

# Algorithms Homework 4

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Please make all algorithms as efficient as you can, and state their time and space complexities.

- 1-13. Solve the following problems from the [Cormen, 2nd Edition] algorithms textbook:
- p. 216: 10.4-5
  - p. 223: 11.1-4
  - p. 384: 16.2-5
  - p. 392: 16.3-8
  - p. 530: 22.1-6
  - p. 539: 22.2-7, 22.2-8
  - p. 549: 22.3-11
  - p. 552: 22.4-2
  - p. 559: 22-3
  - p. 567: 23.1-11
  - p. 574: 23.2-7
  - p. 600: 24.3-4
14. Give an **optimal** algorithm to determine the diameter of a weighted tree (i.e., longest path between any two nodes). Prove the optimality of your algorithm. What is your time complexity?
15. Give an algorithm to determine whether any two of  $N$  segments on a line intersect.
16. Give an algorithm to find the  $N$ -way intersection of  $N$  rectangles with sides parallel to the axis.
17. Give an algorithm to compute the diameter of a given pointset (i.e., the distance between the farthest pair of points).
18. Give a linear-time algorithm to compute the area of a given convex polygon.
19. Give a linear-time algorithm to compute the area of a given non-convex polygon.
20. What is the worst-case cost of a traveling salesman tour over  $n$  points located arbitrarily in the unit square? Prove it. (Express the cost asymptotically as  $O(f(n))$  for some function  $f$ .)
21. What is the expected (average) cost of a minimum spanning tree over  $n$  points uniformly distributed in the unit square? (Express the cost asymptotically as  $O(f(n))$  for some function  $f$ .)
22. Given  $N$  **red** points and  $N$  **blue** points arbitrarily placed in the plane, we seek to match these  $2N$  points into  $N$  pairs, so that no two of the line segments defined by these pairs intersect. (Assume that no three of the  $2N$  distinct points are collinear.) Prove or disprove: there always exists such a non- self-intersecting matching for any arrangement of  $N$  red and  $N$  blue points arbitrarily located in the plane. Devise an efficient algorithm that given an arbitrary set of  $2N$  red & blue points in the plane, finds such a matching, when one exists. Generalize all this to dimension  $D$ .