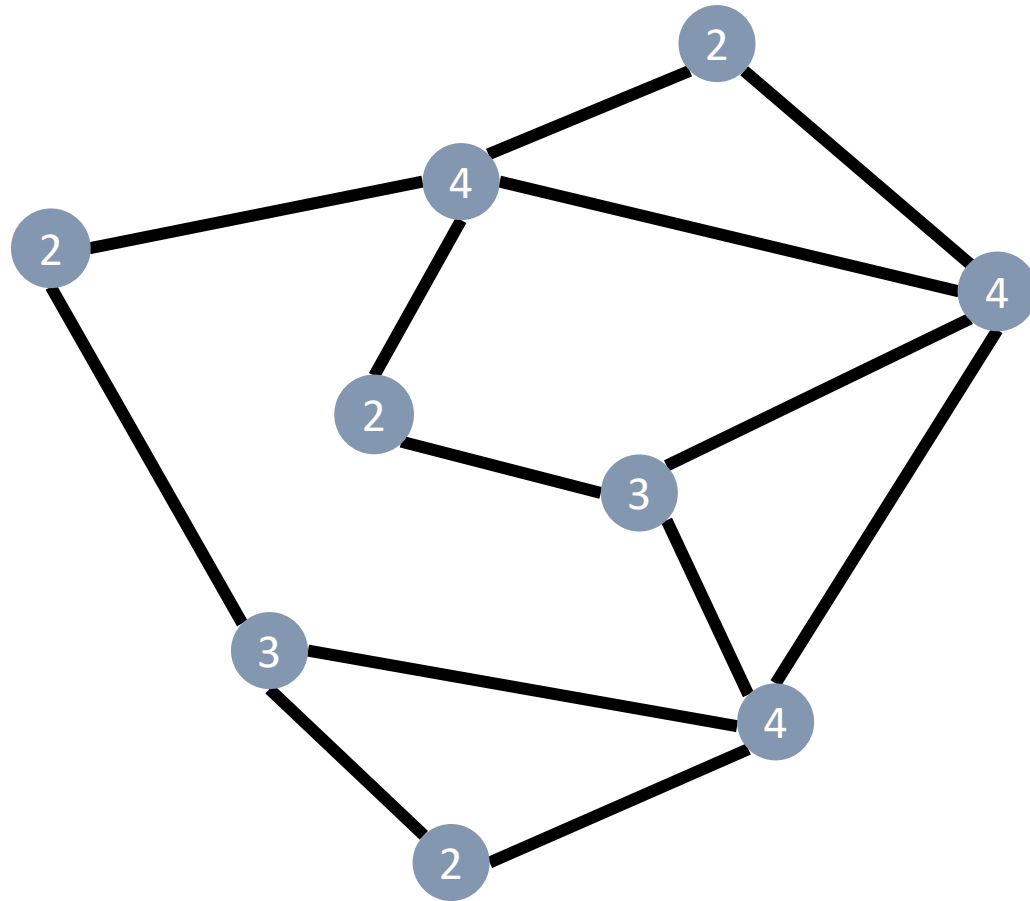


Goal: Find a set of nodes such that every edge is incident on one of the nodes

Greedy approach?

Greedy choice: Node with highest degree (e.g., node that covers the most edges)

Greedy Vertex Cover

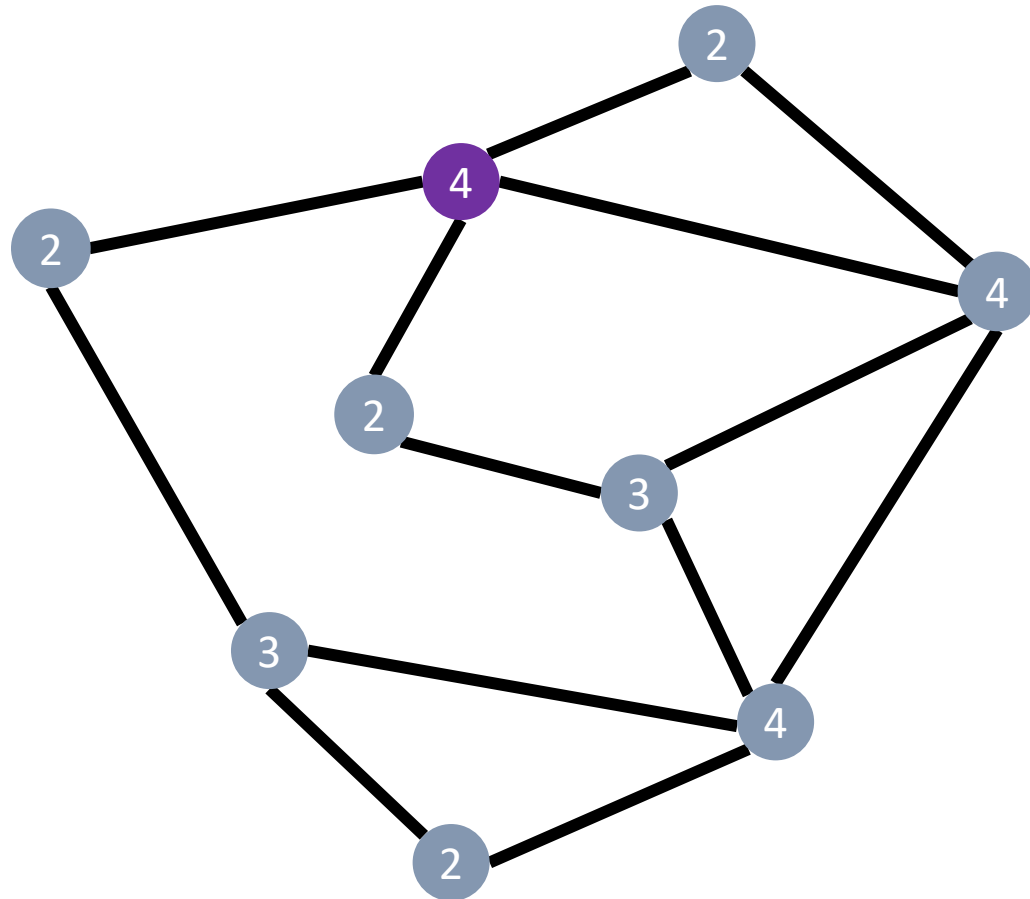


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Greedy Vertex Cover

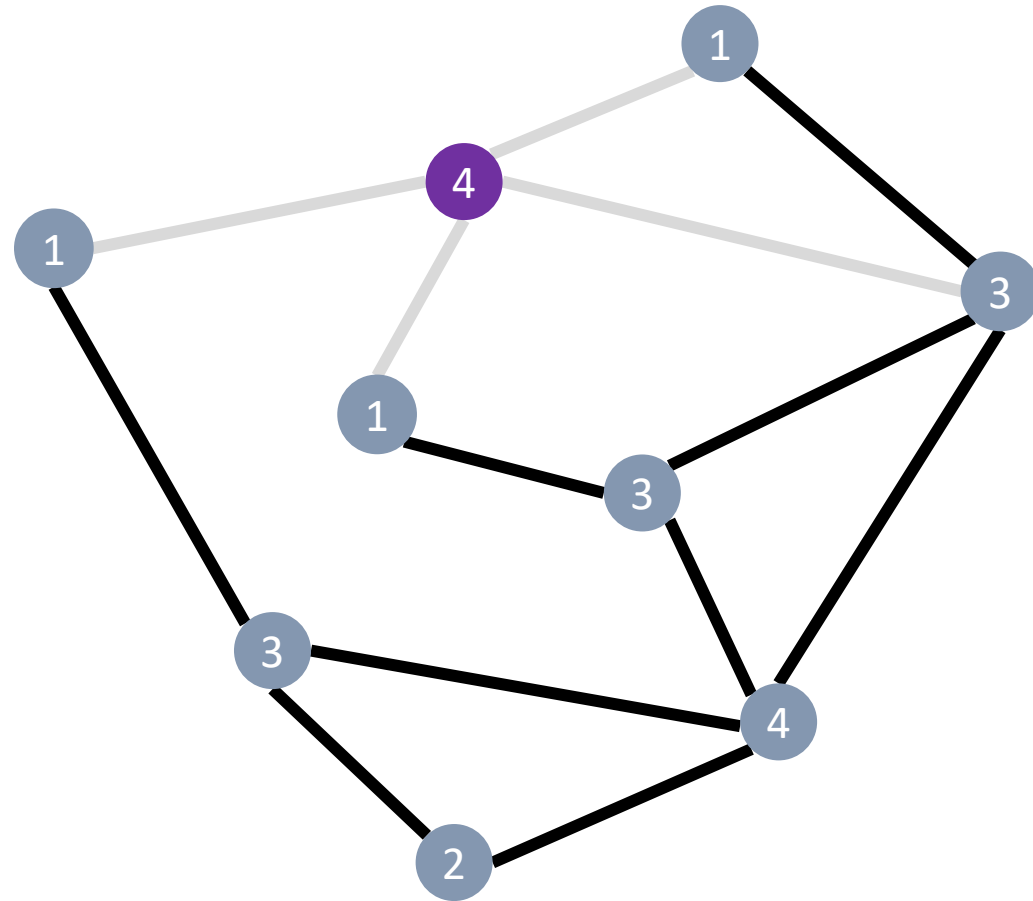


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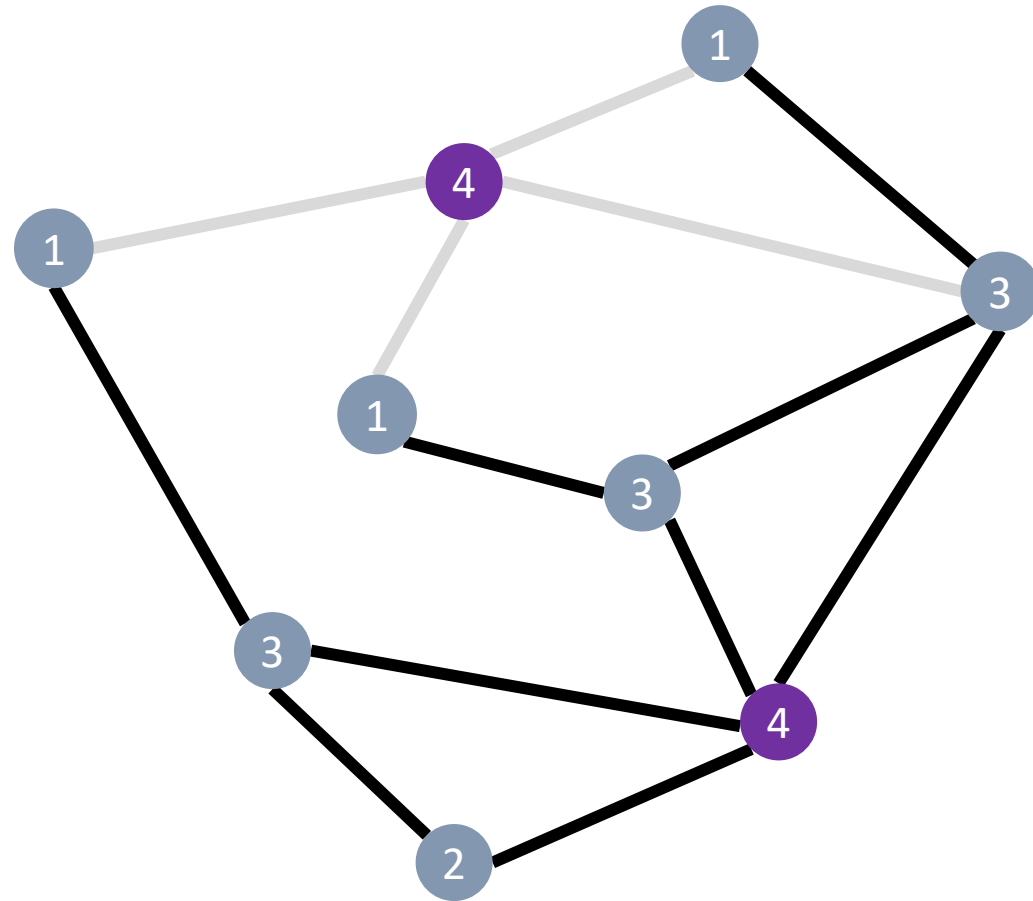


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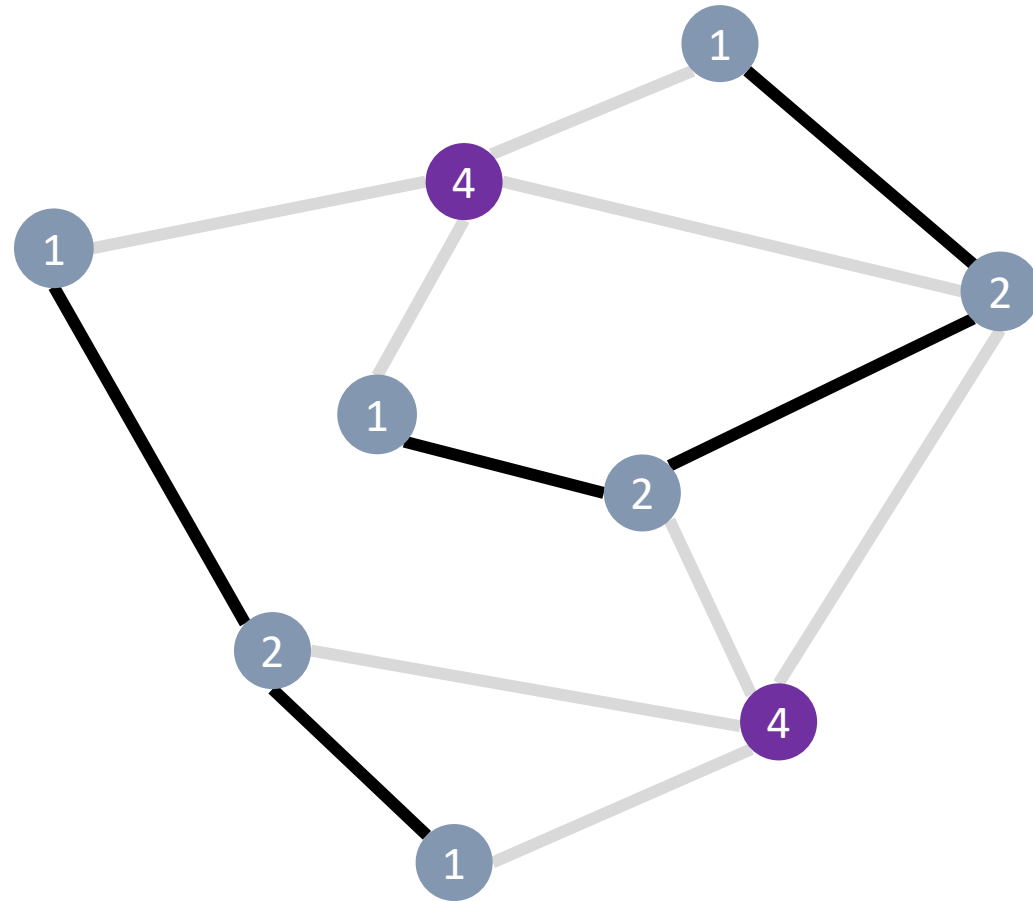


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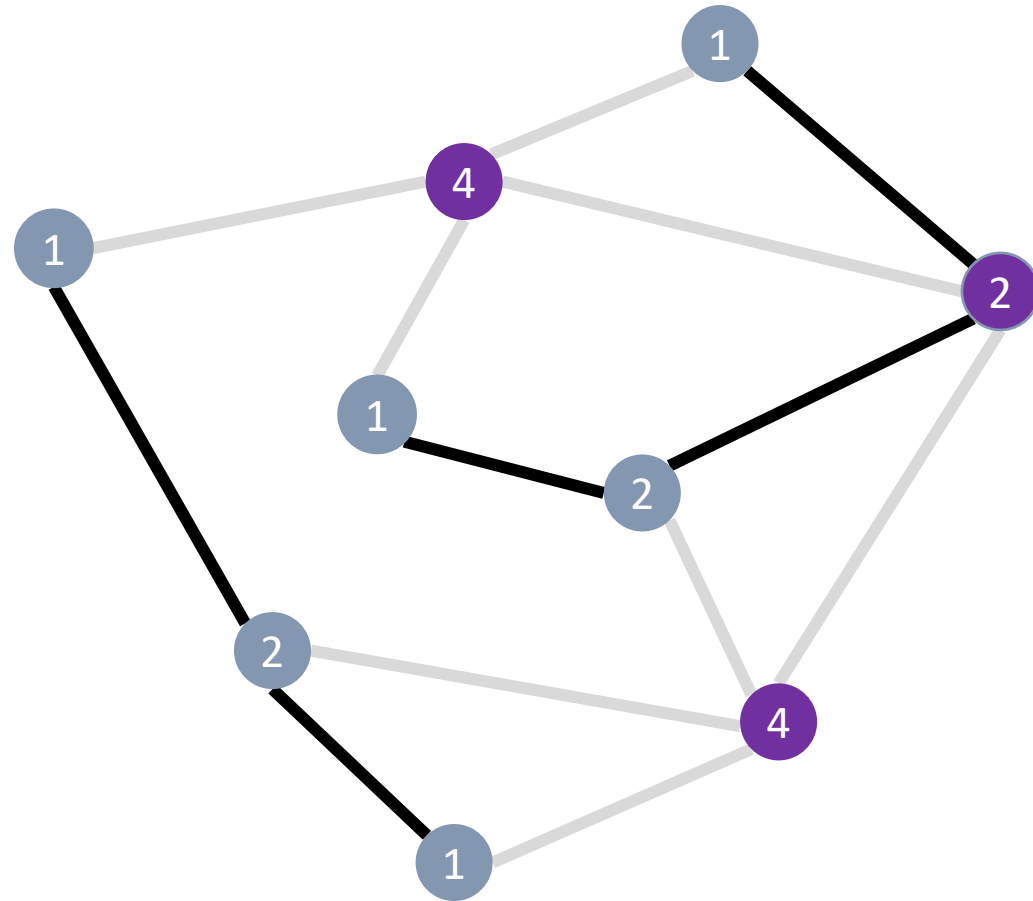


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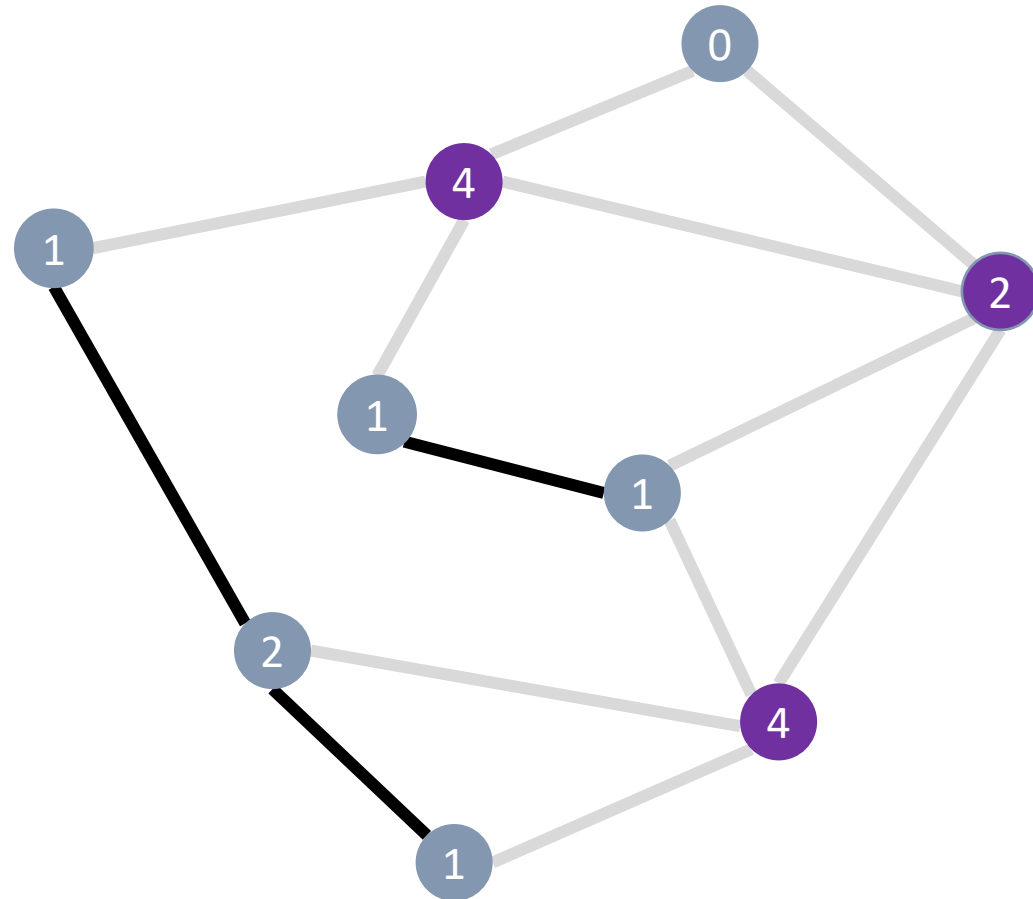


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Greedy Vertex Cover

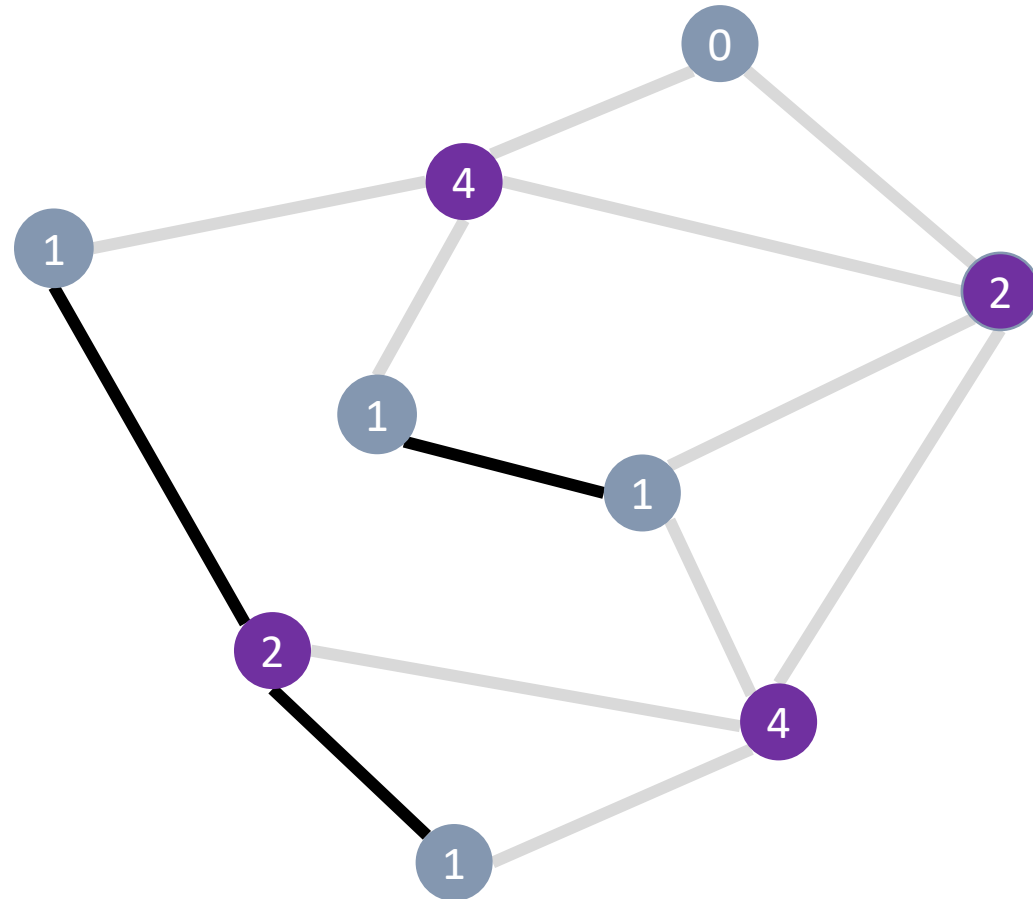


Goal: Find a set of nodes such that every edge is incident on one of the nodes

Greedy approach?

Greedy choice: Node with highest degree (e.g., node that covers the most edges)

Greedy Vertex Cover

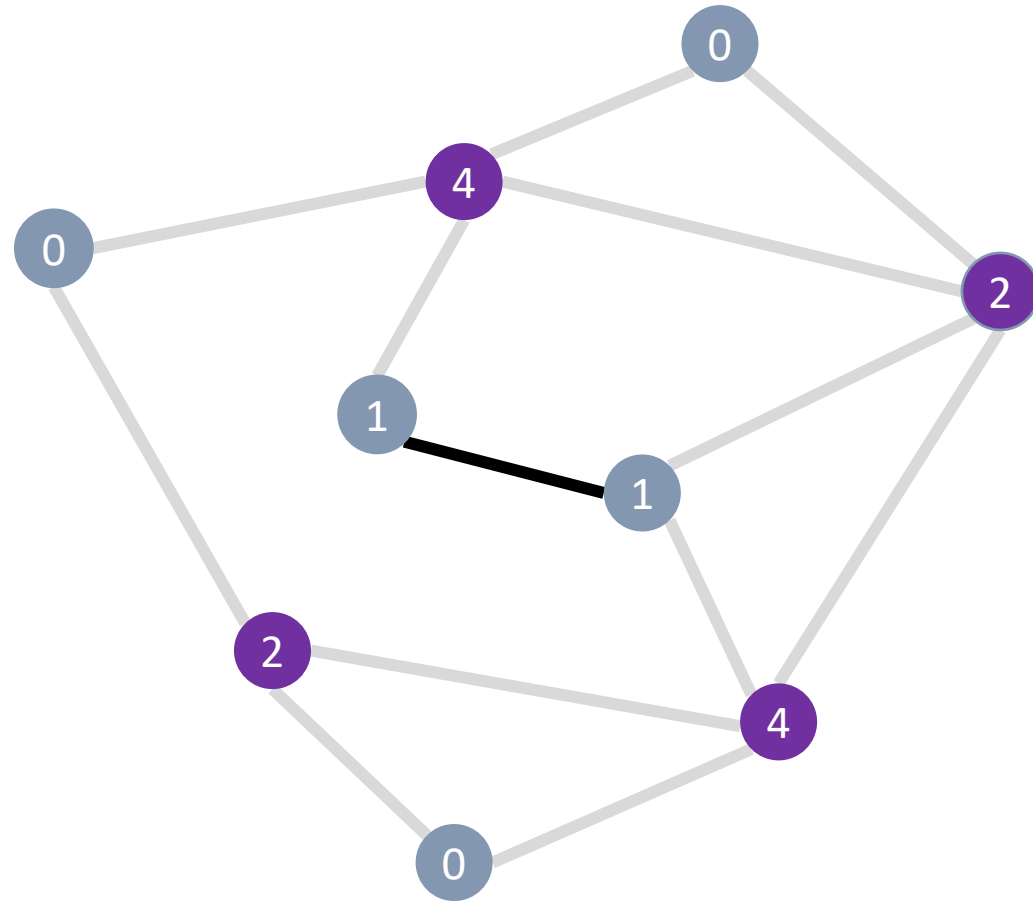


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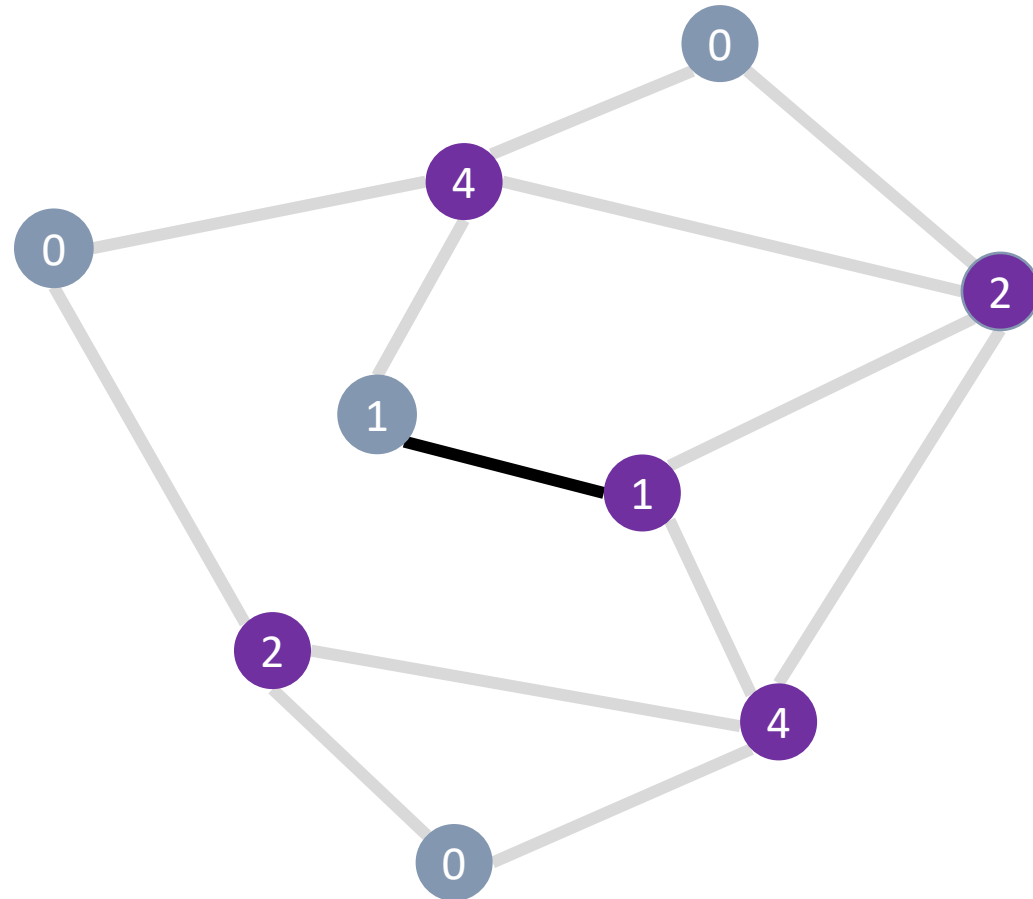


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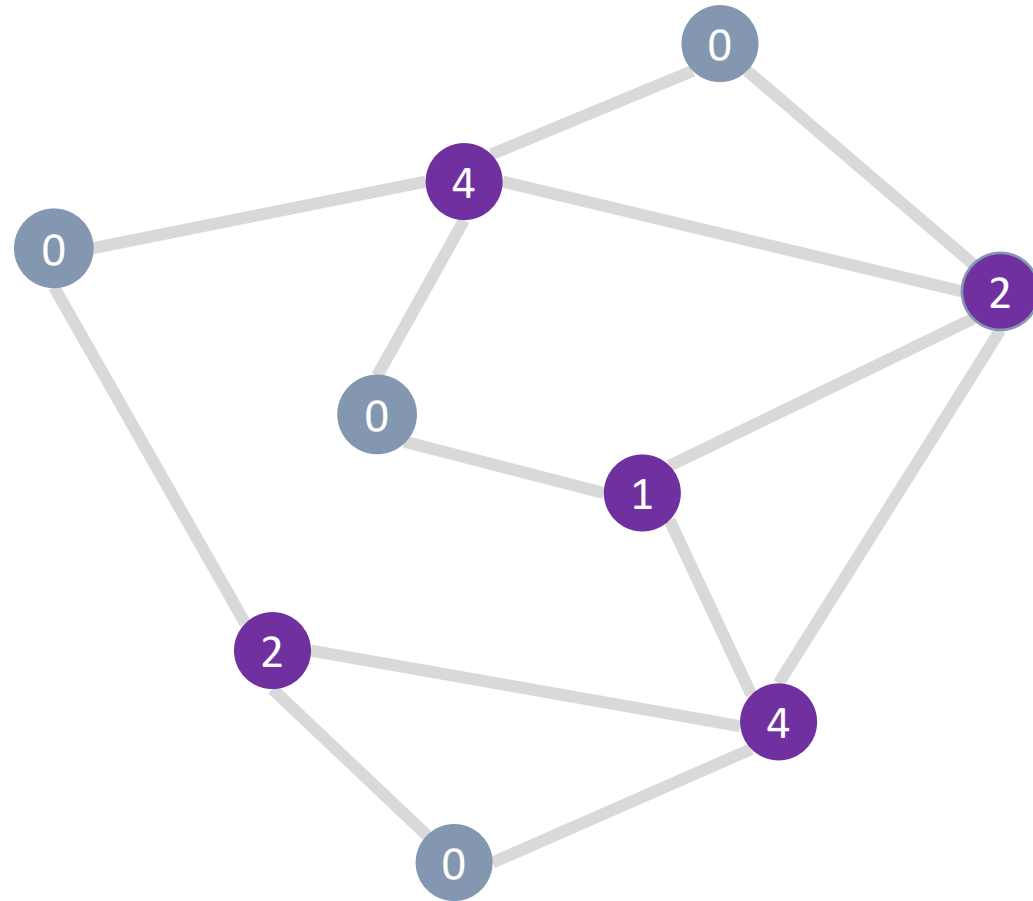


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Greedy Vertex Cover



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Greedy approach?

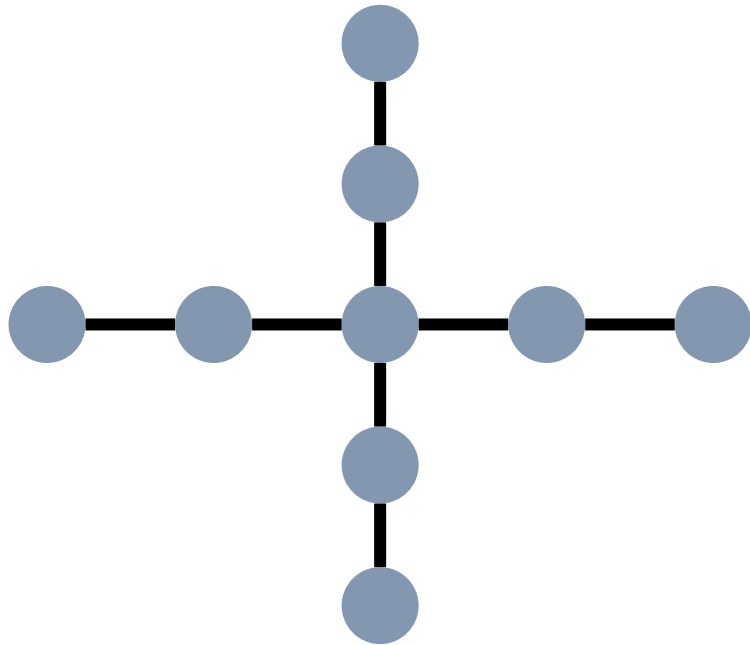
Greedy choice: Node with highest degree (e.g., node that covers the most edges)

Size of vertex cover: 5

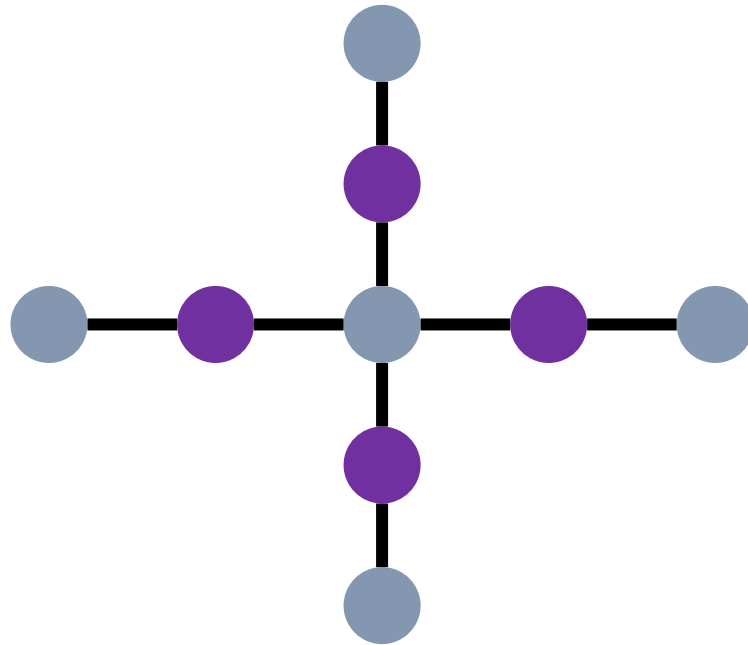
In this case, actually optimal!

Greedy Vertex Cover

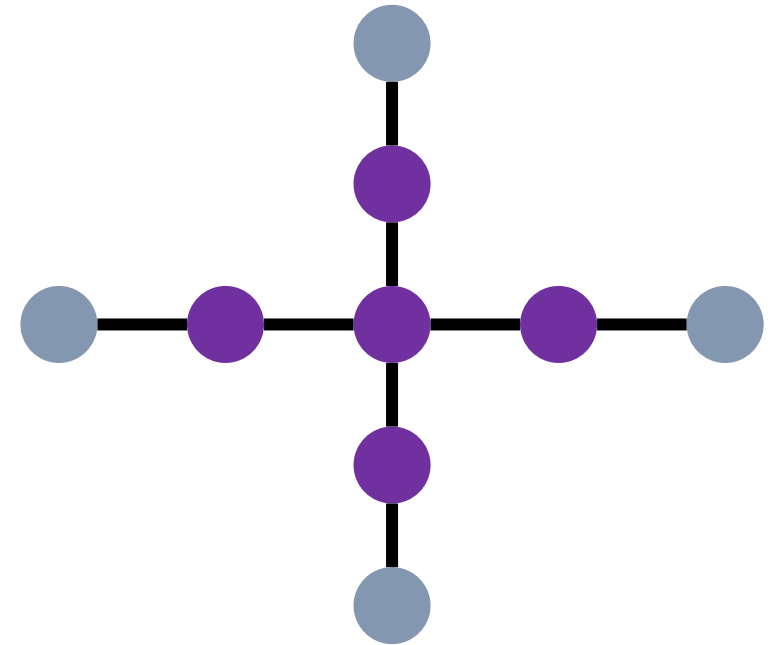
But not always optimal...



Graph G



Optimal



Greedy

Greedy Vertex Cover

But is it “good enough?”

How do we measure good enough?

Let $\text{OPT}(G)$ denote the size of the minimum vertex cover in G and $|A(G)|$ be the size of the cover output by algorithm A

Define the approximation factor of A to be

$$\text{ApproxFactor}(A) = \frac{|A(G)|}{\text{OPT}}$$

The larger this value is, the worse the quality of the approximation
(Goal: as close to 1 as possible)

Greedy Vertex Cover

But is it “good enough?”

How do we measure good enough?

Let $\text{OPT}(G)$ denote the size of the minimum vertex cover in G and $|A(G)|$ be the size of the cover output by algorithm A

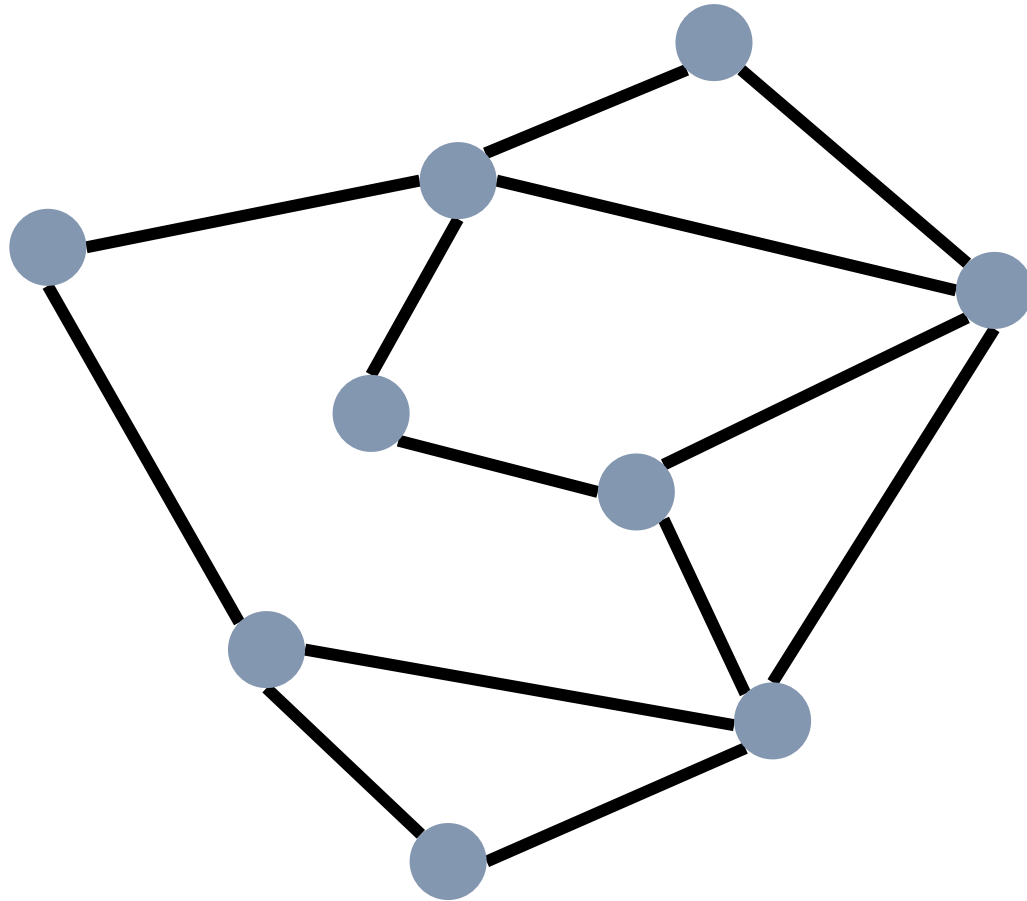
Define the approximation factor of A to be

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Theorem. The greedy algorithm for vertex cover achieves an approximation factor of $\Omega(\log|V|)$

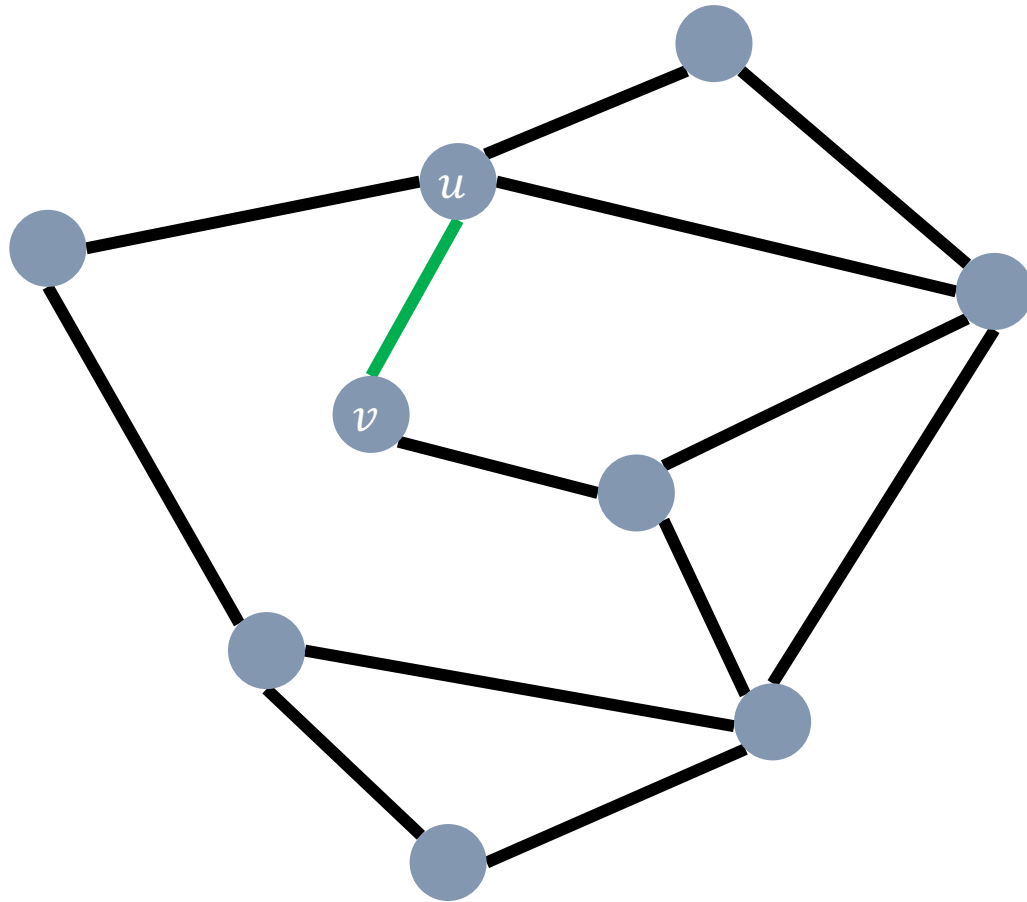
Not that great... quality of solution is worse for large instances

Approximate Vertex Cover



Goal: Obtain a 2-approximation (i.e., vertex cover that is at most twice as large as the optimal)

Approximate Vertex Cover

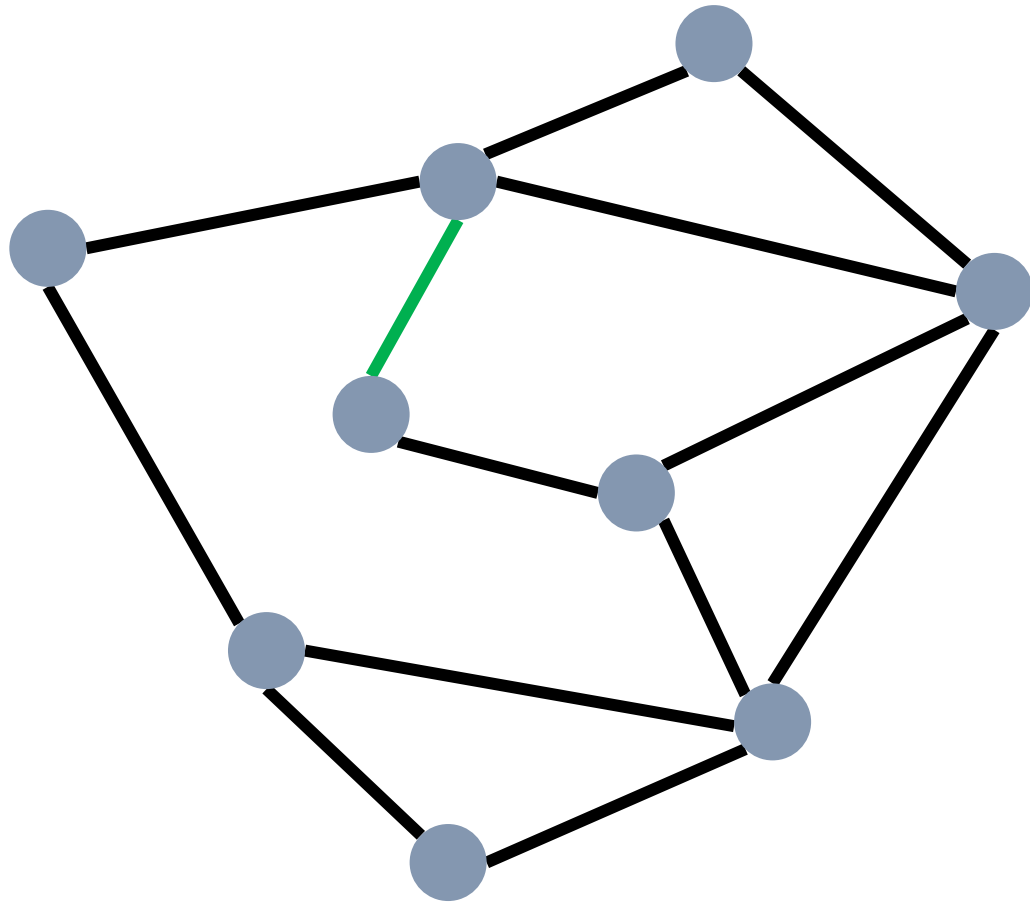


Goal: Obtain a 2-approximation (i.e., vertex cover that is at most twice as large as the optimal)

Consider an edge $e = (u, v) \in E$

- Optimal vertex covering must contain either u or v
- **Our approach:** take both of them!
 - Add u, v to cover
 - Remove all edges incident on u and v
 - Repeat until no edges remain

Approximate Vertex Cover

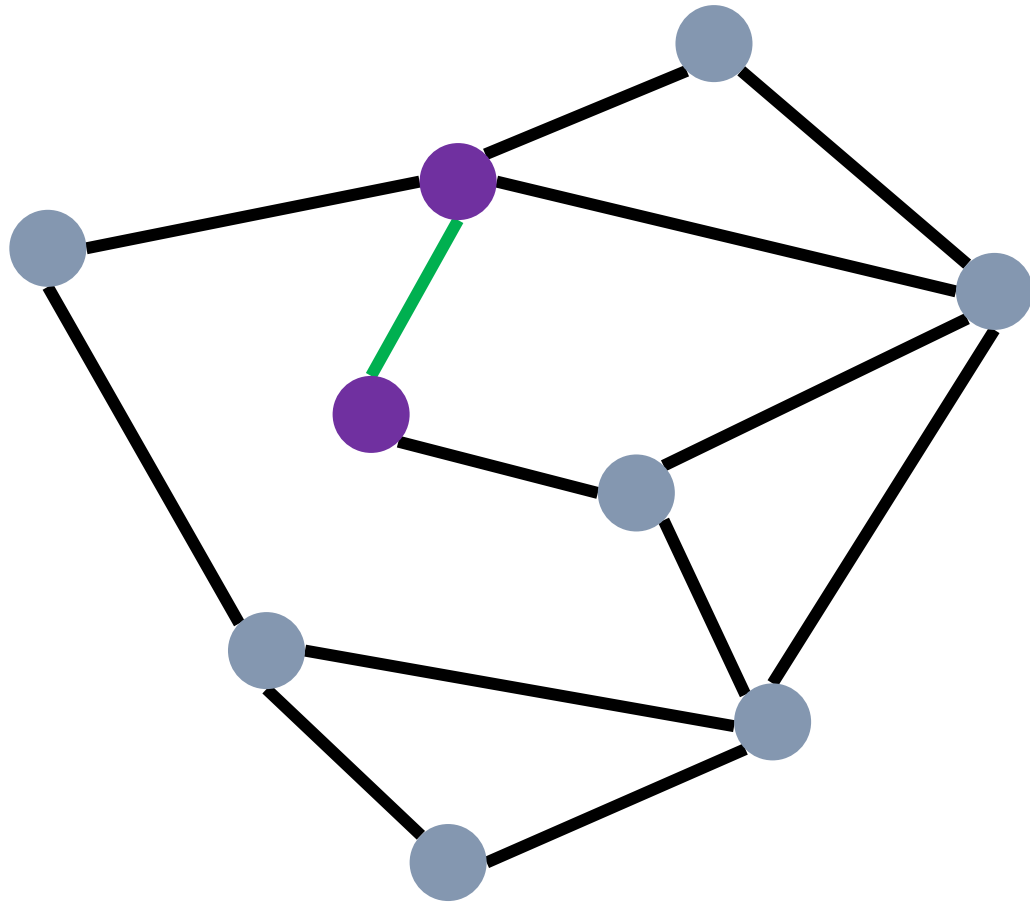


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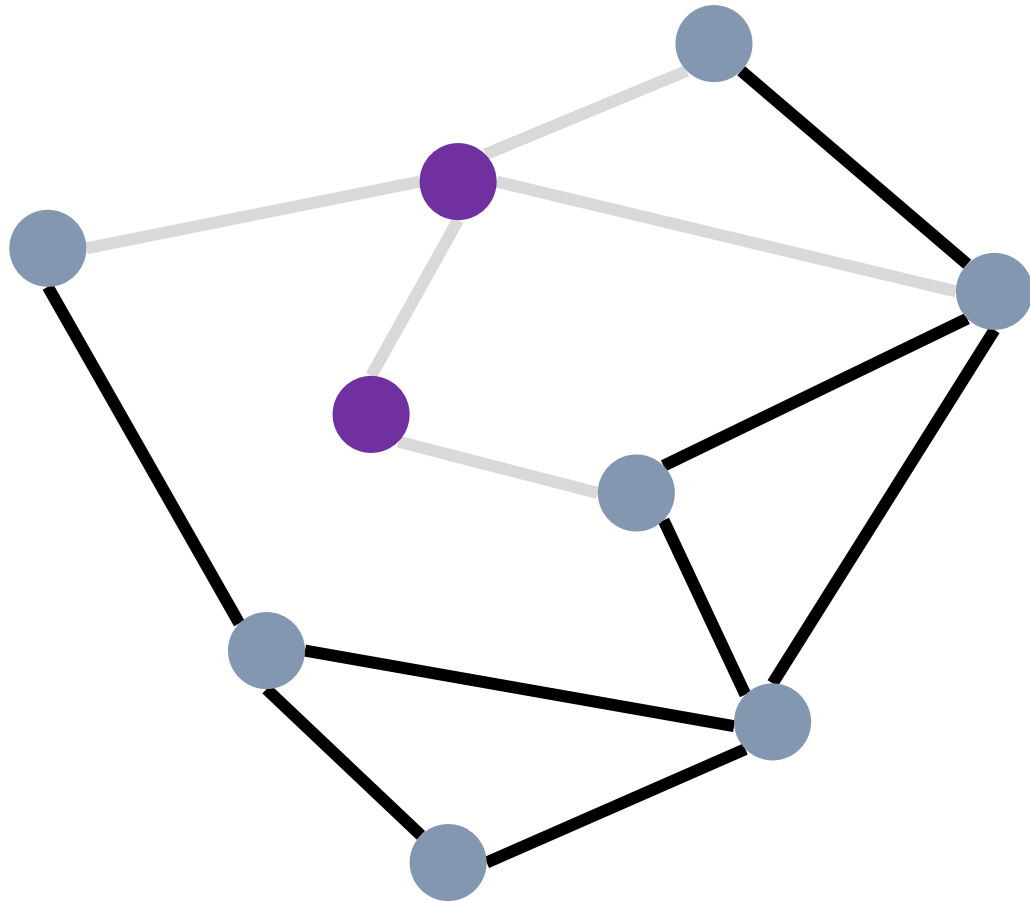


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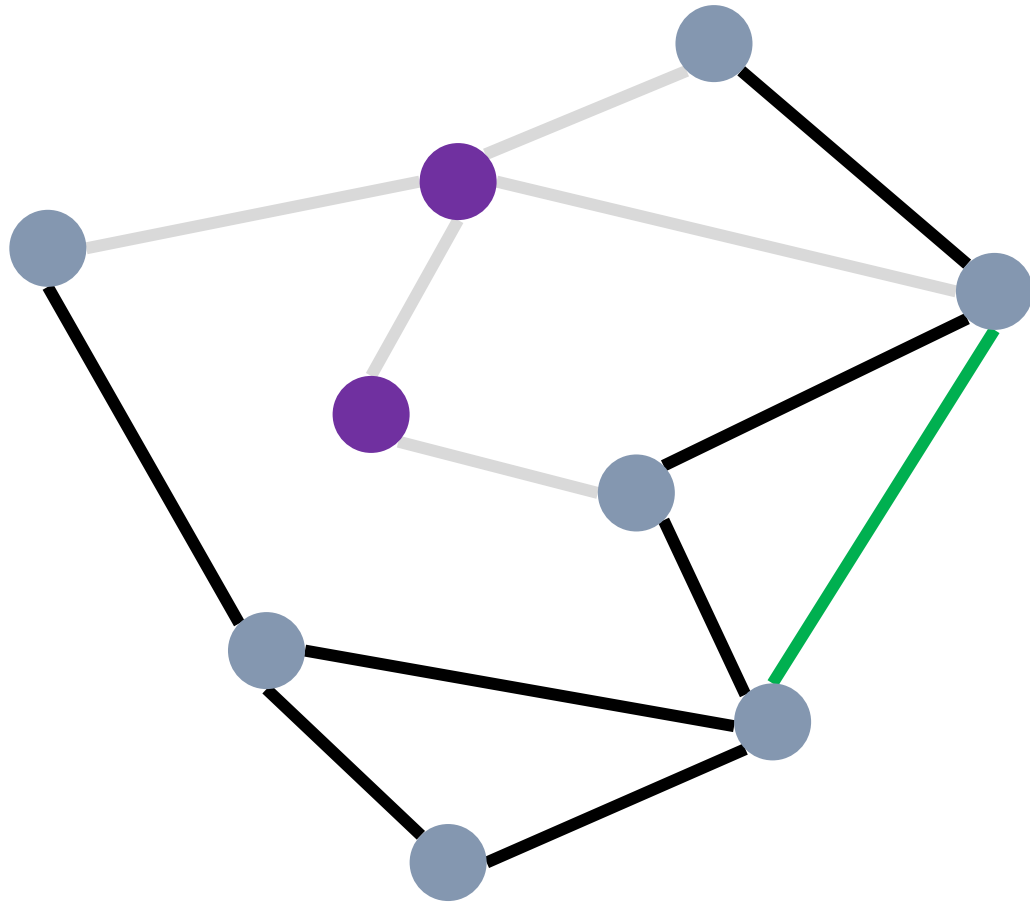


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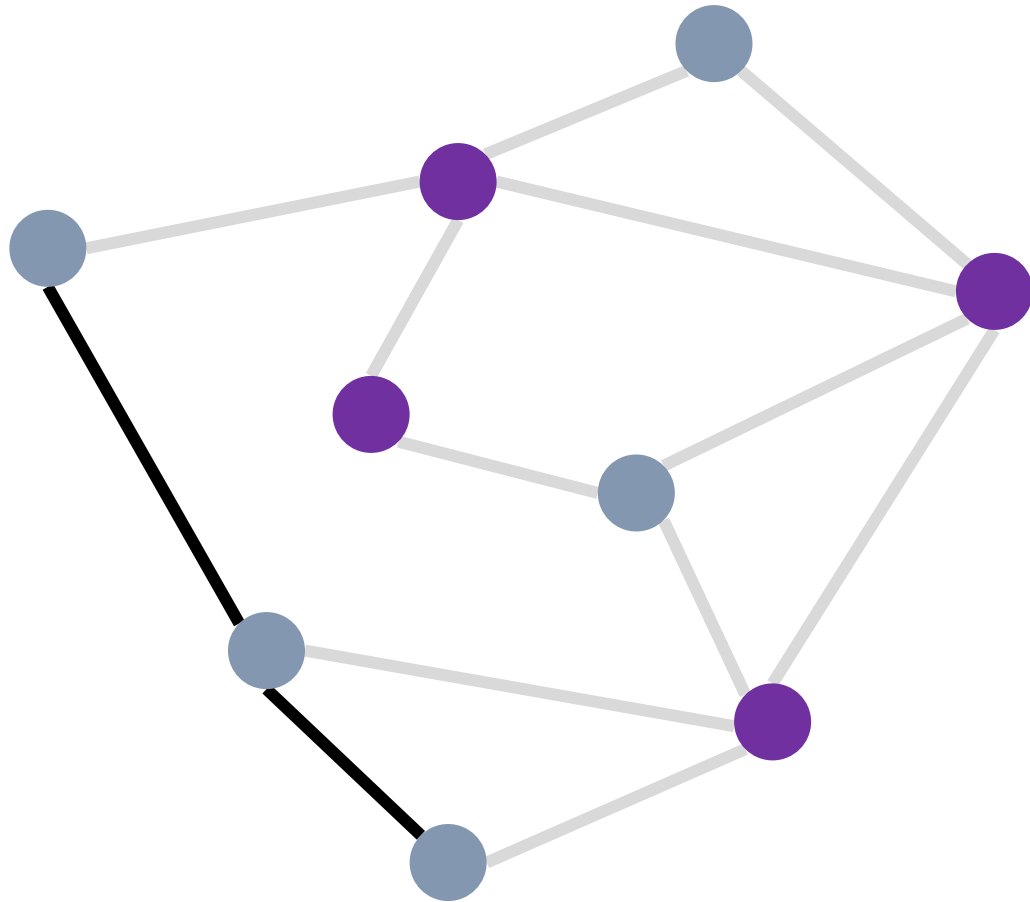


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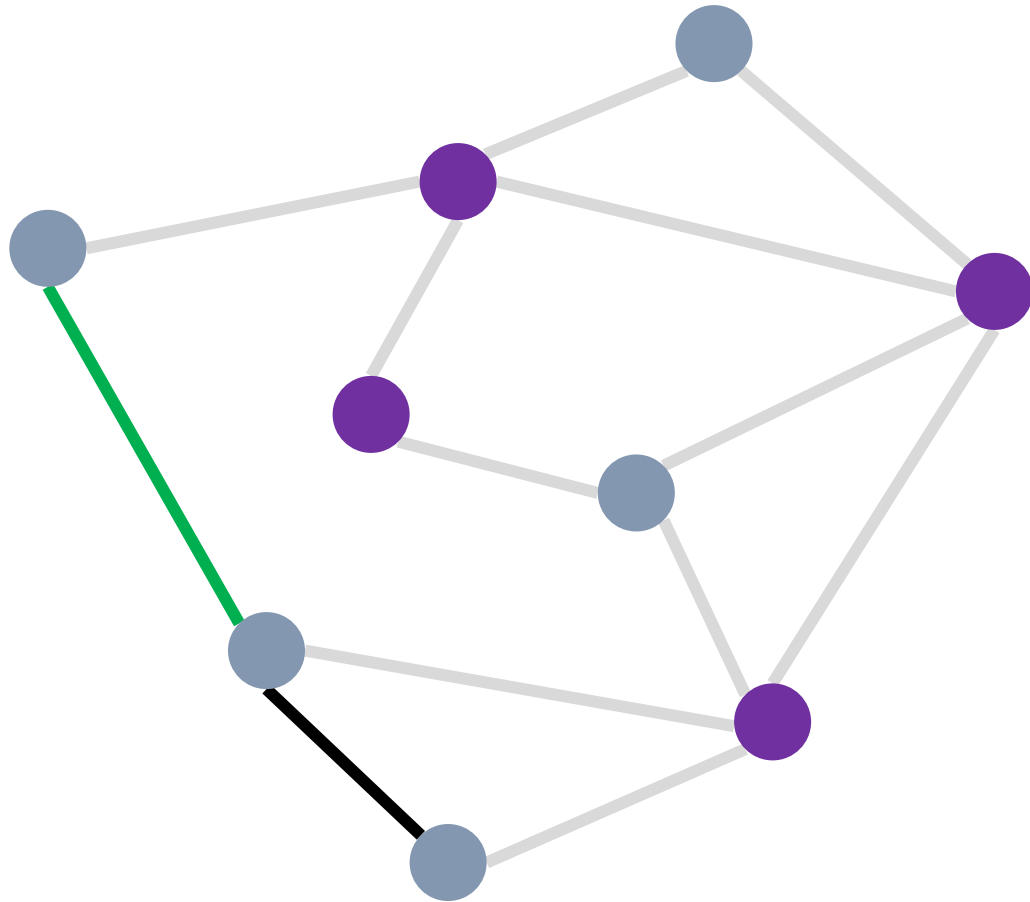


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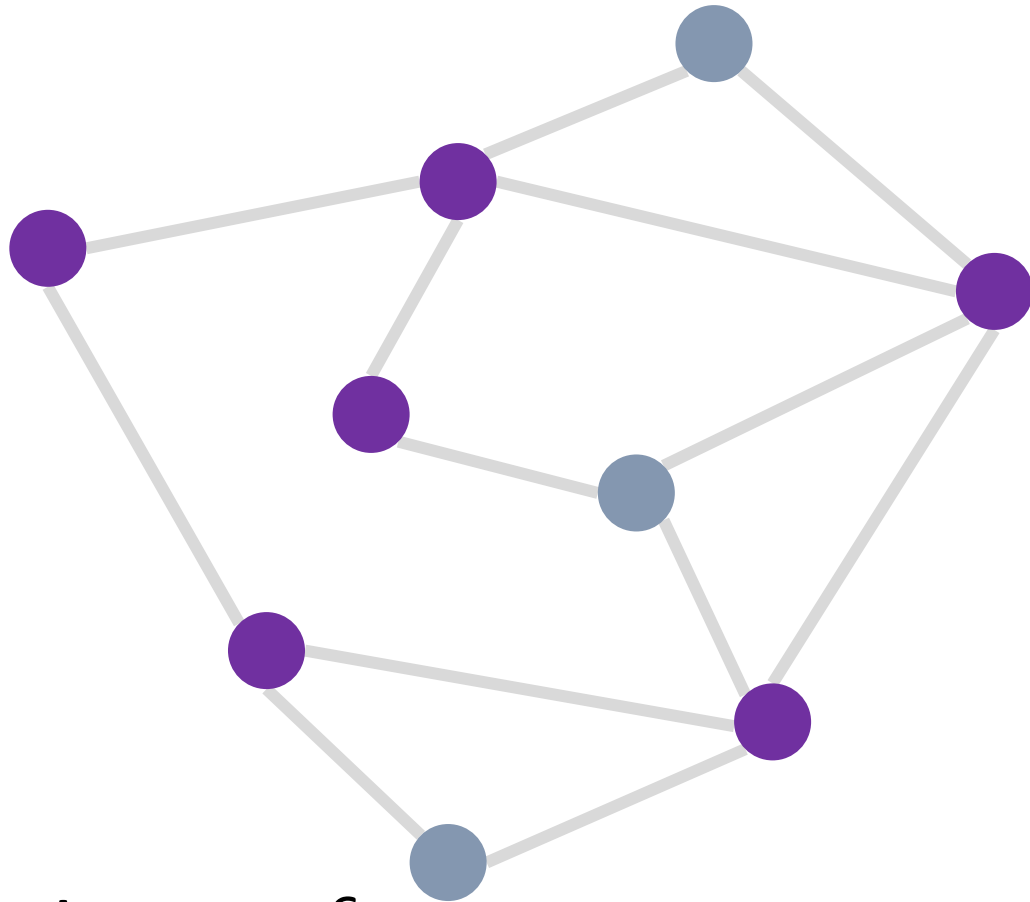


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Approximate Vertex Cover



Size of vertex cover: 6

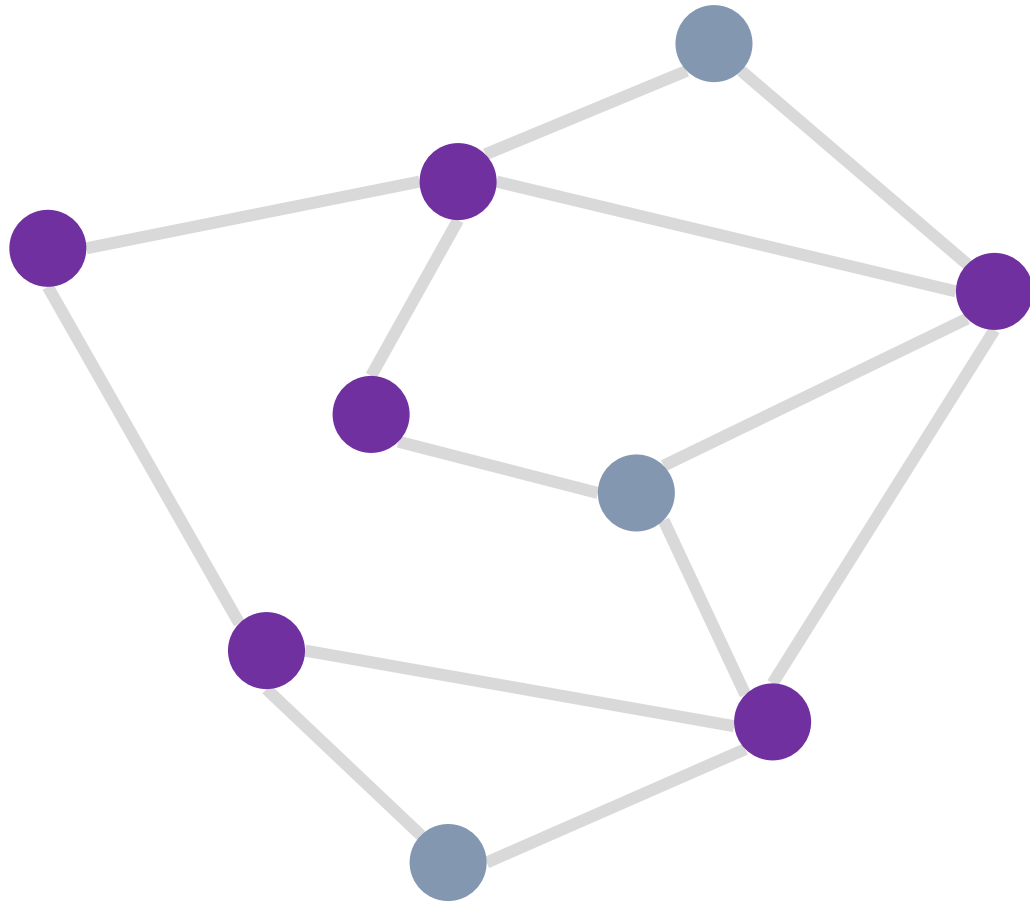
Size of optimal vertex cover: 5

Goal: Obtain a 2-approximation (i.e., vertex cover that is at most twice as large as the optimal)

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Approximate Vertex Cover



Theorem. The approximate algorithm for vertex cover achieves an approximation factor of 2

Consider an edge $e = (u, v) \in E$

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Coping with NP-Hardness

Many optimization problems that come up in practice are NP-complete

What do we do?

Approach 1: Find an algorithm that gives nearly-optimal solutions

Question: Can we do better than a 2-approximation?

Slightly... there is an algorithm that achieves a $\left(2 - O\left(\frac{1}{\sqrt{\log|V|}}\right)\right)$ approximation

Open Problem: Obtain a $(2 - \varepsilon)$ -approximation for constant $\varepsilon > 0$

Question: What's the best we could hope for? Can we have a 1.00001-approximation?

Unlikely, computing a $\sqrt{2} \approx 1.41$ approximation is NP-hard (Khot-Minzer-Safra, 2018)

Earlier lower bounds: $7/6 \approx 1.17$ (Håstad, 1997), $10\sqrt{5} - 21 \approx 1.36$ (Dinur-Safra, 2005)

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Question: Can we do better than a 2-approximation?

Open Problem: Obtain a $(2 - \epsilon)$ approximation (or $(\sqrt{\log|V|})$ approximation)

Open Problem: Obtain a

Hardness of approximation: many NP-hard problems are hard not only to solve exactly, but even hard to approximate (beautiful theory – see also PCP theorem)

Question: What's the

approximation?

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Coping with NP-Hardness

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Approach 2: For small instances, solve using brute force or dynamic programming
Can also improve (expected) run-time using heuristics

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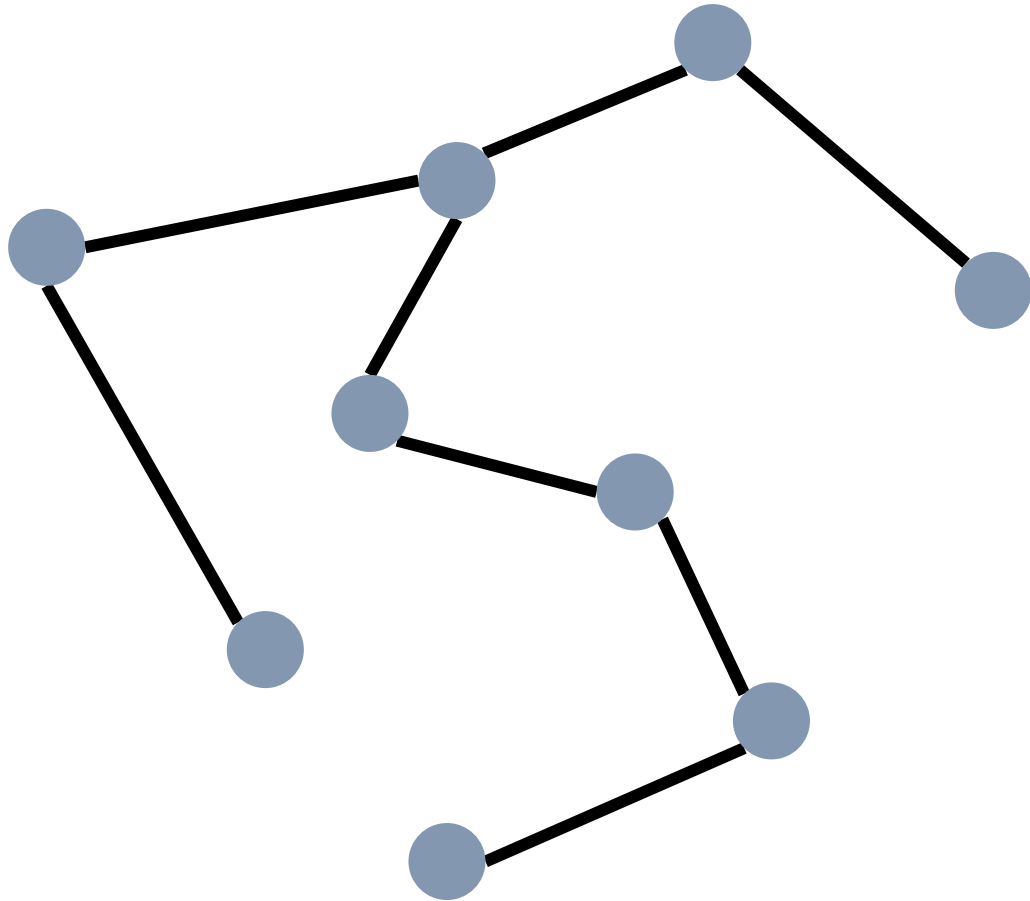
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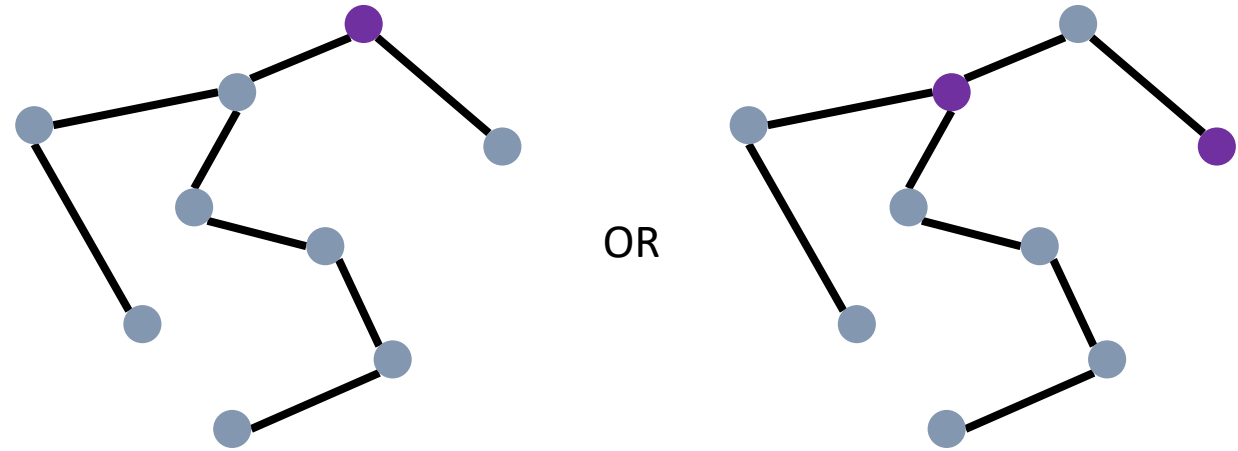
Approach 3: Special cases of the problems can be tractable

Vertex Cover on a Tree



When the graph is a tree, vertex cover can be solved using dynamic programming:

- Consider the root node
- Either it is part of the cover or all of its children are part of the cover



Solve vertex cover on subtrees and take the minimum

Coping with NP-Hardness

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Approach 2: For small instances, solve using brute force or dynamic programming
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Approach 3: Special cases of the problems can be tractable
(see also **parameterized complexity**)